

Preemptive Hardware Multitasking in ReconOS

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Adding preemptive hardware multitasking to a reconfigurable system-on-chip (rSoC).



Preemptive hardware multitasking

multiple tasks execute on a single slot

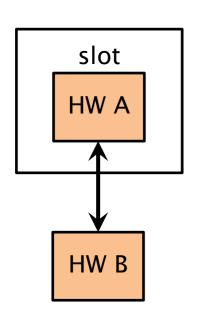
enable rSoCs to use smart schedulers

fairness, responsiveness, avoid starvation

Unmodified hardware source code

task preemption is transparent to developer

For context restoration, we can use task- or FPGA-specific methods.



How to switch between tasks A & B?

- (1) stop task A, save context A
- (2) reconfigure task B, restore context B, run B

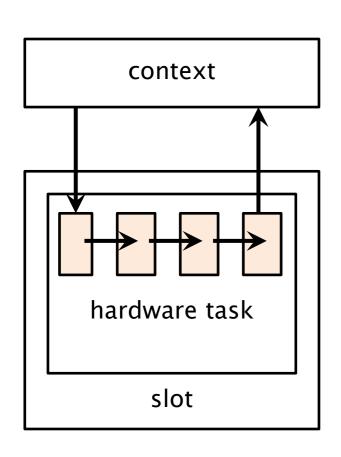
What is the context?

content of all state-holding elements i.e. flip-flops, BRAMs, LUT-RAMs

Which approaches exist?

- (i) task-specific preemption (scan-chains)
- (ii) FPGA-specific bitstream readback

Task-specific preemption techniques extract/insert only the actual context.



Add scan-chains to hardware tasks

extract/insert context from/to scan-chain

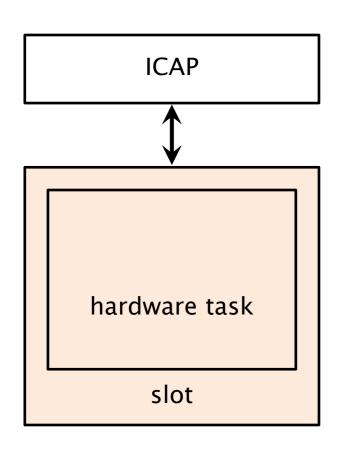
Drawbacks

modifications at source code- or netlist-level considerable hardware overhead

Advantages

approach independent of FPGA architecture only captures/restores used resources

Bitstream readback methods read/ write configuration of the entire slot.



Read back bitstream of a partial region using internal configuration access port (ICAP) read contents of all flip-flops, BRAMs, etc.

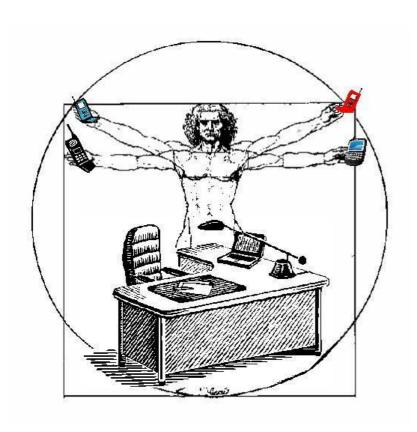
Drawbacks

bitstream format tailored to FPGA family time-inefficient (capture/restore all resources)

Advantages

no modifications at task-level no hardware overhead

Preemptive Hardware Multitasking in ReconOS



Methodology

bitstream readback

ReconOS Integration

ICAP controller, scheduler

Virtex-6 Evaluation

reconfiguration overhead

Our methodology is based on Xilinx PlanAhead PR toolflow.

full bitstream

system_A.bit

partial bitstreams

partial_A.bit

partial_B.bit

Generate bitstreams with PlanAhead

reset_after_reconfiguration attribute: 1

Partial bistreams: in external memory

e.g. on compact flash card

Our methodology is based on Xilinx PlanAhead PR toolflow.

full bitstream

system_A.bit

partial bitstreams

partial_A.bit

partial_A_captured.bit

partial_B.bit

partial_B_captured.bit

Generate bitstreams with PlanAhead

reset_after_reconfiguration attribute: 1

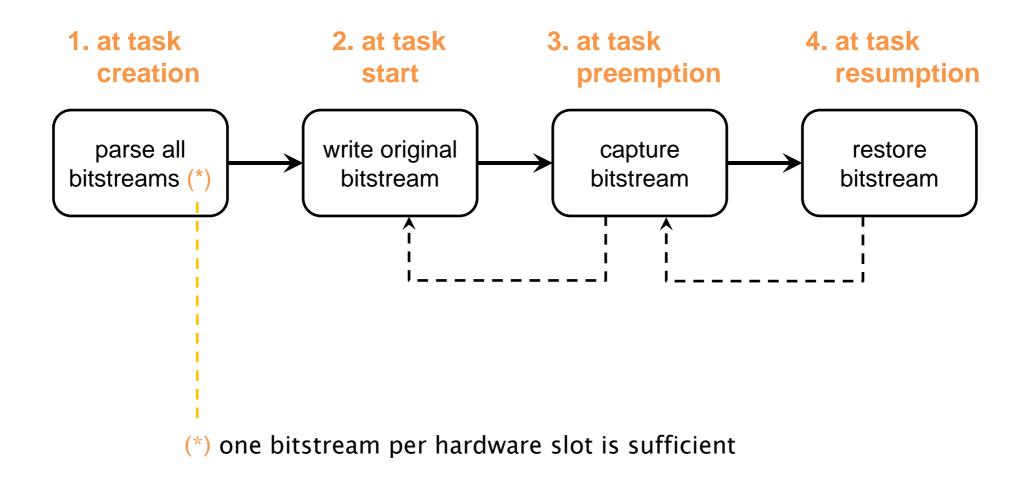
Partial bistreams: in external memory

e.g. on compact flash card

Working copy of partial bitstreams

also contain the context of preempted task initially, working copy identical to original file

Our approach initially parses bitstreams to extract metadata about configuration frames.



Xilinx bitstreams store three types of configuration frames.

partial bitstream A

0x30002001 0x000000000x30008001 0x30002001 0x30004000 0x5000788D 0x00000010 0x20000000 0x30004001

Type 1: FFs, LUTs, etc.

CLBs, input/output blocks, clocks, ...

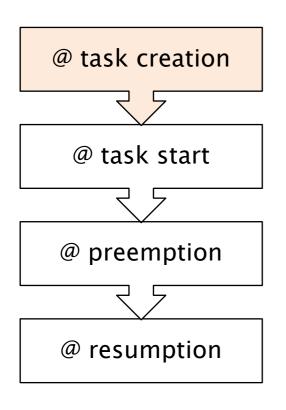
Type 2: BRAMs

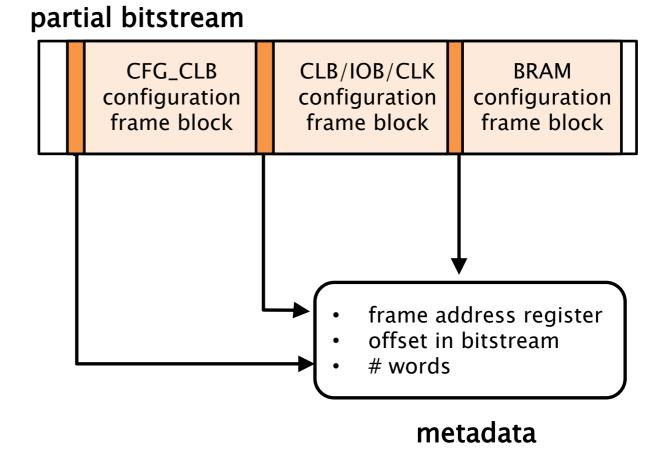
configuration of BRAM contents

Type 3: CFG_CLB

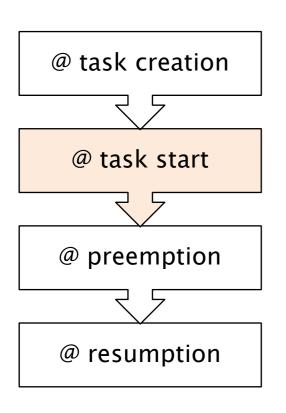
selects which part of the FPGA is reconfigured only present if «reset_after_reconfiguration=1»

We extract a list of metadata for all configuration frame blocks.





At task start, we configure the original bitstream using ICAP write commands.



No context at task start

configure original bitstream from PlanAhead

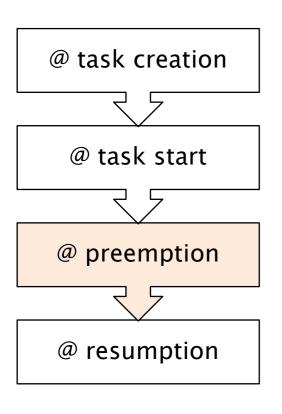
Configuration

using ICAP write commands

During reconfiguration

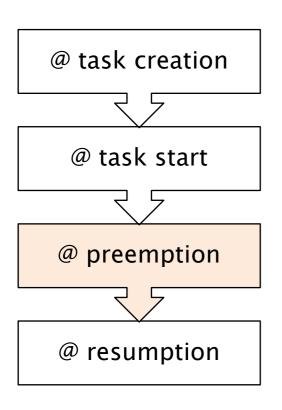
reset interface to/from hardware task

At task preemption, we need to capture the flip-flop states of the slot to hidden registers.



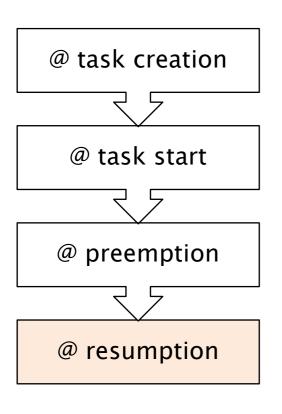
- 1. Prepare hardware slot deactivate clock
- 2. Constrain capture command to slot write CFG_CLB block over ICAP
- 3. Capture states of flip-flops send gcapture command over ICAP states captured to hidden registers INTO/INT1

After reading back all frames, we modify certain configuration bits for the BRAMs.



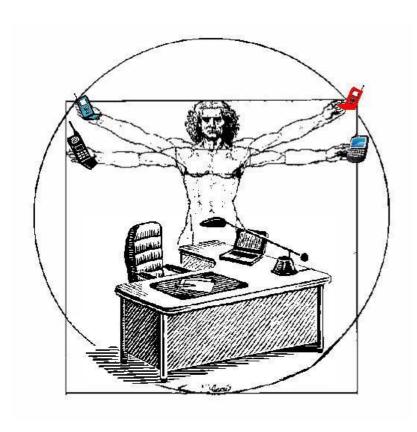
- 4. Read-back configuration frames as defined by metadata (except CFG_CLB block) we update the working copy for these blocks
- 5. Modify BRAM configuration bits otherwise BRAM contents will not be restored not described in official Xilinx documentation

At task resumption, we write the modified captured bitstream to the hardware slot.



- 1. Prepare hardware slot disable clock, reset slot and interfaces
- 2. Download captured bitstream using ICAP write commands
- 3. Trigger global/set reset (GSR) manually trigger GSR port of startup_virtex6 grestore command in bitstream does not work
- 4. Resume clock and hardware thread

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ReconOS extends multithreaded programming model to reconfigurable hardware.



www.reconos.de

Autonomous hardware threads

similar to POSIX softwarte threads access shared memory, semaphores, mqueue

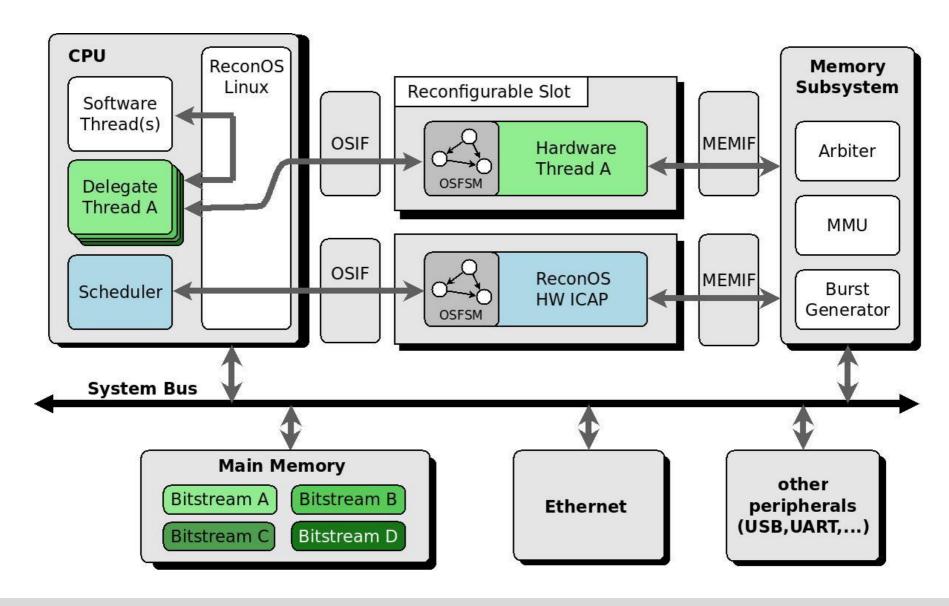
Software delegate threads

represent hardware threads access OS services on behalf of hw threads

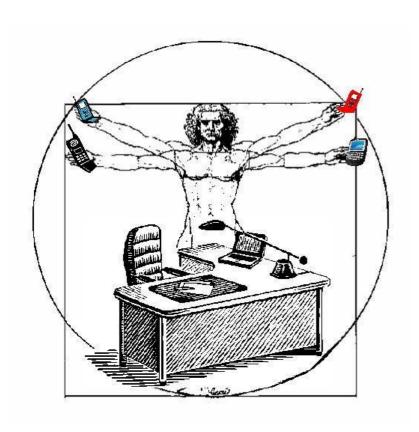
ReconOS @ Linux

extensions implemented in user-space support for virtual memory

Our ReconOS Architecture has one slot and one ICAP core.



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We have performed our experiments on a Xilinx Virtex-6 FPGA for two slot sizes.



Xilinx Virtex-6 ML605 board

implements ReconOS architecture 300k flip-flops, 0.4k BRAMs (36 Kbit)

Tested slot sizes

2% of FPGA area: 361 KB bitstreams

6% of FPGA area: 741 KB bitstreams

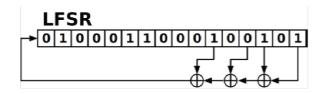
Four hardware threads

ADD, SUB, MUL, LFSR

We implemented four hardware threads to validate the context restoration.

$$R_3 = R_1 \pm R_2$$

$$R_3 = \sum_1^{R_1} R_2$$



ADD/SUB-Threads

add/substract sw-defined registers

MUL-Thread

multiplies sw-defined registers
validate cycle-true restoration of flip-flops

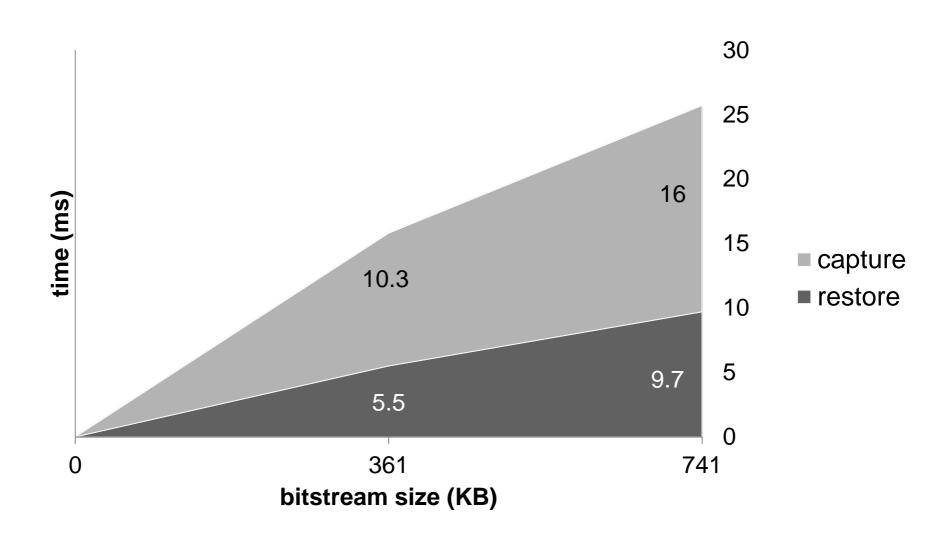
LFSR-Thread

stores several LFSRs in BRAMs, shifts one LFSR validate cycle-true restoration of BRAMs

The hardware threads only occupy a fraction of the slots, but all FFs/BRAMs are restored.

component	#FFs	#LUTs	#BRAMs
HW slot (~2%)	5.8k	2.9k	8
HW slot (~6%)	17k	8.6k	32
ADD/SUB	0.4k	0.6k	2
MUL	0.5k	0.8k	2
LFSR	0.5k	0.8k	2
ReconOS ICAP	0.3k	0.7k	2
XPS_HWICAP	0.8k	0.8k	1

We support context switches in the order of milliseconds.



The maximum number of context switches per second depends on the slot size.

Max. context switches / second

361KB: 63 switches/s

741KB: 38 switches/s

Capture/restore bandwidth

361KB: 22 MB/s

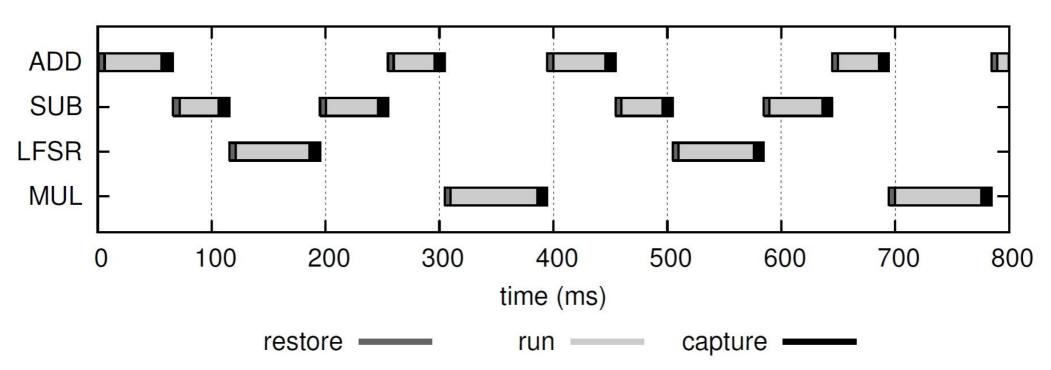
741KB: 28 MB/s

Performance bottleneck

ReconOS memory interface

Periodic tasks can be executed using preemptive scheduling algorithms.

Example measurement with fixed periodic schedule



In summary, we integrated preemptive hardware multitasking to ReconOS.

Novel methodology

preemptive hardware multitasking on Virtex-6 restore states of flip-flops and BRAMs

ReconOS integration

customized ICAP controller, sw scheduler

Experimental results

achieved bandwidth: 22–28 MB/s multiple task swaps per second

In future work, we want to support more FPGA families and relocate tasks.

Restore further FPGA resources

LUT-RAMs, DSP blocks

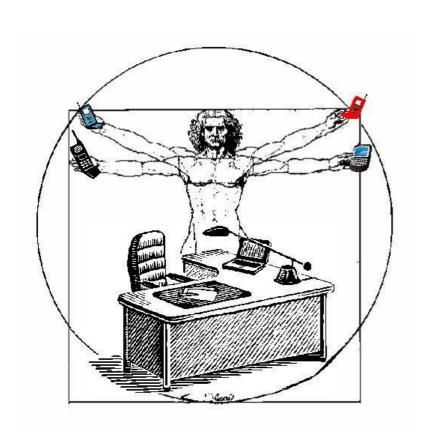
Support more FPGA families

e.g. Virtex-7, Zynq

Task relocation

migrate threads between slots

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