

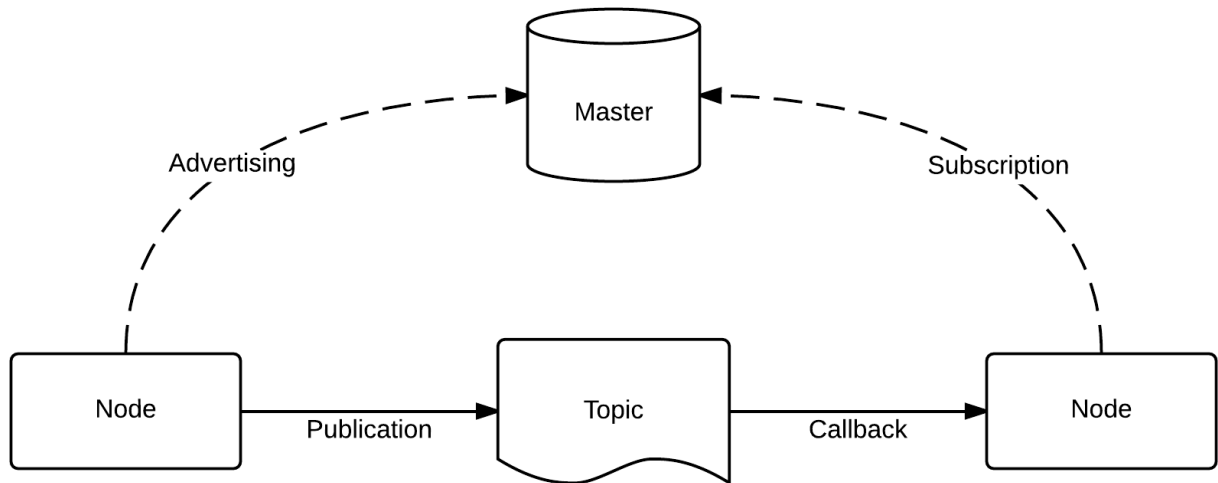
Three Dimensions

1. Community Level
 2. Computation Graph Level
 3. File System Level
-

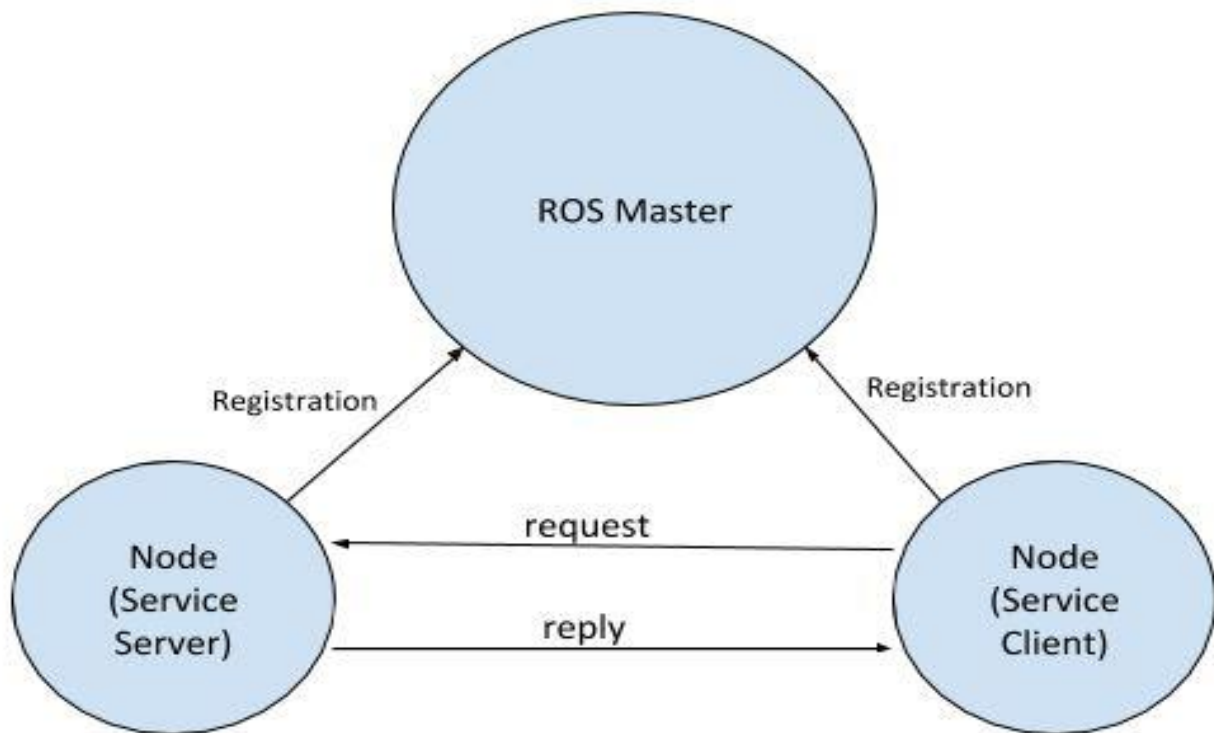
ROS Community Level

- Topic
- Service
- Actionlib

Topic Communicaton

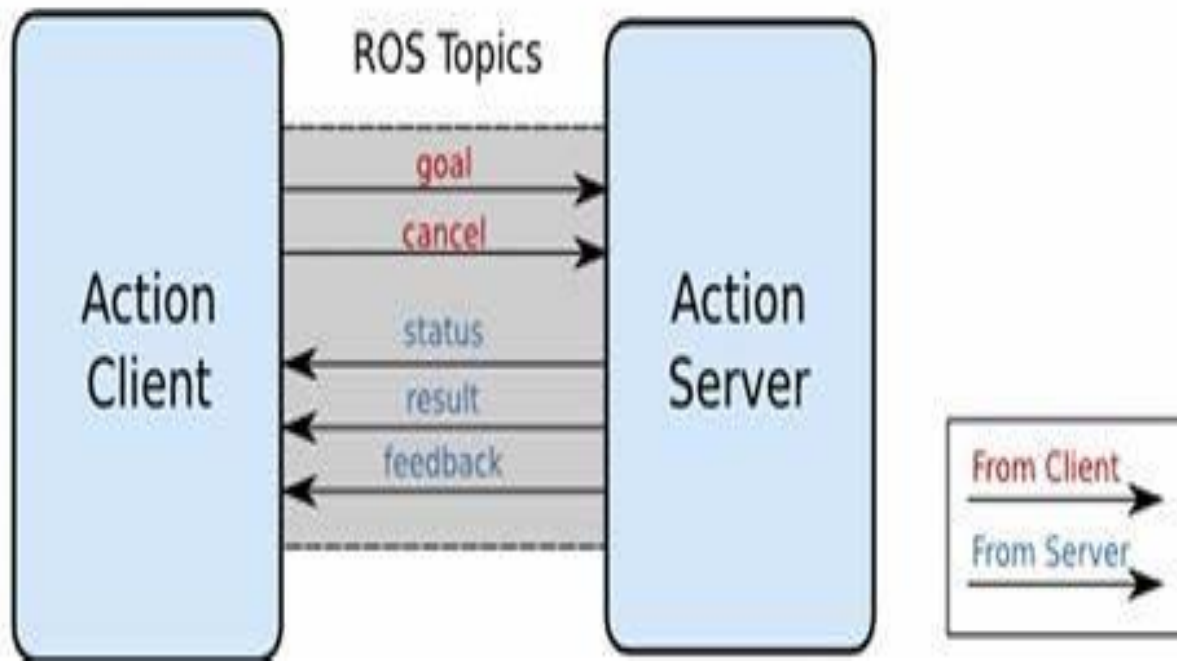


Service Communication

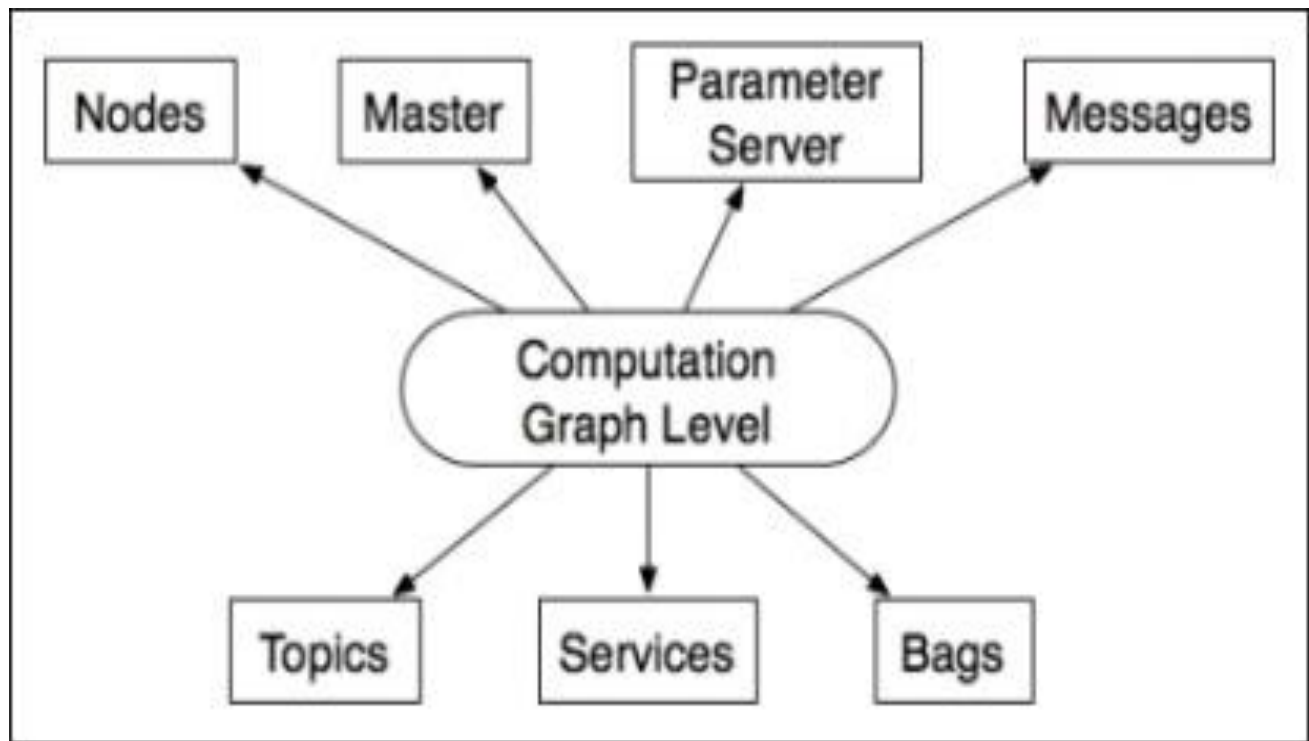


Action Communication

Action Interface



ROS Computation Graph Level



ROS File System Level

