Agata U. Kargol

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Skills

Languages • Native: English, Polish

o Proficient: Python2, Python3, SQL • **Past:** Matlab, C, C++, bash, JavaScript

Frameworks Flask, Pyramid, Django, SQLAlchemy, alembic, pytest, pandas, celery

Technologies PyCharm, git (preferred), SVN, mercurial, *nix, PostgreSQL, SQLAlchemy, RabbitMQ, Redis, Cassandra, Jenkins, ansible, Docker, Kubernetes

Professional Experience

2015-2017 **Software Development Engineer (Pupil Team)**

Zonar Systems, Inc. Seattle, WA

Rider Verification/Route Board: bus driver/dispatcher-facing solution providing feedback on student location

- o Greenfield project where team owned setup, maintenance, and all work on both infrastructure and software
- o Acting technical lead in MVP/Beta phase, with positive feedback both internally and from Beta customer
- Worked with Product Owner to trim scope for an on-time delivery of MVP
- Key member of ongoing effort to move product to the cloud (Google Cloud Platform, Docker, Kubernetes)
- Coordinated with Android contracting team on technical prerequisites and feasibility of requested features
- Worked on both RESTful API layer and ETL process to ingest data from internal and external sources
- Routinely served as test project/team for evaluation of new products, technologies, and processes
- First product at Zonar to have >75% test coverage for core components, CI/CD pipeline
- Python3, flask, SQLAlchemy, Postgres, Angular 1.5, pandas, Jenkins, ansible

MyBusVue: a parent-facing web app which provides near-real time bus tracking and student scan information

- Inherited legacy codebase developed by 3rd party
- o Team re-architected, rebuilt underlying RESTful API and backend services, aiming for stability and testability
- First product at Zonar to have automated functional, unit, performance, and E2E tests
- Python2 (ported to Python3), pyramid, SQLAlchemy, JavaScript, Angular 1.5, celery, rabbitMQ, Postgres, Cassandra, Redis

2011-2015 Graduate Research Assistant

WUSTL St. Louis, MO

Archive of Many Outdoor Scenes (AMOS) Development

- Worked AMOS, the world's largest archive of outdoor webcams, which contains over 500 million images
- Built and managed AMOS crowdsourced tasks with Amazon Mechanical Turk
- Developed backend features and optimizations as part of a team
- Django, Python2, JavaScript, Matlab, AWS Mechanical Turk

Pedestrian Detection in Webcam Imagery for Public Health Applications

- Explored use of existing machine learning tools and algorithms for pedestrian detection in webcams
- Improved detection algorithms through background subtraction and shadow detection methods

Point-and-click Object Manipulation Interface for PR2 Robot

- Developed point-and-click interface for object manipulation for Willow Garage's PR2 robot to allow the PR2 to act a surrogate for a paraplegic user
- · Learned about robot functionality and limitations, interface design based on user requirements, and the mathematical concepts of robot visual processing
- ROS, Python, C++, Qt framework, OpenCV

Education

May 2015 Master of Science in Computer Science

NSF Graduate Research Fellow

Washington University in St. Louis (WUSTL), St. Louis, MO

Select Coursework: Mobile Robotics, Computer Vision, Machine Learning

Bachelor of Science in Computer Science

cum laude

University of Alabama, Tuscaloosa, AL

Minors: Mathematics, Computer-Based Honors Program, Telecommunication and Film

Select Publications

- [1] A. Hipp, D. Adlakha, R. Gernes, A. Kargol, and R. Pless, "Learning from outdoor webcams: Surveillance of physical activity across environments", in Workshop of Big Data and Urban Informatics, 2014.
- A. Hipp, D. Adlakha, R. Gernes, A. U. Kargol, and R. Pless, "Do You See What I See: Crowdsource annotation of captured scenes", in SenseCam, 2013.