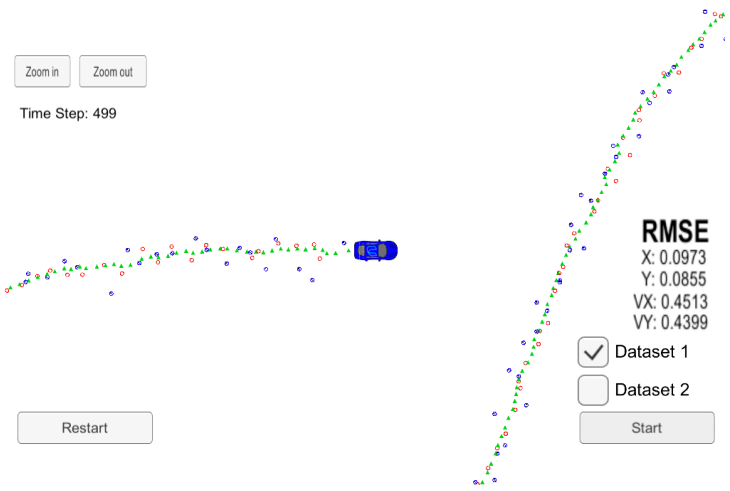
CRITERIA	MEETS SPECIFICATIONS
Your code should compile.	Code is compiled with XCODE IDE profile

Accuracy

CRITERIA	MEETS SPECIFICATIONS
RMSE	

CRITERIA	MEETS SPECIFICATIONS
Your Sensor Fusion algorithm follows the general processing flow as taught in the preceding lessons.	Code in the lesson is used.
Your Kalman Filter algorithm handles the first measurements appropriately.	Initialisation done in Fusion EKF between line 54-104
Your Kalman Filter algorithm first predicts then updates.	Updates implemented between 105 - 165
Your Kalman Filter can handle radar and lidar measurements.	EKF and Kalman filter called for Radar and LIDAR

Code Efficiency

CRITERIA	MEETS SPECIFICATIONS
Your algorithm should avoid unnecessary calculations.	• Avoided