

# STATISTICAL PROPERTIES OF LOG SOS-CONCAVE DENSITY ESTIMATOR

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## 1. INTRODUCTION

In this note, we will describe an assortment of results that we think could eventually lead to a nice analysis of the statistical properties of our estimator. The structure of this note is as follows:

- (i) We show that sos-convex polynomials are dense in continuous convex functions in the sense of  $\|\cdot\|_{\infty, K}$ , where  $K$  is a fixed compact set.
- (ii) Let  $f_n$  denote the Cule estimator for  $n$  data points (i.e. the max-likelihood log-concave estimator). We show that there exists a sequence of log sos-concave densities  $p_n^m$  on  $\mathbb{R}^p$  (of potentially increasing associated degree) that converge to  $f_n$  in distribution on  $\mathbb{R}^p$ .
- (iii) We show that this implies convergence of our objective function value to the likelihood value obtained by Cule's estimator  $f_n$ . We think that these facts will help us show that the estimator *returned by our algorithm* converges to Cule's estimator in distribution. If this is true, then the density returned by our algorithm converges in distribution to the min KL-divergence estimator as we let  $n, d \rightarrow \infty$  i.e. it is asymptotically optimal.

## 2. DENSITY OF SOS-CONVEX FUNCTIONS IN CONTINUOUS CONVEX FUNCTIONS

Fix a compact set  $K \subset \mathbb{R}^p$  star-shaped with respect to  $x_0 \in K$ . All density results in this section are with respect to the norm  $\|\cdot\|_{\infty, K}$ . We begin by showing that sos-convex polynomials (SOSX) are dense in smooth, strictly convex functions on  $K$  (SMSX).

Fix  $f \in \text{SMSX}$ . Let  $H_f(x)$  denote this function's Hessian. For  $x \in K$  we have  $H_f(x) \succ 0$ . Therefore, we can take a Cholesky factorization

$$H_f(x) = L_f(x)L_f(x)^T$$

Note that since the component functions of  $H_f$  are smooth, recursively all of the component functions of  $L_f$  are in particular continuous (computing  $L_{ij}(x)$  just involves adding, multiplying, and potentially taking the square root of other continuous functions).

By Stone-Weierstrass,  $\mathbb{R}[x]_p$  is dense in  $C(K)$ , therefore we can find polynomials  $L_{ij}^m(x) \in \mathbb{R}[x]_p$  with the property  $\|L_{ij}^m(x) - L_{ij}(x)\|_{\infty} \rightarrow 0$  as  $m \rightarrow \infty$  (in particular we can get simultaneous uniform convergence of the  $L_{ij}^m \rightarrow L_{ij}$ ). Define a matrix

$$H_f^m(x) = L_f^m(x)L_f^m(x)^T$$

Then by the above work we have that

$$\|H_f^m - H_f\|_{\infty, K} \rightarrow 0 \quad (m \rightarrow \infty)$$

Note that for each  $m$ ,  $H_f^m(x)$  is a polynomial matrix over  $\mathbb{R}^p$  that factors as  $H_f^m(x) = L_f^m(x)L_f^m(x)^T$ , where the Cholesky factors *are also polynomial matrices*. Suppose that we can construct a polynomial  $p_m$  that has  $H_f^m$  as its Hessian i.e.  $H_{p_m} = H_f^m$ . Then by construction  $p_m$  is sos-convex.

By the above argument, we can find a sequence of polynomial matrices  $H_f^m(x)$  such that

$$\|H_f^m(x) - H_f(x)\|_\infty \rightarrow 0 \quad (m \rightarrow \infty)$$

Build a sequence of polynomials  $p_m(x)$  (of arbitrary degree) as follows. For  $x_0 \in K$  (with respect to which  $K$  is star-shaped), define polynomials  $p_m(x)$  such that

$$\begin{aligned} (1) \quad & p_m(x_0) = f(x_0) \\ (2) \quad & \nabla p_m(x_0) = \nabla f(x_0) \\ (3) \quad & H_{p_m}(x) = H_f^m(x) \quad \forall x \in K \end{aligned}$$

For completeness, one way to do this is as follows. Suppose we want a function  $h$  such that  $\nabla h = g$  and  $h(x_0) = c$ . Then we can set  $h(x) = c + \int_0^1 g(\gamma_x(t)) \cdot \gamma'_x(t) dt$  for  $x \in K$ , where  $\gamma_x$  is the line segment  $[x_0, x]$ . This type of construction allows us to build a polynomial of the form required above.

Given a polynomial  $p_m$  that satisfies (1) – (3) as above, it is simple to bound  $\|f - p_m\|_\infty$ . We include this calculation for the sake of completeness:

**Convergence of functions from Hessian  $\|\cdot\|_\infty$  convergence** - Choose  $m$  such that we have  $\|H_f^m - H_f\|_{\infty, K} < \epsilon$ . Fix a path  $\gamma(t)$  from  $x_0 \rightarrow x$ , which we will take to be the line segment  $[x_0, x]$ . Define a function  $\phi(t) = (f - p_m)(\gamma(t))$ . Then by Taylor's Theorem, we have

$$\begin{aligned} \phi(1) &= \phi(0) + \phi'(0) + \frac{1}{2}\phi''(c) \quad c \in (0, 1) \iff \\ (f - p_m)(x) &= (f - p_m)(x_0) + \nabla(f - p_m)(x_0)^T(x - x_0) + \frac{1}{2}(x - x_0)^T H_{f-p_m}(z)(x - x_0) \end{aligned}$$

Where  $z \in [x_0, x]$ . By construction of our polynomials, the first two terms are identically 0. Moreover, the component functions  $\gamma(x)$  of the Hessian  $H_{f-p_m}(x)$  have  $\|\gamma\|_\infty < \epsilon$ . Then by Gershgorin's Theorem, we have an eigenvalue bound

$$\lambda(x) \leq \epsilon + \sum_{i \neq j} |\gamma_{ij}(x)| \leq p \cdot \epsilon$$

Since the Hessian is in particular Hermitian at each point, this gives a 2-norm bound on the matrix  $H_{f-p_m}$ . Using Cauchy-Schwarz, we have that

$$2|(f - p_m)(x)| \leq \|x - x_0\|_2 \|H_{f-p_m}(x)(x - x_0)\|_2 \leq \|x - x_0\|_2^2 \cdot p\epsilon \leq \text{Diam}(K)^2 \cdot p\epsilon$$

Then we have show that  $\|H_f^m - H_f\|_\infty \rightarrow 0$  implies that  $\|p_m - f(x)\|_\infty \rightarrow 0$ . The  $p_m$  are all sos-convex, so we have shown that  $\overline{SOS} \supset SMX$ .

**Approximation of Smooth Convex Functions** - We want to show that smooth strictly convex functions are dense in smooth convex functions i.e.  $\overline{SMX} \supset SMX$ . This is easy. Fix  $\epsilon > 0$ . Let  $f \in SMX$ . Then  $f_\epsilon(x) := f(x) + \epsilon\|x\|_2^2$  is strictly convex and

$$|f_\epsilon(x) - f(x)| \leq \epsilon\|x\|_2^2 \leq \epsilon \cdot \text{Diam}(K)^2$$

for  $x \in K$ . Then  $\|f_\epsilon - f\|_\infty \rightarrow 0$  as  $\epsilon \rightarrow 0$ , so we have the density result.

**Approximation of Continuous Convex Functions** - Note that convolution with a positive function preserves convexity. This is easily seen from the definition. Let  $f$  convex and  $\phi \geq 0$ , then

$$(\phi * f)(x) = \int_{\mathbb{R}^p} \phi(t) f(x - t) dt$$

Each  $f_t(x) := f(x - t)$  is convex, therefore the convolution above is convex.

Let  $\phi$  be (for instance) the pdf of a Gaussian  $\mathcal{N}(0, I)$  (not actually necessary, we just need the function we are convolving against to be smooth and integrate to 1). For  $\epsilon > 0$ , define a class of functions  $\phi_\epsilon = \frac{1}{\epsilon} \phi(\frac{x}{\epsilon})$ . Fix  $f$  a continuous convex function. If  $f$  is not bounded, redefine  $f = 0$  on  $K^c$ . Define a class of functions  $f_\epsilon := (\phi_\epsilon * f)$ .

The standard arguments show that (i)  $f_\epsilon$  is  $C^\infty$  for each  $\epsilon$  (ii)  $f_\epsilon \rightarrow f$  uniformly on any compact set and (iii)  $f_\epsilon$  is convex for all  $\epsilon$ . Then we have shown that  $f$  is a limit point of  $SMX$ , therefore  $\overline{SMX} \supset CT SX$ .

**Sketch of convolution argument** - I sketch the standard arguments for the sake of completeness. (iii) was shown above and basically follows from the definition of convexity.

For (i), note that

$$(\phi * f)(x) = \int_{\mathbb{R}^p} \phi(t) f(x - t) dt = \int_{\mathbb{R}^p} \phi(x - t) f(t) dt$$

so that whenever we need to take a derivative  $\frac{\partial}{\partial x_\alpha}(\phi * f)(x)$ , we just pass the differentiation operator through the integral (formal justification for this can be provided) and differentiate  $\phi$ , which is  $C^\infty$ .

For (ii), rewrite the integral above as

$$\begin{aligned} f_\epsilon &= (\phi_\epsilon * f)(x) = \int_{\mathbb{R}^p} \phi_\epsilon(t) f(x - t) dt \\ &= \int_{B_\epsilon} \phi_\epsilon(t) f(x - t) dt + \int_{B_\epsilon^c} \phi_\epsilon(t) f(x - t) dt \end{aligned}$$

Where we choose  $B_\epsilon$  a very small ball containing 0 of radius  $h(\epsilon)$  such that (i)  $\int_{B_\epsilon} \phi \approx 1$  and (ii)  $\phi \approx 0$  on  $B_\epsilon^c$  as well as (iii)  $f(x - t) \approx f(x)$  for  $t \in B_\epsilon$  (this is where we use continuity on the class  $CT SX$ ). Then roughly speaking the above decomposition is

$$\begin{aligned} &\int_{B_\epsilon} \phi_\epsilon(t) f(x - t) dt + \int_{B_\epsilon^c} \phi_\epsilon(t) f(x - t) dt \\ &\approx f(x) \int_{B_\epsilon} \phi_\epsilon(t) dt + \int_{B_\epsilon^c} 0 \cdot f(x - t) dt \\ &\approx f(x) \cdot 1 + 0 = f(x) \end{aligned}$$

I claim that this gives uniform convergence  $\|(\phi_\epsilon * f) - f\|_{\infty, K} \rightarrow 0$ . Note that continuity of  $f$  on  $K$  implies uniform continuity, so the the approximation of the first integral in the above decomposition can be made uniform.  $f$  is uniformly bounded on  $\mathbb{R}^p$ , so the 2<sup>nd</sup> integral above goes to 0 uniformly. This sketch can be made rigorous but the arguments are relatively standard.

Then we have shown that

$$SOSX \longrightarrow SMSX \longrightarrow SMX \longrightarrow CTSX$$

where the arrow denotes density (in the sense of  $\|\cdot\|_{K,\infty}$  for a fixed  $K$  compact and star-shaped). In particular, we have shown that sos-convex polynomials are dense in continuous convex functions on a compact, convex set  $K$ .

### 3. CONVERGENCE IN DISTRIBUTION

Consider the shape-constrained maximum-likelihood estimator  $f_n$  from the Cule paper. In this section, we show that there exists a sequence of log sos-concave densities  $p_n^m$  that converge in distribution to the Cule estimator  $f_n$ .

We also show that, as  $d \rightarrow \infty$ , the objective value, i.e. the achieved likelihood, of our program converges to the max-likelihood among log-concave estimators (the objective value of Cule's program).

Our approach will be as follows. Given the convex hull of the data  $C_n$ , we will construct a set  $K = C_n^\epsilon$  such that  $\mathcal{L}(C_n^\epsilon \setminus C_n) = \epsilon$ , where  $\mathcal{L}$  denotes Lebesgue measure.

We will then extend the concave function  $s_n$  defining the Cule estimator ( $f_n = \exp(s_n)$ ) to  $K$  in such a way that (i) our extension is convex and (ii) our extension is increasingly negative on  $\partial K$ . Using our work above, let  $p_m$  be a sequence of sos concave functions such that converge to our extension in  $\|\cdot\|_\infty$ . We will then argue that for any bounded function  $G$  on  $\mathbb{R}^p$ , we have

$$\int_{\mathbb{R}^p} G(x) \exp(p_m(x)) = \int_{K^c} G(x) \exp(p_m(x)) + \int_{K \setminus C_n} G(x) \exp(p_m(x)) + \int_{C_n} G(x) \exp(p_m(x))$$

We will show that (1) the first integral is small because loosely  $p_m(x) \approx -\infty$  on  $K^c$ . (2) The second integral is small because  $\mathcal{L}(C_n^\epsilon \setminus C_n) \rightarrow 0$  as  $\epsilon \rightarrow 0$ . Finally, (3) the last integral converges to  $\int_{C_n} G(x) f_n(x)$  because  $\|p_m - s_n\|_{\infty, C_n} \rightarrow 0$ . A rigorous formulation of this argument will show that for any bounded function  $G$  we have

$$\int_{\mathbb{R}^p} G(x) \exp(p_m(x)) dx \rightarrow \int_{\mathbb{R}^p} G(x) f_n(x) dx \quad (m \rightarrow \infty)$$

i.e.  $p_m$  converges to  $f_n$  in distribution.

**Definition of  $K$**  - Consider the tent function  $s_n$  from Cule's paper.  $s_n = -\infty$  outside of  $C_n$ . Note that as a convex hull, we have  $C_n = \{Ax \leq b\}$  for some matrix  $A \in \mathbb{R}^{n \times p}$  and  $b \in \mathbb{R}^n$ . Consider the set  $C_n^\epsilon = \{Ax \leq b + \epsilon 1\}$ . Note that  $C_n^\epsilon$  is of finite Lebesgue measure since  $C_n$  is [HOW?]. Then we can apply elementary measure theory to show that

$$\mathcal{L}(C_n) = \mathcal{L}\left(\bigcap_{\epsilon > 0} C_n^\epsilon\right) = \lim_{\epsilon \rightarrow 0} \mathcal{L}(C_n^\epsilon)$$

Therefore, for instance, we can make  $\mathcal{L}(C_n^\epsilon \setminus C_n)$  arbitrarily small by letting  $\epsilon \rightarrow 0$ . Let  $K_1 \supset C_n$  a polytope of the above form such that  $\mathcal{L}(K_1 \setminus C_n) < \epsilon$ . From Cule, there exists a triangulation of  $C_n$  such that  $s_n$  is affine on each simplex in the triangulation.

Extend this triangulation to a triangulation of the polytope  $K_1$  and extend  $s_n$  to  $\overline{s_n}$  on  $K_1$  by defining piecewise affine functions such that  $\overline{s_n} = 0$  on  $\partial K_1$ . Since  $\text{Vol}(K_1 \setminus C_n)$  is arbitrarily small and  $\overline{s_n}$  is bounded on  $K_1$ , this extension does not affect the value of the integral

$$\int_{\mathbb{R}^p} G(x) \exp(s_n)$$

asymptotically as  $\epsilon = \text{Vol}(K_1 \setminus C_n) \rightarrow 0$ . Therefore, wlog, we will assume from now on that  $s_n$  vanishes on  $\partial C_n$ .

**Extension of  $s_n$  to  $K$**  - Define  $\widehat{s_n}$  such that  $\widehat{s_n}(x) = s_n(x)$  for  $x \in C_n$  and  $\widehat{s_n}(x) = 0$  on  $C_n^c$ . Then  $s_n$  is continuous but is in general no longer concave. Define a function on  $K$  by

$$g(x) = \widehat{s_n}(x) - M \cdot d(x, C_n)$$

*Claim* - There exists an  $N$  such that  $M \geq N$  implies that  $g$  is concave on  $K$ . Note that the set distance term is identically 0 on  $C_n$  and  $\widehat{s_n}$  is identically 0 on  $C_n^c$ . Moreover, the set distance term is concave, since  $x \rightarrow d(x, S)$  is a convex function whenever  $S$  is a convex set.

By concavity of the original Cule function  $s_n$  on  $C_n$ , for each point  $x \in C_n$ , the subgradient set  $\partial s_n(x)$  is non-empty. In fact, from Cule's work we know that  $s_n$  has the form

$$\begin{aligned} s_n(x) &= \sum_k (a_k^T x + b_k) I(C_n^k) \quad (x \in C_n) \\ &= -\infty \quad \text{else} \end{aligned}$$

Where  $C_n^k$  is a triangulation of the convex hull  $C_n^k$ . We can show that

*Lemma* - For a function of the form above,  $x \in C_n^k \implies a_k \in \partial s_n(x)$ . The only non-trivial part of the argument is dealing with points  $x \in \partial C_n^k$ . Proof omitted.

**Subgradient argument** - To show that our extension  $g(x)$  is concave, it suffices to show that  $\partial g(x) \neq \emptyset$  for each  $x \in K$ . Then by concavity of the disjointly supported pieces of  $g(x)$ , it suffices to show that the subgradient condition is satisfied for each  $x \in C_n$ ,  $y \in K \setminus C_n$  and conversely.

Consider  $x \in C_n$  and  $y \in K \setminus C_n$ . Let  $p_{y^*}$  denote the projection of  $y$  onto  $C_n$ . In our construction of  $g(x)$ , choose

$$M \geq N = \max_k \|a_k\|_2$$

i.e. over all vectors defining the piecewise affine function  $s_n$ . Then we can calculate as follows

$$\begin{aligned} g(y) - g(x) &= g(y) - g(p_{y^*}) + g(p_{y^*}) - g(x) = -M\|y - p_{y^*}\| + g(p_{y^*}) - g(x) \\ &\leq -M\|y - p_{y^*}\| + \partial g(x)^T(p_{y^*} - x) = -M\|y - p_{y^*}\| + \partial g(x)^T(p_{y^*} - y + y - x) \\ &\leq 0 + \partial g(x)^T(y - x) \end{aligned}$$

Note that the 1<sup>st</sup> inequality follows by concavity of  $g$  on  $C_n$ , while the 2<sup>nd</sup> inequality follows from Cauchy-Schwarz and our choice of  $M$ . A similar argument can be used to show that subgradients of  $g$  exist for  $x \in K \setminus C_n$ . Then  $g$  is concave on  $K$ .

By construction, for  $M \geq N$  we have that  $g$  is a concave function. Note that  $x \in \partial K \implies d(x, K) \geq \epsilon$ . Choose  $K = C_n^\epsilon$  as previously defined, where  $M_\epsilon \cdot \epsilon = N_\epsilon \rightarrow \infty$  as  $\epsilon \rightarrow 0$ .

**Convergence argument** - We argue that  $\int_{K^c} \exp(p_m) \rightarrow 0$  as  $m \rightarrow \infty$ . Let  $x \in K^c$ . Let  $\pi_x$  denote the projection of  $x$  onto  $C_n$ . Then there exists a point  $x_0 \in \partial K \cap [\pi_x, x]$ . Consider a function  $\gamma(t) = p_m(\nu(t))$ , where  $\nu$  is a parametrization of the line  $[\pi_x, x]$ . Let  $\nu(0) = \pi_x$  and  $\nu(a) = x_0$ . Then there exists a  $c$  such that

$$\begin{aligned} -M\epsilon &= \gamma(a) - \gamma(0) = \gamma'(c) \|\pi_x - x_0\| \\ \implies \gamma'(c) &\leq \frac{-M\epsilon}{\|\pi_x - x_0\|} \leq \frac{-M\epsilon}{\text{Diam}(K)} \end{aligned}$$

Since  $\gamma$  is concave and  $c \in [0, a]$ , we then also have  $\gamma'(a) \leq \frac{-M\epsilon}{\text{Diam}(K)}$ . Then Taylor implies that

$$\begin{aligned} p_m(x) &= \gamma(1) = \gamma(a) + \gamma'(a) \|x_0 - x\| + \frac{1}{2} \gamma''(d) \|x_0 - x\|^2 \\ &\leq -M\epsilon + \frac{-M\epsilon}{\text{Diam}(K)} \|x - x_0\| \leq \frac{-M\epsilon}{\text{Diam}(K)} \|x - x^*\| \end{aligned}$$

Where  $x^*$  is the projection of  $x$  onto  $K$ . Let  $\phi_m = p_m + M\epsilon$ . Then we have

$$\int_{K^c} \exp(p_m) \leq \exp(-M\epsilon) \int_{K^c} \exp(\phi_m) \leq \exp(-M\epsilon) \int_{K^c} \exp\left(\frac{-M\epsilon}{\text{Diam}(K)} \|x - x_0\|\right)$$

We chose  $m$  such that  $M(\epsilon)\epsilon \rightarrow \infty$  as  $\epsilon \rightarrow 0$ . Then in particular for large enough  $m$  the integral is

$$\leq \int_{K^c} \exp(-\|x - x^*\|) = \int_{K^c} \exp(-d(x, K))$$

This integral clearly converges since  $K$  is compact. Since  $-M\epsilon \rightarrow \infty$  as  $\epsilon \rightarrow 0$ , for any bounded function  $\|G\|_{\infty, \mathbb{R}^p} \leq B$  we have that

$$\int_{K^c} G \cdot \exp(p_m) \rightarrow 0 \quad (m \rightarrow \infty)$$

**Summary of Integral Results** - Note that by construction, we have  $\mathcal{L}(C_n^\epsilon \setminus C_n) \rightarrow 0$  as  $\epsilon \rightarrow 0$ . Moreover, we used density of sos-convex polynomials to choose  $p_m$  such that  $|p_m(x)| \leq |p_m(x) - g_m(x)| + |g_m(x)| \leq \epsilon + 0 \leq 1$  on  $C_n^\epsilon \setminus C_n$ . Therefore we easily have that

$$\int_{C_n^\epsilon \setminus C_n} G \cdot \exp(p_m) \leq \int_{C_n^\epsilon \setminus C_n} B e = B e \cdot \mathcal{L}(C_n^\epsilon \setminus C_n) \rightarrow 0$$

For the final integral in the decomposition, we have

$$\int_{C_n} G \cdot \exp(p_m) \rightarrow \int_{C_n} G \cdot s_n$$

by bounded convergence on a finite measure space, with bound

$$\|G \exp(p_m)\|_{\infty, C_n} \leq B \cdot (\|s_n\|_{\infty, C_n} + 1)$$

Note that the latter bound is fixed for all  $m$ . Therefore, for any bounded function  $G$  we have that

$$\int_{\mathbb{R}^p} G \cdot \exp(p_m) \rightarrow \int_{\mathbb{R}^p} G \cdot \exp(s_n)$$

In particular

$$\int_{\mathbb{R}^p} \exp(p_m) \rightarrow \int_{\mathbb{R}^p} \exp(s_n) = 1$$

Let  $z_m = \frac{\exp(p_m)}{\int_{\mathbb{R}^p} \exp(p_m)}$ . Then the argument above shows that for any bounded function  $G$

$$\int_{\mathbb{R}^p} G \cdot z_m \rightarrow \int_{\mathbb{R}^p} G \cdot f_n$$

So that we have convergence in distribution  $z_m \rightarrow f_n$ .

**Convergence of objective function value** - Consider a function  $z_m$  as constructed above such that  $\|z_m - f_n\|_\infty \leq \epsilon$ . Then for data  $\{x_i\}_{i=1}^n$ , we must have in particular that  $z_m(x_i) \geq f_n(x_i) - \epsilon$ . Therefore, if we let  $L$  denote the non-parametric likelihood, we have

$$L(z_m) \geq L(f_n) - n\epsilon_m \rightarrow L(f_n) \quad (m \rightarrow \infty)$$

Since  $z_m \in \text{SOSX}$ , the function returned by our convex problem must do better, so in particular our objective value converges to Cule's objective value as we let  $d \rightarrow \infty$  (our construction uses  $z_m$  of potentially arbitrarily high log-degrees).

**Convergence of Our Estimator in Distribution** - It remains to show that our estimator converges in distribution to the Cule estimator. Let our estimator for degree  $d$  be denoted by  $\beta_d$ . Then we know that  $L(\beta_d) \rightarrow L(f_n)$  as  $d \rightarrow \infty$ . We somehow need to use convergence of likelihood values + the shape constraint that  $\beta_m$  is in particular log-concave.

*Question* - Does log-concavity + likelihood convergence imply convergence in distribution?

### Things that we had trouble proving / omitted

\*\* Show that we have a density relation  $SOSX \rightarrow SMSX$ . This proof currently has problems.

\*\* Prove or disprove that our estimator  $\beta_d$  converges in distribution to  $f_n$ .

\*\* Need to show that  $\mathcal{L}(C_n) < \infty \implies \mathcal{L}(C_n^1) < \infty$ . Note that this immediately implies that  $\epsilon \rightarrow \mathcal{L}(C_n^\epsilon \setminus C_n)$  is a continuous function by standard measure theory arguments - we just need the measure space to be finite.

\*\* Argumentation for existence of appropriate subgradients on  $K \setminus C_n$  omitted.