Algorithms-Design and Analysis(Stanford) Notes

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目录

1 Divide and Conquer

1. **DIVIDE** into smaller sub-problems
2. **CONQUER** via recursive calls
3. **COMBINE** solutions of sub-problems into one for the original problem

1.1 Master Method

- Cool feature: a "black-box" method for solving recurrences
- Determine the upper bound of **running time** for most of the D&C algos
- **Assumption**: all sub-problems have equal size
  - unbalanced sub-problems?
  - more than one recurrence?
- **Recurrence format**:
  - base case: $T(n) \leq C$ (a constant), for all sufficiently small n
  - for all larger n, $T(n) \leq aT(\frac{n}{b}) + O(n^d)$
    * a: # of recurrence calls (e.g., # of sub-problems), $a \geq 1$
    * b: input size shrinkage factor, $b > 1$, $T(\frac{n}{b})$ is the time required to solve each sub-problem
    * d: exponent in running time of the combine step, $d \geq 0$
    * constants a, b, d independent of n

- **Three Cases**:

$$T(n) = \begin{cases} O(n^d \log n), & a = b^d \text{ (case 1)} \\ O(n^d), & a < b^d \text{ (case 2)} \\ O(n^{\log_b a}), & \text{otherwise (case 3)} \end{cases}$$

If $T(n) = aT(\frac{n}{b}) + \Theta(n^d)$, then (with similar proof)

$$T(n) = \begin{cases} \Theta(n^d \log n), & a = b^d \text{ (case 1)} \\ \Theta(n^d), & a < b^d \text{ (case 2)} \\ \Theta(n^{\log_b a}), & \text{otherwise (case 3)} \end{cases}$$

1.1.1 Proof (Recursion Tree Approach)

3 cases $\Leftrightarrow$ 3 types of recursion trees

For simplicity, we assume:

- $T(1) \leq C$ (for some constant C)
- $T(n) \leq aT(\frac{n}{b}) + Cn^d$
- n is a power of b

At each level $j = 0, 1, \ldots, \log_b n$, there are

- a^j sub-problems,
- each of size n/b^j
- $(1 + \log_b n)$ levels, level-0: **root**, level-$\log_b n$: **leaves**

Then

$$\text{Total work at level-}j \leq a^j \times C \left(\frac{n}{b^j}\right)^d$$

Thus,

$$\text{Total work} \leq Cn^d \sum_{j=0}^{\log_b n} \left(\frac{a}{b^d}\right)^j \quad (\Delta)$$

$\Rightarrow$ all depends on the relationship between a and b^d

For constant $r > 0$,

$$1 + r + r^2 + \cdots + r^k = \frac{1 - r^{k+1}}{1 - r} \leq \begin{cases} \frac{1}{1-r}, & r < 1 \\ \frac{r}{r-1} r^k, & r > 1 \end{cases}$$

- $0 < r < 1$, $LHS \leq Constant$
- $r > 1$, LHS is dominated by the largest power of r

Case 1. $a = b^d$

$$(\Delta) \leq Cn^d \times log_b n = O(n^d \log n)$$

Case 2. $a < b^d$

$$(\Delta) \leq O(n^d)$$

Case 3. $a > b^d$

$$(\Delta) \leq Cn^d \left(\frac{a}{b^d}\right)^{\log_b n} = Ca^{\log_b n} = Cn^{\log_b a} = O(n^{\log_b a})$$

$$n^{\log_b a} = a^{\log_b n} \Leftrightarrow \log_b a \log_b n = \log_b n \log_b a$$

1.1.2 Interpretations

Upper bound on the work at level j:

$$Cn^d \times \left(\frac{a}{b^d}\right)^j$$

a : rate of sub-problem poliferation, RSP - force of evil

b^d : rate of work shrinkage (per sub-problem), RWS - force of good

- $RSP < RWS$
  - amount of work is decreasing with the recursion level j
  - most work at root $\Rightarrow$ root dominates $\Rightarrow$ might expect $O(n^d)$
- $RSP > RWS$
  - amount of work is increasing with the recursion level j
  - leaves dominate $\Rightarrow$ might expect $O(\#\text{leaves}) = O(a^{\log_b n}) = O(n^{\log_b a})$
- $RSP = RWS$
  - amount of work is the same at each recursion level j (like merge sort)
  - might expect $O(\log n) \times O(n^d) = O(n^d \log n)$ (recursion depth $= O(\log n)$)

1.2 Counting Inversions

- **Problem**: counting # of inversions in an array = # of pairs `(i,j)` of array indices with `i<j` and `A[i]>A[j]`
- Number of inversions = Number of intersections of line segments

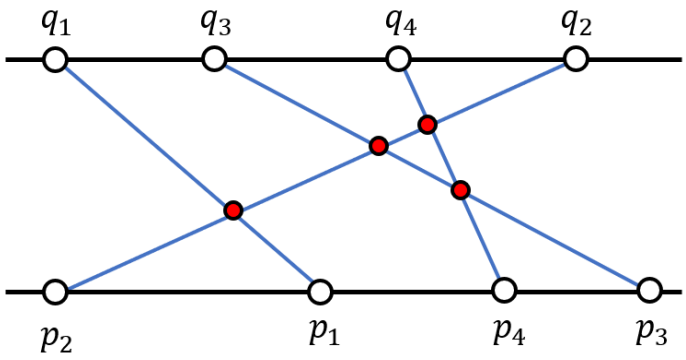

图 1: No. of Inversions = No. of Intersections

- **Application**: measuring similarity between 2 ranked lists => making good recommendations => **collaborative filtering** (CF)
- Largest possible number of inversions that an n-element array can have? C_n^2 (worst case: array in backward order)
- **Brute-force** algorithm: $O(n^2)$
- **D&C** algorithm: pseudocode

A = input array [length = n]
D = output [length= n]
B = 1st sorted array [n/2], C = 2nd sorted array [n/2]

```
SortAndCount(A)
if n=1
    return 0
else
    (B,X) = SortAndCount(1st half of A)
    (C,Y) = SortAndCount(2nd half of A)
    (D,Z) = MergeAndCountSplitInv(A)
return X + Y + Z
```

Goal: implement `MergeAndCountSplitInv` in linear time $O(n)$
The **split inversions** involving an element y of the 2nd array C are precisely the elements left in the 1st array B when y is copied to the output D.

$$T(n) \leq 2T\left(\frac{n}{2}\right) + O(n) \Rightarrow T(n) = O(n \log n)$$

1.2.1 Python Code

```python
def sortAndCount(arr):
        n = len(arr)
        # base case
        if n < 2:
            return arr, 0

        m = n//2
        left, x = sortAndCount(arr[:m])
        right, y = sortAndCount(arr[m:])

        i = j = z = 0
        for k in range(n):
            if j == n - m or (i < m and left[i] < right[j]):
                arr[k] = left[i]
                i += 1
            else:
                arr[k] = right[j]
                j += 1
                z += (m - i)
        return arr, x + y + z
```

1.3 Karatsuba Multiplication

- **Problem**: multiplication of two n-digit numbers x, y (base 10)
- **Application**: cryptography
- Define *primitive operations*: add or multiply 2 single-digit numbers
- Simple method: $\leq 4n^2 = O(n^2)$ operations
- **Recursive method**:

$$x = 10^{n/2}a + b, y = 10^{n/2}c + d, \text{ where } a, b, c, d \text{ are } \frac{n}{2} - \text{digit numbers}$$

$$\Rightarrow xy = 10^n ac + 10^{n/2}(ad + bc) + bd \qquad (*)$$

Algorithm 1 (Naive method)

- recursively compute ac, ad, bc, and bd
- then compute $(*)$

Running time

$$T(n) \begin{cases} = O(1), & n = 1(\text{base case}) \\ \leq 4T(\frac{n}{2}) + O(n), & n \geq 1(4 \text{ subproblems and linear time bit addition}) \end{cases}$$

By master method,

$$a = 4 > 2^1 = b^d(\text{case 3}) \Rightarrow T(n) = O(n^{\log_b a}) = O(n^2)$$

Algorithm 2 (Gauss method)

- recursively compute ac, bd, $(a + b)(c + d)$
- $ad + bc = (a + b)(c + d) - (ac + bd)$
- then compute $(*)$

Running time

$$T(n) \begin{cases} = O(1), & n = 1(\text{base case}) \\ \leq 3T(\lceil \frac{n}{2} \rceil) + O(n), & n \geq 1(3 \text{ subproblems and linear time bit addition}) \end{cases}$$

By master method,

$$a = 3 > 2^1 = b^d(\text{case 3}) \Rightarrow T(n) = O(n^{\log_b a}) = O(n^{\log_2 3}) = O(n^{1.59})$$

Better than simple method!

1.3.1 Python Code

```python
def karatsuba(x, y):
    nx, ny = len(str(x)), len(str(y))
    n = max(nx, ny)

    # base case
    if n == 1:
        return x*y

    m = n//2
    bm = 10**m
    a, b = x//bm, x%bm
    c, d = y//bm, y%bm
    term1 = karatsuba(a, c)
    term2 = karatsuba(b, d)
    term3 = karatsuba(a+b, c+d)
    result = (bm**2)*term1 + bm*(term3 - term1 - term2) + term2
    return result
```

1.4 Binary Search

- **Problem**: looking for an element in a given sorted array
- **Running time**: $T(n) = T(n/2) + O(1)$. By master method,

$$a = 1 = 2^0 = b^d \text{ (case 1)} \Rightarrow T(n) \leq O(n^d \log n) = O(\log n)$$

1.4.1 Python Code

See link

1.5 Strassen's Matrix Multiplication

- **Problem**: compute $Z_{n\times n} = X_{n\times n} \cdot Y_{n\times n}$ (Note: input size = $O(n^2)$)
- Naive iterative algorithm: $O(n^3)$ (3 **for** loops)

$$z_{ij} = \sum_{k=1}^{n} x_{ik} \cdot y_{kj}$$

- Write

$$X = \begin{pmatrix} A & B \\ C & D \end{pmatrix}, Y = \begin{pmatrix} E & F \\ G & H \end{pmatrix}$$

where A through H are all $\frac{n}{2} \times \frac{n}{2}$ matrices. Then

$$X \cdot Y = \begin{pmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{pmatrix}$$

- Recursive method #1:
  - **step1**. recursively compute the 8 products
  - **step2**. do additions ($O(n^2)$ time)
  - **Running time**: by master method,

$$a = 8 > 2^2 = b^d \text{ (case 3)} \Rightarrow T(n) \leq O(n^{\log_b a}) = O(n^{\log_2 8}) = O(n^3)$$

- **Strassen's method**:
  - **step1**. recursively compute only 7 (cleverly chosen) products
  - **step2**. do (clever) additions ($O(n^2)$ time)
  - **Running time**: by master method,

$$a = 7 > 2^2 = b^d \text{ (case 3)} \Rightarrow T(n) \leq O(n^{\log_b a}) = O(n^{\log_2 7}) = O(n^{2.81})$$

The 7 products:

$$P_1 = A(F - H)$$
$$P_2 = (A + B)H$$
$$P_3 = (C + D)E$$
$$P_4 = D(G - E)$$
$$P_5 = (A + D)(E + H)$$
$$P_6 = (B - D)(G + H)$$
$$P_7 = (A - C)(E + F)$$

Then

$$X \cdot Y = \begin{pmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{pmatrix}$$
$$= \begin{pmatrix} P_5 + P_4 - P_2 + P_6 & P_1 + P_2 \\ P_3 + P_4 & P_1 + P_5 - P_3 - P_7 \end{pmatrix}$$

```python
import numpy as np
def strassen(X, Y):
    n = X.shape[0]
    if n == 1:
        return np.array([X[0, 0]*Y[0, 0]])

    if n%2 == 1: # padding with zeros
        Xpad = np.zeros((n + 1, n + 1))
        Ypad = np.zeros((n + 1, n + 1))
        Xpad[:n, :n], Ypad[:n, :n] = X, Y
        return strassen(Xpad, Ypad)[:n, :n]

    m = n//2
    A, B, C, D = X[:m, :m], X[:m, m:], X[m:, :m], X[m:, m:]
    E, F, G, H = Y[:m, :m], Y[:m, m:], Y[m:, :m], Y[m:, m:]

    P1 = strassen(A, F - H)
    P2 = strassen(A + B, H)
    P3 = strassen(C + D, E)
    P4 = strassen(D, G - E)
    P5 = strassen(A + D, E + H)
    P6 = strassen(B - D, G + H)
    P7 = strassen(A - C, E + F)

    Z = np.zeros((n, n))
    Z11 = P5 + P4 - P2 + P6
    Z12 = P1 + P2
    Z21 = P3 + P4
    Z22 = P1 + P5 - P3 - P7

    Z[:m, :m], Z[:m, m:], Z[m:, :m], Z[m:, m:] = Z11, Z12, Z21, Z22

    return Z
```

1.6 Closest Pair

- **Input**: a set $P = \{p_1, \ldots, p_n\}$ of n points in the plane ($\mathbb{R}^2$)
- Notation: $d(p, q)$ = Euclidean distance
- **Output**: $p^*, q^* = \arg \min_{p \neq q \in P} d(p, q)$
- **Assumption**: (for convenience) all points have distinct x-coordinates, y-coordinates
- **Brute-force search**: $\Theta(n^2)$
- 1-d version of CP:
  - sort points ($O(n \log n)$ time)
  - return CP of adjacent points ($O(n)$ time)
- **Goal**: $O(n \log n)$ time algo for 2-d version
- **D&C**: make copies of points sorted by x-coordinates (P_x) and by y-coordinates (P_y) [$O(n \log n)$ time]

`ClosestPair`(P_x, P_y)

1. Q = left half of P, R = right half of P. Form Q_x, Q_y, R_x, R_y [$O(n)$ time]
2. (p_1, q_1) = `ClosestPair`(Q_x, Q_y)
3. (p_2, q_2) = `ClosestPair`(R_x, R_y)
4. let $\delta = \min\{d(p_1, q_1), d(p_2, q_2)\}$
5. (p_3, q_3) = `ClosestSplitPair`(P_x, P_y). Requirements:
   (a) $O(n)$ time
   (b) correct whenever CP of P is a split pair
6. return best of $(p_1, q_1), (p_2, q_2), (p_3, q_3)$

`ClosestSplitPair`(P_x, P_y)

1. Let $\bar{x}$= biggest x-coordinate in the left of P [$O(1)$ time]
2. Let S_y = points of P with x-coordinate in $[\bar{x} - \delta, \bar{x} + \delta]$, sorted by y-coordinate
3. Initialize best = δ, best point = `NULL`, $m = |S_y|$.

```
For i = 1 to m-1
    For j = 1 to min(7, m-i)
        Let p, q = ith, (i+j)th points of P
        If d(p, q) < best
            best point = (p, q), best = d(p, q)
```

[$O(n)$ time]

Claim. Let $p \in Q$, $q \in R$ be a split pair with $d(p, q) < \delta$. Then

1. $p, q \in S_y$
2. p, q are at most 7 positions apart in S_y

Corollary 1. If CP of P is a split pair, then `ClosestSplitPair` can find it.
Corollary 2. `ClosestPair` is correct, and runs in $O(n \log n)$ time.

1.6.1 Python Code