

Notes Masters Thesis

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Abstract

Notes

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1 Baby Case

((Name for cut point which is not conj point)) ((Quotient direction set up to rescaling or restrict to unit length vectors)) ((Null geodesics intersect backwards cone exactly once))

Theorem 1.1 (Baby Case). *Let $(M_j, g_j), j = 1, 2$ be two open globally hyperbolic, time-oriented Lorentzian manifolds. For $p_j^- \ll p_j^+$ two points in M_j we denote $K_j = J(p_j^-, p_j^+) \setminus I^-(p_j^+)$, the closed and compact backwards light cone from p_j^+ cut off at the intersection with the forwards light cone of p_j^- . We assume that there exist a conformal diffeomorphism $\Phi : K_1 \rightarrow K_2$ and that none of the past null geodesics starting at p_j^+ have a cut point in K_j .*

Now let V_j be open sets such that $\overline{V_j} \subset \text{int } J(p_j^-, p_j^+)$ is compact. We assume that no null geodesic starting in V_j has a conjugate point on K_j .

Then, if

$$\tilde{\Phi}(\mathcal{P}_{K_1}(V_1)) = \mathcal{P}_{K_2}(V_2)$$

there exists a conformal diffeomorphism $\Phi : V_1 \rightarrow V_2$ that preserves causality.

1.1 Preliminary Constructions

((Intro))

Lemma 1.2. *Let $(M, g), K, V, p^+, p^-$ be as in the statement of theorem 1.1 (we suppress the indices to simplify notation) then the following holds:*

- (1) $(J^-(p^+) \setminus I^-(p^+)) \cap K = \mathcal{L}_{p^+}^- \cap K$ and thus $K = \mathcal{L}_{p^+}^- \cap J^+(p^-)$.
- (2) *There exists a surjective smooth map $\Psi : S^n \times [0, 1] \rightarrow K$ such that the curves $t \mapsto \Psi(v, t), v \in S^n$ are null geodesics and*

$$\Psi(S^n \times \{1\}) = \{p^+\}, \quad \Psi(S^n \times \{0\}) = (J^-(p^+) \setminus I^-(p^+)) \cap J^+(p^-)$$

- (3) *There exist $0 < t_- < t_+ < 1$ such that the restriction $\Psi|_{S^n \times [t_-, t_+]}$ is a diffeomorphism onto its image and that for all $v \in S^n$, we have*

$$\Psi(v, t_-) \notin \bigcup_{p \in \overline{V}} J^+(p), \quad \Psi(v, t_+) \in \bigcap_{p \in \overline{V}} J^+(p)$$

Proof. ((Overhaul)) As we have no cut point in $J(p_1^-, p_1^+)$, the exponential map at p_1^+ is a diffeomorphism onto $J(p_1^-, p_1^+)$. Thus the preimage $\exp_{p_1^+}^{-1}(R)$ of the smooth submanifold

$$R = (J^-(p_j^+) \setminus I^-(p_j^+)) \cap (J^+(p_j^-) \setminus I^+(p_j^-)) = \mathcal{L}_{p_1^+}^- \cap \mathcal{L}_{p_1^-}^+$$

is a smooth submanifold of $L_{p_1^+}^- M$. We then let $\mathcal{A} = R$ and denote by $\mu_a(s) = \gamma_{p_1^+, a}^+(1-s)$ for $a \in R$. It is then easily checked that this parameterization satisfies all requirements and we are done. \square

Note that this implies that K is a smooth n -dimensional submanifold of M at any point away from its boundary. We will often treat K itself as a submanifold when it is clear that we are working away from the boundary. This is almost always the case since any light cone originating in \bar{V} will intersect K in $\Psi(S^n \times (t_-, t_+)) \subset K$.

The next proposition allows us to endow K with a number of “laboratory frames” we will use to conveniently describe the light cone observations on K .

Proposition 1.3 (Laboratory Frames). *Let $(M_j, g_j), K_j, V_j, p_j^+, p_j^-, \Phi$ be as in the statement of theorem 1.1 Then there exists a family of future pointing, null geodesics $\mu_a^{(1)} : [0, 1] \rightarrow K_1$ indexed by $a \in \mathcal{A}$ where \mathcal{A} is a metric space. Furthermore we can require the map $[0, 1] \times \mathcal{A} \rightarrow K_1; (s, a) \mapsto \mu_a^{(1)}(s)$ to be open ((almost, needed?)) and continuous. If we then take $\mu_a^{(2)} := \Phi(\mu_a^{(1)})$ we can achieve*

$$K_j = \bigcup_{a \in \mathcal{A}} \mu_a^{(j)}([0, 1]). \quad (1)$$

Proof. ((TODO)) \square

Remark 1.4. To simplify notation we will continue with the construction on just one Lorentzian manifold (M, g) of dimension $1+n$ and assume that we are given the following data to construct the required conformal diffeomorphism ((explain better)) from theorem 1.1.

1. A the quasi-manifold K ,
2. the conformal class of $g|_K$ (but not only restricted to tangent vectors in K ((i think??))),
3. the paths $\mu_a : [0, 1] \rightarrow K, a \in \mathcal{A}$,
4. the set $\mathcal{P}_K(V)$ where V is open and $\bar{V} \subset \text{int } J(p^-, p^+)$ is compact.

Note that these data are invariant under conformal diffeomorphism, and any map we construct from it will thus also be invariant. We also remark that $\bar{V} \subset \text{int } J(p^-, p^+)$ implies that $q \notin K$ for any $q \in \bar{V}$. ((Also mention that any light observation must lie in $[t_-, t_+]$)).

1.1.1 Geometry of Light Observation Sets

Lemma 1.5. *For any $q \in \bar{V}$ the restriction of the exponential map to null vectors $\exp_q : L_q^+ M \rightarrow M$ is transverse to K , i.e. for all $w \in L_q^+ M$ such that $\gamma_{q,w}(1) = p \in K$ we have $\gamma'_{q,w}(1) \notin T_p K$.*

Proof. ((Update proof)) Suppose that there exists a $q \in \bar{V}$ and a $w \in L_q^+ M$ such that with $v := \gamma_{q,w}(1) \in L_p K$. Now, by definition of $\overrightarrow{\mathcal{P}_K}(q)$ we have $\exp_p(-v) = q \in V$. Also since $v \in L_p K$ there exists a $w \in L_{p^+}^- M$ and a $t \in \mathbb{R}_{>0}$ such that $\gamma_{p^+,w}(t) = p$ and $\gamma'_{p^+,w}(t) = -v$. This implies that $\gamma_{p^+,w}(t+1) = q \in V$. We thus have $q \in \mathcal{L}_{p^+}^-$. Furthermore we note that $q \in J^+(p^-)$ since $\bar{V} \subset \text{int } J(p^-, p^+)$. Thus by 1.2(1) we have that $q \in K$. But this is a contradiction to the fact that $q \notin K$. \square

Lemma 1.6 (Direction Reconstruction). *((Adjust formulation)) Let $p \in K$ then there exists an isomorphism Φ between the space \mathcal{S} of linear spacelike hypersurfaces $S \subset T_p K$ and the space \mathcal{V} of rays $\mathbb{R}_+ V \subset T_p M$ along future-directed outward facing null vectors, given by the mapping $S \in \mathcal{S}$ to the unique future-directed outward pointing null ray $\Phi(S)$ contained in S^\perp . The inverse map is given by $\mathcal{V} \ni \mathbb{R}_+ V \mapsto T_p K \cap V^\perp \in \mathcal{S}$.*

Moreover there exists an isomorphism between \mathcal{S} and the space \mathcal{N} of linear null hypersurfaces $N \subset T_p M$ which contain a future-directed outward pointing null vector given by $\mathcal{S} \mapsto S \oplus \text{span } \Phi(S) \in \mathcal{N}$.

Proof. ((Works same as in timelike boundary case)) \square

Definition 1.7 (Observation Preimage). For any $q \in \bar{V}$ with light observation set $\mathcal{P}_K(q) \subset K$ we define the *observation preimage* $L_q^K M$ to be the preimage of K under the exponential map restricted to $L_q^+ M$, i.e.

$$L_q^K M := (\exp_q|_{L_q^+ M})^{-1}(K) \subset L_q^+ M$$

Lemma 1.8. *For any $q \in \bar{V}$, $L_q^K M$ is a $n - 1$ -dimensional submanifold of $T_p M$ and $\exp_q : L_q^K M \rightarrow \mathcal{P}_K(q)$ is a local diffeomorphism ((onto its image)).*

Proof. ((For first part use transversality. Use the fact that we have no conj points on K for the second part)) \square

Proposition 1.9. *For any $q \in \bar{V}$, $\mathcal{P}_K(q)$ is locally the the finite union of transversal dimension $n - 1$ submanifolds.*

Proof. To prove this we will first show that for any $p \in \mathcal{P}_K(q)$, $\pi^{-1}(p) \cap \overrightarrow{\mathcal{P}_K}(q)$ only contains finitely many elements, i.e. p can only be hit by finitely many light rays originating at q :

Let $q \in \bar{V}$ and $v \in L_q^+ M$ such that $p = \exp_q(v)$. Since we required that $p \in K$ cannot be a conjugate point of q , \exp_q must be a local diffeomorphism around v . This means that there exist open sets $v \in \mathcal{O}_v \subset T_q M, p \in \mathcal{U}_v \subset M$ such that $\exp_q : \mathcal{O}_v \rightarrow \mathcal{U}_v$ is a diffeomorphism. But this means that there cannot exist another $v' \in \mathcal{O}_v$ with $\exp_q(v') = p$. We now restrict ourselves only to null *directions* at q i.e. the quotient $L_q^+ M / \mathbb{R}_+ \simeq S^{n-1}$. Since any null vector v with $\exp_q(v) = p$ has an open neighborhood where no other vector can have this property, the set of null *directions* in S^{n-1} which hit p is discrete and thus finite because S^{n-1} is compact. Because we only have finitely many null directions which hit p , $\pi^{-1}(p) \cap \overrightarrow{\mathcal{P}}_K(q)$ can only have finitely many elements, as desired.

Let now $v_1, \dots, v_n \in L_q^+ M$ be these finitely many vectors with $\exp_q(v_i) = p$. As p cannot be a conjugate point there exists a neighborhood $d \exp_q$ is a local diffeomorphs

Next we will prove that the restricted canonical projection $\pi : \overrightarrow{\mathcal{P}}_K(q) \rightarrow \mathcal{P}_K(q)$ is locally diffeomorphic. Since any $(p, v) \in \overrightarrow{\mathcal{P}}_K(q)$ has an open neighborhood where there exists no $(p, v' \neq v)$ we can construct a smooth local inverse to π by attaching the appropriate direction vector.

((finish + transversality)) □

Definition 1.10 (Regular Point). We call a point $p \in \mathcal{P}_K(q)$ *regular* if there exists an open neighborhood $\mathcal{O} \subset M$ of p such that $\mathcal{O} \cap \mathcal{P}_K(q)$ is a submanifold.

Corollary 1.11. ((Maybe false)) *The subset of non-cut points is dense in $\mathcal{P}_K(q)$.*

Proof. It suffices to show that for every cut point $p \in \mathcal{P}_K(q)$, every relatively open neighborhood $\mathcal{O} \subset \mathcal{P}_K(q)$ contains a non-cut point. □

Proposition 1.12. $\overrightarrow{\mathcal{P}}_K(q)$ is diffeomorphic to S^{n-1} ((Probably not necessary)).

Proof. ((TODO)) □

1.1.2 Observation Time Functions

Definition 1.13 (Observation Time Function). For $a \in \mathcal{A}$ the *observation time function* is defined as

$$f_a : \bar{V} \rightarrow [0, 1]$$

$$q \mapsto \inf(\{s \in [0, 1] \mid \mu_a(s) \in J^+(q)\} \cup \{1\}).$$

Moreover, let $\mathcal{E}_a(q) := \mu_a(f_a(q)) \in M$ be the earliest point where μ_a sees light from q .

Lemma 1.14. *Let $a \in \mathcal{A}$ and $q \in \bar{V}$. Then*

- (1) It holds that $t_- \leq f_a(q) \leq t_+$.
- (2) We have $\mathcal{E}_a(q) \in J^+(q)$ and $\tau(q, \mathcal{E}_a(q)) = 0$. Moreover the function $s \mapsto \tau(q, \mu_a(s))$ is continuous, non-decreasing on $[0, 1]$ and strictly increasing on $[f_a(q), 1]$.
- (3) Let $p \in K$. Then $p = \mathcal{E}_a(q)$ with some $a \in \mathcal{A}$ if and only if $p \in \mathcal{P}_K(q)$ and $\tau(p, q) = 0$. Furthermore, these are equivalent to the fact that there are $v \in L_q^+ M$ and $t \in [0, \rho(q, v)]$ such that $p = \gamma_{q,v}(t)$.
- (4) The function $q \mapsto f_a(q)$ is continuous on \overline{V} .

Proof. Let $a \in \mathcal{A}$ and $q \in \overline{V}$.

We begin by showing (1): By lemma 1.2(3) we have that $\mu_a(t_-) \notin J^+(q)$ and $\mu_a(t_+) \in J^+(q)$. The second part immediately yields $f_a(q) \leq t_+$ as $f_a(q)$ is the infimum over all observation times. For the first part we assume by contradiction that there were to exist a $t_{-2} < t_-$ with $\mu_a(t_{-2}) \in J^+(q)$. This allows us to construct a causal path from q to $\mu_a(t_-)$ by joining the causal path from $q \rightarrow \mu_a(t_{-2})$ and the null geodesic μ_a from t_{-2} to t_- . Since this would imply that $\mu_a(t_-) \in J^+(q)$ this is a contradiction and $f_a(q)$ must be bigger than t_- proving (1).

(2) By the definition of the infimum we can find a sequence $t_n \searrow f_a(q)$ such that for all t_n we have $\mu_a(t_n) \in J^+(q)$. Now since $t \mapsto \mu_a(t)$ is continuous we have that $\mu_a(t_n) \rightarrow \mu_a(f_a(q)) = \mathcal{E}_a(q)$. Since $J^+(q)$ is closed this yields $\mathcal{E}_a(q) \in J^+(q)$.

For the second part we assume by contradiction that $\tau(q, \mathcal{E}_a(q)) > 0$. Since this means that a timelike path from q to $\mathcal{E}_a(q)$ exists we have $\mathcal{E}_a(q) \in I^+(q)$. Then, since $I^+(q)$ is open we can find a $t < f_a(q)$ such that $\mu_a(t) \in I^+(q) \subset J^+(q)$. This is a contradiction since $f_a(q)$ is the infimum over such t .

To show that $s \mapsto \tau(q, \mu_a(s))$ is continuous and non-decreasing on $[0, 1]$ we first note that it is the composition of two continuous functions. Non-decreasing then follows from the reverse triangle inequality together with the fact that μ_a is a null path.

Finally to show that $s \mapsto \tau(q, \mu_a(s))$ is strictly increasing in $[f_a(q), 1]$ we let $f_a \leq t_1 < t_2 \leq 1$. Now by ((REF)) there exists a causal geodesic $\gamma_1 : [0, 1] \rightarrow M$ with $\gamma_1(0) = q$ and $\gamma_1(1) = \mu_a(t_1)$ such that $L(\gamma_1) = \tau(p, \mu_a(t_1))$. If we then connect γ_1 to $\mu_a|_{[t_1, t_2]}$ we get a path γ_2 connecting q to $\mu_a(t_2)$ which has length $L(\gamma_2) = L(\gamma_1)$ as μ_a is a null geodesic. Next we argue that γ_2 must have a break at the connecting point, i.e. $\gamma_1'(1) \neq c\mu_a'(t_1)$ for any $c \in \mathbb{R}_+$. If γ_1 is timelike this observation is trivial as μ_a is lightlike. If however, γ_1 is lightlike (which is exactly the case if $t_1 = f_a(1)$), this fact follows from the transversality of light cone observations as noted in proposition 1.5. This means that γ_2 is a broken causal geodesic, which by ((REF)) implies that there exists a strictly longer timelike path

γ_3 connecting the endpoints and we get

$$\tau(q, \mu_a(t_2)) \geq L(\gamma_3) > L(\gamma_2) = L(\gamma_1) = \tau(q, \mu_a(t_1)).$$

Next to prove (3): To prove the first direction we assume that $p = \mathcal{E}_a(q)$ for some $a \in \mathcal{A}$. Now by (2) we have $\mathcal{E}_a(q) \in J^+(q)$ and $\tau(q, \mathcal{E}_a(q)) = \tau(q, p) = 0$. But now, by ((REF)) there exists a null geodesic from q to p which means $p \in \mathcal{P}_K(q)$.

For the other direction we let $p \in \mathcal{P}_K(q)$ with $\tau(q, p) = 0$. Now let $a \in \mathcal{A}$ such that $p = \mu_a(t)$ for some $t \in [0, 1]$. We then assume by contradiction that $\mathcal{E}_a(q) \neq p$, i.e. $f_a(q) < t$. But by (2) we have that $s \mapsto \tau(q, \mu_a(s))$ is strictly increasing after $f_a(q)$ which is in contradiction with $\tau(q, p) = 0$.

The other equivalence follows the definition of $\mathcal{P}_K(q)$ together with the definition of cut points.

Finally we prove (4): Let $q_i \rightarrow q$ in \bar{V} , let $t_i = f_a(q_i)$ and $t = f_a(q)$. Since τ is continuous, for any $\varepsilon > 0$ we have $\lim_{j \rightarrow \infty} \tau(q_j, \mu_a(t + \varepsilon)) = \tau(q, \mu_a(t + \varepsilon)) > 0$. Thus for j big enough we have $\tau(q_i, \mu_a(t + \varepsilon)) > 0$. But by (3) this implies that a must have observed q_i before $t + \varepsilon$ i.e. $f_a(q_i) < t + \varepsilon = f_a(q) + \varepsilon$. As ε was arbitrary we get $\limsup_{j \rightarrow \infty} t_j \leq t$.

We assume now that $\liminf_{j \rightarrow \infty} t_j = t' < t$. Let (t_i) be a convergent subsequence such that $f_a(q_i) = t_i \rightarrow t' < f_a(q)$. Now by the continuity of τ and μ_a we have

$$0 = \tau(q_i, \mu_a(f_a(q_i))) \rightarrow \tau(q, \mu_a(t')).$$

Furthermore by ((REF)) $\mu(s_i) \in J^+(q_i)$ for all i implies $\mu(s') \in J^+(q)$. But now we have $\mu(s') \in \mathcal{P}_K(q)$ and $\tau(q, \mu_a(s')) = 0$ which by (3) implies that $\mu_a(s') = \mathcal{E}_a(q) = \mu_a(f_a(q))$. But this is a contradiction as $s' < f_a(q)$. ((More in-detail?)) \square

By (3) of the above lemma, for any $q \in \bar{V}$ and $a \in \mathcal{A}$ we have $\mathcal{E}_a(q) \in \mathcal{P}_K(q)$. Since $\mathcal{P}_K(q) \subset J^+(q)$, we can see using definition 1.13 that the set of earliest observations $\mathcal{P}_K(q)$ and the path μ_a completely determine the functions

$$f_a(q) = \min\{s \in [-1, 1] \mid \mu_a(s) \in \mathcal{P}_U(q)\}, \quad \mathcal{E}_a(q) = \mu_a(f_a(q)) \quad (2)$$

1.1.3 Set of earliest observations

Definition 1.15 (Set of earliest observations). For $q \in \bar{V}$ we define

$$\begin{aligned} \mathcal{D}_K(q) &= \{(p, v) \in L^+K \mid (p, v) = (\gamma_{q,w}(t), \gamma'_{q,w}(t)) \\ &\quad \text{where } w \in L_q^+M, 0 \leq t \leq \rho(q, w)\}, \\ \mathcal{D}_K^{reg}(q) &= \{(p, v) \in L^+K \mid (p, v) = (\gamma_{q,w}(t), \gamma'_{q,w}(t)) \\ &\quad \text{where } w \in L_q^+M, 0 < t < \rho(q, w)\}, \end{aligned}$$

We say that $\mathcal{D}_K(q)$ is the *direction set* of q and $\mathcal{D}_K^{reg}(q)$ is the *regular direction set* of q .

Let $\mathcal{E}_U(q) = \pi(\mathcal{D}_U(q))$ and $\mathcal{E}_U^{reg}(q) = \pi(\mathcal{D}_U^{reg}(q))$, where $\pi : TU \rightarrow U$ is the canonical projection. We say that $\mathcal{E}_U(q)$ is the set of earliest observations and $\mathcal{E}_{reg_U}(q)$ is the set of earliest regular observations of q in U . We denote the collection of earliest observation sets by $\mathcal{E}_U(V) = \{\mathcal{E}_U(q) \mid q \in V\}$.

Note that $\mathcal{E}_U(q) = \{\mathcal{E}_a(q) \mid a \in \mathcal{A}\}$.

Proposition 1.16. *For any $q \in \bar{V}$ it holds that*

- (1) $\mathcal{E}_K(q)$ fails to be a submanifold exactly at cut points,
- (2) $\mathcal{E}_K^{reg}(q)$ is a $n - 1$ -dimensional nonempty spacelike submanifold of K which is open relative to $\mathcal{P}_K(q)$ and has $\overline{\mathcal{E}_K^{reg}(q)} = \mathcal{E}_K(q)$ and,
- (3) \mathcal{D}_K^{reg} is a nonempty submanifold of $\overrightarrow{K} := \pi^{-1}(K)$ ((...)) which is open

Proof. We begin by proving (1):

Let p

□

Note that since $\mathcal{E}_K^{reg}(q)$ is exactly $\mathcal{E}_K(q)$ without the cut points, it is also the collection of all points where $\mathcal{E}_K(q)$ is locally a submanifold.

Proposition 1.17. *For any $q \in \bar{V}$, $\mathcal{E}_{reg_K}(q) \subset K$ and $\mathcal{D}_K^{reg}(q) \subset TU$ are smooth submanifolds of dimension $n - 1$ ((D has $\dim n$)).*

Proof. ((TODO))

We will focus our attention to the case of $\mathcal{E}_{reg_U}(q)$ as the argument for $\mathcal{D}_U^{reg}(q)$ is analogous. Note first that $\mathcal{E}_{reg_U}(q)$ can be rewritten as

$$\{\exp_q(w) \mid w \in L_q^+ M \text{ with } 1 < \rho(q, w)\}.$$

Next by lower semi-continuity of ρ we get that $R = \{w \in L_q^+ M \mid 1 < \rho(q, w)\}$ is an open set and thus a dimension $(n - 1)$ submanifold (this is because $L_q^+ M$ itself is of dimension $(n - 1)$). But since $\rho(q, w)$ describes where \exp_q first fails to be a diffeomorphism we get that the surjection $\exp_p : R \rightarrow \mathcal{E}_{reg_U}(q)$ is a diffeomorphism. Thus, since R was a manifold of dimension $(n - 1)$, $\mathcal{E}_{reg_U}(q)$ is also a manifold and has the required dimension. □

Finally in this section we will prove

Proposition 1.18. *Let $q \in \bar{V}$, then*

$$\mathcal{E}_K(q) = \{p \in \mathcal{P}_K(q) \mid \text{there are no } p' \in \mathcal{P}_K(q) \text{ such that } p' < p\}.$$

Proof. ((Still True?)) For the left inclusion assume $p \in \mathcal{E}_U(q)$, i.e. there exists an $a \in \mathcal{A}$ such that $\mathcal{E}_a(q) = p$. Then lemma 1.14(3) immediately yields, $p \in \mathcal{P}_U(q)$ and $\tau(q, p) = 0$. Now suppose there were a $p' \in \mathcal{P}_U(q)$ with $p' \ll p$. By as $\mathcal{P}_U(q) \subset J^+(q)$ we have $q \leq p'$, then as $p' \ll p$ we get $q \ll p$. But this would imply $\tau(p, q) > 0$, a contradiction.

For the other direction we assume we have $p \in \mathcal{P}_U(q)$ such that there are no $p' \in \mathcal{P}_U(q)$ such that $p' \ll p$. Again by lemma 1.14(3) we only need to prove that $\tau(p, q) = 0$. Suppose that $\tau(p, q) > 0$. By equation 1 there exists an $a \in \mathcal{A}$ and a $s \in [-1, 1]$ such that $\mu_a(s) = p$. Now since $\tau(p, q) > 0$, we must have $s > f_a(q)$. But then $\mathcal{E}_a(q) = \mu_a(f_a(q)) \ll \mu_a(s)$, since μ_a is timelike, which is a contradiction. \square

Thus $\mathcal{E}_U(q)$ truly deserves to be called the “set of earliest observations”.

1.2 Constructive Solution of the Inverse Problem

((Intro))

1.2.1 Reconstruction ...

Lemma 1.19. *Thing with dir set reconstruction Also intersection is spacelike somewhere*

Proposition 1.20. ((Given data)) *The light observations $\mathcal{P}_K(q)$ uniquely determines the light direction observation set $\mathcal{C}_K(q)$ and the set of earliest observations $\mathcal{E}_K(q)$.*

Proof. 2nd part: from formula

1st part: from lemma + only finite nonconj cut points + we can parameterize $\mathcal{P}_K(q)$ by a spacelike submanifold of the forwards lightcone \square

Proposition 1.21. ((Given data)) *Given the light direction observation set $\mathcal{P}_K(q)$ and the set of earliest observations $\mathcal{E}_K(q)$, we can determine the sets $\mathcal{E}_{reg}_K(q)$, $\mathcal{D}_K(q)$ and $\mathcal{D}_K^{reg}(q)$.*

Proof. ((Take $\pi^{-1}(\mathcal{E}_K(q)) \cap \mathcal{C}_K(q)$ for $\mathcal{D}_U(q)$, then remove all cut points (in this case points with equal p but different v) in $\mathcal{D}_U(q)$ to obtain $\mathcal{D}_K^{reg}(q)$ and project again)) \square

1.2.2 Construction of V as a topological manifold

((Intro))

Next we aim to reconstruct the topological and differential data of V . To that end we define the following functions.

For $q \in \bar{V}$ we define the function $F_q : \mathcal{A} \rightarrow \mathbb{R}$ by $a \mapsto f_a(q)$. We can then define the function

$$\begin{aligned}\mathcal{F} : \bar{V} &\rightarrow \mathbb{R}^{\mathcal{A}} \\ q &\mapsto F_q\end{aligned}$$

mapping a $q \in \bar{V}$ to the function $F_q : \mathcal{A} \rightarrow \mathbb{R}$. We endow the set $\mathbb{R}^{\mathcal{A}} = \{f : \mathcal{A} \rightarrow \mathbb{R}\}$ with the product topology.

((...))

We begin by establishing the topological structure:

Lemma 1.22. *((V or \bar{V} ?) The map $\mathcal{F} : V \rightarrow \mathcal{F}(V)$ is a homeomorphism.*

Proof. ((Works the same, use direction set reconstruction)) □

1.2.3 Construction of V as a smooth manifold

Having established the topological structure of V we next aim to establish coordinates on $\mathcal{F}(V)$ near any $\mathcal{F}(q)$ that make $\mathcal{F}(V)$ diffeomorphic to V .

Definition 1.23 (Coordinates on V). We first define

$$\mathcal{Z} = \{(q, p) \in V \times K \mid p \in \mathcal{E}_U^{reg}(q)\}.$$

Then for every $(q, p) \in \mathcal{Z}$ there is a unique $w \in L_q^+ M$ such that $\gamma_{q,w}(1) = p$ and $\rho(q, w) > 1$. Existence follows from lemma 1.14 while uniqueness follows from the fact that $p \in \mathcal{E}_U^{reg}(q)$ and thus cannot be a cut point. We can then define the map

$$\begin{aligned}\Theta : \mathcal{Z} &\mapsto L^+ V \\ (q, p) &\mapsto (q, w)\end{aligned}$$

Note that this map is injective. Below we will $\mathcal{W}_\varepsilon(q_0, w_0) \subset TM$ be a ε -neighborhood of (q_0, w_0) with respect to the Sasaki-metric induced on TM by g^+ .

Lemma 1.24. *Let $(q_0, p_0) \in \mathcal{Z}$ and $(q_0, w_0) = \Theta(q_0, p_0)$. When $\varepsilon > 0$ is small enough the map*

$$\begin{aligned}X : \mathcal{W}_\varepsilon(q_0, w_0) &\rightarrow M \times M \\ (q, w) &\mapsto (q, \exp_q(w))\end{aligned}$$

is open and defines a diffeomorphism $X : \mathcal{W}_\varepsilon(q_0, w_0) \rightarrow \mathcal{U}_\varepsilon(q_0, p_0) := X(\mathcal{W}_\varepsilon(q_0, w_0))$. When ε is small enough, Θ coincides in $\mathcal{Z} \cap \mathcal{U}_\varepsilon(q_0, p_0)$ with the inverse map of X . Moreover \mathcal{Z} is a $(2n - 1)$ -dimensional manifold and the map $\Theta : \mathcal{Z} \rightarrow L^+ M$ is smooth.

Proof. ((Works the same with minor adjustments?)) □

((Explain what we're doing now))

Proposition 1.25. *Let $q \in \bar{V}$ and $(q_0, p_j) \in \mathcal{Z}, j = 1, \dots, n$ and $w_j \in L_{q_0}^+ M$ such that $\gamma_{q_0, w_j}(1) = p_j$. Assume that $w_j, j = 1, \dots, n$ are linearly independent. Then, if $a_j \in A$ and $\vec{a} = (a_j)_{j=1}^n$ are such that $p_j \in \mu_{a_j}$, there is a neighborhood $V_1 \subset M$ of q_0 such that the corresponding observation time functions*

$$\mathbf{f}_{\vec{a}}(q) = (f_{a_j}(q))_{j=1}^n$$

define smooth coordinates on V_1 . Moreover $\nabla f_{a_j}|_{q_0}$, i.e. gradient of f_{a_j} with respect to q at q_0 , satisfies $\nabla f_{a_j}|_{q_0} = c_j w_j$ for some $c_j \neq 0$.

Proof. ((Works almost the same, maybe clarify implicit function theorem stuff)) □

Definition 1.26 (Observation Coordinates). Let $\hat{q} = \mathcal{F}(q) \in \hat{V}$ and $\vec{a} = (a_j)_{j=1}^n \subset \mathcal{A}^n$ with $p_j = \mathcal{E}_{a_j}(q)$ such that $p_j \in \mathcal{E}_U^{reg}(q)$ for all $j = 1, \dots, n$. Let $s_{a_j} = f_{a_j} \circ \mathcal{F}^{-1}$ and $\mathbf{s}_{\vec{a}} = \mathbf{f}_{\vec{a}} \circ \mathcal{F}^{-1}$. Let $W \subset \hat{V}$ be an open neighborhood of \hat{q} . We say that $(W, \mathbf{s}_{\vec{a}})$ are C^0 -observation coordinates around \hat{q} if the map $\mathbf{s}_{\vec{a}} : W \rightarrow \mathbb{R}^n$ is open and injective. Also we say that $(W, \mathbf{s}_{\vec{a}})$ are C^∞ -observation coordinates around \hat{q} if $\mathbf{s}_{\vec{a}} \circ \mathcal{F} : \mathcal{F}^{-1}(W) \rightarrow \mathbb{R}^n$ are smooth local coordinates on $V \subset M$.

Note that by the invariance of domain theorem, the above $\mathbf{s}_{\vec{a}} : W \rightarrow \mathbb{R}^n$ is open if it is injective. Although for a given $\vec{a} \in \mathcal{A}^n$ there might be several sets W for which $(W, \mathbf{s}_{\vec{a}})$ form C^0 -observation coordinates to clarify the notation we will sometimes denote the coordinates $(W, \mathbf{s}_{\vec{a}})$ as $(W_{\vec{a}}, \mathbf{s}_{\vec{a}})$.

We will consider $\mathcal{F}(V)$ a topological space and denote $\mathcal{F}(V) = \hat{V}$. We denote the points of this manifold by $\hat{q} = \mathcal{F}(q)$. Next we construct a differentiable structure on \hat{V} that is compatible with that of V and makes \mathcal{F} a diffeomorphism.

Proposition 1.27. *Let $\hat{q} \in \hat{V}$. Then there exist C^∞ -observation coordinates $(W_{\vec{a}}, \mathbf{s}_{\vec{a}})$ around \hat{q} .*

Furthermore, given the data from 1.4 we can determine all C^0 -observation coordinates around \hat{q} .

Finally given any C^0 -observation coordinates $(W_{\vec{a}}, \mathbf{s}_{\vec{a}})$ around \hat{q} , the data 1.4, allows us to determine whether they are C^∞ -observation coordinates around \hat{q} .

Proof. ((Works the same way)) □

1.2.4 Construction of the conformal type of the metric

We will denote by $\hat{g} = \mathcal{F}_*g$ the metric on $\hat{V} = \mathcal{F}$ that makes $\mathcal{F} : V \rightarrow \hat{V}$ an isometry. Next we will show that the set $\mathcal{F}(V)$, the paths μ_a and the conformal class of the metric on U determine the conformal class of \hat{g} on \hat{V} .

Lemma 1.28. *The data given in 1.4 determine a metric G on $\hat{V} = \mathcal{F}(V)$ that is conformal to \hat{g} and a time orientation on \hat{V} that makes $\mathcal{F} : V \rightarrow \hat{V}$ a causality preserving map.*

Proof. ((Works the same))

□

References

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