Agata U. Kargol

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Skills

Languages • Native: English, Polish

o Proficient: Python2, Python3, SQL

• Past: Matlab, C, C++, bash, JavaScript

Frameworks Flask, Pyramid, Django, SQLAlchemy, alembic, pytest, pandas, celery

Technologies PyCharm, git (preferred), SVN, mercurial, *nix, PostgreSQL, RabbitMQ, Redis, Cassandra, Jenkins,

ansible, Docker, Kubernetes

Professional Experience

2015-2017 **Software Development Engineer (Pupil Team)**

Zonar Systems, Inc. Seattle, WA

Rider Verification/Route Board: bus driver/dispatcher facing solution providing feedback on student location

- Acting lead in MVP/Beta phase, with positive feedback both internally and from Beta customer
- Assisted Product Owner in trimming scope for an on-time delivery of MVP
- o Coordinated with Android contracting team on technical prerequisites and feasibility of requested features
- Routinely used as test project/team for evaluation of new products, technologies, and processes
- Greenfield project where team owned setup, maintenance, and all work on both infrastructure and software
- Key member of effort to move product to the cloud Google Cloud Platform, Docker, Kubernetes)
- Worked on both RESTful API layer and ETL process to ingest data from internal and external sources o Stack includes Python3, flask, SQLAlchemy, Postgres, Angular 1.5, pandas, Jenkins, ansible
- First product at Zonar to have >75% test coverage for core components, CI/CD pipeline

MyBusVue: a parent facing web app which provides near-real time bus tracking and student scan information

- Inherited legacy codebase developed by 3rd party
- o Team rearchitected, rebuilt underlying RESTful API and backend services, aiming for stability and testability
- First product at Zonar to have automated functional, unit, performance, and E2E tests
- o Python2 (ported to Python3), pyramid, SQLAlchemy, JavaScript, Angular 1.5, celery, rabbitMQ, Postgres, Cassandra, and Redis

2011-2015 Graduate Research Assistant

Washington Univ. in St. Louis

Archive of Many Outdoor Scenes (AMOS) Development

- Worked AMOS, the world's largest archive of outdoor webcams, which contains over 500 million images
- Built and managed AMOS crowdsourced tasks with Amazon Mechanical Turk
- Developed backend features and optimizations as part of a team
- o Django, Python2, JavaScript, Matlab, AWS Mechanical Turk

Pedestrian Detection in Webcam Imagery for Public Health Applications

- Explored use of existing machine learning tools and algorithms for pedestrian detection in webcams
- Improved detection algorithms through background subtraction and shadow detection methods

Point-and-click Object Manipulation Interface for PR2 Robot

- Developed point-and-click interface for object manipulation for Willow Garage's PR2 robot to allow the PR2 to act a surrogate for a paraplegic user
- · Learned about robot functionality and limitations, interface design based on user requirements, and the mathematical concepts of robot visual processing
- Required ROS, Python, C++, Qt framework, OpenCV

Education

May 2015 Master of Science in Computer Science

NSF Graduate Research Fellow

Washington University in St. Louis, St. Louis, MO

Select Coursework: Mobile Robotics, Computer Vision, Machine Learning

May 2011 Bachelor of Science in Computer Science

cum laude

University of Alabama, Tuscaloosa, AL

Minors: Mathematics, Computer-Based Honors Program, Telecommunication and Film

Select Publications

- [1] A. Hipp, D. Adlakha, R. Gernes, A. Kargol, and R. Pless, "Learning from outdoor webcams: Surveillance of physical activity across environments", in Workshop of Big Data and Urban Informatics, 2014.
- A. Hipp, D. Adlakha, R. Gernes, A. U. Kargol, and R. Pless, "Do You See What I See: Crowdsource annotation of captured scenes", in SenseCam, 2013.

Outreach and Leadership

2013 Invited expert panelist on "Frameworks to Guide Image Annotations" at SenseCam 2012 Participated in the PR2 Workshop held in Freiburg, Germany