

Compiling ..\src\Lab2.cpp:
Source file timestamp: 2016-03-14 04:06:45
Compiled at: 2016-03-14 06:33:13

```
1. /**
2. -----
3. ----- PARALLEL PROGRAMMING -----
4. ----- LAB #2 -----
5. - Win32. Semaphores, events, mutex and critical section -
6. ----- A = sort(a*B + b*C*(M0*MK)) -----
7. -----CREATED ON 12.03.2016-----
8. -----BY OLEG PEDORENKO, IP-31-----
9. -----
10. */
11.
12. #include <iostream>
13. #include <windows.h>
14. #include "data.h"
15.
16. using namespace std;
17.
18. int main(int argc, char** argv)
19. {
20.     int size = 8;
21.     if(argc > 1)
22.     {
23.         size = atoi(argv[1]);
24.     }
25.
26.     HANDLE* T = initThreads(size);
27.     WaitForMultipleObjects(4, T, true, INFINITE);
28.     cout << "All threads finished successfully" << endl;
29.     return 0;
30. }
```

30 lines: No errors

Compiling ..\src\data.h:
Source file timestamp: 2016-03-14 04:04:56
Compiled at: 2016-03-14 06:33:13

```
1. #ifndef DATA_H
2. #define DATA_H
3. #define M_VALUE 1
4. #include <windows.h>
5. #include <ctime>
6. #include "Eigen/Dense"
7.
8. using namespace std;
9. using namespace Eigen;
10.
11. HANDLE* initThreads(int size);
12.
13. #endif
```

13 lines: No errors

Compiling ..\src\data.cpp:
Source file timestamp: 2016-03-14 06:30:15

Compiled at: 2016-03-14 06:33:13

```
1. #include "data.h"
2. #include <iostream>
3. #include <fstream>
4. #include <string>
5.
6. int M_SIZE = 8;
7. int P = 4;
8. int H = M_SIZE/P;
9.
10. RowVectorXd A, B, C;
11. MatrixXd M0, MK;
12. double a, b;
13.
14. CRITICAL_SECTION CS_1;
15. HANDLE Evt_1, Evt_2, Sem_1, Sem_2, Sem_3;
16. HANDLE Mut_1;
17. typedef DWORD WINAPI (*FP)(LPVOID);
18.
19. DWORD WINAPI F1(LPVOID lparam);
20. DWORD WINAPI F2(LPVOID lparam);
21. DWORD WINAPI F3(LPVOID lparam);
22. DWORD WINAPI F4(LPVOID lparam);
23.
24. MatrixXd inputMatrix();
25. RowVectorXd inputVector();
26. double inputScalar();
27. MatrixXd sortMatrix(MatrixXd m);
28.
29. HANDLE* initThreads(int size = 8)
30. {
31.     M_SIZE = size;
32.     H = M_SIZE / P;
33.
34.     HANDLE* T = new HANDLE[P];
35.     FP F[] = {&F1, &F2, &F3, &F4};
36.     HANDLE* S[] = {&Sem_1, &Sem_2, &Sem_3};
37.     HANDLE* E[] = {&Evt_1, &Evt_2};
38.
39.     cout << "Matrix and vector size: ";
40.     cout << M_SIZE << endl;
41.
42.     for(int i = 0; i < 2; i++)
43.     {
44.         *(E[i]) = CreateEvent(NULL, true, false, NULL);
45.     }
46.
47.     for(int i = 0; i < 3; i++)
48.     {
49.         *(S[i]) = CreateSemaphore(NULL, 0, 1, NULL);
50.     }
51.     InitializeCriticalSection(&CS_1);
52.
53.     Mut_1 = CreateMutex(NULL, false, NULL);
54.
55.     for(int i = 0; i < P; i++)
56.     {
57.         T[i] = CreateThread(
58.             NULL,
59.             20000000,
60.             F[i],
```

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61.     NULL,
62.     0,
63.     NULL);
64. }
65.
66.     return T;
67. }
68.
69. //Th = aBh + bCh*(MO*MKh)
70. void calcTh(
71.     RowVectorXd &T,
72.     const double &a,
73.     const RowVectorXd &B,
74.     const double &b,
75.     const RowVectorXd &C,
76.     const MatrixXd &MO,
77.     const MatrixXd &MK,
78.     int k)
79. {
80.     int i = k-1;
81.     int size = H;
82.     if(k == P)
83.     {
84.         size = M_SIZE - i*H;
85.     }
86.     T.segment(i*H, size) =
87.         a * B.segment(i*H, size) +
88.         b * (C * (MO * MK.block(0, i*H, M_SIZE, size)));
89. }
90.
91. ////////////////////////////////// TASK 1 //////////////////////////////////
92. DWORD WINAPI F1(LPVOID lparam)
93. {
94.     int threadNo = 1;
95.     double a1, b1;
96.     MatrixXd MO1;
97.
98.     WaitForSingleObject(Mut_1, INFINITE);
99.     cout << "Thread " << threadNo << " started" << endl;
100.    ReleaseMutex(Mut_1);
101.
102.    //Ввод A, B, MO
103.    A = RowVectorXd::Zero(M_SIZE);
104.    B = inputVector();
105.    MO = inputMatrix();
106.    //Сигнал о завершении ввода S2,3,4.1 (Evt_1)
107.    SetEvent(Evt_1);
108.    //Ожидание ввода в T4 W4.1 (Evt_2)
109.    WaitForSingleObject(Evt_2, INFINITE);
110.    //Вход в KC
111.    EnterCriticalSection(&CS_1);
112.        //Копирование OP a->a1, b->b1, MO->MO1
113.        a1 = a;
114.        b1 = b;
115.        MO1 = MO;
116.    //Выход из KC
117.    LeaveCriticalSection(&CS_1);
118.    //Счет Ah
119.    calcTh(A, a1, B, b1, C, MO1, MK, 1);
120.    //Сортировка Ah
121.    auto begin = A.segment(0, H).data();
122.    sort(begin, begin+H);

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123.    //Ожидание завершения сортировки в T2 W2.1 (Sem_1)
124.    WaitForSingleObject(Sem_1, INFINITE);
125.    //Слияние первой половины A
126.    auto begin2 = A.segment(0, 2*H).data();
127.    inplace_merge(begin2, begin2 + H, begin2 + 2*H);
128.    //Ожидание слияния второй половины A, W4.2 (Sem_3)
129.    WaitForSingleObject(Sem_3, INFINITE);
130.    //Слияние вектора A
131.    auto begin3 = A.data();
132.    inplace_merge(begin3, begin3 + 2*H, begin3 + M_SIZE);
133.    //Вывод вектора A
134.    WaitForSingleObject(Mut_1, INFINITE);
135.    if(M_SIZE < 9)
136.    {
137.        cout << A << endl;
138.    }
139.    ReleaseMutex(Mut_1);
140.    WaitForSingleObject(Mut_1, INFINITE);
141.    cout << "Thread " << threadNo << " finished" << endl;
142.    ReleaseMutex(Mut_1);
143.    return true;
144. }
145.
146. ////////////////////////////////// TASK 2 //////////////////////////////////
147. DWORD WINAPI F2(LPVOID lparam)
148. {
149.     int threadNo = 2;
150.     double a2, b2;
151.     MatrixXd MO2;
152.
153.     WaitForSingleObject(Mut_1, INFINITE);
154.     cout << "Thread " << threadNo << " started" << endl;
155.     ReleaseMutex(Mut_1);
156.
157.     //Ожидание ввода в T1 W1.1 (Evt_1)
158.     WaitForSingleObject(Evt_1, INFINITE);
159.     //Ожидание ввода в T4 W4.1 (Evt_2)
160.     WaitForSingleObject(Evt_2, INFINITE);
161.     //Вход в KC
162.     EnterCriticalSection(&CS_1);
163.        //Копирование OP a->a1, b->b1, MO->MO1
164.        a2 = a;
165.        b2 = b;
166.        MO2 = MO;
167.    //Выход из KC
168.    LeaveCriticalSection(&CS_1);
169.    //Счет Ah
170.    calcTh(A, a2, B, b2, C, MO2, MK, 2);
171.    //Сортировка Ah
172.    auto begin = A.segment(H, H).data();
173.    sort(begin, begin+H);
174.    //Сигнал о сортировке Ah S1.2 (Sem_1)
175.    ReleaseSemaphore(Sem_1, 1, NULL);
176.
177.    WaitForSingleObject(Mut_1, INFINITE);
178.    cout << "Thread " << threadNo << " finished" << endl;
179.    ReleaseMutex(Mut_1);
180.    return true;
181. }
182.
183. ////////////////////////////////// TASK 3 //////////////////////////////////
184. DWORD WINAPI F3(LPVOID lparam)

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185. {
186.     int threadNo = 3;
187.     double a3, b3;
188.     MatrixXd M03;
189.
190.     WaitForSingleObject(Mut_1, INFINITE);
191.     cout << "Thread " << threadNo << " started" << endl;
192.     ReleaseMutex(Mut_1);
193.
194.     //Ожидание ввода в T1 W1.1 (Evt_1)
195.     WaitForSingleObject(Evt_1, INFINITE);
196.     //Ожидание ввода в T4 W4.1 (Evt_2)
197.     WaitForSingleObject(Evt_2, INFINITE);
198.     //Вход в KC
199.     EnterCriticalSection(&CS_1);
200.     //Копирование OP a->a1, b->b1, MO->M01
201.     a3 = a;
202.     b3 = b;
203.     M03 = M0;
204.     //Выход из KC
205.     LeaveCriticalSection(&CS_1);
206.     //Счет Ah
207.     calcTh(A, a3, B, b3, C, M03, MK, 3);
208.     //Сортировка Ah
209.     auto begin = A.segment(2*H, H).data();
210.     sort(begin, begin+H);
211.     //Сигнал о сортировке Ah S4.2 (Sem_2)
212.     ReleaseSemaphore(Sem_2, 1, NULL);
213.
214.     WaitForSingleObject(Mut_1, INFINITE);
215.     cout << "Thread " << threadNo << " finished" << endl;
216.     ReleaseMutex(Mut_1);
217.     return true;
218. }
219.
220. ////////////////////////////////// TASK 4 //////////////////////////////////
221. DWORD WINAPI F4(LPVOID lparam)
222. {
223.     int threadNo = 4;
224.     double a4, b4;
225.     MatrixXd M04;
226.
227.     WaitForSingleObject(Mut_1, INFINITE);
228.     cout << "Thread " << threadNo << " started" << endl;
229.     ReleaseMutex(Mut_1);
230.     //Ввод a, b, C, MK
231.     a = inputScalar();
232.     b = inputScalar();
233.     C = inputVector();
234.     MK = inputMatrix();
235.     //Сигнал о завершении ввода S1,2,3.2 (Evt_2)
236.     SetEvent(Evt_2);
237.     //Ожидание ввода в T1 W1.1 (Evt_1)
238.     WaitForSingleObject(Evt_1, INFINITE);
239.     //Вход в KC
240.     EnterCriticalSection(&CS_1);
241.     //Копирование OP a->a1, b->b1, MO->M01
242.     a4 = a;
243.     b4 = b;
244.     M04 = M0;
245.     //Выход из KC
246.     LeaveCriticalSection(&CS_1);

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247.     //Счет Ah
248.     calcTh(A, a4, B, b4, C, M04, MK, 4);
249.     //Сортировка Ah
250.     auto begin = A.segment(3*H, (M_SIZE - 3*H)).data();
251.     sort(begin, begin+(M_SIZE - 3*H));
252.     //Ожидание завершения сортировки в T3 W3.1 (Sem_2)
253.     WaitForSingleObject(Sem_2, INFINITE);
254.     //Слияние второй половины A
255.     auto begin2 = A.segment(2*H, (M_SIZE - 2*H)).data();
256.     inplace_merge(begin2, begin2 + H, begin2 + (M_SIZE - 2*H));
257.     //Сигнал о слиянии второй половины A, S1.3 (Sem_3)
258.     ReleaseSemaphore(Sem_3, 1, NULL);
259.
260.     WaitForSingleObject(Mut_1, INFINITE);
261.     cout << "Thread " << threadNo << " finished" << endl;
262.     ReleaseMutex(Mut_1);
263.     return true;
264. }
265.
266.
267. MatrixXd inputMatrix()
268. {
269.     MatrixXd res;
270.     #ifdef M_VALUE
271.     res = MatrixXd::Constant(M_SIZE, M_SIZE, M_VALUE);
272.     #endif
273.     #ifdef M_RANDOM
274.     res = MatrixXd::Random(M_SIZE, M_SIZE);
275.     res = (res + MatrixXd::Constant(M_SIZE, M_SIZE, 1.2)) * 50;
276.     #endif
277.     return res;
278. }
279.
280. RowVectorXd inputVector()
281. {
282.     RowVectorXd res;
283.     #ifdef M_VALUE
284.     res = RowVectorXd::Constant(M_SIZE, M_VALUE);
285.     #endif
286.     #ifdef M_RANDOM
287.     srand(time(0));
288.     res = RowVectorXd::Random(M_SIZE);
289.     res = (res + RowVectorXd::Constant(M_SIZE, 1.2)) * 50;
290.     #endif
291.     return res;
292. }
293.
294. double inputScalar()
295. {
296.     double res;
297.     #ifdef M_VALUE
298.     res = M_VALUE;
299.     #endif
300.     #ifdef M_RANDOM
301.     res = 1 + rand() % 100;
302.     res = res / ((double) (1 + rand() % 10));
303.     #endif
304.     return res;
305. }

```

305 lines: No errors