大话成像之

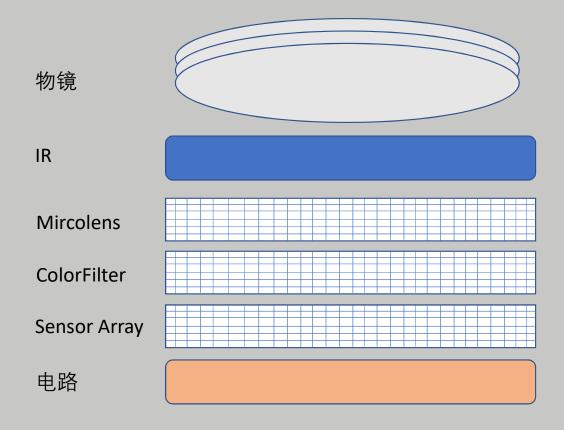
数字成像系统 32讲

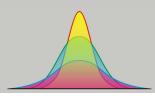
• CMOS sensor 基础

Maver Jiang imaging algorithm specialist staff image quality engineer maver.jiang@gmail.com

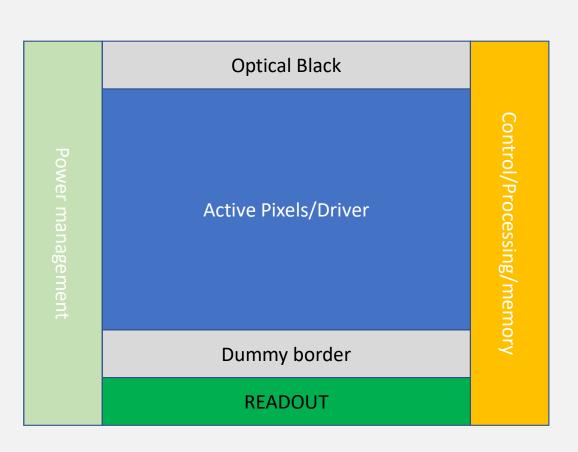


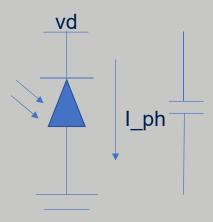
Cmos sensor stack





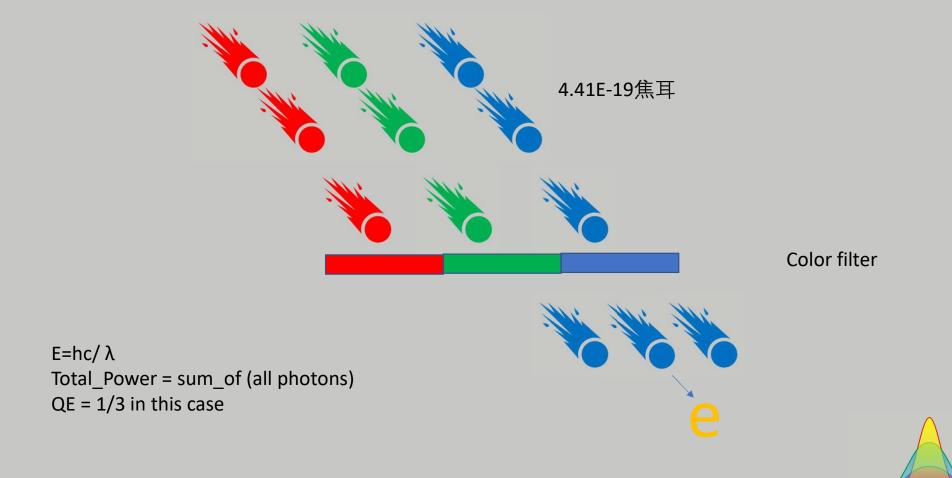
sensor floorplan





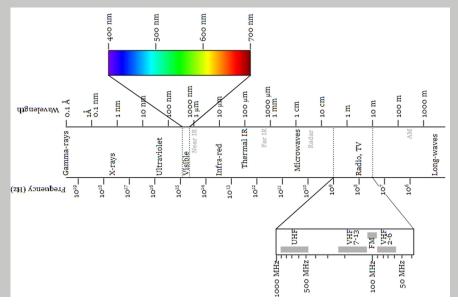


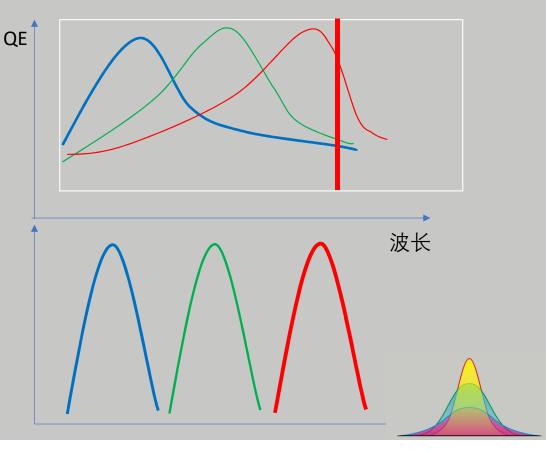
光子(Photon)与量子效率quantum efficiency



与量子效率QE有关的几个重要概念

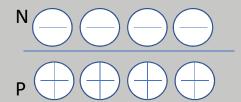
- QE是衡量某个颜色通道某个频率/波长的光子转换成电子的效率
- IR cutter----cut near IR
- Crosstalk
- Sensitivity 感光度=QE X Pixel_Size

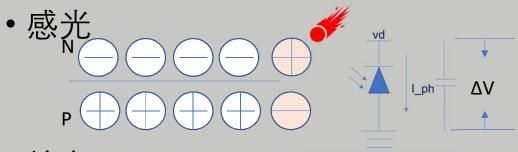




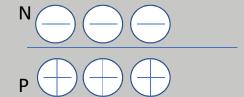
感光过程

• 充电----reset





• 放电

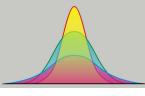


 Δ Q = Ne x e x QE Q = V x C Δ V = Δ Q/C

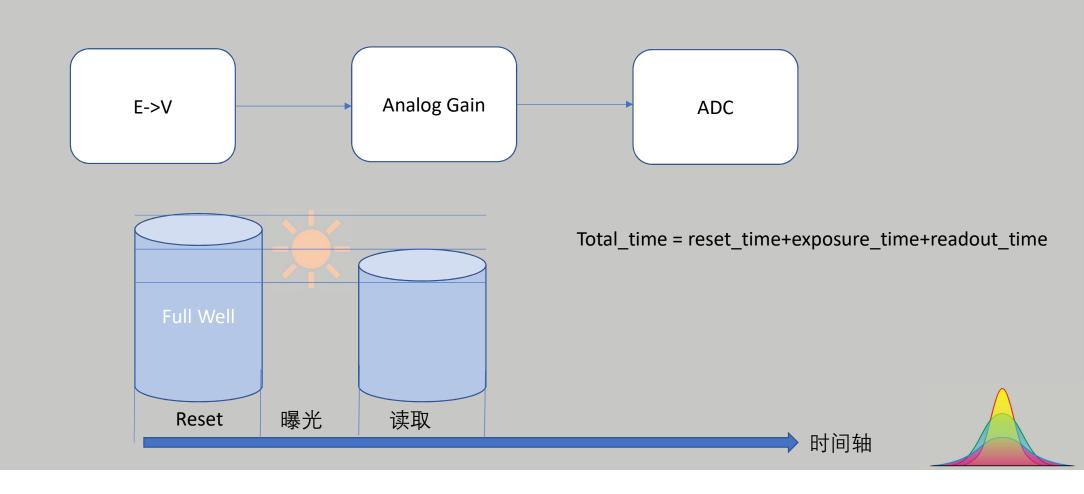




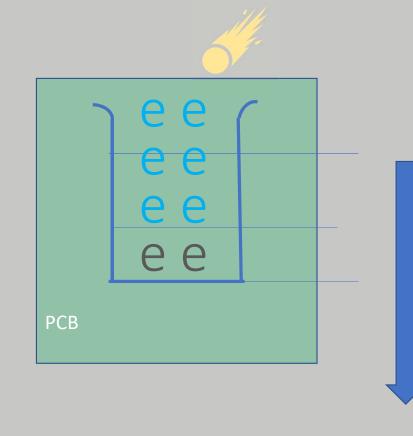




读取过程



Sensor动态范围

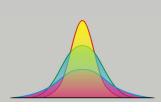


1: Full well Capacity

2 : Dark Current

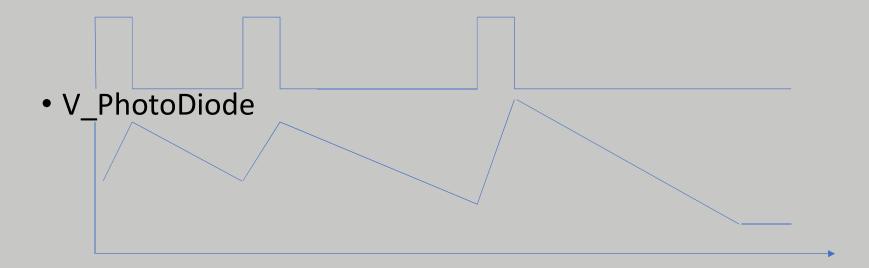
3 : Fill Factor

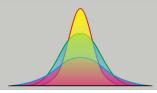
Dynamic Range = Saturation / Noise floor ———— 简化算法 Dynamic Range = Saturation / black level



Sensor 时序

• Reset





Noise in Sensor

• 时域噪声与空域噪声

时域噪声----

KTC Noise(readout), Photon Shot Noise, Dark Current Noise, Power Noise

• 空域噪声

空域噪声----DefectPixel,Row/ColumnNoise,PRNU,DSNU



Crosstalk 对 noise的影响

$$\begin{bmatrix} R' \\ G' \\ B' \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

$$R' = a11 \times R + a12 \times G + a13 \times B$$

加模型的噪声计算:

ADD $(N1,N2) = (N1^2+N2^2) ^0.5$

$$N' = (a11 \times R)^2 + (a12xG)^2 + (a13xB)^2$$

负的系数越大SNR越低

http://www.ericfossum.com/Publications/Papers/2015%20JOS AA%20Color%20Filters.pdf



THANKS

本课程由 Maver Jiang提供



大话成像之 数字成像系统 32 讲

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- 3. 光学基础
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- 6. 3A概述
- 7. 黑电平与线性化
- 8. Green Imbalance
- 9. 坏点消除
- 10. Vignetting与Color shading
- 11. SNR 与Raw Denoise
- 12. Dynamic Range与Tone Mapping
- 13. MTF与Demosaic
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- 15. Color Correction Matrix与3D LUT
- 16. Gamma与对比度增强
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- 20. 时域去噪
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- 25. 自动对焦
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- 31. 图像质量评价工具与方法
- 32. 画质调优

