

ERI_DHT version 1.0

User Guide

Saket kunwar

Aug 26,2009

Copyright 2009 saket kunwar

Licensed under the Apache License, Version 2.0 (the "License");
you may not use this file except in compliance with the License.
You may obtain a copy of the License at

<http://www.apache.org/licenses/LICENSE-2.0>

Unless required by applicable law or agreed to in writing, software
distributed under the License is distributed on an "AS IS" BASIS, WITHOUT
WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied. See the
License for the specific language governing permissions and limitations under the
License.

Erly_ring

Intro

erly_ring is an implementation of erl_dht(gitclone) for use with tcp/ip socket based communication. All modules and functions remains unchanged. i.e it is used as in the simulation version. This is largely due to the message passing programming feature facilitated by the use of erlang. The only difference is that erly_ring is adapted to use the communication interface provided by tcp_node_client.erl, tcp_node_server.erl. The module dispatcher.erl does all internal routing which is especiall suitable if a host intends to use multiple erly_ring node on one host and same port.

Running erly_ring

edit the config file("config.txt") first provided in ./ebin directory

to point to boot host and other nodes

config example

```
{ {localhostname,"localhost"}, %%address of the host...change the name to that of the
host comp
{startport,5000}, %%the port used by the node
{maxapp,10}, %%this is currently not used...but leave the default
{boothost,"localhost"}, %%address of boot host ....change the name to that of the host
comp
{bootport,5009}}. %% port of boot host
```

1.

From erlang shell

cd to ../ebin

it's better to spawn the shell with a name i.e erl -sname node1,
especiall when spawning multile nodes with same node and host.

2.erly_ring:start_boot().

and then to start other nodes

3.erly_ring:start_node(node()).

4.for nodes that wants to utilize the same port as other node

do erly_ring:start_node(masternode@localhost) where masternode@localhost is the name of a node that has already been initialized to erly_ring node. This is where the tcp_node_server.erl and dispatcher.erl work together to route the messages to the particular node concerned.

To_do

There are a lot of timing related issues that needs to be fixed
such as stabilization periods and query periods.
som tcp error handling also needs to be provided.
and extensive testing in a large network environment

Erl_dht

Erl_dht is a simulation framework for evaluating and deploying routing schemes for distributed hash tables. Currently chord has been implemented but the modular nature of the core api makes it extensible making it possible to implemented other protocols. An important feature of erl_dht is the ease of use for live deployment by implementing a costum communication interface such as tcp/ip.

Erl_dht is coded in erlang otp ,a highly concurrent ,distributed and fault tolerant functional programming language. The message passing feature of erlang is especially suited for performing simulation. The basic architecture of the api is as in fig 1.

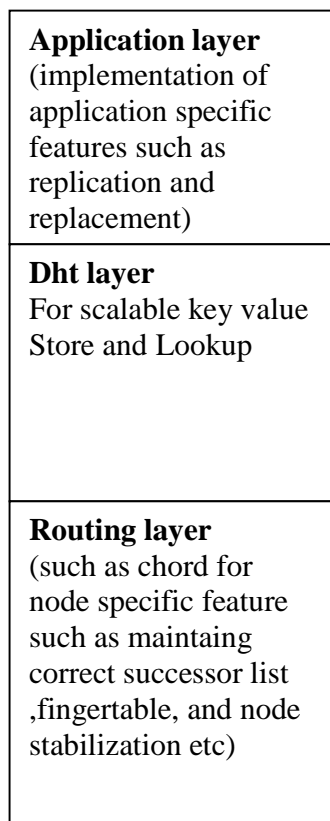


Fig 1

Building

```
cd /src
make
```

the binary will be stored at ebin directory /ebin

Running

There is an example of events file i.e "events.txt" that contains the events to be executed..

run the script erl_dht_test or erl_dht_test.bat (windows)

or

```
erl -pa ./ebin
```

and at the erl prompt erl_dht:eventtest("events.txt").

or erl_dht:start(Num). where Num is the number of nodes

When performing simulation the terminal that runs the simulation often gets swamped with simulation result outputs and is difficult to send other live commands. To overcome this I usually spawn a terminal with

erl -sname somename and execute the simulation at the erl terminal then

I spawn another terminal with erl -sname someothername and send node

join, node leave, store or lookup commands through the someothername

terminal with rpc calls as :

```
rpc:call(somename@host,simul,stop,[]). etc
```

This way I can monitor simulation events as well as send commands or queries to the simulation. Have a look at simul.erl or its doc to perform other simulation specific tests.

add node:

To add node during simulation

```
Boot=rpc:call(somename@host,simul,get_boot,[]).
```

```
rpc:call(somename@host,simul,add_node,[Boot]).
```

kill Node:

To kill node during simulation

```
rpc:call(somename@host,boot,nodelist,[]).
```

Select node Node from the nodelist then do

```
rpc:call(somename@host,simul,kill_node,[Node]).
```

Follow the same procedures for store, lookup and other test.

Event Prototype

Most Simulation specific use can be accomplished through a script i.e `simul:eventtest("eventfile.txt")`. Where `eventfile.txt` is the event script

```
{init,{numNode,2,0},{resultfile,"result.txt"}}.  
{{event,Sn},{function,join,random},{at,T}}.  
{{event,Sn},{function,leave,Num},{at,T}}. %%the num node in masterlist of nodes  
{{event,Sn},{function,{store,"kunwar",10},3}{at,T}}.  
{{event,Sn},{function,{lookup,"kunwar"},3}{at,T}}.  
{{event,Sn},{function,all_test,{"saket",Val}},{at,T}}.  
{{event,Sn},{function,analyse,{"data.dat",succlist}},{at,T}}.
```

where T is the time interval to wait till next execution

The eventmanager module loads events to be executed sequentially from the event file and evaluates a lazy function for each events. The stored lazy function are executed in a discrete event driven simulation. The parameter `{at,T}` determines T ,which is the time the next event waits to be executed.

The analyserZ module does the required analysis of the correctness of the routing List i.e the successor list and the finger table entries. The lists are compared against a brute computation. Due to the algorithm of chord all predecessor nodes are correct as compared to brute evaluation however it is not necessary that all nodes should have correct successor or finger list since nodes are only aware of the departure of immediate successor and are thus updated or when the analysis is performed the nodes haven't had enough stabilization period to update it's successor list.

Directory Structure

ebin	Directory where all the beam files are stored after compilation
src	Contains all the source files
doc	Contains all the edoc generated doc files
example	Few examples of simulation usage

example	Contains some example of event script
----------------	---------------------------------------