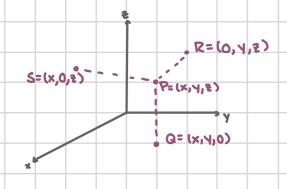
Introduction to the 3-D coordinate System

The 3-D coordinate system is often denoted by \mathbb{R}^3 , mimicking \mathbb{R}^2 for the 2-D coordinate system and \mathbb{R} for the 1-D coordinate system. We can also bring this out to a n-dimensional coordinate system denoted by \mathbb{R}^n . Visually the 3-D coordinate system is shown below:

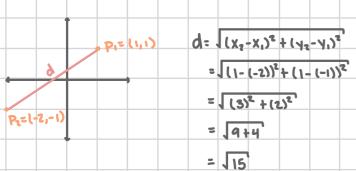


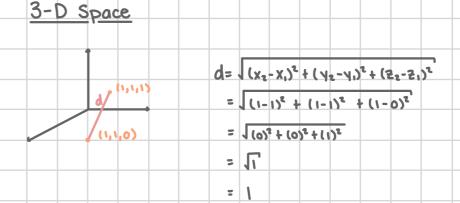
This is the standard placement of the axes with it assumed that only the positive directions are shown. We will add the negative axes only if needed and label them. The point P=(x,y,z) is a general point sitting in 3-D space. We may use the word projection to describe going from the xyz-system to any of the 2-D planes, e.g. if you drop down to z=0 then we get the point Q=(x,y,0) in the xy-plane. In addition, we can find points S and R in the xz- and yz- plane, respectively.

Properties of 3-D

Many of the formulas you are familiar with in R² have natural extensions into the R³ coordinate system. For example, the distance between two points:



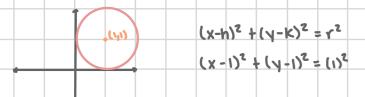




Likewise, the general equation of a circle with center (h,k) and radius r extends to a sphere with center (h,k,l) and radius r:

3-D Space

2-D Space



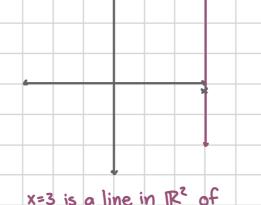
$$(x-h)^{2} + (y-k)^{2} + (z-l)^{2} = r^{2}$$

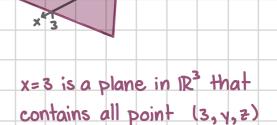
$$(x-1)^{2} + (y-1)^{2} + (z-1)^{2} = (1)^{2}$$

Not everything about \mathbb{R}^2 translates to \mathbb{R}^3 the way we expect. For example, let's graph x=3 in \mathbb{R} , \mathbb{R}^2 , \mathbb{R}^3 .



x=3 is a point on IR





x=3 is a line in \mathbb{R}^2 of all points of the form (3,y)

Standard 03: Planes Planes in 3D Equation of a Plane in 3-D A plane in 3D requires two things: · a point in the plane 70 = (x0, y0, 20) · the direction orthogonal to the plane n= <a,b,c> vector equation = no (t-to)=0. standard equation = ax + by + cz = d = nord example. Find the equation of the plane that contains the point (7,2,-1) and is orthogonal to the line given by the parametrization = (t) = <1-2t, 3t, 2-t>. We are given the point (7, 2,-1) and a vector that is orthogonal. 7= (7,2,-1) i n= k-2,3,-1> Since F(t) is orthogonal, its direction vector is orthogonal to the -2x +3y -17= <-2,3,-1>0 < 7,2,-1 -2x+3y-2 = -14+6+1 =-7 plane. So we have our two parts. -2x+3y-2=-7 example. Find an equation for P. the plane that goes through the points (0,1,2), (-1,1,3), and (1,2,2). To find the equation of a plane we need a point on the plane and normal vector n (-1,1,3) , (1,2,2) We are given three points to choose from and can find a normal vector by finding (0,1,2) a cross product between two vectors in the plane, the vector between given points work: (0,1,2) to (-1,1,2) is <-1,0,1> and (0,1,2) to (1,2,2) is <1,1,0>. $\vec{n} = \langle -1, 0, 1 \rangle \times \langle 1, 1, 0 \rangle = \vec{t} \vec{j} \vec{k} = (0-1)\vec{t} - (0-1)\vec{j} + (-1-0)\vec{k}$ =-12+17-18 = < -1, 1, -1> standard equation: ax + by + cz = n. r. -1x+1y-12=4-1,1,-1> · <0,1,2> -x +y -2 = 0 +1 -2 -X + 7 - 5 = -1 example. Let P, be the plane found in the above example and Pz be the plane described by x-y+2z=1. Do these planes intersect? If so, find the line of intersection and the cosine of the angle between the planes? If the normal vectors of P. F.P. are scalars of each other then they do not intersect, otherwise we can find L. Since Lis contained in R and Pz, L must be orthogonal to the normal vectors for each plane, in, and \vec{n}_2 . Thus the direction of L is $\vec{n}_1 \times \vec{n}_2$. To find the initial point of the line, we must find a x, y, z s.t. P, and Pz are satisfied. $\vec{n}_1 = \langle -1, 1, -1 \rangle \neq \vec{n}_2 = \langle 1, -1, 2 \rangle$ using the point (1,0,0) and $\vec{n} = \langle 1,1,0 \rangle$ $\vec{n}_1 \times \vec{n}_2 = \vec{l} \vec{j} \vec{k}$ 7(t)= <1,0,0>+ t <1,1,0> Finding initial point: -X+Y-5=-1 -1 1 -1 1 -1 2 x -y+2==1 = (2-1) = (-2-(-1)) = + (1-1) = 0x +0y + 12 = 0 = 11-(-1) + 0 k 2=0 if z=0 then xty=1 = <1,1,0>

