ME 535 Assignment 5 - Fall 2018

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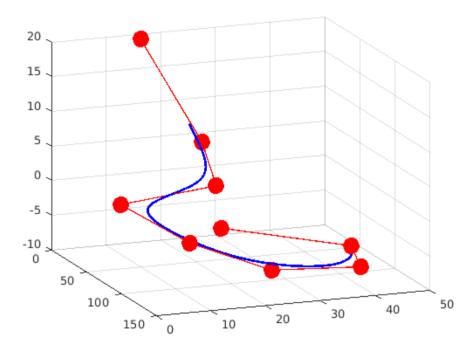
Question 5.5: Plot the cubic B-spline curve defined with the control points. Evaluate it at u = 1.5

```
Ans:
```

```
The Knot vector is: {0 0 0 1 2 3 4 5 6 6 6}
Points are:
P_0 = (10, 15, 20)
P_1 = (20, 25, 5)
P_2 = (40, 25, 0)
P_3 = (60, 5, 0)
P_4 = (80, 15, -5)
P_5 = (80, 30, -10)
P_6 = (90, 45, -10)
P_7 = (115, 40, -5)
P_8 = (125, 15, 0)
%define control points
%P=[0 0; 1 2; 3 5; 5 0; 7 -1];
%define order
%define knot vector
%knots = [0 0 0 0 0.5 1 1 1 1];
%u=0.2;
%L=4; % u=0.2 is between u4=0 and u5=0.5
% P=[0 0;1 0;2 0;4 1;5 2;8 2;9 3];
% order = 4;
% knots=[0 0 0 0 .25 .5 .75 1 1 1 1];
% u=0.6;
% L= 6;
P=[10,15,20; 20,25,5; 40,25,0; 60,5,0; 80,15,-5;
     80,30,-10; 90,45,-10; 115,40,-5; 125,15,0];
order = 4;
knots = [0 0 0 1 2 3 4 5 6 6 6];
u = 1.5
 u = 1.5000
%L = 5;
L = findspan(size(P,1), order-1, u, knots)
 L = 4
disp("Value of the curve at u=1.5")
 Value of the curve at u=1.5
Q = deBoor (order, knots, P, u, L)
    30.1042 24.2708
                        2.9688
%define display configuration
```

```
n = 40;
%do calculation
Q = bsplineCurve(P, order, knots, n);
%do plot of control polygon
plot3(P(:,1),P(:,2),P(:,3),'r-o', 'linewidth',1,'MarkerFaceColor', 'r', 'MarkerSize',14);
hold on;
%do plot of b-spline curve
plot3(Q(:,1),Q(:,2),Q(:,3),'-b', 'linewidth',2);
grid on
hold off

view([68.9 18.8])
```



Question 5.6: Blossom for B Splines

```
P=[0, 0; 1, 0; 1, 1; 0, 1; 0, 2; 2, 2];
order = 4;
knots = [-2 -2 -1 0 2 4 5 6 6 6];
u = 3
```

u = 3

```
%L = 5;
L = findspan(size(P,1),order-1,u,knots)
```

L = 5

```
Q = deBoor(order, knots, P, u, L)
```

Q = 0.4083 1.0167

```
%define display configuration
n = 40;
%do calculation
Q = bsplineCurve(P, order, knots, n);
```

```
%do plot of control polygon
plot(P(:,1),P(:,2),'r-o', 'linewidth',1,'MarkerFaceColor', 'r', 'MarkerSize',14);
hold on;
%do plot of b-spline curve
plot(Q(:,1),Q(:,2),'-b', 'linewidth',2);
hold on
```

Question 5.6(d): Bezier extraction and original curve

Obtain the Bézier representation of the curve segment for knot interval [2, 4]. Draw the original curve and the new Bézier curve and their control points on the same plot.

(Extracted Bezier shown as green segment)

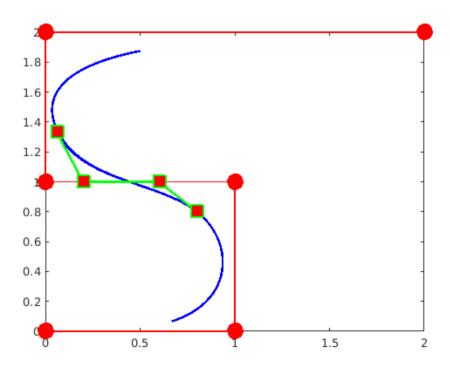
```
n = 100;
disp("Control Points of Extracted Bezier")
```

Control Points of Extracted Bezier

```
P1 = [0.8 0.8;0.6 1;0.2 1;0.06 1.33]
```

```
P1 =
    0.8000    0.8000
    0.6000    1.0000
    0.2000    1.0000
    0.0600    1.3300
```

```
Q = bezierCurve(P1, n);
bezierCurvePlot(P1, Q, '-gs','b');
```



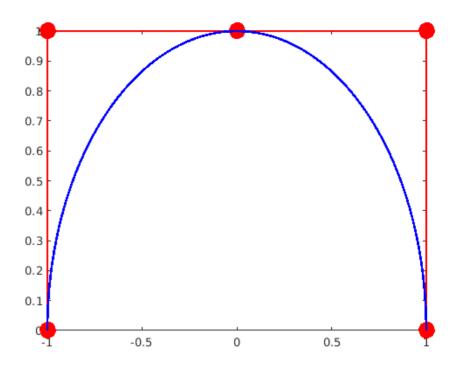
Question 5.7: NURBS curve evaluation

Value of the curve at c(1.25) = (-0.36809, 0.9297), Detailed solution attached at the end of this script.

```
clear all
close all
P=[1, 0; 1, 1; 0, 1; -1, 1; -1, 0];
P_w = [1, 0, 1; 0.7071, 0.7071, 0.7071; 0, 1, 1; -0.7071, 0.7071, 0.7071; -1, 0, 1];
```

```
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order = 3;
knots = [0 \ 0 \ 0 \ 1 \ 1 \ 2 \ 2 \ 2];
u = 1.25
u = 1.2500
%L = 5;
L_w = findspan(size(P_w,1),order-1,u,knots)
L_{w} = 5
Q_w = deBoor(order, knots, P_w, u, L_w)
0 w =
   -0.3277 0.8277
                       0.8902
disp('The value of the curve at c=1.25 is')
The value of the curve at c=1.25 is
Q = Q_w(:,:)/Q_w(:,3)
0 =
   -0.3681 0.9298
                     1.0000
n = 40;
%do calculation
Qw = bsplineCurve(P_w, order, knots, n);
p = size(Qw, 1);
Q = zeros(p, 2);
for i=1:p
```

```
Q(i,1) = Qw(i,1)/Qw(i,3);
    Q(i,2) = Qw(i,2)/Qw(i,3);
end
%do plot of control polygon
plot(P(:,1),P(:,2),'r-o', 'linewidth',1,'MarkerFaceColor', 'r', 'MarkerSize',14);
hold on;
%do plot of b-spline curve
plot(Q(:,1),Q(:,2),'-b','linewidth',2);
hold off
```



Additional functions implemented:

deBoor Algorithm

```
function [R] = deBoor(k, t, P, u, L)
%k order of b-spline
%t knot vector
%P control points with format that every row is a point
%u parameter value
%L index of knot such as t(L) \le u < t(L+1)
for j=1:k
   A(j,:) = P(L-k+j,:); %the control points that affect the computation of point on curve
end
for r=1:(k-1) %time to do recursive computation
    for j=(k):(-1):(r+1) %do one time computation to get next level control points
       i = L-k+j;
        d1 = u - t(i);
                            %for left term in recursive format
       d2 = t(i+k-r) - u; %for right term in recursive format
       A(j,:) = (d1*A(j,:) + d2*A(j-1,:))/(d1 + d2); %carry out computation
    end
end
R = A(k,:); %return the computed point value
end
```

finding Knot Span

```
%%% ========== find knot span =========

% U: knots
% n: number of CP minus 1; that is, p0, p1, ..., p_n
% p: degree
% u: u value
% return the span, starting from u_0.
% Date: Oct 14, 2018
```

```
function s = findspan(n, p, u, U)
if u < U(p) \mid \mid u > U(n+p-1)
    print "error in u value wrt knots"
    П
    return;
end
if (u==U(n+p-1)) % XQ
    s=n;
    return,
end
low = p;
high = n + 1;
mid = floor((low + high) / 2);
while (u < U(mid+1) \mid\mid u >= U(mid+2))
    if (u < U(mid+1))
        high = mid;
    else
        low = mid;
    end
    mid = floor((low + high) / 2);
end
s = mid;
s= s+1; % XQ. For Matlab, we should add one to the return value.
```

bSplineCurve

```
function [Q] = bsplineCurve(P, k, t, n)
%P control points of b-spline
%k order of b-spline
%t knot vector of b-spline
%n for display, namely how many points to be computed on every segment
[m,d] = size(P); %get number of control points m
L = 1;
                %index to computed point
for i=(k):(m)
                 %b-splinbe parameter domain is t(k) - t(m+1)
   step = (t(i+1)-t(i))/(n-1); %parameter increment step
   Q(L,:) = deBoor(k, t, P, u, i); %P, degree, u, knots, i, 0);
       L = L+1;
   end
end
end
```

Functions for BSpline

```
function bezierCurvePlot(P, Q, sP, sQ)
% plot the given control points P and points Q on beizer curve
% P control points
% Q points on bezier curve
% style for P and style for Q: sP, sQ

dim = length(P(1,:));
if dim == 2;
    plot(Q(:,1),Q(:,2),sQ, 'linewidth',2);
    hold on;
    plot(P(:,1),P(:,2),sP, 'linewidth',2,'MarkerFaceColor', 'r', 'MarkerSize',14);
    %hold off;
else
```

```
if dim == 3
        plot(P(:,1),P(:,2),sP, 'linewidth',2);
        hold on:
        plot(Q(:,1),Q(:,2),sQ, 'linewidth',2);
        %hold off;
    end
end
function [Q] = deCasteljau(P, u)
% computer point with parameter value u on bezier curve defined by control points P
% P control points, in matrix format: {size of P} * {dimension of P}
% dimension of P is 2 or 3
% u parameter with value [0 1]
% O point lying on the bezier curve
% input: P: control points P; u: parameter value
% output: 0: the Bezier curve point at u
% example: >> P = [0 \ 0; \ 1 \ 2; \ 3 \ 5; \ 4,4; \ 5 \ 0];
% >> Q=deCasteljau(P, 0.5)
% output:Q =
% 2.6875
           3.3750
% m: # of control points; m = the degree of the curve +1
[m, n] = size(P);
if m <= 1
    err('please specify at least 2 control points');
end
if u < 0 | u > 1
    err('u must be in range from 0 to 1');
end
d = m-1; \% degree
for r=1:d
    for i=1:(d+1-r) % the array index in Matlab starts with 1, not 0.
        P(i,:) = (1-u)*P(i,:) + u*P(i+1,:);
        % ':' operator on all columns: x, y, z
    end
end
Q=P(1,:);
end
function [0] = bezierCurve(P, n)
% computer points on bezier curve defined by control points P
% P control points, in matrix format: {size of P} * {dimension of P}
% n the number of points need to be computed
% isPlot 1 for plot, 0 for non plot
% Q points lying on the bezier curve
i = 1;
for u=0:(1/(n-1)):1
    Q(i,:) = deCasteljau(P, u);
    i = i + 1;
end
end
```