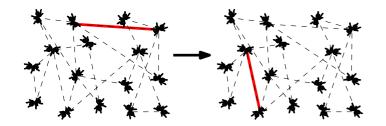
Friend or Foe?

Population Protocols can perform Community Detection

L. Becchetti¹, A. Clementi², **Emanuele Natale**⁰, F. Pasquale², P. Raghavendra³ and L. Trevisan³

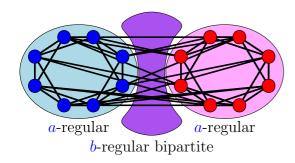
Population protocols

At each round a random edge is chosen and the two corresponding agents interact.



Regular Stochastic Block Model

A graph $G = (V_1 \cup V_2, E)$ s.t. $|V_1| = |V_2|, G|_{V_1}$, $G|_{V_2} \sim \text{random } a\text{-regular graphs, } G|_{E(V_1, V_2)} \sim \text{random } b\text{-regular bipartite graph.}$



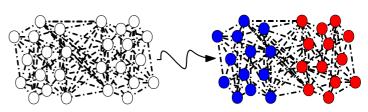
Theorem

 $G = (V_1 \bigcup V_2, E)$ Regular Stochastic Block Model s.t. $d\epsilon^4 \gg b \log^2 n$, then w.h.p. CSL(m,T) with $m = \Theta(\epsilon^{-1} \log n)$ and $T = \Theta(\log n)$ labels all nodes but a set U with size $|U| \leq \sqrt{\epsilon}n$, in such a way that

- nodes' labels in the same community agree on at least 5/6 of entries, and
- nodes' labels in different communities differ in more than 1/6 of entries.

Reconstruction problem

Given graph generated by Regular Stochastic Block Model, find original partition.

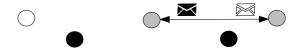




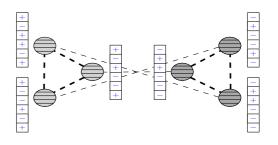
• At the outset $\mathbf{x}_u^{(0)} \sim \text{Unif}(\{-1,+1\}^m)$.



• In each round, the endpoints of the random edge choose a random index $j \in [m]$ and set $\mathbf{x}_u(j) = \mathbf{x}_v(j) = \frac{\mathbf{x}_u(j) + \mathbf{x}_v(j)}{2}$;



• At the *T*-th update of *j*-th component, u sets $\mathbf{h}_u(j) = \mathbf{sgn}(\mathbf{x}_u(j))$.



A Taste of Spectral Analysis

CSL is a **linear** dynamics



$$\mathbf{x}^{(t)} = W^{(t)} \cdot \mathbf{x}^{(t-1)} = (W^{(t)} \cdots W^{(1)}) \cdot \mathbf{x}^{(0)}$$

 $\mathbf{E}[W] = P$ transition matrix of r.w. eigenvec. $\mathbf{v}_1, ..., \mathbf{v}_n$, eigenval. $\lambda_1, ..., \lambda_n$.

