

COMP 341 Intro to AI

Bayesian Networks – Exact Inference

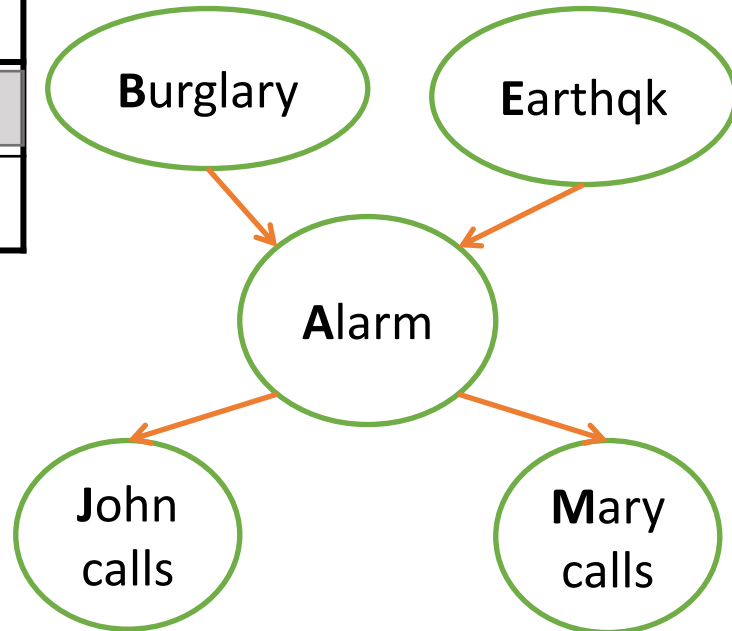


How certain are we
that the butler did it?

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Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998

B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= \\
 P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) &= \\
 0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7 &
 \end{aligned}$$

Probabilistic Inference

- Inference: Calculating a useful quantity from a joint probability distribution
- We have seen “inference by enumeration”
- Posterior Probability: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Most Likely Explanation: $\operatorname{argmax}_q P(Q = q|E_1 = e_1, \dots, E_k = e_k)$
- Mary called me to tell me that my house alarm was ringing. How likely is it that there is a burglar?
- Why did Mehmet get a medical report for the exam?

Probabilistic Inference Methods

- Enumeration (exact, exponential complexity)
- Variable elimination (exact, worst-case exponential complexity, often better)
- Exact Inference is NP-Hard
- Sampling (approximate)

Inference by Enumeration given the Joint Dist.

- General case:

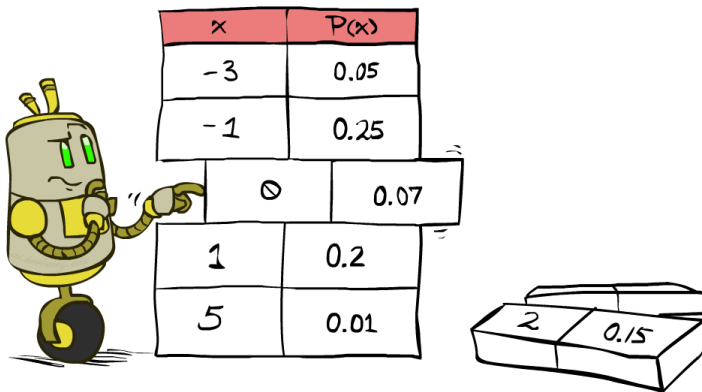
- Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
 - Query* variable: Q
 - Hidden variables: $H_1 \dots H_r$
- $$\left. \begin{array}{l} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{array} \right\} \begin{array}{l} X_1, X_2, \dots X_n \\ \text{All variables} \end{array}$$

- We want:

** Works fine with multiple query variables, too*

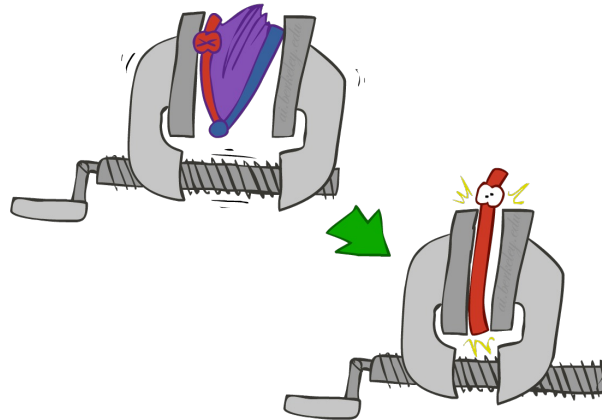
$$P(Q|e_1 \dots e_k)$$

- Step 1: Select the entries consistent with the evidence



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

- Step 2: Sum out H to get joint of Query and evidence (marginalize)



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} P(\underbrace{Q, h_1 \dots h_r, e_1 \dots e_k}_{X_1, X_2, \dots X_n})$$

- Step 3: Normalize

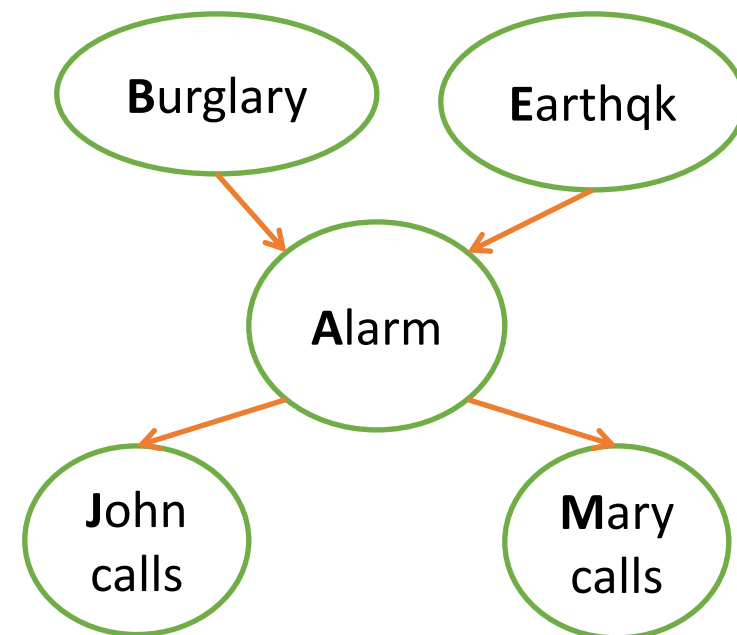
$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

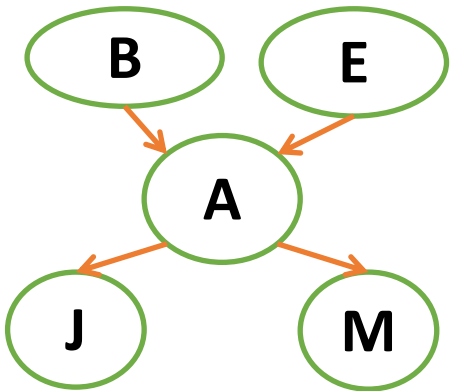
Inference by Enumeration in BNs

- Easy! Just need lots of time
 - State all conditional probabilities needed
 - Figure out all atomic probabilities needed
 - Combine, marginalize and normalize
- E.g.
 $P(B, E, A, J, M) = P(B)P(E)P(A|B, E)P(J|A)P(M|A)$
 $P(B \mid +j, +m) = ?$



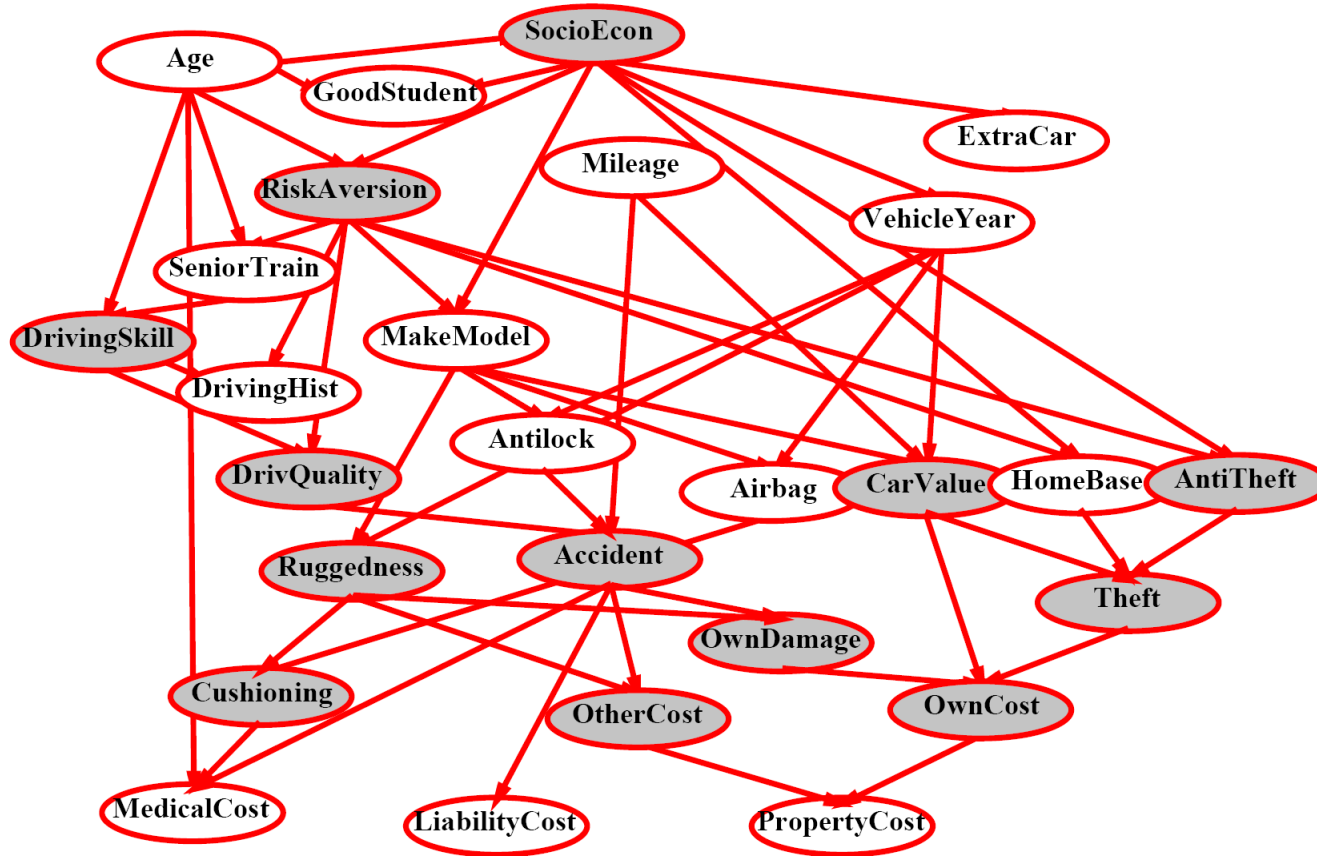
Inference Example

$$\begin{aligned}P(B \mid +j, +m) &= \frac{P(B, +j, +m)}{P(+j, +m)} = \alpha P(B, +j, +m) = \alpha \sum_{e,a} P(B, e, a, +j, +m) \\&= \alpha \sum_{e,a} P(B)P(e)P(a \mid B, e)P(+j \mid a)P(+m \mid a) \\&= \alpha (P(B)P(+e)P(+a \mid B, +e)P(+j \mid +a)P(+m \mid +a) \\&\quad + P(B)P(-e)P(+a \mid B, -e)P(+j \mid +a)P(+m \mid +a) \\&\quad + P(B)P(+e)P(-a \mid B, +e)P(+j \mid -a)P(+m \mid -a) \\&\quad + P(B)P(-e)P(-a \mid B, -e)P(+j \mid -a)P(+m \mid -a))\end{aligned}$$



Calculate for both +b and -b. Then normalize to get rid of α

Another Example

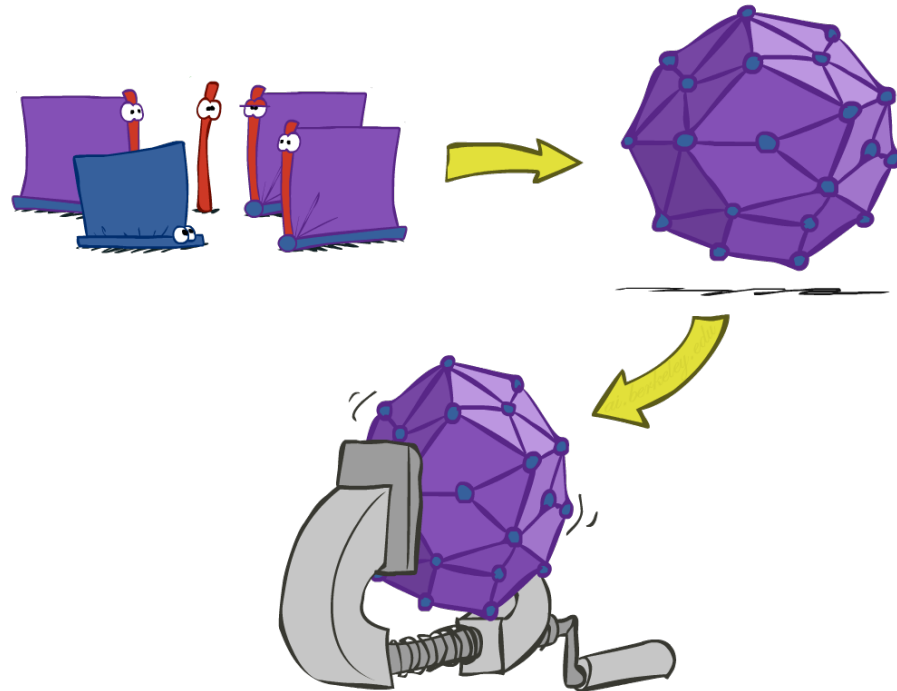


$$P(\text{LiabilityCost} | \text{ShadedVariables}) = ?$$

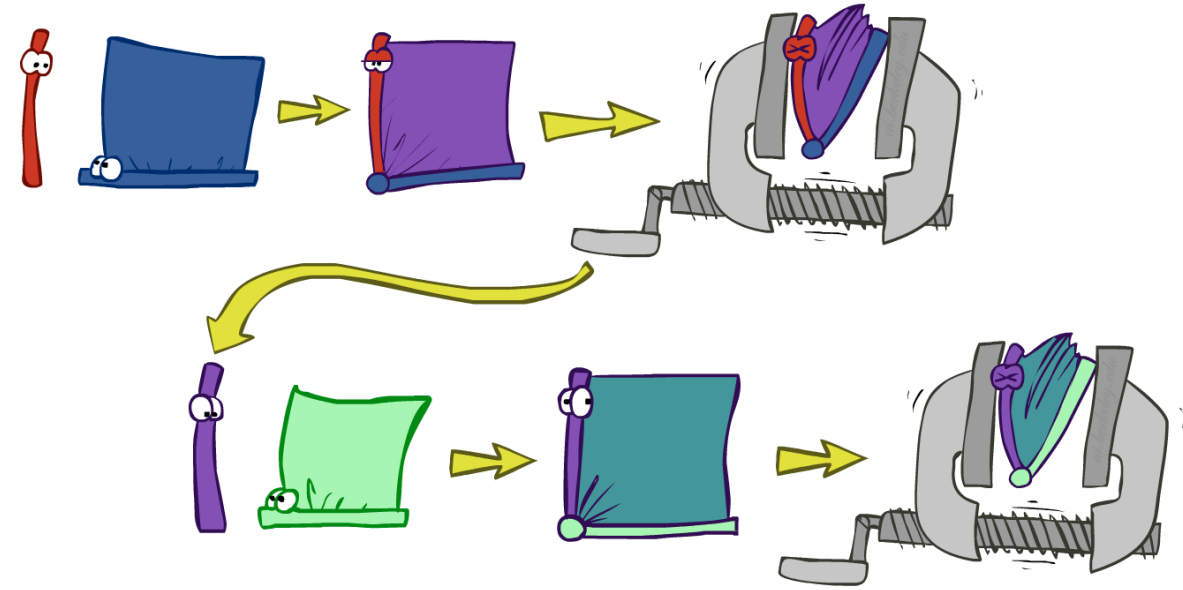
Would be cumbersome with enumeration (aka brute force), but there is a much easier way for this example

Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables



- Idea: interleave joining and marginalizing!
 - Called “Variable Elimination”
 - Still NP-hard, but usually faster than inference by enumeration



- First we'll need some new notation: factors

Factors

- **Factorization:** “Decomposition of an object into product of other objects or *factors*”
- Pointwise product of two factors:
$$f_1(x_1, \dots, x_n, \underline{y_1, \dots, y_k}) \cdot f_2(\underline{y_1, \dots, y_k}, z_1, \dots, z_l) = f(x_1, \dots, x_n, \underline{y_1, \dots, y_k}, z_1, \dots, z_l)$$
- What are some factors that we can use in BNs?

Factors I

- Joint distribution: $P(X,Y)$
 - Entries $P(x,y)$ for all x, y
 - Sums to 1
- Selected joint: $P(x,Y)$
 - A slice of the joint distribution
 - Entries $P(x,y)$ for fixed x , all y
 - Sums to $P(x)$
- Number of capitals (unobserved variables) affect dimensionality of the table

$$P(T, W)$$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

$$P(\text{cold}, W)$$

T	W	P
cold	sun	0.2
cold	rain	0.3

Factors II

- Single conditional: $P(Y \mid x)$
 - Entries $P(y \mid x)$ for fixed x , all y
 - Sums to 1

$$P(W \mid \text{cold})$$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals:

$$P(X \mid Y)$$

- Multiple conditionals
- Entries $P(x \mid y)$ for all x, y
- Sums to $|Y|$

$$P(W \mid T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$$P(W \mid \text{hot})$$

$$P(W \mid \text{cold})$$

Factors III

- Specified family: $P(y \mid X)$
 - Entries $P(y \mid x)$ for fixed y , but for all x
 - Sums to ... who knows!

$P(rain \mid T)$			
T	W	P	
hot	rain	0.2	} $P(rain \mid hot)$ $P(rain \mid cold)$
cold	rain	0.6	

- In general, a factor is $P(Y_1, \dots, Y_N \mid X_1, \dots, X_M)$
 - Multi-dimensional array
 - Its values are $P(y_1 \dots y_N \mid x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array

Example: Traffic Domain

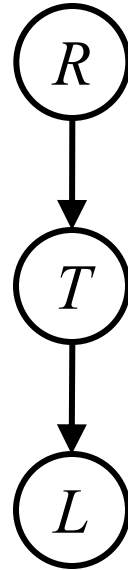
- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!

$$P(L) = ?$$

$$= \sum_{r,t} P(r, t, L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$



$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$P(R)$		$P(T R)$			$P(L T)$		
+r	0.1	+r	+t	0.8	+t	+l	0.3
-r	0.9	+r	-t	0.2	+t	-l	0.7
		-r	+t	0.1	-t	+l	0.1
		-r	-t	0.9	-t	-l	0.9

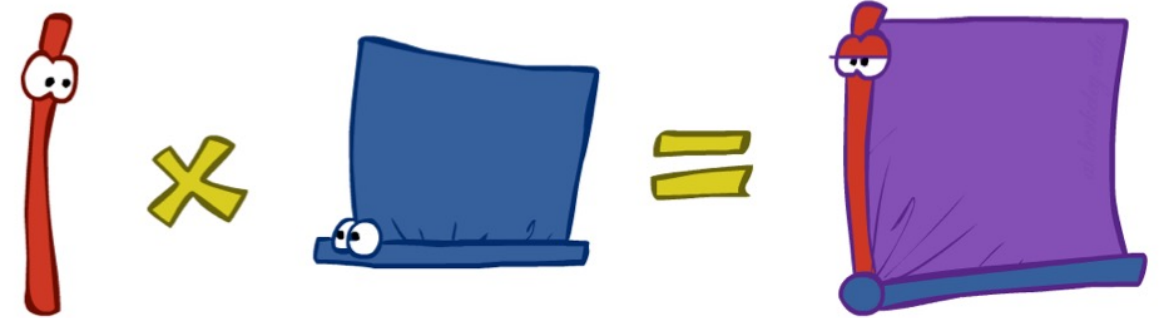
- Any known values are selected
 - E.g. if we know $L = +\ell$ the initial factors are

$P(R)$		$P(T R)$			$P(+\ell T)$		
+r	0.1	+r	+t	0.8	+t	+l	0.3
-r	0.9	+r	-t	0.2	-t	+l	0.1
		-r	+t	0.1			
		-r	-t	0.9			

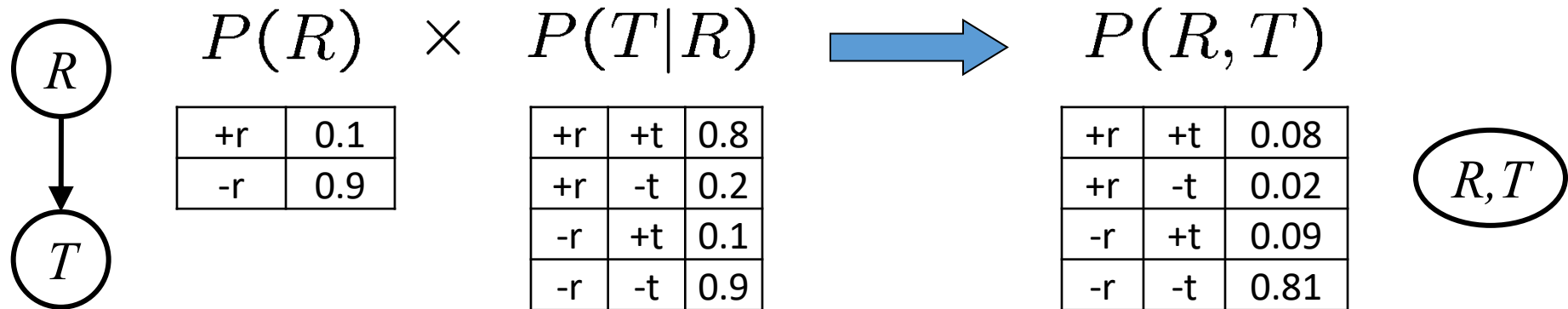
- Procedure: Join all factors, then eliminate all hidden variables

Operation 1: Join Factors

- First basic operation: **joining factors**
- Combining factors:
 - Get all factors over the joining variable
 - Build a new factor over the union of the variables involved

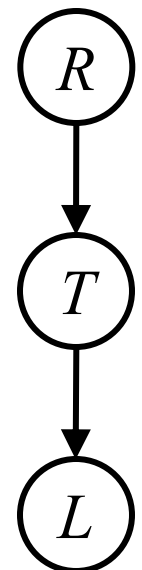


- Example: Join on R



- Computation for each entry: pointwise products $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

Example: Multiple Joins



$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

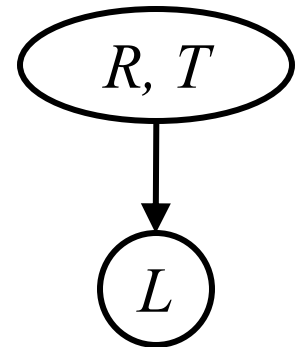
Join R

$P(R, T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

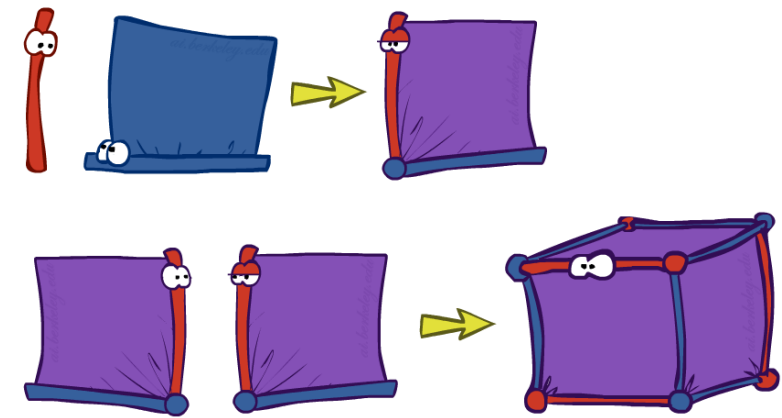


Join T

R, T, L

$P(R, T, L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729




Operation 2: Eliminate

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A **projection** operation
- Example:

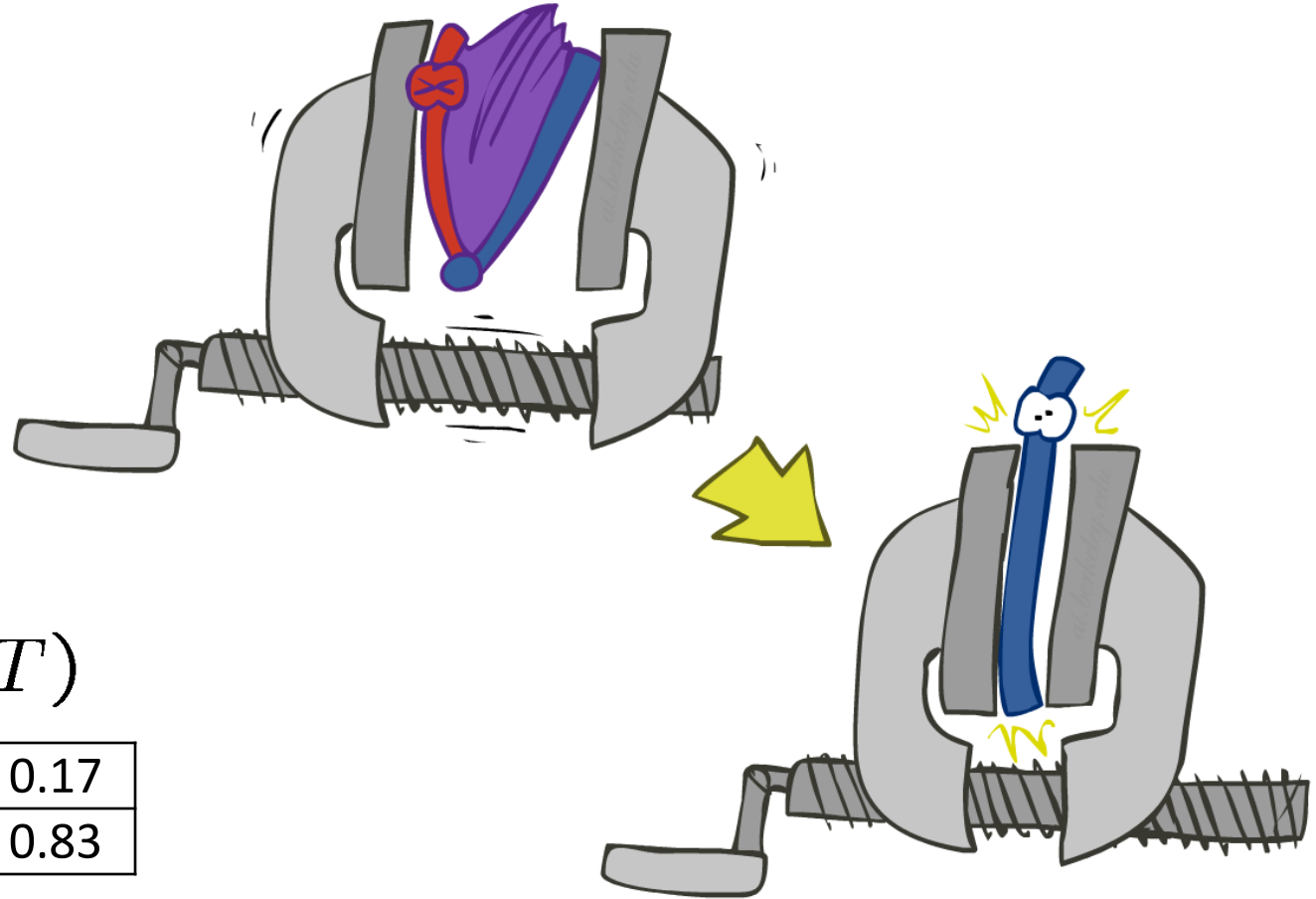
$$P(R, T)$$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

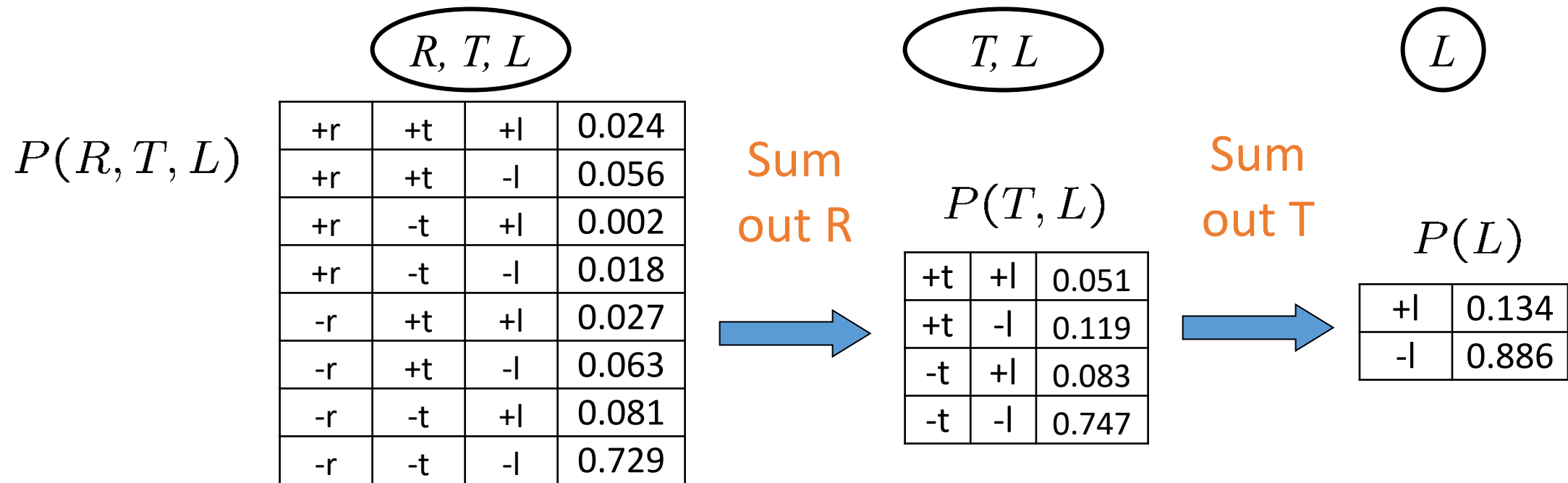
sum R


$$P(T)$$

+t	0.17
-t	0.83

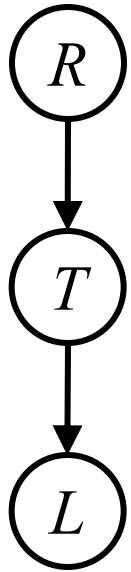


Multiple Elimination



Thus far, we have seen multiple-join and multiple-eliminate which is inference by enumeration!
Variable elimination is when we marginalize early

Traffic Domain



$$P(L) = ?$$

- Inference by Enumeration

$$= \sum_t \sum_r \underbrace{P(L|t)P(r)P(t|r)}_{\text{Join on } r}$$

$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

- Variable Elimination (VE)

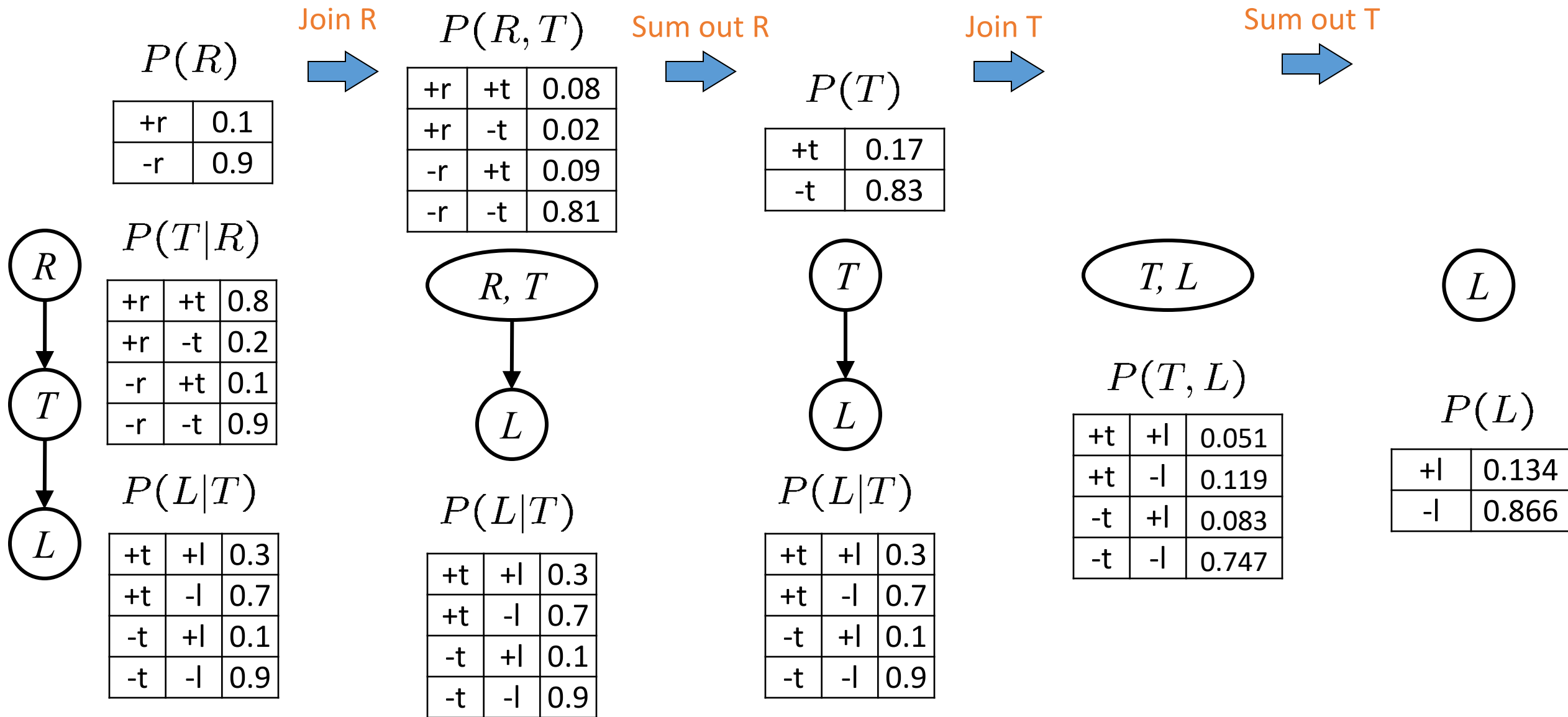
$$= \sum_t P(L|t) \underbrace{\sum_r P(r)P(t|r)}_{\text{Join on } r}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$

$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$

$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

Marginalizing Early! (aka VE)



Evidence

- If you have evidence, start with factors that select that evidence
 - No evidence uses these initial factors:

$P(R)$		$P(T R)$			$P(L T)$		
+r	0.1	+r	+t	0.8	+t	+l	0.3
-r	0.9	+r	-t	0.2	+t	-l	0.7
		-r	+t	0.1	-t	+l	0.1
		-r	-t	0.9	-t	-l	0.9

- Computing $P(L|+r)$ the initial factors become:

$P(+r)$		$P(T +r)$			$P(L T)$		
+r	0.1	+r	+t	0.8	+t	+l	0.3
		+r	-t	0.2	+t	-l	0.7
					-t	+l	0.1
					-t	-l	0.9

- We eliminate all vars other than query + evidence

Evidence II

- Result will be a selected joint of query and evidence
 - E.g. for $P(L \mid +r)$, we would end up with:

$$P(+r, L)$$

+r	+l	0.026
+r	-l	0.074

Normalize



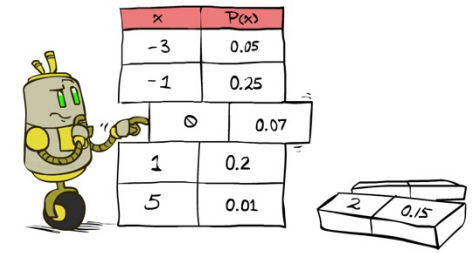
$$P(L \mid +r)$$

+l	0.26
-l	0.74

- To get our answer, just normalize this!
- That's it!

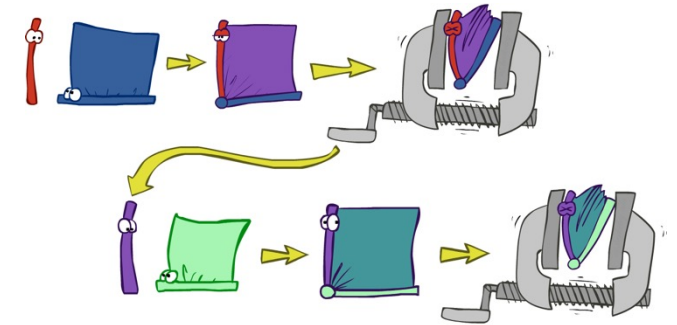
General Variable Elimination

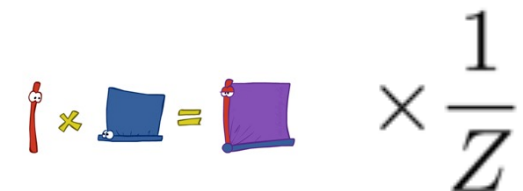
- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H
- Join all remaining factors and normalize



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

0.15




$$\text{red stick} \times \text{blue square} = \text{purple square} \times \frac{1}{Z}$$

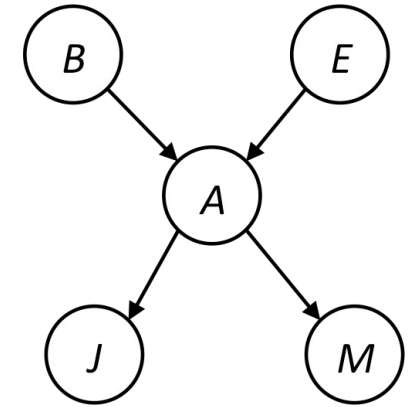
Example

- What is the probability of a burglar being in my house if both John and Marry calls? OR $P(B|+j, +m) = ?$

Query Variables: B

Evidence Variables: $+j, +m$

Hidden Variables: A, E

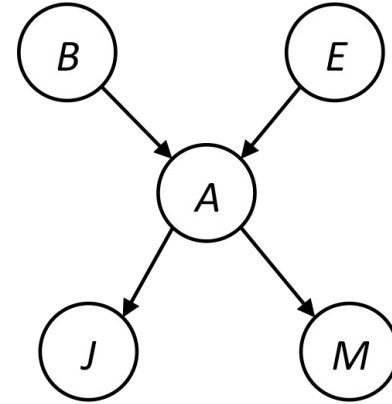


Example

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
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Current factors

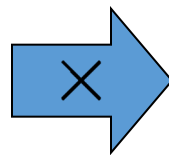


Choose A

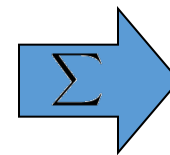
$$P(A|B, E)$$

$$P(j|A)$$

$$P(m|A)$$



$$P(j, m, A|B, E)$$

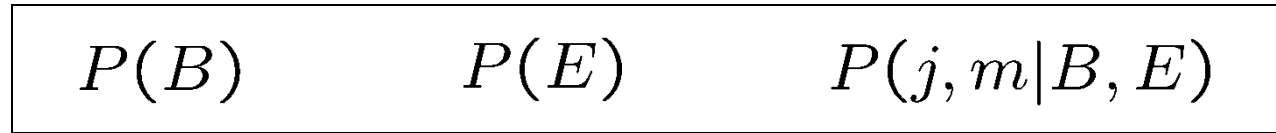


$$P(j, m|B, E)$$

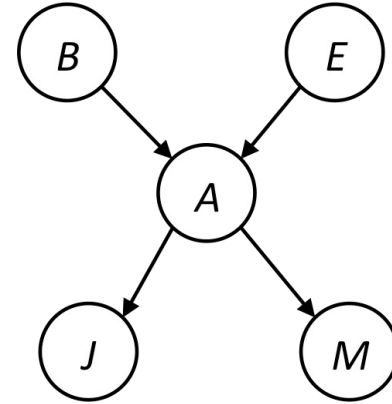
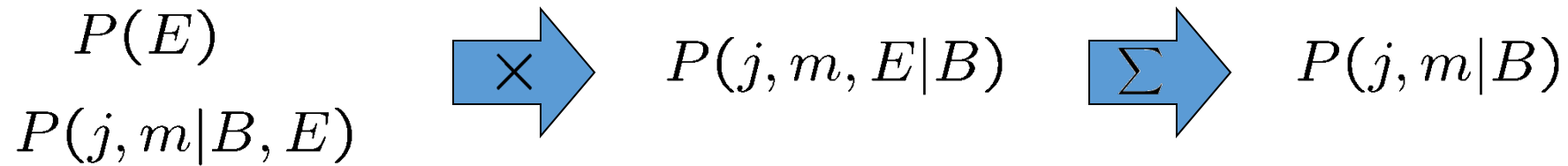
$P(B)$	$P(E)$	$P(j, m B, E)$
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Factors after
eliminating A

Example

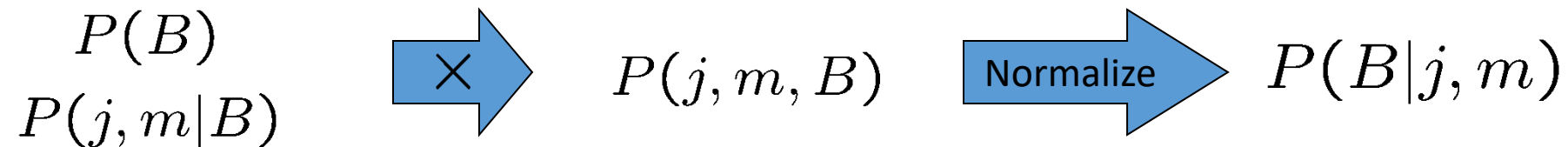


Choose E



No more hidden vars, now what?
"Join all remaining and normalize"

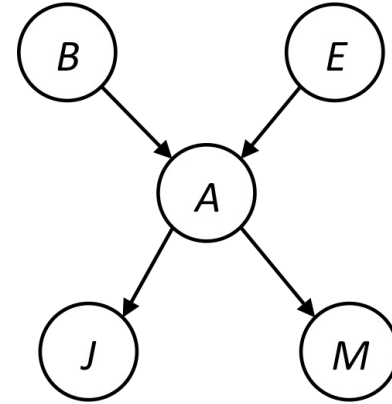
Finish with B



Same Example in Equations

$$P(B|j, m) \propto P(B, j, m)$$

$P(B)$	$P(E)$	$P(A B, E)$	$P(j A)$	$P(m A)$
--------	--------	-------------	----------	----------



$$\begin{aligned}
 P(B|j, m) &\propto P(B, j, m) \\
 &= \sum_{e, a} P(B, j, m, e, a) \\
 &= \sum_{e, a} P(B)P(e)P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) \sum_a P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e)f_1(B, e, j, m) \\
 &= P(B) \sum_e P(e)f_1(B, e, j, m) \\
 &= P(B)f_2(B, j, m)
 \end{aligned}$$

marginal can be obtained from joint by summing out

use Bayes' net joint distribution expression

use $x^*(y+z) = xy + xz$

joining on a, and then summing out gives f_1

use $x^*(y+z) = xy + xz$

joining on e, and then summing out gives f_2

All we are doing is exploiting $uwv + uwz + uxy + uxz + vwy + vwz + vxy + vxz = (u+v)(w+x)(y+z)$ to improve computational efficiency!

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_1 , this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_2 , this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

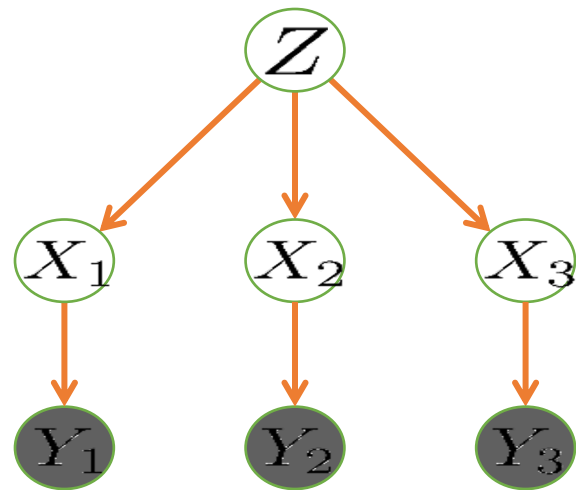
Eliminate Z , this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$, and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

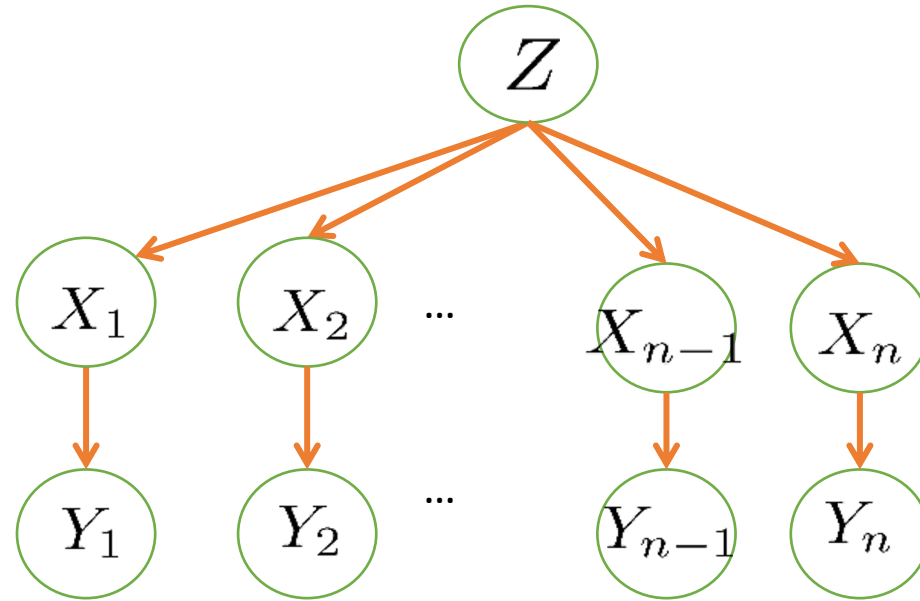
Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one parent.

Variable Elimination Ordering

- For the query $P(X_n | y_1, \dots, y_n)$ work through the following two different orderings as done in previous slide:
 Z, X_1, \dots, X_{n-1} and X_1, \dots, X_{n-1}, Z . What is the size of the maximum factor generated for each of the orderings?



- Answer: 2^{n+1} versus 2^2 (assuming binary)
- In general: the ordering can greatly affect efficiency.

VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2^n vs. 2^2
- Does there always exist an ordering that only results in small factors?
 - No!

Variable Elimination Summary

- Interleave joining and marginalizing
- d^k entries computed for a factor over k variables with domain sizes d
- Ordering of elimination of hidden variables can affect size of factors generated
- Worst case: running time exponential in the size of the Bayes' net
- Better than enumeration in practice, saves time by marginalizing variables as soon as possible rather than at the end
- Not efficient enough for big BNs, so next we'll talk about *Approximate Inference* techniques

