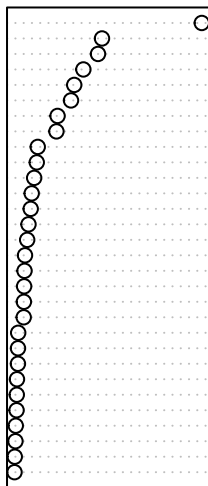


rfo2

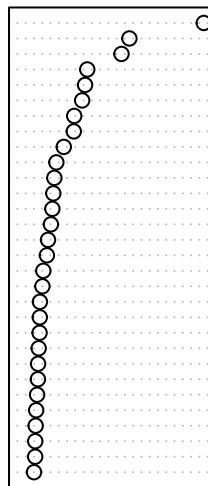
raw\_timestamp\_part\_1  
yaw\_belt  
roll\_window  
magnet\_dumbbell\_z  
pitch\_belt  
magnet\_dumbbell\_y  
pitch\_forearm  
gyros\_dumbbell\_z  
accel\_dumbbell\_y  
roll\_dumbbell  
gyros\_dumbbell\_x  
roll\_arm  
magnet\_belt\_y  
gyros\_arm\_y  
accel\_dumbbell\_z  
magnet\_belt\_z  
magnet\_forearm\_z  
gyros\_forearm\_z  
magnet\_belt\_x  
magnet\_dumbbell\_x  
accel\_belt\_z  
roll\_forearm  
yaw\_dumbbell  
gyros\_belt\_z  
accel\_dumbbell\_x  
yaw\_arm  
gyros\_forearm\_y  
total\_accel\_dumbbell  
accel\_forearm\_x



30 50 70

MeanDecreaseAccura

raw\_timestamp\_part\_1  
roll\_window  
yaw\_belt  
pitch\_forearm  
magnet\_dumbbell\_z  
pitch\_belt  
magnet\_dumbbell\_y  
roll\_forearm  
magnet\_dumbbell\_x  
accel\_belt\_z  
accel\_dumbbell\_y  
roll\_dumbbell  
magnet\_belt\_y  
magnet\_belt\_z  
accel\_dumbbell\_z  
accel\_forearm\_x  
roll\_arm  
gyros\_belt\_z  
total\_accel\_dumbbell  
accel\_dumbbell\_x  
yaw\_dumbbell  
magnet\_arm\_x  
total\_accel\_belt  
gyros\_dumbbell\_y  
magnet\_belt\_x  
magnet\_forearm\_z  
magnet\_arm\_y  
accel\_arm\_x  
accel\_forearm\_z



0 400 1000

MeanDecreaseGini