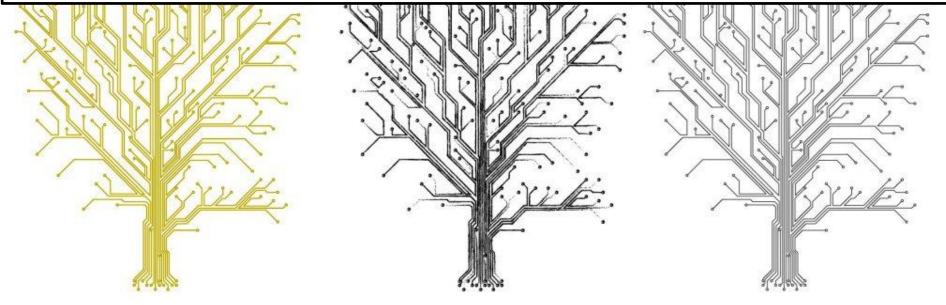


جامعة حلب كلية الهندسة الكهربائية والالكترونية مخبر النظم الالكترونية المتقدمة

# WELLING STATESTICS

### «محاضرات القسم العملي لمقرر النظم الالكترونية القابلة للبرمجة»

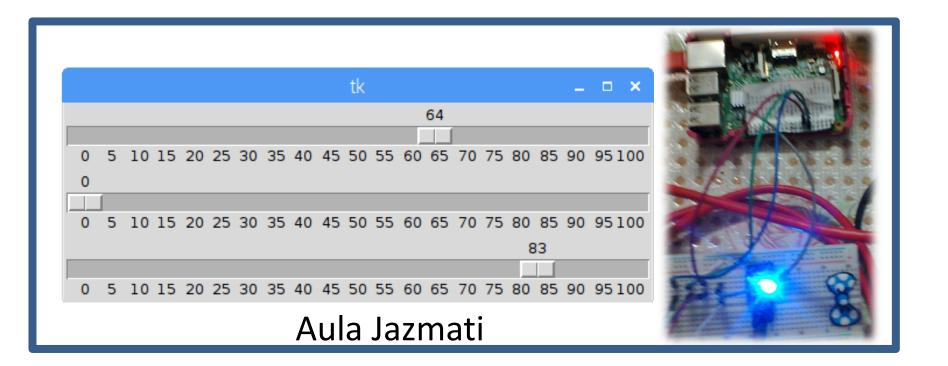


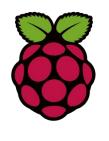
التجربة التاسعة

إعداد: م. علا جزماتي

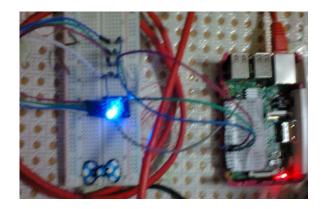


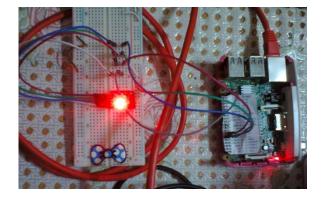
1

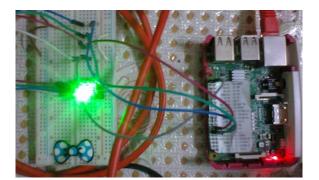




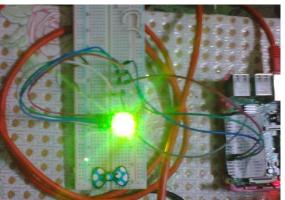
```
from tkinter import *
     import time
     import RPi.GPIO as io
     io.setmode(io.BOARD)
 4
     io.setwarnings(False)
 5
     Top = Tk()
 6
     io.setup(11,io.OUT)
     io.setup(15,io.OUT)
 8
 9
     io.setup(13,io.OUT)
10
     pr = io.PWM(11,50)
11
     pr.start(5)
     pg = io.PWM(15,50)
12
13
     pg.start(5)
14
     pb = io.PWM(13,50)
15
     pb.start(5)
16
     def updater1(dutyr):
17
         dutyr = w1.get()
18
         pr.ChangeDutyCycle(float(dutyr))
19
         print(dutyr)
20
     def updater2(dutyg):
21
         dutyg = w2.get()
22
         pg.ChangeDutyCycle(float(dutyg))
23
         print(dutyg)
```

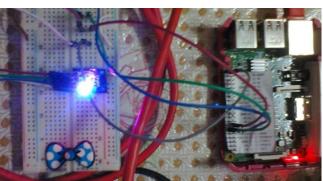


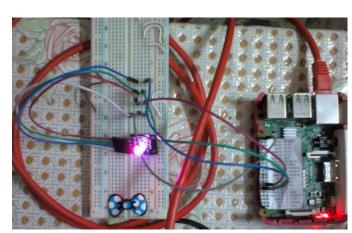


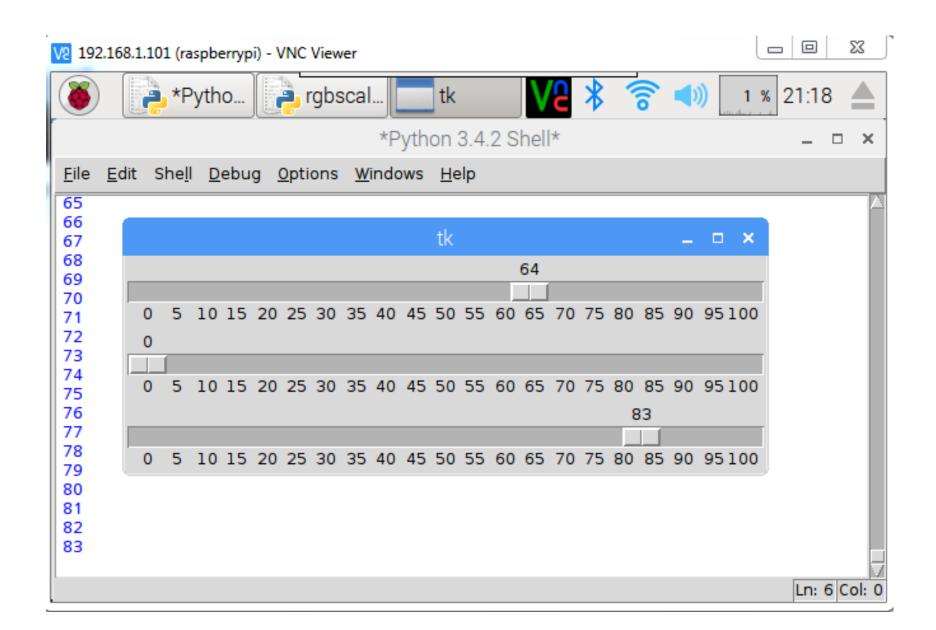


```
def updater3(dutyb):
24
25
         dutyb = w3.get()
         pb.ChangeDutyCycle(float(dutyb))
26
27
         print(dutyb)
     w1 = Scale(Top ,from =0,to =100,orient = HORIZONTAL ,length =500,tickinterval=5,command = updater1)
28
     w1.set(5)
29
     w1.pack()
30
     w2 = Scale(Top ,from =0,to =100,orient = HORIZONTAL,length =500,tickinterval=5,command = updater2)
31
32
     w2.set(5)
     w2.pack()
34
     w3 = Scale(Top ,from =0,to =100,orient = HORIZONTAL,length =500,tickinterval=5,command = updater3)
     w3.set(5)
    w3.pack()
36
     mainloop()
37
```

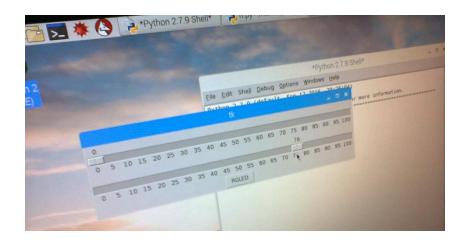


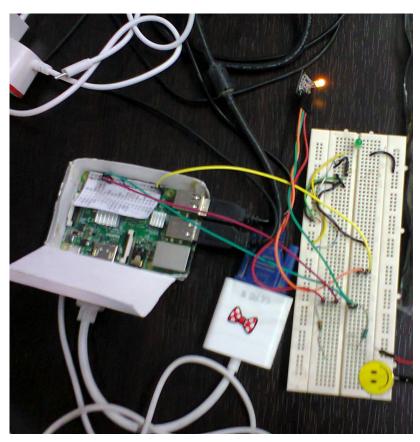












#### RGlednew.py - /home/pi/RGle

<u>File Edit Format Run Options Windows Help</u>

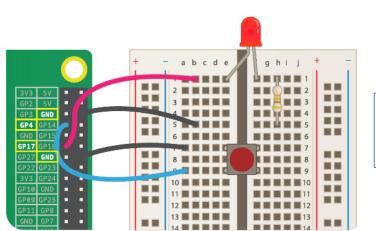
```
# -*- coding: utf-8 -*-
import time
import RPi.GPIO as GPIO
from Tkinter import *
GPI0.setmode(GPI0.BOARD)
red = 11 #pin numbers to match LED legs
green = 12
GPIO.setup(red, GPIO.OUT) #setup all the pins
GPI0.setup(green, GPI0.0UT)
Freq = 50 \#Hz
```

```
#setup all the colours
RED = GPIO.PWM(red, Freq) #Pin, frequency
RED.start(80) #Initial duty cycle of 0, so off
GREEN = GPIO.PWM(green, Freq)
GREEN.start(80)
top = Tk()
def updater(duty1):
    duty1 = w.get()
    RED.ChangeDutyCycle(int(duty1))
def updateg(duty2):
    duty2 = w1.get()
    GREEN.ChangeDutyCycle(int(duty2))
def update2():
    print(w.get(),w1.get())
```

```
w= Scale(top,from =0,to=99, orient = HORIZONTAL,
command=updater)
w.set(50)
w.pack()
w1= Scale(top,from =0,to=99,length =500,tickinterval=5, orient =
HORIZONTAL, command=updateg)
w1.set(50)
w1.pack()
Button(top, text='Red Green LED', command=update2).pack()
mainloop()
```



#### Homework:



صمم واجهة تحتوي على زر للتحكم بتشغيل LED موصول إلى القطب 11 من اللوحة.