
Numerical Algorithms for Physics : Project List

Andrea Mignone
Physics Department, University of Torino
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Writing the Project

- In the following I will show a list of projects for this course.
- Each project should be no more than ≈ 10 pages long (excluding the code listed in the appendix).
- A .pdf file is strongly recommended.
- The document structure should consists of
 - An abstract / Introductory part where the physical problem is explained and why we need to resort to numerical integration.
 - A test section where the numerical method is validated against known analytical / reference solution.
 - A model study of the problem including plots.
 - A final summary/discussion.
 - An appendix including the code used for the project, using fixed-size fonts (a font whose letters and characters each occupy the same amount of horizontal space, e.g., Courier, Courier New, Lucida Console, Monaco, and Consolas).

Project #1: Finite Potential Well

- Consider the time-independent Schrödinger equation in one dimension,

$$-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} \psi(x) + V(x)\psi(x) = E\psi(x)$$

where $\psi(x)$ is the wave function, m is the particle mass, E its energy and $V(x)$ is the potential energy.

The probability to find the particle between x and $x+dx$ is $\psi(x)\psi^*(x)dx = |\psi(x)|^2 dx$

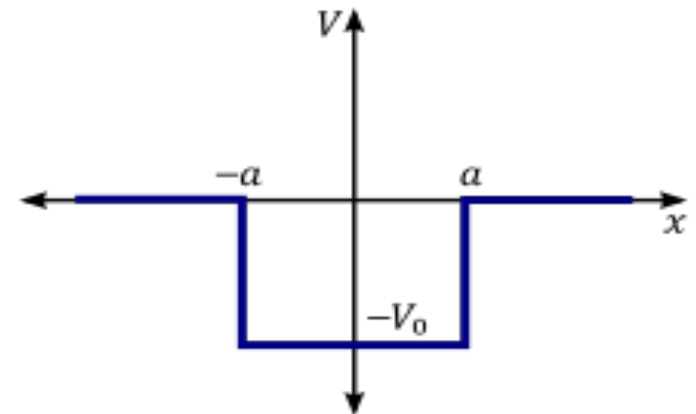
- Consider the potential well given by

$$V(x) = \begin{cases} 0 & \text{for } |x| > a \\ -V_0 & \text{for } |x| < a \end{cases}$$

- In this case the Schrödinger equation becomes

$$\begin{cases} \frac{d^2\psi(x)}{dx^2} + \frac{2m}{\hbar^2}(E + V_0)\psi(x) = 0 & \text{for } |x| < a \\ \frac{d^2\psi(x)}{dx^2} + \frac{2m}{\hbar^2}E\psi(x) = 0 & \text{for } |x| > a \end{cases}$$

- Since the potential is symmetric, we assume that the wave functions have defined parity (odd or even).



Project #1: Finite Potential Well: Wavefunctions

- For an **even** wavefunction we must have

$$\psi(x) = \psi_{II}(x) = A \cos(\alpha x) \quad \text{for } |x| < a$$

$$\psi(x) = \psi_{I,III}(x) = B e^{-\beta|x|} \quad \text{for } |x| > a$$

$$\alpha = \sqrt{\frac{2m}{\hbar^2}(E + V_0)};$$

$$\beta = \sqrt{\frac{2m}{\hbar^2}(-E)}$$

In $x = a$ we impose **continuity** conditions:

$$\psi_{II}(x = a) = \psi_{III}(x = a)$$

$$\left. \frac{d\psi_{II}}{dx} \right|_{x=a} = \left. \frac{d\psi_{III}}{dx} \right|_{x=a} \quad \longrightarrow \quad \begin{cases} A \cos(\alpha a) = B e^{-\beta a} \\ -\alpha A \sin(\alpha a) = -\beta B e^{-\beta a} \end{cases} \quad \Rightarrow \quad \boxed{\alpha \tan(\alpha a) = \beta}$$

By solving this equation we obtain the eigenvalues E . Remember that α and β are functions of E .

- For an **odd** function, $\psi_{II}(x) = \tilde{A} \sin(\alpha x)$, $\psi_{III}(x) = \tilde{B} e^{-\beta x}$
and imposing the same continuity conditions we get

$$\boxed{\alpha \cot(\alpha a) = -\beta}$$

Project #1: Finite Potential Well: Purpose

- Compute the eigenvalues of the finite potential well.

- Use dimensionless units by introducing $\eta = \frac{E}{\hbar^2/(2ma^2)}$, $K = \frac{V_0}{\hbar^2/(2ma^2)}$ so that the equations to be solved (in η) are:

$$\begin{cases} \tan(\sqrt{\eta + K}) = \sqrt{-\frac{\eta}{\eta + K}} & (\text{even}) \\ \cot(\sqrt{\eta + K}) = -\sqrt{-\frac{\eta}{\eta + K}} & (\text{odd}) \end{cases}$$

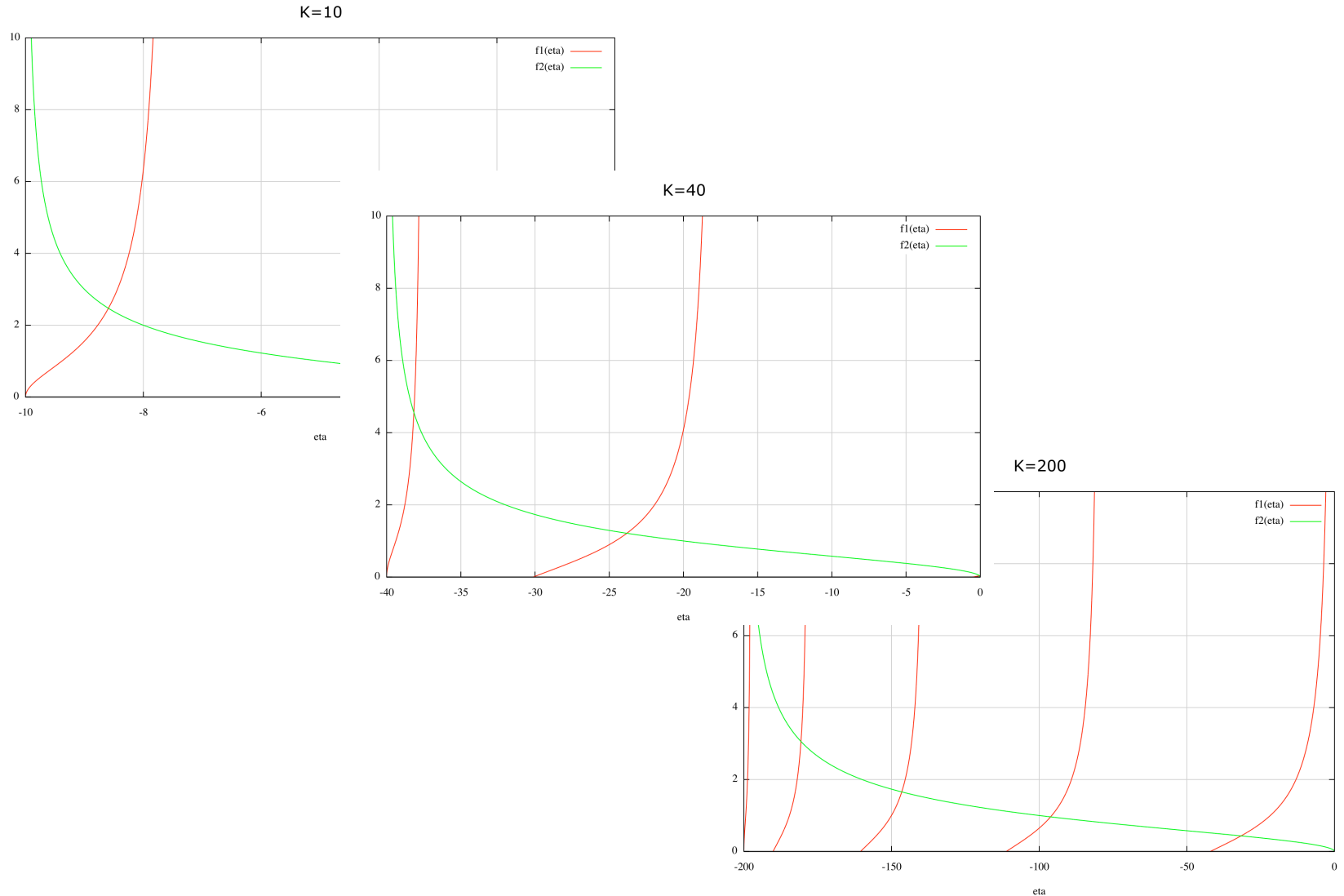


- Look for bound states which satisfy $-K < \eta < 0$ and, to avoid dealing with singularities in the tangent it is better to rewrite the equations as

$$\begin{cases} f_e(\eta) = \sqrt{\eta + K} \sin \sqrt{\eta + K} - \sqrt{-\eta} \cos \sqrt{\eta + K} = 0 \\ f_o(\eta) = \sqrt{\eta + K} \cos \sqrt{\eta + K} + \sqrt{-\eta} \sin \sqrt{\eta + K} = 0 \end{cases}$$

Project #1: Finite Potential Well: Graphical Solution

- A graphical representation of the solution is given below:



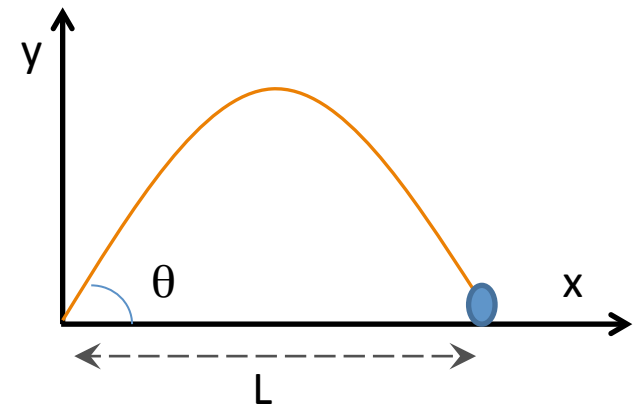
Project #2: Realistic Projectile Motion

- We consider the motion of a particle subject to drag force

$$\begin{cases} \ddot{x} = F_{d,x} \\ \ddot{y} = -g + F_{d,y} \end{cases}$$

where $\vec{F}_d = -Bv\vec{v}$ is the drag force due to air resistance (for the present calculation you can use $B = 4 \cdot 10^{-5} \text{ m}^{-1}$).

- This force is always opposite to velocity and therefore remember to write it in vector components.
- For a given initial velocity v_0 and distance L to a target, determine the angles (if any) you must orient your cannon at in order to hit the target.



Project #3: Realistic Pendulum

- Here we consider the equation of a pendulum for arbitrary amplitude and subject to damping as well as driving force:

$$\frac{d^2\theta}{dt^2} = -\frac{g}{L} \sin \theta - q \frac{d\theta}{dt} + F_D \sin(\Omega_D t)$$

- Here q is a measure of damping while F_D and Ω_D are the amplitude and frequency of the driving term. Transform the problem into a system of coupled 1st order ODE:

$$\frac{d\theta}{dt} = \omega$$

$$\frac{d\omega}{dt} = -(g/L) \sin \theta - q\omega + F_D \sin(\Omega_D t) \quad \text{💬}$$

- So that our vector of unknowns is, $\mathbf{y} = (\theta, \omega)$.
- With zero driving force the motion is damped.
 - With $F_D = 0.5$ there are two regimes:
 - An initial transient decay where the motion with angular frequency Ω is damped
 - A following phase where the pendulum settles in into a steady oscillation in response to the driving force.

Project #3: Realistic Pendulum

- The behavior changes dramatically when $F_D = 1.2$ since the motion is no longer simple even at long times.
- The system does not settle into a repeating steady state behavior and this is an indication of chaotic behavior.

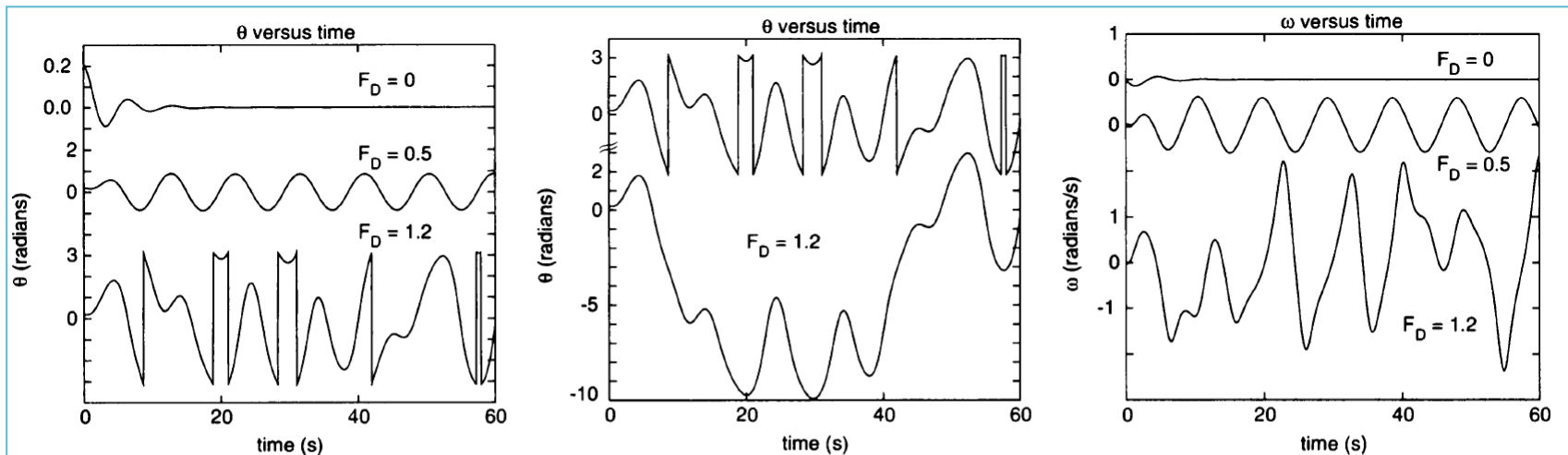


Figure 3.4: Left: behavior of θ as a function of time for our driven, damped, nonlinear pendulum, for several different values of the driving force. The vertical “jumps” in θ occur when the angle is reset so as to keep it in the range $-\pi$ to $+\pi$; they do not correspond to discontinuities in $\theta(t)$. Center: behavior of $\theta(t)$ for $F_D = 1.2$ with and without these “resets.” Right: corresponding behavior of the angular velocity of the pendulum, ω . The parameters for the calculation were $q = 1/2$, $\ell = g = 9.8$, $\Omega_D = 2/3$, and $dt = 0.04$, all in SI. The initial conditions were $\theta(0) = 0.2$ and $\omega(0) = 0$.

Project #4: the Double Pendulum

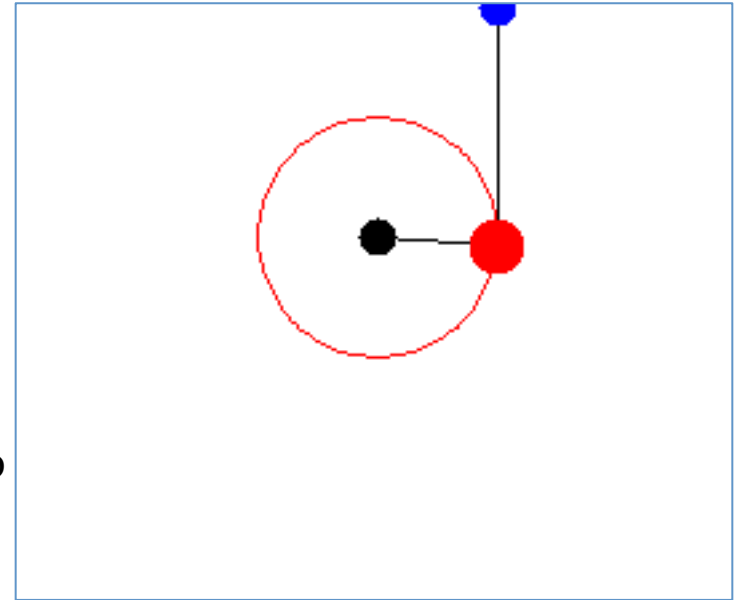
- A double pendulum consists of one pendulum attached to another. It is an example of a simple physical system which can exhibit chaotic behavior.
- Consider a double bob pendulum with masses m_1 and m_2 attached by rigid massless wires of lengths L_1 and L_2 . Further, let the angles the two wires make with the vertical be denoted θ_1 and θ_2 .
- The position of the two masses are given by

$$x_1 = L_1 \sin \theta_1$$

$$x_2 = x_1 + L_2 \sin \theta_2$$

$$y_1 = -L_1 \cos \theta_1$$

$$y_2 = y_1 - L_2 \cos \theta_2$$



Project #4: the Double Pendulum

- After some tedious algebra, the equations of motion can be written as:

$$\theta_1'' = \frac{-g(2m_1 + m_2) \sin \theta_1 - m_2 g \sin(\theta_1 - 2\theta_2) - 2 \sin(\theta_1 - \theta_2) m_2 (\theta_2'^2 L_2 + \theta_1'^2 L_1 \cos(\theta_1 - \theta_2))}{L_1 (2m_1 + m_2 - m_2 \cos(2\theta_1 - 2\theta_2))}$$

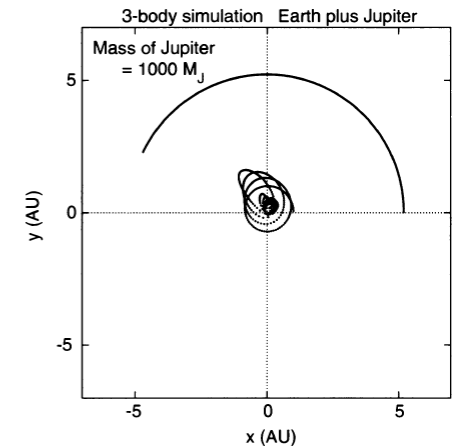
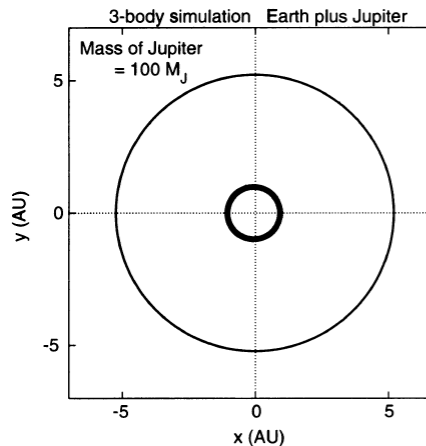
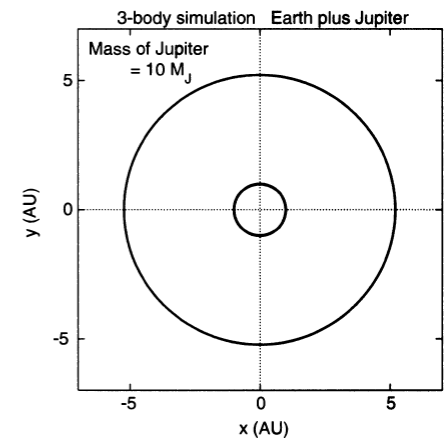
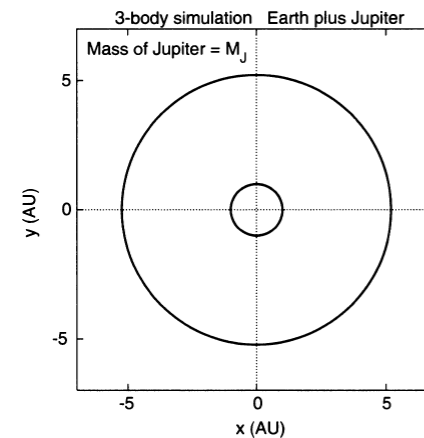
$$\theta_2'' = \frac{2 \sin(\theta_1 - \theta_2) (\theta_1'^2 L_1 (m_1 + m_2) + g(m_1 + m_2) \cos \theta_1 + \theta_2'^2 L_2 m_2 \cos(\theta_1 - \theta_2))}{L_2 (2m_1 + m_2 - m_2 \cos(2\theta_1 - 2\theta_2))}$$

- Using $m_1 = m_2$ and $L_1 = L_2$, study the double pendulum motion by direct integration of the equations of motion.
- Try to address the following issues:
 - Is energy conserved ?
 - Can you determine a range of initial condition that leads the system to chaos ?
 - Does the pendulum flip ?



Project #5: Three-body problem

- Consider the simplest three-body problem given by the earth, the Sun and Jupiter.
- We know that without Jupiter, the Earth's orbit is stable and does not change in time.
- Our objective is to quantify how much effect the gravitational field of Jupiter has on Earth's motion.
- Change the Jupiter mass by a factor of 10, 100 and 1000: do you start seeing an effect ?



Project #6: Lane-Emden Equation

- In astrophysics, the **Lane–Emden equation** is a **dimensionless** form of Poisson's equation for the gravitational potential of a Newtonian self-gravitating, spherically symmetric, polytropic fluid. It is named after astrophysicists Jonathan Homer Lane and Robert Emden.
- A spherically symmetric star in hydrostatic equilibrium must obey the hydrostatic balance equation

$$\frac{dP}{dr} = -\rho \frac{GM_r}{r^2} \quad \text{where mass is related to density by} \quad \frac{dM_r}{dr} = 4\pi r^2 \rho$$

- Assuming an adiabatic “quasi-static” change of state of the gas following:

$$P = K\rho^\gamma = K\rho^{(n+1)/n},$$

one can rewrite the previous equation as
This is the Lane-Emden equation.

$$\boxed{\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) = -\theta^n .}$$

- The equation is written in terms of dimensionless variable defined by

$$\rho = \rho_c \theta^n$$

$$r = a \xi$$

$$\begin{aligned} a &= \left[(n+1) \frac{K}{4\pi G} \rho_c^{(1-n)/n} \right]^{1/2} \\ &= \left[(n+1) \frac{K}{4\pi G} \right]^{1/2} \rho_c^{(1-n)/2n}, \end{aligned}$$

Project #6: Lane-Emden Equation

- Exact solutions to the Lane-Emden exist for $n=0,1,5$ (see e.g., wikipedia) but otherwise numerical integration must be used.
- Boundary conditions: to get a unique solution to the Lane-Emden Equation, we need to specify two boundary conditions for this 2nd order ODE. A realistic model cannot have a 'cusp' at the origin which means that

$$\begin{aligned}\theta &= 1 \quad \text{at} \quad \xi = 0 \\ \frac{d\theta}{d\xi} &= 0 \quad \text{at} \quad \xi = 0\end{aligned}$$

- Because $\rho \approx \theta^n$, only $\theta \geq 0$ can be realistic: this defines the surface of the polytrope is defined as the radius at which θ first becomes zero (or quite small). This is designated as ξ_s , so

$$R = a \xi_s .$$

- If the surface seems to be approaching infinity in size, (e.g. for $n = 5$) the code should stop the integration.
- Note that, at the beginning, an indefinite value of $1/\xi * d\theta/d\xi$ exists. This is solved by expanding θ as

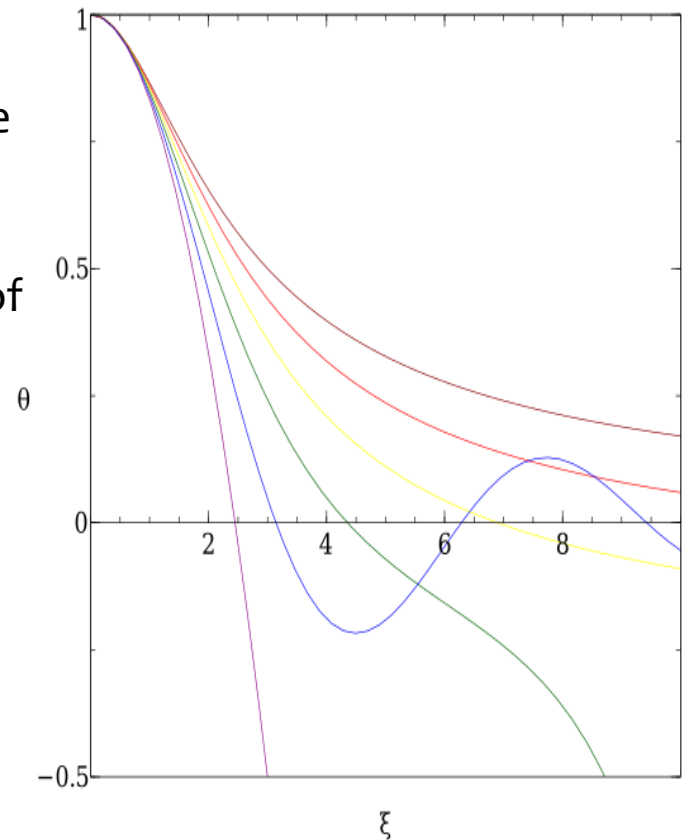
$$\theta = 1 - \frac{1}{6}\xi^2 + \frac{n}{120}\xi^4 + \dots$$

Project #6: Lane-Emden Equation

- Solve the Lane-Emden equations for different values of $n = 0, 1, 3/2, 3$.
- Verify (when possible) against analytical solution (e.g. $n = 1 \rightarrow \theta = \sin \xi / \xi$).
- Find the radius of the different polytropes and make plot of the density in units of the central density.
- For white dwarfs with high densities, the equation of state is well approximated by a polytropic equation of state with index $n = 3$. The constant K in the polytropic equation of state then is

$$K = \frac{3^{1/3} \pi^{2/3}}{2^{4/3} 4} \frac{\hbar c}{m_p^{4/3}},$$

- What is the mass of a high density white dwarf? If you have done everything
- right, you will have rediscovered the Chandrasekhar Mass!

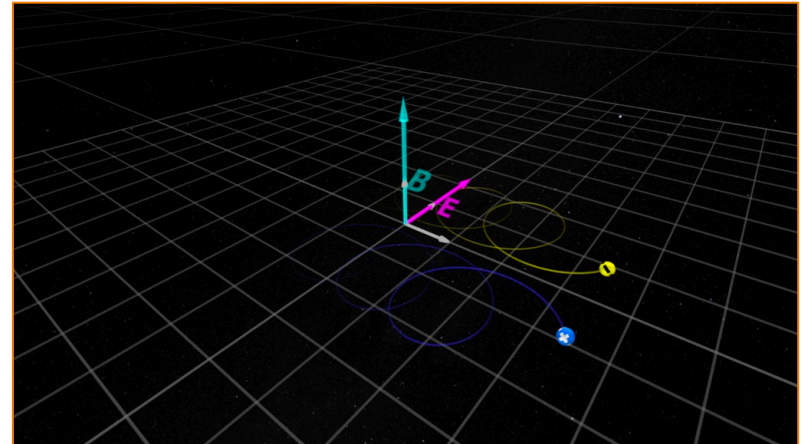


Project #7: Particle(s) in EM Fields

- Study the motion of one or more (non-relativistic) particles in a fixed electromagnetic field:

$$\frac{d\vec{v}}{dt} = \frac{e}{m} \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$$

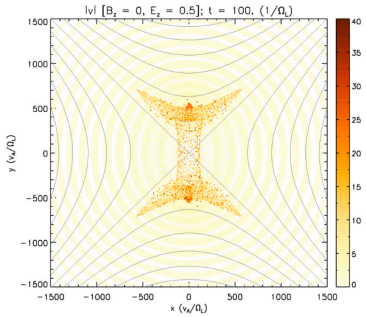
- The previous equation is written in the c.g.s sytem (widely used in astrophysics) but dimensionless units are recommended.



- The equation of motion (possibly) involves propagation in all 3 direction (x,y,z).
- The electric and magnetic field vector are given externally and particles do not interact with each other.
- The project involves direct integration of the equation of motion using RK-type integrators and/or the generalization of symplectic integration scheme to the case of velocity-dependent force (the Boris algorithm is the progenitor of such schemes).

Project #7: Particle(s) in EM Fields

- Provide a project with at least three different cases. A suggestion is given here:

Case	N_{part}	E	B	Notes
Simple gyration	1	(0,0,0)	(0,0,1)	Consider both perpendicular and parallel propagation. Check your results with analytical formula.
ExB drift	1	(0,E,0) with $E < 1$	(0,0,1)	Consider propagation along y-direction: what motion do you see ? Does the particle accelerate ? Explain.
X point 	10^3	(0,0,1/2)	(y/L, x/L, 0) $L=10^3$.	Place particles uniformly in the square domain $[-L,L]^2$ and initialize particle velocity to 0.1 using randomly numbers distributed angles. Describe your results: <ul style="list-style-type: none"> - What kind of motion is observed ? - Do particles accelerate ? Where ?

Project #8: Physics of Partially Ionized Hydrogen

- In a variety of astrophysical scenarios (protoplanetary disks, interstellar medium, stellar interiors, supernovae, etc...) the internal energy of the plasma is subject to radiative cooling due to a variety of processes, including bremsstrahlung, collisional ionization and excitation, etc...
- For a uniform gas distribution (no spatial variation) and assuming a partially ionized hydrogen gas, this equation may be simplified and written as

$$\frac{d(\rho e)}{dt} = -n_e n \Lambda(T)$$

where $\Lambda(n, T)$ is the cooling function, n_e is the number of electrons, n is the hydrogen number density.

- The gas internal energy includes a standard kinetic term plus the ionization energy (neutral atoms have a potential energy that is lower than that of ions by an amount $\chi_0 = 13.6$ eV).

$$\rho e = \frac{3}{2} n k_B T + \chi_0 n x(T)$$

- Here $x(T)$ is the ionization fraction, defined by $x = \frac{n_e}{n}$

Project #8: Physics of Partially Ionized Hydrogen

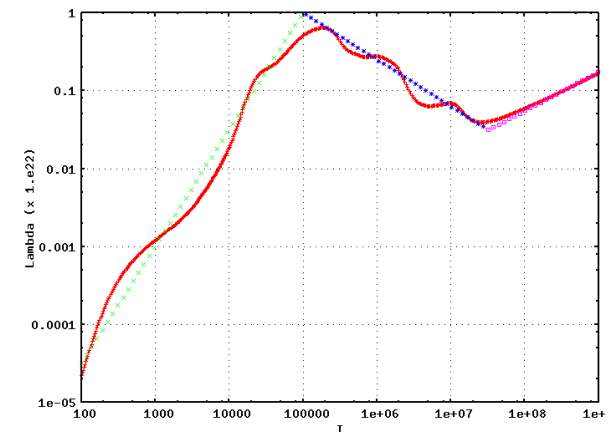
- In dilute gases (as it is the case for several astrophysical environments such as the interstellar medium or a proto-planetary disk), the degree of ionization x can be computed using Collisional excitation equilibrium (CIE), according to which

$$x = \frac{c_r(T)}{c_i(T) + c_r(T)}, \quad \text{where} \quad c_r = \frac{2.6 \cdot 10^{-11}}{\sqrt{T}}, \quad c_i = \frac{1.08 \cdot 10^{-8} \sqrt{T}}{\chi_0^2} \exp(-\alpha/T)$$

where $\alpha = 157890.0$, while $\chi_0 = 13.6$.

- The cooling function is usually tabulated but, as a very crude approximation, we can use the following empirical relation:

$$\Lambda(T) = \begin{cases} C \left(\frac{T}{T_M} \right)^{3/2} & \text{for } 10^2 \lesssim T \lesssim T_M \\ C \left(\frac{T}{T_M} \right)^{-0.6} & \text{for } T_M \lesssim T \lesssim T_B \\ C \left(\frac{T_B}{T_M} \right)^{-0.6} \left(\frac{T}{T_B} \right)^{1/2} & \text{for } T \gtrsim T_B \end{cases}$$



where $C = 10^{-22} \text{ erg}/(\text{cm}^3 \text{ s})$.

Project #8: Physics of Partially Ionized Hydrogen

- Assuming an initial temperature of $T = 10^6$ K and a cloud of constant density $n = 1 \text{ cm}^{-3}$, solve the internal energy equation

$$\frac{d(\rho e)}{dt} = -n_e n \Lambda(T)$$

- Note that at each step, the temperature must be found from the internal energy by inverting the expression for the internal energy:

$$\rho e = \frac{3}{2} n k_B T + \chi_0 n x(T) \quad \text{💬}$$

where n (the gas number density) is fixed throughout the evolution.

A root finding algorithm must be used. 💬

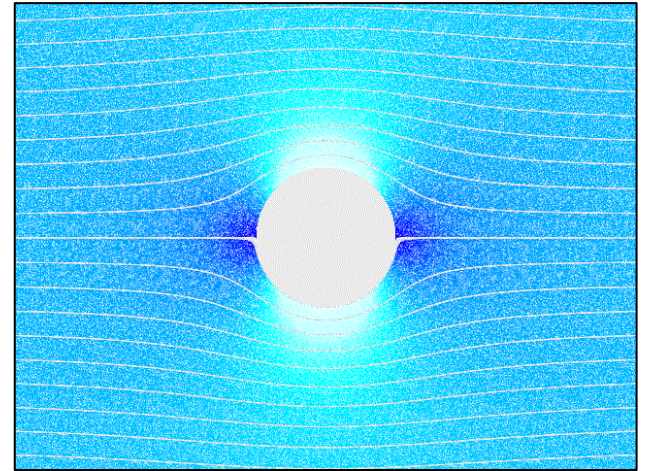
- Stop when you reach $T \approx 10^3$ K.
- Produce a plot of the temperature as a function of time.


Project #9: Potential flow around cylinder

- The potential flow around a circular cylinder is a classical solution for the equations of an inviscid, incompressible fluid flow.
- Far from the cylinder, the flow is unidirectional and uniform.
- The flow is incompressible and has no vorticity :

$$\nabla \cdot \vec{V} = \nabla \times \vec{V} = 0$$

so that its velocity can thus be written



1. as the gradient of a potential: $\vec{V} = \nabla \phi$ 
2. using the stream function: $\vec{V} = \nabla \psi \times \hat{k}$

- Both the velocity potential and the stream functions satisfy the Laplace equation:

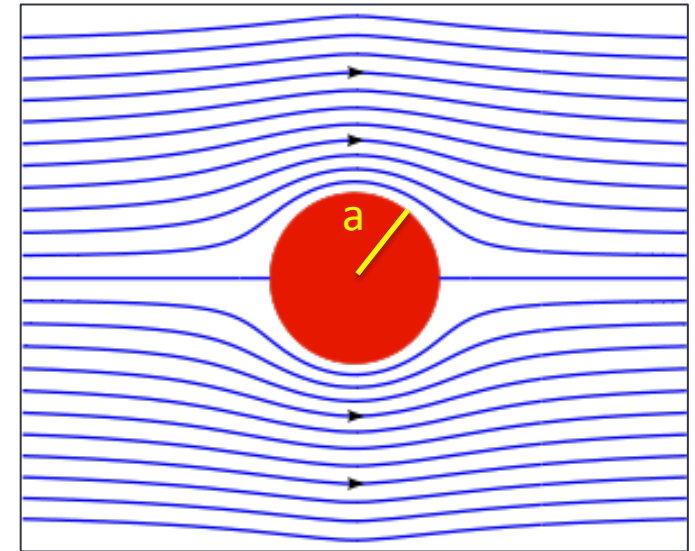
$$\nabla^2 \phi = \nabla^2 \psi = 0$$


Project #9: Potential flow around cylinder

- Solve the problem in polar coordinates (r, θ)

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} = 0$$

- Discretized the previous equation on a domain defined by $a \leq r \leq 5a$, $0 \leq \theta \leq 2\pi$ [or similar, set $a=1$]
- Use the exact solution (simple) to prescribe the boundary conditions.



- $$\begin{cases} \phi(r, \theta) = U \left(r + \frac{a^2}{r} \right) \cos \theta \\ \psi(r, \theta) = U \left(r - \frac{a^2}{r} \right) \sin \theta \end{cases}$$
- Or a combination of Dirichlet + Neumann b.c. 
 - Compute error.

Project #10: Poisson Equation in Axial symmetry

- Three dimensional problems with axial symmetry can be treated using cylindrical coordinates (r,z).
- Generalize the iterative algorithms presented in Ch. 10 to solve the Poisson equation in 2D cylindrical coordinates

$$\frac{1}{r} \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \varphi}{\partial r} \right) + \frac{\partial^2 \varphi}{\partial z^2} + S(r, z) = 0$$

- Apply the resulting discretization to a number of problems such as:
 - Uniformly charged disk
 - Uniformly charged ring
 - Dipole field (assume charges are distributed on a finite size spheres).
- Compare results with known analytical solutions on the axis.