```
> restart;
  with(LinearAlgebra):
  with (Physics):
  with(plots):
  with(plottools):
  with(Typesetting):
  interface(typesetting=extended):
  interface(showassumed=0):
> L:=15:
  EI:=10000:
  #apply 1 unit of load at x = 10
  f:=x->1*Dirac(x-10);
                                                      L := 15
                                                     EI := 10000
                                                  f := x \mapsto \delta(x - 10)
\Gamma> eq1:=EI*diff(y(x),x,x,x,x)=f(x)
                                            eq1 := 10000 \ v''''(x) = \delta(x-10)
> #simply supported
  ic1:=y(0)=0, (D@@2)(y)(0)=0, y(L)=0, (D@@2)(y)(L)=0;
  #clamped at both ends
  ic2:=y(0)=0, (D@@1)(y)(0)=0, y(L)=0, (D@@1)(y)(L)=0;
  #clamped at one end, free at another end
  ic 3:=y(0)=0, (D@@1)(y)(0)=0,(D@@2)(y)(L)=0(D@@3)(y)(L)=0
                                  ic1 := v(0) = 0, D^{(2)}(v)(0) = 0, v(15) = 0, D^{(2)}(v)(15) = 0
                                    ic2 := v(0) = 0, D(v)(0) = 0, v(15) = 0, D(y)(15) = 0
                                 ic3 := v(0) = 0, D(v)(0) = 0, D^{(2)}(v)(15) = 0, D^{(3)}(v)(15) = 0
> sol1:=dsolve({eq1, ic1}, {y(x)}): y1:=rhs(sol1);
  sol2:=dsolve({eq1, ic2}, {y(x)}): y2:=rhs(sol2);
  sol3:=dsolve(\{eq1, ic3\}, \{y(x)\}): y3:=rhs(sol3);
  M1:=-EI*diff(diff(y1,x),x):
  V1:=diff(M1,x):
  M2:=-EI*diff(diff(y2,x),x):
  V2:=diff(M1,x):
```

```
M3:=-EI*diff(diff(y3,x),x):
  V3:=diff(M1,x):
                           yI := -\frac{x^2 \theta(x-10)}{2000} - \frac{\theta(x-10)}{60} + \frac{x^3 \theta(x-10)}{60000} - \frac{x^3}{180000} + \frac{x \theta(x-10)}{200} + \frac{x}{900}
                         y2 := \frac{x^2}{18000} - \frac{x^2 \theta(x - 10)}{2000} - \frac{\theta(x - 10)}{60} + \frac{x^3 \theta(x - 10)}{60000} - \frac{7x^3}{1620000} + \frac{x \theta(x - 10)}{200}
                           y3 := \frac{x^2}{2000} - \frac{x^2 \theta(x - 10)}{2000} - \frac{\theta(x - 10)}{60} + \frac{x^3 \theta(x - 10)}{60000} - \frac{x^3}{60000} + \frac{x \theta(x - 10)}{200}
> a:=plot(y1,x=0..L,title="Displacement function, simply supported"):
   b:=plot(M1,x=0..L,title="Moment distribution"):
  c:=plot(V1,x=0..L,title="Shear distribution"):
  d:=plot(y2,x=0..L,title="Displacement function, clamped at both end"):
  e:=plot(M2,x=0..L,title="Moment distribution"):
  f:=plot(V2,x=0..L,title="Shear distribution"):
  g: =plot(y3,x=0..L,title="Displacement function, clamped at one end, free at another end"):
  h: =plot(M3,x=0..L,title="Moment distribution"):
  i:=plot(V3,x=0..L,title="Shear distribution"):
> display(Array([a,b,c]));
  display(Array([d,e,f]));
  display(Array([g,h,i]));
```





