

Einführung in die Neuroinformatik

Tim Luchterhand, Paul Nykiel (Gruppe P)

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1 Backpropagation [Pen and Paper]

1. Forwärts propagieren:

$$\begin{aligned}u_1^{(1)} &= x_1 \cdot w_{11}^{(1)} + x_2 \cdot w_{21}^{(1)} + b_1^{(1)} \\y_1^{(1)} &= f_1(u_1^{(1)}) \\u_1^{(2)} &= y_1^{(1)} \cdot w_{11}^{(2)} + y_2^{(1)} \cdot w_{21}^{(2)} + b_1^{(2)} \\y_1^{(2)} &= f_2(u_1^{(2)})\end{aligned}$$

2. Fehler in der Ausgabeschicht bestimmen:

$$\delta_1^{(2)} = y_1^{(2)} - T_1$$

3. Backpropagation

$$\delta_1^{(1)} = \delta_1^{(2)} w_{11}^{(2)} f' \left(u_i^{(1)} \right)$$

4. Gewichte adaptieren

$$\tilde{w}_{11}^{(1)} = w_{11}^{(1)} + \eta x_1 \delta_1^{(1)}$$

2 Backpropagation [Matlab]

2.1

```

1 function [weights] = initWeights(inputDimensions, hiddenNeurons,
    outputDimensions)
2 %initWeights initializes the weights of the network
3 % Arguments:
4 %     - inputDimensions: number of input neurons
5 %     - hiddenNeurons: number of hidden neurons
6 %     - outputDimensions: number of output neurons
7 %
8 % Returns:
9 %     - weights: struct with the parameters w1, w2, theta1 and
    theta2
10 %
11 %rng(1337, 'combRecursive');
12 weights.w1 = rand(hiddenNeurons, inputDimensions) .* 0.5;
13 weights.w2 = rand(outputDimensions, hiddenNeurons) .* 0.5;
14 weights.theta1 = rand(hiddenNeurons, 1) .* 0.5;
15 weights.theta2 = rand(outputDimensions, 1) .* 0.5;
16 end

```

2.2

```

1 function [y2, u2, y1, u1] = forward(inputX, weights, trans)
2 %forward calculates the network output
3 % Arguments:
4 %     - inputX: input data organized as samples x dimensions (
    each row denotes a point)
5 %     - weights: struct with the parameters w1, w2, theta1 and
    theta2
6 %     - trans: activation function f(x) of the hidden layer
7 %
8     u1 = weights.w1 * inputX + weights.theta1;
9     y1 = trans(u1);
10    u2 = weights.w2 * y1 + weights.theta2;
11    y2 = u2;
12 end

```

2.3

```

1 function [delta1, delta2] = propagateError(T, y2, w2, u1Diff)
2 %propagateError calculates the error of the network (delta1 and
    delta2)
3 % Arguments:
4 %     - T: teacher signal
5 %     - y2: output of the last neuron

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6 %      - w2: weights matrix of the second layer
7 %      - u1Diff: f'(u1)
8 %
9      delta2 = norm(T-y2)^2;
10     delta1 = delta2 * (transpose(w2) .* u1Diff);
11 end

```

2.4

```

1 function [weights, errors] = train(hiddenNeurons, learnRate,
   inputX, outputT, epochs, trans, transDiff)
2 %train trains the neural network
3 % Arguments:
4 %      - hiddenNeurons: number of hidden neurons
5 %      - learnRate: learning rate \eta
6 %      - inputX: input data organized as samples x dimensions (
   each row denotes a point)
7 %      - outputT: teacher signal as column vector
8 %      - epochs: number of epochs to train the network
9 %      - trans: transfer function to use in the hidden layer (
   activation function)
10 %      - transDiff: derivative of the transfer function
11 %
12     assert(iscolumn(outputT), 'T must be a column vector');
13     assert(size(inputX, 1) == size(outputT, 1), 'Each data point
   must have an associated label');
14     %rng(1337, 'combRecursive'); % For reproducibility (does
   also work with parfor: http://de.mathworks.com/help/
   distcomp/control-random-number-streams.html#btms9o\_)
15     weights = initWeights(size(inputX,2),hiddenNeurons,size(
   outputT,2));
16     E = 0;
17     for e=1:epochs
18         indexSet = randperm(size(inputX,1));
19         for c=indexSet
20             currentInput = transpose(inputX(c,:));
21             trainerOutput = transpose(outputT(c,:));
22             [mlpOutput,u2,hiddenOutput,u1] = forward(
   currentInput, weights,trans);
23             [delta1,delta2] = propagateError(trainerOutput,
   mlpOutput,weights.w2,transDiff(u1));
24
25             weights.w1 += learnRate * (delta1 * transpose(
   currentInput));

```

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26         weights.w2 += learnRate * delta2 * transpose(
27             hiddenOutput);
28         weights.theta1 -= learnRate * delta1;
29         weights.theta2 -= learnRate * delta2;
30     end;
31     E = 0;
32     %Fehler berechnen
33     for c=1:size(inputX,1)
34         currentInput = transpose(inputX(c,:));
35         trainerOutput = transpose(outputT(c,:));
36         [mlpOutput,u2,hiddenOutput,u1] = forward(
37             currentInput, weights,trans);
38         E += norm(mlpOutput-trainerOutput)^2;
39     end;
40     E
41 end

```