

# **ERI\_DHT version 1.0**

## **User Guide**

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## Erl\_dht

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Erl\_dht is a simulation framework for evaluating and deploying routing schemes for distributed hash tables. Currently chord has been implemented but the modular nature of the core api makes it extensible making it possible to implement other protocols.

An important feature of erl\_dht is the ease of use for live deployment by implementing a custom communication interface such as tcp/ip.

Erl\_dht is coded in erlang otp, a highly concurrent, distributed and fault tolerant functional programming language. The message passing feature of erlang is especially suited for performing simulation. The basic architecture of the api is as in fig 1.

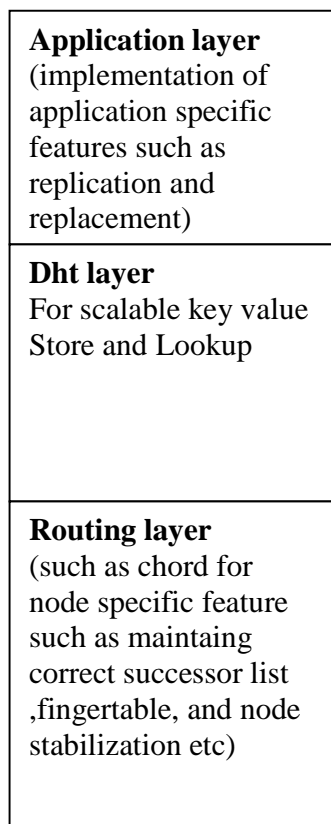


Fig 1

## Building

```
cd /src
make
```

the binary will be stored at ebin directory /ebin

## Running

There is an example of events file i.e "events.txt" that contains the events to be executed..

run the script erl\_dht\_test or erl\_dht\_test.bat (windows)

or

```
erl -pa ./ebin
```

and at the erl prompt erl\_dht:eventtest("events.txt").

or erl\_dht:start(Num). where Num is the number of nodes

When performing simulation the terminal that runs the simulation often gets swamped with simulation result outputs and is difficult to send other live commands. To overcome this I usually spawn a terminal with

erl -sname somename and execute the simulation at the erl terminal then

I spawn another terminal with erl -sname someothername and send node

join,node leave ,store or lookup commands through the someothername

terminal with rpc calls as :

```
rpc:call(somename@host,simul,stop,[]). etc
```

This way I can monitor simulation events as well as send commands or queries to the simulation. Have a look at simul.erl or it's doc to perform other simulation specific tests.

add node:

To add node during simulation

```
Boot=rpc:call(somename@host,simul,get_boot,[]).
```

```
rpc:call(somename@host,simul,add_node,[Boot]).
```

kill Node:

To kill node during simulation

```
rpc:call(somename@host,boot,nodelist,[]).
```

Select node Node from the nodelist then do

```
rpc:call(somename@host,simul,kill_node,[Node]).
```

Follow the same procedures for store,lookup and other test.

## Event Prototype

Most Simulation specific use can be accomplished through a script i.e `simul:eventtest("eventfile.txt")`. Where `eventfile.txt` is the event script

```
{init,{numNode,2,0},{resultfile,"result.txt"}}.  
{{event,Sn},{function,join,random},{at,T}}.  
{{event,Sn},{function,leave,Num},{at,T}}. %%the num node in masterlist of nodes  
{{event,Sn},{function,{store,"kunwar",10},3}{at,T}}.  
{{event,Sn},{function,{lookup,"kunwar"},3}{at,T}}.  
{{event,Sn},{function,all_test,{"saket",Val}}{at,T}}.  
{{event,Sn},{function,analyse,{"data.dat",succlist}}{at,T}}.
```

where T is the time interval to wait till next execution

The eventmanager module loads events to be executed sequentially from the event file and evaluates a lazy function for each events. The stored lazy function are executed in a discrete event driven simulation. The parameter `{at,T}` determines T ,which is the time the next event waits to be executed.

The analyserZ module does the required analysis of the correctness of the routing List i.e the successor list and the finger table entries. The lists are compared against a brute computation. Due to the algorithm of chord all predecessor nodes are correct as compared to brute evaluation however it is not necessary that all nodes should have correct successor or finger list since nodes are only aware of the departure of immediate successor and are thus updated or when the analysis is performed the nodes haven't had enough stabilization period to update it's successor list.

## Directory Structure

<b>ebin</b>	Directory where all the beam files are stored after compilation
<b>src</b>	Contains all the source files
<b>doc</b>	Contains all the edoc generated doc files
<b>example</b>	Few examples of simulation usage
<b>developer</b>	Usage documentation

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