ME 535 Assignment 7 - Fall 2018

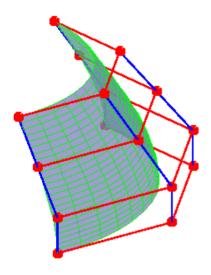
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Exercise 6.2(e):

Exercise 6.2 (f):

Render this patch and its control net.

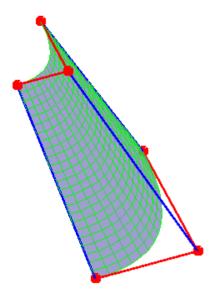
```
clear all, close all;
% control points A for a degree 3 * 3 patch
 P = [1.5 0 2.4; 1.5 -0.84 2.4; 0.84 -1.5 2.4; 0 -1.5 2.4;
      1.75 0 1.875; 1.75 -0.98 1.875; 0.98 -1.75 1.875; 0 -1.75 1.875;
       2 0 1.35; 2 -1.12 1.35; 1.12 -2 1.35; 0 -2 1.35;
       2 0 0.9; 2 -1.12 0.9; 1.12 -2 0.9; 0 -2 0.90]; % Example problem
 nr = 4;
 nc = 4;
% surface evaluation
u = 1/2.; v = 1/2.;
tQ = deCasteljauSurf(P, nr, nc, u, v);
%number of sampled points
snr = 25; % number of sampled points in row (in u direction)
snc = 15; % number of sampled points in col (in v direction)
hold on;
Q = bezierSurf(P, nr, nc, snr, snc);
%plot the surface
bezierSurfPlot(P, Q, nr, nc, snr, snc);
view(3)
axis off;
```



Exercise 6.3

Render the B'ezier patch and its control net

```
clear all;
close all;
%close all;
figure(1)
% Control poits for a degree 2 * 1 patch
P1 = [0 -4 0; 1 -4 0; 2 0 0;
   0 -2 2; 0.5 -2 2; 1 0 2;];
nr = 2;
nc = 3;
% surface evaluation
u = 1/2.; v = 1/2.;
tQ = deCasteljauSurf(P1, nr, nc, u, v);
%number of sampled points
snr = 25; % number of sampled points in row (in u direction)
snc = 15; % number of sampled points in col (in v direction)
%hold on;
Q1 = bezierSurf(P1, nr, nc, snr, snc);
%plot the surface
bezierSurfPlot(P1, Q1, nr, nc, snr, snc);
view(3)
axis off;
```



Functions added:

deCasteljau

```
function [Q] = deCasteljau(P, u)
% computer point with paremeter value u on bezier curve defined by control points P
% P control points, in matrix format: {size of P} * {dimension of P}
% dimension of P is 2 or 3
% u parameter with value [0 1]
% Q point lying on the bezier curve
% input: P: control points P; u: parameter value
% output: Q: the Bezier curve point at u
% example: >>
        P = [0 \ 0; \ 1 \ 2; \ 3 \ 5; \ 4,4; \ 5 \ 0];
% call: 0=deCasteljau(P, 0.5)
% output:0 =
   2.6875
            3.3750
% m: # of control points; m = the degree of the curve +1
[m, n] = size(P);
% if m <= 2
     err('please specify more than 2 control points');
% end
if u < 0 | u > 1
    err('u must be in range from 0 to 1');
end
for i=1:(m-1)
    for j=1:(m-i) % the array index in Matlab starts with 1, not 0.
        P(j,:) = (1-u)*P(j,:) + u*P(j+1,:);
        % ':' meaning for all the columns: x, y, z
    end
end
Q=P(1,:);
end
```

Bezier Surf Plot:

```
function bezierSurfPlot(P, Q, nl, nc, snl, snc)
```

```
% plot the given control points P and points Q on beizer curve
% P control points
% Q points on bezier curve
% nr number of rows of control points
% nc number of columns of control points
% snl number of sampled points in u-dir
% snc number of sampled points in v-dir
hold on;
%plot control points
for i=0:(nl-1)
     PL = P((i*nc+1):(i+1)*nc,:);
     plot3(PL(:,1),PL(:,2),PL(:,3),'-ro', 'linewidth',2,'MarkerFaceColor', 'r', 'MarkerSize',8);
end
for i=0:(nc-1)
     k = (i+1):nc:(nc*nl);
     PL = P(k,:);
     plot3(PL(:,1),PL(:,2),PL(:,3),'-b', 'linewidth',2);
end
%plot surface points
% for i=0:(snl-1)
       QL = Q((i*snc+1):(i+1)*snc,:);
%
       plot3(QL(:,1),QL(:,2),QL(:,3),'-g');
%
       hold on;
% end
% for i=0:(snc-1)
       k = (i+1):snc:(snc*snl);
       QL = Q(k,:);
%
       plot3(QL(:,1),QL(:,2),QL(:,3),'-g');
% end
%figure(2);
[r,c] = size(0);
out = (reshape(Q, [snc, snl, c]));
 p = surf(out(:,:,1), out(:,:,2), out(:,:,3));
% style 1
% p.EdgeColor=0.1*[1 1 1];
% p.FaceAlpha=.75;
% p.FaceColor='green';
% style 2
p.FaceColor = [0.5 \ 0.5 \ 0.75];
p.FaceAlpha=.75; %0.75 %.75;
p.EdgeColor = 'green'; %'interp';
p.LineStyle = '-'; %'none';'
hold off;
end
```

deCasteljau surf function

```
function [Q] = deCasteljauSurf(P, nr, nc, u, v)
%P bezier control points with format [p0; p1; p2;....p(nr*nc)]
%every p(i) is of form (x, y, z) or (x, y)
%nr number of rows
%nc number of columns
%u u-parameter value
```

```
%v v-parameter value

for i=0:(nr-1) %do decasteljau on every row in v-dir
    PR = P((i*nc+1):(i+1)*nc,:); % i-th row CPs
    QR(i+1,:) = deCasteljau(PR, v);
end
Q = deCasteljau(QR, u); %do decastlejau in u-dir
end
```

Bezier surf function

```
function [Q] = bezierSurf(P, nr, nc, snr, snc)
% return points on the surface.
% compute points on bezier surface defined by control points P
% P control points, in matrix format: {size(nr*nc) of P} * {dimension of P}
% nr number of rows of control points
% nc number of colums of control points
% snr the number of points need to be computed in row
% snc the number of points need to be computed in column
% Q points lying on the bezier surface
i = 1;
for u=0:(1/(snr-1)):1
    for v=0:(1/(snc-1)):1
    Q(i,:) = deCasteljauSurf(P,nr, nc, u, v);
    i = i + 1;
    end
end
end
```

6.2

Bernstein functions can be written as:

$$B_{0,3}(u) B_{3,3}(v) = (1-u)^3 v^3$$

$$B_{1,3}(u) B_{3,3}(v) = 3(1-u)^2 u v^3$$

$$B_{2,3}(u) B_{3,3}(v) = 3(1-u) u^2 v^3$$

$$= (0.5)^{3} (0.5)^{3} = \frac{1}{64}$$

$$= 3(0.5)^{2} (0.5) (0.5)^{3} = \frac{3}{64}$$

$$= 3 (0.5) (0.5)^{2} (0.5)^{3} = \frac{3}{64}$$

$$= (0.5)^3(0.5)^3 = \frac{1}{64}$$

$$\sum_{i=0}^{3} B_{i,3}(u) B_{3,3}(v) = \frac{1}{64} + \frac{3}{64} + \frac{3}{64} + \frac{1}{64} = \frac{1}{8}$$

(b) Surjace point s(u,v) =

$$[P] = (1.75 - 0.98 + 1.875) (0.98 - 1.75 + 1.875) (0 - 1.75 + 1.875)$$

$$(2 \ 0 \ 1.35)$$
 $(2 \ -1.12 \ 1.35)$ $(1.12 \ -2)$ $(2 \ 0 \ 0.9)$ $(2 \ -1.12 \ 0.9)$ $(1.12 \ -2)$

$$= > \left[(1-u)^3 \quad 3(1-u)^2 u \quad 3(1-u)u^2 \quad u^3 \right] \left[\frac{1}{4} \right] \left[\frac{(1-v)^3}{3(1-v)^2} \right]$$

$$= \begin{bmatrix} 1.84375 \\ 0 \\ 1.621875 \end{bmatrix} \begin{bmatrix} 1.0325 \\ -1.84375 \\ 1.621875 \end{bmatrix} \begin{bmatrix} 0.125 \\ 0.375 \\ 0.375 \\ 0.125 \end{bmatrix}$$

$$\begin{bmatrix} 1.3090625 \\ 0.125 \end{bmatrix}$$

$$= \begin{pmatrix} 1.3090625 \\ -1.3090625 \\ 1.621875 \end{pmatrix} = 5 \left(\frac{1}{2}, \frac{1}{2} \right) \longrightarrow ANS.$$

$$C(i) \frac{\partial S(\frac{1}{2}, \frac{1}{2})}{\partial U} = \begin{bmatrix} -3(1-u)^2 & 3(3u^2-4u 11) & 3(2u-3u^2) & 3u^2 \end{bmatrix} : \text{ Derivative of blanching functions with } U$$

$$B_{i,m}(u) = \begin{bmatrix} -\frac{3}{4} & -\frac{3}{4} & \frac{3}{4} \end{bmatrix}$$

$$B_{i,m}(v) = \begin{bmatrix} \frac{1}{8} & \frac{3}{8} & \frac{3}{8} & \frac{1}{8} \end{bmatrix}^{T}$$

$$\Rightarrow \begin{bmatrix} -\frac{3}{4} - \frac{3}{4} \end{bmatrix} \begin{bmatrix} (1.5 - 0.84 - 2.4) & (0.84 - 1.5 - 2.4) & (0 - 1.5 - 2.4) \\ (1.75 - 0.98 + 1.815) & (0.98 - 1.75 + 1.825) & (0 - 1.75 + 1.825) \\ (2 - 0.1.35) & (2 - 1.12 + 1.35) & (0.12 - 2 + 1.35) & (0 - 2 + 1.35) \\ (2 - 0.9) & (2 - 1.12 + 0.9) & (0.12 - 2 + 0.9) & (0 - 2 + 0.90) \end{bmatrix}$$

$$= > \begin{bmatrix} 0.5825 \\ 0 \\ -0.315 \\ -1.51575 \end{bmatrix} \begin{bmatrix} 0.315 \\ -0.5825 \\ -1.51575 \end{bmatrix} \begin{bmatrix} 0.315 \\ -0.5875 \\ -1.51575 \end{bmatrix} \begin{bmatrix} 1/8 \\ 3/8 \\ 1/8 \end{bmatrix} = \begin{bmatrix} 0.399375 \\ -0.399375 \\ -1.51875 \end{bmatrix} \rightarrow Amo$$

(d(i)
$$\frac{25}{2}(\frac{1}{2},\frac{1}{2}) = \left[-3(1-v)^2 \ 3(3v^2-4v+1) \ 3(2v-3v^2) \ 3v^2\right].$$

at
$$u = 0.5$$
 and $v = 0.5$

$$B_{i,m}(u) = \begin{bmatrix} \frac{1}{8} & \frac{3}{8} & \frac{3}{8} & \frac{1}{8} \end{bmatrix}$$
 $B_{i,m}(v) = \begin{bmatrix} -\frac{3}{4} & -\frac{3}{4} & \frac{3}{4} \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} \frac{1}{8} & \frac{3}{8} & \frac{3}{8} & \frac{1}{8} \end{bmatrix} \begin{bmatrix} (1.5 & 0.2.4) & (1.5 & -0.84.24) & (0.84 & -1.5.24) & (0.15.24) & -\frac{9}{4} \\ (1.75 & 0.1.875) & (1.75 & -0.98.1.875) & (0.98 & -1.75.180) & (0.425.185) & \frac{3}{4} \\ (2 & 0.1.35) & (2 & -1.12.1.35) & (1.12 & -2.1.35) & (0.2.1.35) & \frac{3}{4} \\ (2 & 0.0.9) & (2 & -1.12.0.9) & (1.12 & -2.0.9) & (0.-2.0.90) \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} (1.84375) & (1.9325) & (1.0$$

$$\Rightarrow \begin{bmatrix} 1.84375 \\ 0 \\ -1.0325 \end{bmatrix} \begin{bmatrix} -1.84375 \\ -1.84375 \end{bmatrix} \begin{bmatrix} -3/4 \\ -3/4 \\ 3/4 \end{bmatrix} = \begin{bmatrix} -1.99125 \\ -1.99125 \end{bmatrix}$$

$$\begin{vmatrix} -1.99125 \\ -1.621875 \end{vmatrix} \begin{vmatrix} -621875 \\ 1.621875 \end{vmatrix} \begin{vmatrix} -621875 \\ 3/4 \end{vmatrix} = \begin{bmatrix} -1.99125 \\ 3/4 \end{vmatrix}$$

$$\begin{vmatrix} 0.5625 \\ 0 \\ -0.315 \\ -1.51875 \end{vmatrix} \begin{vmatrix} 0.315 \\ -0.5625 \\ -0.5625 \end{vmatrix} \begin{vmatrix} 0.315 \\ -0.5625 \\ -0.5625 \end{vmatrix} \begin{vmatrix} -3/4 \\ -3/4 \\ 3/4 \\ 0 \end{vmatrix} = \begin{vmatrix} -0.6075 \\ -0.6075 \\ 3/4 \end{vmatrix}$$

$$\begin{vmatrix} -1.51875 \\ -1.51875 \end{vmatrix} \begin{vmatrix} -1.51875 \\ -1.51875 \end{vmatrix} \begin{vmatrix} -1.51875 \\ -1.51875 \end{vmatrix}$$

@ Tangent plane and (usface normal at point 5(1/2,1/2)

Normal vector given as: $\frac{ds}{du} \times \frac{ds}{du} = \begin{bmatrix} -3.0223 & 3.0223 & -1.5888 \end{bmatrix}$

Tangent vector given as: $\{s(u,v)\}$. $\{\frac{ds}{du} \times \frac{ds}{dv}\} = -3.0223x + 3.0223y - 1.5888z = -10.488$

[CALCULATION IN CODE].

· Parametric representation of a parabolic come

$$S(u,v) = (u(2-v), 2(u^2-1)(2-v), 2v)$$

* With tensor product blossom form, blossoming in u or v Can be represented as:

$$S(u,v) = (u(2-v), 2(u^2-1)(2-v), 2v).$$

 $b[u_1,u_2|v] = (u_1+u_2/2*(2-v), 2(u_1u_2-1)(2-v), 2v)$

* The control foints can be obtained as

$$P_{ov} = b[0,0|v] = (0,-2(2-v),2v) = (0,2v-4,2v)$$

$$\rightarrow P_{00} = (0, -4, 0)$$

$$\rightarrow P_{01} = (0, -2, 2)$$

$$P_{iv} = b[0, 1|v] = (\frac{1}{2}(2-v), -2(2-v), 2v) = (\frac{2-v}{2}, 2v-4, 2v)$$

$$\rightarrow P_{11} = (0.5, -2, 2)$$

$$P_{2V} = b[1,1|V] = (2-V,0,2V) = (2-V,0,2V)$$

$$\rightarrow P_{2i} = (1, 0, 2)$$

* The Bexus Depresentation: