CH-53K 1.0.0

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Chapter 1

Data Structure Index

1.1 Data Structures

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TimerStruct				 		 				 				 								5

2 Data Structure Index

Chapter 2

File Index

2.1 File List

Here is a list of all files with brief descriptions:

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This module contains definitions and structures to support SPI FRAM operations	11
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C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Src/fram.c	
This module contains routines to access the SPI FRAM. The FRAM used in the device is 32Kx8	
with an operating frequency up to 20 MHz. It supports SPI Mode 0 & 3. The hardware supports	
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Chapter 3

Data Structure Documentation

3.1 PwmStruct Struct Reference

```
#include <stm321412xx-bsp.h>
```

Data Fields

- uint8_t is_running
- uint32_t pulse_width

3.1.1 Field Documentation

3.1.1.1 is_running

uint8_t is_running

3.1.1.2 pulse_width

uint32_t pulse_width

The documentation for this struct was generated from the following file:

C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/stm32l412xx-bsp.h

3.2 TimerStruct Struct Reference

#include <stm321412xx-bsp.h>

Data Fields

- uint8_t is_running
- uint32_t time

3.2.1 Field Documentation

3.2.1.1 is_running

uint8_t is_running

3.2.1.2 time

uint32_t time

The documentation for this struct was generated from the following file:

• C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/stm32l412xx-bsp.h

Chapter 4

File Documentation

4.1 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_

Controller/Core/Inc/button_handler.h File Reference

```
#include <stdint.h>
#include "stm321412xx-bsp.h"
```

Functions

- GPIO_PinState IsDimPressed (void)
- GPIO_PinState IsBrightPressed (void)

4.1.1 Function Documentation

4.1.1.1 IsBrightPressed()

4.1.1.2 IsDimPressed()

4.2 button_handler.h

```
Go to the documentation of this file.
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 // Any use without the prior written consent of Luminator Mark IV 00005 // is strictly prohibited.
00008 //
00009 // Filename: button_handler.h
00010 //
00011 // Description: Returns the button state of the three board buttons
00012 //
00013 // Revision History:
00014 // Date - Name - Ver - Remarks
00015 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00016 // 00017 // Notes: Depends on the board support package bsp for GPIO_PinState
00018 //
00020
00021 #ifndef INC_button_handlerh
00022
          #define INC_button_handlerh
00023
00024
          #include <stdint.h>
00025
00026
          #include "stm321412xx-bsp.h"
00027
00028
          /\star Return state of buttons \star/
          GPIO_PinState IsDimPressed ( void );
GPIO_PinState IsBrightPressed ( void );
00029
00030
00031
00032 #endif /* INC_button_handlerh */
```

4.3 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/current handler.h File Reference

```
#include <stdint.h>
```

Enumerations

• enum CurrentRange_e { CurrentNormal = 0 , CurrentHigh = 1 , CurrentError = 2 }

Functions

- uint16 t GetCurrent (void)
- CurrentRange_e GetCurrentRange (void)

4.3.1 Enumeration Type Documentation

4.3.1.1 CurrentRange e

enum CurrentRange_e

Enumerator

CurrentNormal	
CurrentHigh	
CurrentError	

4.4 current_handler.h

4.3.2 Function Documentation

4.3.2.1 GetCurrent()

4.3.2.2 GetCurrentRange()

4.4 current_handler.h

```
Go to the documentation of this file.
```

```
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 /\!/ Any use without the prior written consent of Luminator Mark IV 00005 /\!/ is strictly prohibited.
00009 // Filename: current_handler.h
00010 //
00011 // Description: Handles getting current and reporting values.
00012 //
00013 // Revision History:
00014 // Date
                        - Ver - Remarks
                - Name
00015 // 08/05/2024 - Austin Green - 1.0 - Initial Document
00016 //
00017 // Notes:
00018 //
00020
00021 #ifndef INC_current_handlerh
00022
       #define INC_current_handlerh
00023
00024
       #include <stdint.h>
00025
00026
       /* Current Range Enum */
       typedef enum
00028
           CurrentNormal = 0,
00029
       CurrentHigh
CurrentError
00030
00031
00032
       } CurrentRange e;
00033
00034
       /* Get Current */
00035
       uint16_t GetCurrent( void ); // in dA
00036
       CurrentRange_e GetCurrentRange( void );
00037
00038 #endif /* INC_current_handlerh */
```

4.5 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/delay_handler.h File Reference

```
#include <stdint.h>
```

Functions

- void StartDelayCounter (void)
- void RestartDelayCounter (void)
- uint8_t DelayHit (uint32_t delay_ms)
- uint16 t BrightnessDelay (int8 t brightness)

4.5.1 Function Documentation

4.5.1.1 BrightnessDelay()

4.5.1.2 DelayHit()

4.5.1.3 RestartDelayCounter()

4.5.1.4 StartDelayCounter()

4.6 delay_handler.h

Go to the documentation of this file.

```
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 // Any use without the prior written consent of Luminator Mark IV 00005 // is strictly prohibited.
00009 // Filename: delay_handler.h
00010 //
00011 // Description: Handles system counters and delays
00012 //
00013 // Revision History:
00014 // Date - Name - Ver - Remarks
00015 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00016 //
00017 // Notes:
00018 //
00020
00021 /* Define to prevent recursive inclusion -----
00022 #ifndef INC_delay_handlerh
00023
        #define INC_delay_handlerh
00024
00025
         #include <stdint.h>
00026
00027
         /\star Check if delay has been hit \star/
00028
         void StartDelayCounter(void);
                                           // start the counter
         void RestartDelayCounter(void); // restart the counter uint8_t DelayHit(uint32_t delay_ms); // is delay in ms hit /* Get ms delay for given brightness */
00029
00030
00031
00032
         uint16_t BrightnessDelay(int8_t brightness);
00034 #endif /* INC_delay_handlerh */
```

4.7 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/fram.h File Reference

This module contains definitions and structures to support SPI FRAM operations.

```
#include "stm321412xx-bsp.h"
```

Enumerations

```
    enum OPCODE_COMMANDS {
        OC_WREN = 6, OC_WRDI = 4, OC_RDSR = 5, OC_WRSR = 1,
        OC_READ = 3, OC_WRITE = 2 }

    enum STATUS_REGISTER { SR_WEL = 0x2, SR_BP0 = 0x4, SR_BP1 = 0x8, SR_WPEN = 0x80 }

    enum WRITE_PROTECT_STATE { WPS_PROTECTED = 0, WPS_WRITEABLE = 1 }

    enum CHIP_SELECT_STATE { CSS_ASSERT = 0, CSS_RELEASE = 1 }
```

Functions

- void framWriteProtect (WRITE_PROTECT_STATE state)
- void framChipSelect (CHIP SELECT STATE state)
- void framReadSr (unsigned char *srP)
- void framWriteSr (unsigned char sr)
- void framWriteDisable (void)
- void framWriteEnable (void)
- void framReadMemory (unsigned short addr, unsigned char *rdBufP, unsigned short len)
- · void framWriteMemory (unsigned short addr, const unsigned char *const wrBufP, unsigned short len)
- uint8_t framTest (void)

4.7.1 Detailed Description

This module contains definitions and structures to support SPI FRAM operations.

Attention

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Revision History: Date Name Ver Remarks 04/09/2023 Mark Lane 0 Original Version Notes:

4.7.2 Enumeration Type Documentation

4.7.2.1 CHIP_SELECT_STATE

```
enum CHIP_SELECT_STATE
chip select state
```

Enumerator

CSS_ASSERT	chip select disabled	
CSS_RELEASE	chip select enabled	

4.7.2.2 OPCODE_COMMANDS

enum OPCODE_COMMANDS
opcode command

Enumerator

OC_WREN	set write enable latch
OC_WRDI	write disable
OC_RDSR	read status register
OC_WRSR	write status register
OC_READ	read memory data
OC_WRITE	write memory data

4.7.2.3 STATUS_REGISTER

enum STATUS_REGISTER
status register

Enumerator

SR_WEL	write-enable latch
SR_BP0	block protect bit 0
SR_BP1	block protect bit 1
SR_WPEN	enable write protect pin

4.7.2.4 WRITE_PROTECT_STATE

enum WRITE_PROTECT_STATE
write protect state

Enumerator

write protected
write enabled

4.7.3 Function Documentation

4.7.3.1 framChipSelect()

This routine sets the chip select pin to the correct "state".

Parameters

in	state	assert = 0, release = 1
out	none	

4.7.3.2 framReadMemory()

```
void framReadMemory (
          unsigned short addr,
          unsigned char * rdBufP,
          unsigned short len)
```

This routine reads FRAM memory starting at "addr" for "len" byte(s). The FRAM read data is stored at the pointer referenced by "rdBufP".

Parameters

in	addr	FRAM memory address to read data
in	rdBufP	destination pointer to store read data
in	len	number of byte(s) to read
out	none	

4.7.3.3 framReadSr()

```
void framReadSr ( \mbox{unsigned char} \ * \ srP)
```

This routine reads the FRAM status register

Parameters

in	destination	pointer for FRAM status register
out	none	

4.7.3.4 framTest()

```
uint8_t framTest (
     void )
```

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

Parameters

```
out | pass | = 1, fail = 0
```

4.7.3.5 framWriteDisable()

```
void framWriteDisable (
     void )
```

This routine resets the write enable latch

Parameters

4.7.3.6 framWriteEnable()

```
void framWriteEnable (
     void )
```

This routine sets the write enable latch

Parameters

out	none	

4.7.3.7 framWriteMemory()

```
void framWriteMemory (
          unsigned short addr,
          const unsigned char *const wrBufP,
          unsigned short len)
```

This routine writes FRAM memory starting at "addr" for "len" byte(s). The data referenced by the pointer "wrBufP" is written into FRAM memory.

Parameters

in	addr	FRAM memory address to write data
in	wrBufP	pointer to data to write
in	len	number of byte(s) to write
out	none	

4.7.3.8 framWriteProtect()

This routine sets the hardware write protect pin to the correct "state".

Parameters

in	state	disable = 0, $enable = 1$
out	none	

4.7.3.9 framWriteSr()

This routine writes the FRAM status register

Parameters

in	data	value written to FRAM status register
out	none	

4.8 fram.h 15

4.8 fram.h

```
Go to the documentation of this file.
```

```
00030 #ifndef _FRAM_H_
00031 #define _FRAM_H_
00032
00033 #include "stm321412xx-bsp.h"
00034
00035 /* Definition */
00039 typedef enum {
00040
       OC_WREN = 6 ,
OC_WRDI = 4 ,
00041
00042
       OC_RDSR
00043
                 = 5 ,
        OC_WRSR
00044
00045
        OC_READ
00046 OC_WRITE = 2 ,
00048 } OPCODE_COMMANDS ;
00049
00050
00054 typedef enum {
00055
00056
        SR\_WEL = 0x2
00057
       SR\_BP0 = 0x4

SR\_BP1 = 0x8
00058
        SR WPEN = 0x80
00059
00061 } STATUS_REGISTER;
00063
00067 typedef enum {
00068
       WPS_PROTECTED = 0 ,
00069
00070
        WPS_WRITEABLE = 1
00072 } WRITE_PROTECT_STATE ;
00073
00074
00078 typedef enum {
00079
        CSS_ASSERT = 0 ,
08000
        CSS_RELEASE = 1
00083 } CHIP_SELECT_STATE ;
00084
00085
00086 /* Prototype Definition */
00087
00094 void framWriteProtect( WRITE_PROTECT_STATE state );
00102 void framChipSelect ( CHIP_SELECT_STATE state );
00103
00104
00111 void framReadSr( unsigned char *srP ) ;
00112
00119 void framWriteSr( unsigned char sr ) ;
00120
00121
00126 void framWriteDisable( void );
00127
00132 void framWriteEnable( void ) ;
00134
00144 void framReadMemory (unsigned short addr, unsigned char *rdBufP, unsigned short len );
00145
00155 void framWriteMemory( unsigned short addr, const unsigned char* const wrBufP, unsigned short len );
00156
00164 uint8_t framTest( void ) ;
00165
00166
00167 #endif
```

4.9 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/logger.h File Reference

```
#include <stdint.h>
```

Functions

• void LogString (const char *const string, uint8_t write_beginning)

- void LogNumber (const int32_t number, uint8_t write_beginning)
- void ReadLog (const uint32_t address, char *string, const uint32_t bytes)

4.9.1 Function Documentation

```
4.9.1.1 LogNumber()
```

const uint32_t bytes)

4.10 logger.h

Go to the documentation of this file.

```
00001 //
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 // Any use without the prior written consent of Luminator Mark IV
00005 // is strictly prohibited.
00008 //
00009 // Filename: logger.h
00011 // Description: Handles logging and reading of data to memory
00012 //
00013 // Revision History:
00014 // Date - Name - Ver - Remarks
00015 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00016 // 08/05/2024 - Austin Green - 1.1 - Added Log Number
00018 // Notes:
00019 //
00021
00022 #ifndef INC_loggerh
00023
        #define INC_loggerh
00024
00025
        #include <stdint.h>
00026
00027
        /* Store and Read Logs */
        void LogString( const char* const string, uint8_t write_beginning );
00028
        void LogNumber( const int32_t number, uint8_t write_beginning );
00030
        void ReadLog( const uint32_t address, char* string, const uint32_t bytes );
00031
00032 #endif /* INC_loggerh */
```

4.11 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/main.h File Reference

```
#include "stm321412xx-bsp.h"
```

4.12 main.h 17

Functions

void Error_Handler (void)

This function is executed in case of error occurrence.

4.11.1 Function Documentation

4.11.1.1 Error Handler()

This function is executed in case of error occurrence.

Return values

None

4.12 main.h

Go to the documentation of this file.

```
00001 /* USER CODE BEGIN Header */
00002 /****
00003
        * @file : main.h
* @brief : Header for main.c file.
00004
00005
00006
                          This file contains the common defines of the application.
00007
        *******************
80000
        * @attention
00009
        * Copyright (c) 2024 STMicroelectronics.
00010
00011
        * All rights reserved.
00012
00013
        \star This software is licensed under terms that can be found in the LICENSE file
00014
        \star in the root directory of this software component.
        * If no LICENSE file comes with this software, it is provided AS-IS.
00015
00016
00017
         ******************
00018
00019 /* USER CODE END Header */
00020
00021 /* Define to prevent recursive inclusion -----*/
00022 #ifndef INC_mainh
00023
        #define INC_mainh
00024
        #ifdef __cplusplus
    extern "C" {
00025
00026
00027
        #endif
00028
00029
        /* Includes ----
00030
00031
        /* Private includes ------*/
        /* USER CODE BEGIN Includes */
#include "stm321412xx-bsp.h"
00032
00033
00034
00035
        /* USER CODE END Includes */
00036
00037
         /* Exported types ----
00038
         /* USER CODE BEGIN ET */
00039
00040
        /* USER CODE END ET */
00041
00042
         /* Exported constants ---
00043
        /* USER CODE BEGIN EC */
00044
00045
        /* USER CODE END EC */
00046
00047
         /* Exported macro -
00048
        /* USER CODE BEGIN EM */
00049
00050
         /* USER CODE END EM */
00051
00052
         /* Exported functions prototypes -----*/
00053
        void Error Handler (void);
00054
00055
         /* USER CODE BEGIN EFP */
00056
```

```
/* USER CODE END EFP */
00059
         /* Private defines -----
00060
00061
         /* USER CODE BEGIN Private defines */
00062
         /* USER CODE END Private defines */
00063
00064
00065
         #ifdef __cplusplus
00066
00067
         #endif
00068
00069 #endif /* INC_mainh */
```

4.13 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/my_printf.h File Reference

4.14 my_printf.h

Go to the documentation of this file.

```
00002 // Copyright © 2007 Luminator Mark IV
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00004 // Any use without the prior written consent of Luminator Mark IV
00005 // is strictly prohibited.
00008 //
00009 // Filename: my_printf.h
00010 //
00011 // Description: Prints characters to a terminal for debugging purposes
00012 //
00013 // Revision History:
00014 // Date - Name - Ver - Remarks
00015 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00016 //
00017 // Notes:
00018 //
00021 // Software tracing with printf()
00022 #ifndef INC_my_printfh
```

#ifdef ENABLE_UART_DEBUGGING /* tracing enabled */

4.15 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/pwm_handler.h File Reference

```
#include <stdint.h>
```

Macros

00023

00024

00026

00027

• #define BRIGHTNESS STEPS (50)

#define INC_my_printfh

00029 #endif /* INC_my_printfh */

#include <stdio.h>
#endif /* ENABLE_UART_DEBUGGING */

• #define HOLD BRIGHTNESS JUMP (3)

Functions

- void InitPwm (void)
- void DecreaseBrightness (uint8_t button_held)
- void IncreaseBrightness (uint8_t button_held)
- · void SetPwm (void)
- void TurnOffPwm (void)
- int8_t GetBrightness (void)

- void SetBrightness (int8_t brightness)
- uint8_t GetPwm (void)

4.15.1 Macro Definition Documentation

4.15.1.1 BRIGHTNESS_STEPS

```
#define BRIGHTNESS_STEPS (50)
```

4.15.1.2 HOLD_BRIGHTNESS_JUMP

```
#define HOLD_BRIGHTNESS_JUMP (3)
```

4.15.2 Function Documentation

4.15.2.1 DecreaseBrightness()

```
void DecreaseBrightness (
          uint8_t button_held)
```

4.15.2.2 GetBrightness()

```
int8_t GetBrightness (
     void )
```

4.15.2.3 GetPwm()

4.15.2.4 IncreaseBrightness()

4.15.2.5 InitPwm()

```
void InitPwm (
     void )
```

4.15.2.6 SetBrightness()

4.15.2.7 SetPwm()

```
void SetPwm (
     void )
```

4.15.2.8 TurnOffPwm()

```
void TurnOffPwm (
     void )
```

4.16 pwm handler.h

```
Go to the documentation of this file.
00002 // Copyright © 2007 Luminator Mark IV
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00004 // Any use without the prior written consent of Luminator Mark IV
00005 // is strictly prohibited.
00008 //
00009 // Filename: pwm_handler.h
00010 //
00011 // Description: Handles the PWM output of the lights. Output is
00012 //
                       determined by a Brightness variable that is
                        controlled by this file.
00013 //
00014 //
00015 // Revision History:
00016 // Date - Name - Ver - Remarks
00017 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00018 //
00019 // Notes:
00020 //
00022
00023 #ifndef INC_pwm_handlerh
00024
         #define INC_pwm_handlerh
00025
00026
         #include <stdint.h>
00027
00028
        /* Brightness Steps */
00029
         #define BRIGHTNESS_STEPS
00030
         #define HOLD BRIGHTNESS JUMP
00031
00032
         /* Initialize system */
00033
        void
                InitPwm(void);
                                                          // Init Pwm var
00034
         /* Decrease/Increase brightness levels */
         void DecreaseBrightness( uint8_t button_held ); // decrease brightness
00035
                IncreaseBrightness( uint8_t button_held ); // increase brightness
00036
         void
00037
         /\star Set PWM value based on internal brightness \star/
```

4.17 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/stm32l412xx-bsp.h File Reference

// turn on and set PWM

// get value of Brightness
// set value of Brightness

// get value of current PWM

// turn of PWM

#include <stdint.h>

Data Structures

- struct PwmStruct
- struct TimerStruct

Macros

00039

00040

00041

00042

00043

• #define THERMISTOR_ADC_Pin 0

void SetPwm(void);
void TurnOffPwm(void);

uint8_t GetPwm(void);

00045 #endif /* INC_pwm_handlerh */

 $/\star$ Get or set internal values $\star/$

int8_t GetBrightness(void);
void SetBrightness(int8_t brightness);

- #define THERMISTOR ADC GPIO Port 0
- #define BRIGHT_Pin 0
- #define BRIGHT_GPIO_Port 0
- #define DIM_Pin 0
- #define DIM_GPIO_Port 0
- #define EEPROM_SCK_Pin 0
- #define EEPROM_SCK_GPIO_Port 0
- #define EEPROM MISO Pin 0
- #define EEPROM_MISO_GPIO_Port 0

- #define EEPROM_MOSI_Pin 0
- #define EEPROM_MOSI_GPIO_Port 0
- #define VOLTMETER ADC Pin 0
- #define VOLTMETER ADC GPIO Port 0
- #define AMPMETER ADC Pin 0
- #define AMPMETER ADC GPIO Port 0
- #define PWM OUT Pin 0
- #define PWM OUT GPIO Port 0
- #define SPI WP Pin 0
- #define SPI WP GPIO Port 0
- #define SPI NSS Pin 0
- #define SPI_NSS_GPIO_Port 0
- #define NVIC_PRIORITYGROUP_0 ((uint32_t)0x00000007)
- #define NVIC_PRIORITYGROUP_1 ((uint32_t)0x00000006)
- #define NVIC_PRIORITYGROUP_2 ((uint32_t)0x00000005)
- #define NVIC PRIORITYGROUP 3 ((uint32 t)0x00000004)
- #define NVIC_PRIORITYGROUP_4 ((uint32_t)0x00000003)
- #define CLK FREQ HZ (8000000)
- #define TIM2_CLK_DEV (1)
- #define TIM2 CLK PRESCALER (8000)

Typedefs

· typedef uint8_t GPIO_PinState

Enumerations

- enum { BUTTON PRESSED = 1 , BUTTON UNPRESSED = 0 }
- enum { PIN SET = 1 , PIN RESET = 0 }

Functions

- GPIO PinState ReadDimPin (void)
- GPIO PinState ReadBrightPin (void)
- void EnablePWM1 (void)
- void DisablePWM1 (void)
- void StartPWM11 (void)
- void StopPWM11 (void)
- void SetPW11 (uint32 t pulse width)
- void StartTIM2 (void)
- void RestartTIM2 (void)
- uint32_t GetTIM2Cnt (void)
- int16_t GetThermistorValue (void)
- int16_t GetCurrentValue (void)
- int16_t GetVoltageValue (void)
- void enableWriteProtect (void)
- void disableWriteProtect (void)
- void enableChipSelect (void)
- void disableChipSelect (void)
- void transferData (const unsigned char *const txData, const uint32_t bytes)
- void receiveData (unsigned char *rxData, const uint32 t bytes)
- void sendUARTChar (char c)
- void Error_Handler (void)

This function is executed in case of error occurrence.

4.17.1 Macro Definition Documentation

4.17.1.1 AMPMETER_ADC_GPIO_Port

#define AMPMETER_ADC_GPIO_Port 0

4.17.1.2 AMPMETER_ADC_Pin

#define AMPMETER_ADC_Pin 0

4.17.1.3 BRIGHT_GPIO_Port

#define BRIGHT_GPIO_Port 0

4.17.1.4 BRIGHT_Pin

#define BRIGHT_Pin 0

4.17.1.5 CLK_FREQ_HZ

#define CLK_FREQ_HZ (8000000)

4.17.1.6 DIM_GPIO_Port

#define DIM_GPIO_Port 0

4.17.1.7 DIM_Pin

#define DIM_Pin 0

4.17.1.8 EEPROM_MISO_GPIO_Port

#define EEPROM_MISO_GPIO_Port 0

4.17.1.9 EEPROM_MISO_Pin

#define EEPROM_MISO_Pin 0

4.17.1.10 EEPROM_MOSI_GPIO_Port

#define EEPROM_MOSI_GPIO_Port 0

4.17.1.11 EEPROM_MOSI_Pin

#define EEPROM_MOSI_Pin 0

4.17.1.12 EEPROM_SCK_GPIO_Port

#define EEPROM_SCK_GPIO_Port 0

4.17.1.13 EEPROM_SCK_Pin

#define EEPROM_SCK_Pin 0

4.17.1.14 NVIC_PRIORITYGROUP_0

 $\label{thm:priority} \mbox{\sharp define NVIC_PRIORITYGROUP_0 ((uint32_t)0x00000007)$} \\ \mbox{$0$ bit for pre-emption priority, 4 bits for subpriority}$

4.17.1.15 NVIC_PRIORITYGROUP_1

#define NVIC_PRIORITYGROUP_1 ((uint32_t)0x00000006)
1 bit for pre-emption priority, 3 bits for subpriority

4.17.1.16 NVIC_PRIORITYGROUP_2

#define NVIC_PRIORITYGROUP_2 ((uint32_t)0x00000005)
2 bits for pre-emption priority, 2 bits for subpriority

4.17.1.17 NVIC PRIORITYGROUP 3

4.17.1.18 NVIC PRIORITYGROUP 4

#define NVIC_PRIORITYGROUP_4 ((uint32_t)0x00000003)
4 bits for pre-emption priority, 0 bit for subpriority

4.17.1.19 PWM_OUT_GPIO_Port

#define PWM_OUT_GPIO_Port 0

4.17.1.20 PWM OUT Pin

#define PWM_OUT_Pin 0

4.17.1.21 SPI_NSS_GPIO_Port

#define SPI_NSS_GPIO_Port 0

4.17.1.22 SPI_NSS_Pin

#define SPI_NSS_Pin 0

4.17.1.23 SPI_WP_GPIO_Port

#define SPI_WP_GPIO_Port 0

4.17.1.24 SPI_WP_Pin

#define SPI_WP_Pin 0

4.17.1.25 THERMISTOR_ADC_GPIO_Port

#define THERMISTOR_ADC_GPIO_Port 0

4.17.1.26 THERMISTOR_ADC_Pin

#define THERMISTOR_ADC_Pin 0

4.17.1.27 TIM2_CLK_DEV

#define TIM2_CLK_DEV (1)

4.17.1.28 TIM2_CLK_PRESCALER

#define TIM2_CLK_PRESCALER (8000)

4.17.1.29 VOLTMETER_ADC_GPIO_Port

```
#define VOLTMETER_ADC_GPIO_Port 0
```

4.17.1.30 VOLTMETER_ADC_Pin

#define VOLTMETER_ADC_Pin 0

4.17.2 Typedef Documentation

4.17.2.1 GPIO_PinState

typedef uint8_t GPIO_PinState

4.17.3 Enumeration Type Documentation

4.17.3.1 anonymous enum

anonymous enum

Enumerator

BUTTON_PRESSED	
BUTTON_UNPRESSED	

4.17.3.2 anonymous enum

anonymous enum

Enumerator

```
PIN_SET
PIN_RESET
```

4.17.4 Function Documentation

4.17.4.1 disableChipSelect()

4.17.4.2 DisablePWM1()

```
void DisablePWM1 (
     void )
```

4.17.4.3 disableWriteProtect()

4.17.4.4 enableChipSelect()

4.17.4.5 EnablePWM1()

```
void EnablePWM1 (
     void )
```

4.17.4.6 enableWriteProtect()

4.17.4.7 Error_Handler()

This function is executed in case of error occurrence.

Return values

None

4.17.4.8 GetCurrentValue()

4.17.4.9 GetThermistorValue()

4.17.4.10 GetTIM2Cnt()

4.17.4.11 GetVoltageValue()

4.17.4.12 ReadBrightPin()

4.17.4.13 ReadDimPin()

4.17.4.14 receiveData()

```
void receiveData (
          unsigned char * rxData,
          const uint32_t bytes)
```

4.17.4.15 RestartTIM2()

```
void RestartTIM2 (
     void )
```

4.17.4.16 sendUARTChar()

void sendUARTChar (

4.17.4.18 StartPWM11()

```
void StartPWM11 (
     void )
```

4.17.4.19 StartTIM2()

```
void StartTIM2 (
     void )
```

4.17.4.20 StopPWM11()

```
void StopPWM11 (
     void )
```

4.17.4.21 transferData()

4.18 stm32l412xx-bsp.h

```
Go to the documentation of this file.
```

```
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 /\!/ Any use without the prior written consent of Luminator Mark IV 00005 /\!/ is strictly prohibited.
00008 //
00009 // Filename: stm321412xx-bsp.h
00010 //
00011 // Description: Board Support Package for STM32L412xx 00012 //
00013 // Revision History:
00014 // Date
00014 // Date - Name - Ver - Remarks
00015 // 07/31/2024 - Austin Green - 1.0 - Initial Document
00016 //
00017 // Notes: This uses the Low Level ST API to access the board pins
00018 //
00021 #ifndef INC_bsph
00022
        #define INC_bsph
00023
        #include <stdint.h>
00024
00025
00026
        /* Private defines
00027
00028
00029
            #include "stm3214xx_11_adc.h"
            #include "stm3214xx_l1_crs.h"
00030
            #include "stm3214xx_11_rcc.h"
00031
00032
            #include "stm3214xx_11_bus.h"
00033
            #include "stm3214xx_11_system.h"
00034
            #include "stm3214xx_11_exti.h"
            #include "stm3214xx_ll_cortex.h"
00035
            #include "stm3214xx_11_utils.h'
00036
            #include "stm3214xx_ll_pwr.h"
00037
```

```
#include "stm3214xx_11_dma.h"
00039
                #include "stm3214xx_11_spi.h"
                #include "stm3214xx_l1_tim.h"
00040
                #include "stm3214xx_l1_usart.h"
00041
               #include "stm3214xx_ll_gpio.h"
00042
00043
               #if defined(USE_FULL_ASSERT)
00045
                    #include "stm32_assert.h"
00046
               #endif /* USE_FULL_ASSERT */
00047
00048
               /* Peripherals */
               #include "adc.h
00049
               #include "gpio.h"
00050
                #include "spi.h"
00051
00052
                #include "tim.h"
00053
               #ifdef ENABLE_UART_DEBUGGING /\star tracing enabled \star/
00054
00055
                   /* Peripherals enabled for UART */
                    #include "usart.h"
               #endif /* ENABLE_UART_DEBUGGING */
00057
00058
               #define THERMISTOR_ADC_Pin LL_GPIO_PIN_0
#define THERMISTOR_ADC_GPIO_POrt GPIOA
#define BRIGHT_Pin LL_GPIO_PIN_1
#define BRIGHT_GPIO_POrt GPIOA
00059
00060
00061
00062
                #define DIM_Pin LL_GPIO_PIN_3
00063
00064
                #define DIM_GPIO_Port GPIOA
00065
                #define EEPROM_SCK_Pin LL_GPIO_PIN_5
00066
                #define EEPROM_SCK_GPIO_Port GPIOA
               #define EEPROM_MISO_Pin LL_GPIO_PIN_6
00067
00068
               #define EEPROM_MISO_GPIO_Port GPIOA
00069
                #define EEPROM_MOSI_Pin LL_GPIO_PIN_7
00070
                #define EEPROM_MOSI_GPIO_Port GPIOA
00071
                #define VOLTMETER_ADC_Pin LL_GPIO_PIN_0
00072
               #define VOLTMETER_ADC_GPIO_Port GPIOB
00073
               #define AMPMETER_ADC_Pin LL_GPIO_PIN_1
#define AMPMETER_ADC_GPIO_PORT GPIOB
00074
               #define PWM_OUT_Pin LL_GPIO_PIN_8
00076
                #define PWM_OUT_GPIO_Port GPIOA
00077
                #define SPI_WP_Pin LL_GPIO_PIN_10
               #define SPI_WP_GPIO_Port GPIOA
#define SPI_NSS_Pin LL_GPIO_PIN_11
00078
00079
00080
               #define SPI NSS GPIO Port GPIOA
00081
00082
          #else /* STM32L412xx */
00083
00084
                /* Below is for debugging purposes */
               #define THERMISTOR_ADC_Pin
#define THERMISTOR_ADC_GPIO_Port
00085
00086
00087
               #define BRIGHT_Pin
00088
                #define BRIGHT_GPIO_Port
00089
                #define DIM_Pin
00090
               #define DIM_GPIO_Port
00091
               #define EEPROM_SCK_Pin
               #define EEPROM_SCK_GPIO_Port
00092
00093
               #define EEPROM_MISO_Pin
               #define EEPROM_MISO_GPIO_Port
00095
                #define EEPROM_MOSI_Pin
00096
               #define EEPROM_MOSI_GPIO_Port
               #define VOLTMETER_ADC_Pin
#define VOLTMETER_ADC_GPIO_Port
00097
00098
               #define AMPMETER_ADC_Pin
00099
                                                         0
00100
               #define AMPMETER_ADC_GPIO_Port
00101
                #define PWM_OUT_Pin
00102
               #define PWM_OUT_GPIO_Port
00103
               #define SPI_WP_Pin
               #define SPI_WP_GPIO_Port
#define SPI_NSS_Pin
00104
00105
00106
               #define SPI_NSS_GPIO_Port
00107
00108
               typedef struct
00109
                   uint8_t is_running;
uint32_t pulse_width;
00110
00111
               } PwmStruct;
00112
00113
00114
                typedef struct
00115
                    uint8_t is_running;
uint32 t time;
00116
00117
               } TimerStruct;
00118
00119
00120
           #endif /* STM32L412xx */
00121
00122
           /* Interrupt Handlers */
           #ifndef NVIC_PRIORITYGROUP_0
00123
               #define NVIC_PRIORITYGROUP_0
00124
                                                          ((uint32 t)0x00000007)
```

```
#define NVIC_PRIORITYGROUP_1
                                                       ((uint32_t)0x00000006)
               #define NVIC_PRIORITYGROUP_2
#define NVIC_PRIORITYGROUP_3
                                                       ((uint32_t)0x00000005)
((uint32_t)0x00000004)
00128
00130
00132
              #define NVIC_PRIORITYGROUP_4
                                                       ((uint32_t)0x00000003)
00134
          #endif
00135
00136
          /* Button Defines */
00137
          typedef uint8_t GPIO_PinState;
00138
          enum { BUTTON_PRESSED = 1, BUTTON_UNPRESSED = 0};
00139
          enum { PIN_SET = 1, PIN_RESET = 0};
00140
00141
          /* Clock frequency Values *,
          #define CLK_FREQ_HZ (8000000)
#define TIM2_CLK_DEV (1)
00142
00143
00144
           #define TIM2_CLK_PRESCALER
00145
00146
          /* Returns button state */
          GPIO_PinState ReadDimPin( void );
GPIO_PinState ReadBrightPin( void );
00147
00148
          /* PWM Outputs */
00150
          void EnablePWM1( void );
00151
          void DisablePWM1( void );
          void StartPWM11( void );
00152
          void StopPWM11( void );
00153
00154
          void SetPW11( uint32_t pulse_width );
00155
          /* Timers */
00156
          void StartTIM2( void );
00157
          void RestartTIM2( void );
00158
          uint32_t GetTIM2Cnt( void );
00159
          /* Thermistor */
00160
          int16 t GetThermistorValue( void );
00161
           /* Current Sensing */
00162
          int16_t GetCurrentValue( void );
00163
          /* Voltage Sensing */
00164
          int16_t GetVoltageValue( void );
00165
          /* Logging */
          void enableWriteProtect( void );
00166
          void disableWriteProtect( void );
00167
00168
          void enableChipSelect( void );
00169
          void disableChipSelect( void );
00170
          void transferData( const unsigned char* const txData, const uint32_t bytes );
00171
          void receiveData( unsigned char* rxData, const uint32_t bytes );
00172
          /* UART Output */
00173
          void sendUARTChar(char c);
00174
          /* Errors */
00175
          void Error_Handler(void);
00176
00177
00178 #endif /* INC bsph */
```

4.19 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/temperature_handler.h File Reference

#include <stdint.h>

Enumerations

enum TemperatureRange_e { TempCool = 0 , TempWarm = 1 , TempHot = 2 }

Functions

- int32 t GetTemperature (void)
- TemperatureRange e GetTemperatureRange (void)

4.19.1 Enumeration Type Documentation

4.19.1.1 TemperatureRange_e

enum TemperatureRange_e

Enumerator

TempCool

Enumerator

TempWarm	
TempHot	

4.19.2 Function Documentation

4.19.2.1 GetTemperature()

4.19.2.2 GetTemperatureRange()

4.20 temperature_handler.h

Go to the documentation of this file.

```
00001 // ****
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 // Any use without the prior written consent of Luminator Mark IV
00005 // is strictly prohibited.
00008 //
00009 // Filename: temperature_handler.h
00011 // Description: Handles getting this temperature and transitioning
00012 //
                    between temperature states.
00013 //
00014 // Revision History:
00015 // Date - Name - Ver - Remarks

00016 // 07/31/2024 - Austin Green - 1.0 - Initial Document

00017 // 08/05/2024 - Austin Green - 1.1 - Refactor to not use floats
00018 //
00019 // Notes:
00020 //
00022
00023 #ifndef INC_temperature_handlerh
00024
        #define INC_temperature_handlerh
00025
00026
        #include <stdint.h>
00027
00028
        /* Temperature Range Enum */
        typedef enum
00030
00031
            TempCool
        TempWarm = 1,
TempHot = 2
00032
00033
00034
        } TemperatureRange_e;
00035
00036
        /* Get Temperature */
00037
        int32_t GetTemperature( void ); // in dC
00038
        TemperatureRange_e GetTemperatureRange( void );
00039
00040 #endif /* INC_temperature_handlerh */
```

4.21 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/voltage handler.h File Reference

```
#include <stdint.h>
```

Enumerations

```
    enum VoltageRange_e {
    VoltageNormal = 0 , VoltageLow = 1 , VoltageHigh = 2 , VoltageErrorLow = 3 , VoltageErrorHigh = 4 }
```

Functions

- uint16_t GetVoltage (void)
- VoltageRange_e GetVoltageRange (void)

4.21.1 Enumeration Type Documentation

4.21.1.1 VoltageRange e

```
enum VoltageRange_e
```

Enumerator

VoltageNormal	
VoltageLow	
VoltageHigh	
VoltageErrorLow	
VoltageErrorHigh	

4.21.2 Function Documentation

4.21.2.1 GetVoltage()

```
uint16_t GetVoltage (
     void )
```

4.21.2.2 GetVoltageRange()

4.22 voltage_handler.h

Go to the documentation of this file.

```
00002 // Copyright © 2007 Luminator Mark IV
00003 // All rights reserved.
00004 // Any use without the prior written consent of Luminator Mark IV
00005 // is strictly prohibited.
00008 //
00009 // Filename: voltage_handler.h
00010 \ensuremath{//} 00011 \ensuremath{//} Description: Handles getting voltage and reporting values.
00012 //
00013 // Revision History:
00014 // Date
                              - Ver - Remarks
00015 // 08/05/2024 - Austin Green - 1.0 - Initial Document
00017 // Notes:
00018 //
00020
00021 #ifndef INC_voltage_handlerh
00022
        #define INC_voltage_handlerh
00023
00024
        #include <stdint.h>
00025
00026
        /* Voltage Range Enum */
```

```
00027
         typedef enum
00028
00029
             VoltageNormal
                                = 0,
00030
             VoltageLow
                                = 1,
00031
             VoltageHigh
            VoltageErrorLow
00032
           VoltageErrorHigh
00034
        } VoltageRange_e;
00035
        /* Get Voltage */
00036
         uint16_t GetVoltage( void ); // in dV
00037
         VoltageRange_e GetVoltageRange( void );
00038
00039
00040 #endif /* INC_voltage_handlerh */
```

4.23 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/button handler.c File Reference

```
#include "button_handler.h"
#include "stm321412xx-bsp.h"
```

Functions

- · GPIO PinState IsDimPressed (void)
- GPIO PinState IsBrightPressed (void)

4.23.1 Function Documentation

4.23.1.1 IsBrightPressed()

4.23.1.2 IsDimPressed()

4.24 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/current_handler.c File Reference

```
#include <stdio.h>
#include "current_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

- uint16 t GetCurrent (void)
- CurrentRange_e GetCurrentRange (void)

Variables

- const uint16_t RawTodAmps = (1)
- const uint16 t dAmpsToRaw = (1)
- const uint16_t CurrentHighThreshold_dA = 35u
- const uint16 t CurrentErrorThreshold dA = 40u

4.24.1 Function Documentation

4.24.1.1 GetCurrent()

4.24.1.2 GetCurrentRange()

4.24.2 Variable Documentation

4.24.2.1 CurrentErrorThreshold_dA

```
const uint16_t CurrentErrorThreshold_dA = 40u
```

4.24.2.2 CurrentHighThreshold_dA

```
const uint16_t CurrentHighThreshold_dA = 35u
```

4.24.2.3 dAmpsToRaw

```
const uint16_t dAmpsToRaw = (1)
```

4.24.2.4 RawTodAmps

```
const uint16_t RawTodAmps = (1)
```

4.25 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/delay_handler.c File Reference

```
#include "delay_handler.h"
#include "stm321412xx-bsp.h"
```

Functions

- void StartDelayCounter (void)
- void RestartDelayCounter (void)
- uint8_t DelayHit (uint32_t delay_ms)
- uint16_t BrightnessDelay (int8_t brightness)

Variables

const float Tim2ClkKhz = (CLK_FREQ_HZ / (float)TIM2_CLK_DEV / (float)TIM2_CLK_PRESCALER / 1000.0f)

4.25.1 Function Documentation

4.25.1.1 BrightnessDelay()

4.25.1.2 DelayHit()

4.25.1.3 RestartDelayCounter()

```
\begin{tabular}{ll} \beg
```

4.25.1.4 StartDelayCounter()

4.25.2 Variable Documentation

4.25.2.1 Tim2ClkKhz

```
const float Tim2ClkKhz = (CLK_FREQ_HZ / (float)TIM2_CLK_DEV / (float)TIM2_CLK_PRESCALER /
1000.0f)
```

4.26 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/fram.c File Reference

This module contains routines to access the SPI FRAM. The FRAM used in the device is 32Kx8 with an operating frequency up to 20 MHz. It supports SPI Mode 0 & 3. The hardware supports the external Write Protect pin. The nature of this FRAM supports unlimited read/writes and data retention beyond the human life span.

```
#include <string.h>
#include "fram.h"
#include "stm321412xx-bsp.h"
#include "spi.h"
```

Macros

- #define TLEN (16)
- #define TADD (0x200)

Functions

- void framWriteProtect (WRITE PROTECT STATE state)
- void framChipSelect (CHIP_SELECT_STATE state)
- void framReadSr (unsigned char *srP)
- void framWriteSr (unsigned char sr)
- void framWriteDisable (void)
- void framWriteEnable (void)
- void framReadMemory (unsigned short addr, unsigned char *rdBufP, unsigned short len)
- void framWriteMemory (unsigned short addr, const unsigned char *const wrBufP, unsigned short len)
- uint8_t framTest (void)

4.26.1 Detailed Description

This module contains routines to access the SPI FRAM. The FRAM used in the device is 32Kx8 with an operating frequency up to 20 MHz. It supports SPI Mode 0 & 3. The hardware supports the external Write Protect pin. The nature of this FRAM supports unlimited read/writes and data retention beyond the human life span.

Attention

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Revision History: Date Name Ver Remarks

04/09/2023 Mark Lane 0 Original Version 06/10/2024 Austin Green 1 Add Logging 08/12/2024 Austin Green 1.2 Remove Mirror References

Notes:

4.26.2 Macro Definition Documentation

4.26.2.1 TADD

```
#define TADD (0x200)
```

4.26.2.2 TLEN

```
#define TLEN (16)
```

4.26.3 Function Documentation

4.26.3.1 framChipSelect()

This routine sets the chip select pin to the correct "state".

Parameters

in	state	assert = 0, release = 1
out	none	

4.26.3.2 framReadMemory()

```
void framReadMemory (
          unsigned short addr,
          unsigned char * rdBufP,
          unsigned short len)
```

This routine reads FRAM memory starting at "addr" for "len" byte(s). The FRAM read data is stored at the pointer referenced by "rdBufP".

Parameters

in	addr	FRAM memory address to read data
in	rdBufP	destination pointer to store read data
in	len	number of byte(s) to read
out	none	

4.26.3.3 framReadSr()

```
void framReadSr ( unsigned\ char\ *\ srP)
```

This routine reads the FRAM status register

Parameters

in	destination	pointer for FRAM status register
out	none	

4.26.3.4 framTest()

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

Parameters

out <i>pass</i>	= 1, fail = 0
-----------------	---------------

4.26.3.5 framWriteDisable()

This routine resets the write enable latch

Parameters

4.26.3.6 framWriteEnable()

```
void framWriteEnable (
     void )
```

This routine sets the write enable latch

Parameters

out	none	
-----	------	--

4.26.3.7 framWriteMemory()

```
void framWriteMemory (
          unsigned short addr,
          const unsigned char *const wrBufP,
          unsigned short len)
```

This routine writes FRAM memory starting at "addr" for "len" byte(s). The data referenced by the pointer "wrBufP" is written into FRAM memory.

Parameters

in	addr	FRAM memory address to write data
in	wrBufP	pointer to data to write
in	len	number of byte(s) to write
out	none	

4.26.3.8 framWriteProtect()

This routine sets the hardware write protect pin to the correct "state".

Parameters

_			
	in	state	disable = 0, enable = 1
	out.	none	

4.26.3.9 framWriteSr()

This routine writes the FRAM status register

Parameters

in	data	value written to FRAM status register
out	none	

4.27 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/logger.c File Reference

```
#include <string.h>
#include <stdio.h>
#include "logger.h"
#include "fram.h"
#include "stm321412xx-bsp.h"
```

Functions

- void LogString (const char *const string, uint8_t write_beginning)
- void LogNumber (const int32_t number, uint8_t write_beginning)
- void ReadLog (const uint32 t address, char *string, const uint32 t bytes)

4.27.1 Function Documentation

4.27.1.1 LogNumber()

4.27.1.2 LogString()

4.27.1.3 ReadLog()

4.28 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/main.c File Reference

```
#include "main.h"
#include "stm321412xx-bsp.h"
#include "pwm_handler.h"
#include "delay_handler.h"
#include "button_handler.h"
#include "current_handler.h"
#include "voltage_handler.h"
#include "my_printf.h"
```

Macros

- #define LOWER SWEEP TIME MS (3375)
- #define UPPER SWEEP TIME MS (4000)
- #define TOTAL_SWEEP_TIME_MS (7375)
- #define LOWER_STEP_TIME_MS (LOWER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
- #define UPPER_STEP_TIME_MS (UPPER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
- #define AVG_STEP_TIME_MS ((UPPER_STEP_TIME_MS + LOWER_STEP_TIME_MS) / 2.0f)
- #define AVG STEP DIFF MS (AVG STEP TIME MS LOWER STEP TIME MS)

Functions

- void SystemClock_Config (void)
 System Clock Configuration.
- int main (void)

The application entry point. Initialize variables and go into bare metal loop. Polls buttons and sensors.

Variables

- const float LowStepTimeMs = (LOWER_STEP_TIME_MS AVG_STEP_DIFF_MS)
- const float HighStepTimeMs = (UPPER_STEP_TIME_MS + AVG_STEP_DIFF_MS)

4.28.1 Macro Definition Documentation

```
4.28.1.1 AVG_STEP_DIFF_MS
```

```
#define AVG_STEP_DIFF_MS (AVG_STEP_TIME_MS - LOWER_STEP_TIME_MS)
```

4.28.1.2 AVG_STEP_TIME_MS

```
#define AVG_STEP_TIME_MS ((UPPER_STEP_TIME_MS + LOWER_STEP_TIME_MS) / 2.0f)
```

4.28.1.3 LOWER STEP TIME MS

```
#define LOWER_STEP_TIME_MS (LOWER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
```

4.28.1.4 LOWER_SWEEP_TIME_MS

```
#define LOWER_SWEEP_TIME_MS (3375)
```

4.28.1.5 TOTAL SWEEP TIME MS

```
#define TOTAL_SWEEP_TIME_MS (7375)
```

4.28.1.6 UPPER_STEP_TIME_MS

```
#define UPPER_STEP_TIME_MS (UPPER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
```

4.28.1.7 UPPER_SWEEP_TIME_MS

```
#define UPPER_SWEEP_TIME_MS (4000)
```

4.28.2 Function Documentation

4.28.2.1 main()

```
int main (
     void )
```

The application entry point. Initialize variables and go into bare metal loop. Polls buttons and sensors.

Return values

int

4.28.2.2 SystemClock_Config()

```
\begin{tabular}{ll} \beg
```

System Clock Configuration.

Return values

None

4.28.3 Variable Documentation

4.28.3.1 HighStepTimeMs

```
const float HighStepTimeMs = (UPPER_STEP_TIME_MS + AVG_STEP_DIFF_MS)
```

4.28.3.2 LowStepTimeMs

```
const float LowStepTimeMs = (LOWER_STEP_TIME_MS - AVG_STEP_DIFF_MS)
```

4.29 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/my_printf.c File Reference

4.30 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/pwm_handler.c File Reference

```
#include "pwm_handler.h"
#include "stm321412xx-bsp.h"
#include "temperature_handler.h"
#include "my_printf.h"
```

Macros

• #define PW_PERIOD (255)

Functions

- void InitPwm (void)
- void DecreaseBrightness (uint8_t button_held)
- · void IncreaseBrightness (uint8_t button_held)
- void SetPwm (void)
- void TurnOffPwm (void)
- int8_t GetBrightness (void)
- void SetBrightness (int8_t brightness)
- uint8_t GetPwm (void)

Variables

```
    const uint8_t MaxBrightness = (BRIGHTNESS_STEPS - 1)
    const uint8_t MinBrightness = (0)
    const uint8_t HalfBrightness = ((uint8_t)((BRIGHTNESS_STEPS - 1) / 2.0f))
    const float MinPw = (0)
    const float MaxPw = (PW_PERIOD)
    const float WarmPwmRatio = (0.90f)
    const float HotPwmRatio = (0.50f)
```

4.30.1 Macro Definition Documentation

4.30.1.1 PW_PERIOD

#define PW_PERIOD (255)

4.30.2 Function Documentation

4.30.2.1 DecreaseBrightness()

4.30.2.2 GetBrightness()

4.30.2.3 GetPwm()

4.30.2.4 IncreaseBrightness()

4.30.2.5 InitPwm()

```
void InitPwm (
     void )
```

4.30.2.6 SetBrightness()

4.30.2.7 SetPwm()

```
void SetPwm (
     void )
```

4.30.2.8 TurnOffPwm()

```
void TurnOffPwm (
     void )
```

4.30.3 Variable Documentation

4.30.3.1 HalfBrightness

```
const uint8_t HalfBrightness = ((uint8_t)((BRIGHTNESS_STEPS - 1) / 2.0f))
```

4.30.3.2 HotPwmRatio

```
const float HotPwmRatio = (0.50f)
```

4.30.3.3 MaxBrightness

```
const uint8_t MaxBrightness = (BRIGHTNESS_STEPS - 1)
```

4.30.3.4 MaxPw

```
const float MaxPw = (PW_PERIOD)
```

4.30.3.5 MinBrightness

```
const uint8_t MinBrightness = (0)
```

4.30.3.6 MinPw

```
const float MinPw = (0)
```

4.30.3.7 WarmPwmRatio

const float WarmPwmRatio = (0.90f)

4.31 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/stm32l412xx-bsp.c File Reference

```
#include "stm321412xx-bsp.h"
```

Functions

- GPIO PinState ReadDimPin (void)
- GPIO_PinState ReadBrightPin (void)
- void EnablePWM1 (void)
- void DisablePWM1 (void)
- void StartPWM11 (void)
- void StopPWM11 (void)
- void SetPW11 (uint32_t pulse_width)
- void StartTIM2 (void)
- void RestartTIM2 (void)
- uint32_t GetTIM2Cnt (void)
- int16_t GetThermistorValue (void)
- int16_t GetCurrentValue (void)
- int16_t GetVoltageValue (void)
- void enableWriteProtect (void)
- · void disableWriteProtect (void)
- void enableChipSelect (void)
- void disableChipSelect (void)
- void transferData (const unsigned char *const txData, const uint32_t bytes)
- void receiveData (unsigned char *rxData, const uint32_t bytes)
- void sendUARTChar (char c)

• void Error_Handler (void)

This function is executed in case of error occurrence.

4.31.1 Function Documentation

4.31.1.1 disableChipSelect()

```
\begin{tabular}{ll} \begin{tabular}{ll} void \ disable Chip Select \ ( \\ void \ ) \end{tabular}
```

4.31.1.2 DisablePWM1()

```
void DisablePWM1 (
     void )
```

4.31.1.3 disableWriteProtect()

```
void disableWriteProtect ( \label{eq:void} \mbox{void} \mbox{ } \mbox{)}
```

4.31.1.4 enableChipSelect()

4.31.1.5 EnablePWM1()

```
void EnablePWM1 (
     void )
```

4.31.1.6 enableWriteProtect()

4.31.1.7 Error_Handler()

```
void Error_Handler (
     void )
```

This function is executed in case of error occurrence.

Return values

None

4.31.1.8 GetCurrentValue()

4.31.1.9 GetThermistorValue()

4.31.1.10 GetTIM2Cnt()

```
4.31.1.11 GetVoltageValue()
```

4.31.1.12 ReadBrightPin()

4.31.1.13 ReadDimPin()

4.31.1.14 receiveData()

```
void receiveData (
          unsigned char * rxData,
          const uint32_t bytes)
```

4.31.1.15 RestartTIM2()

```
void RestartTIM2 (
     void )
```

4.31.1.16 sendUARTChar()

```
void sendUARTChar ( {\tt char} \ c)
```

4.31.1.17 SetPW11()

4.31.1.18 StartPWM11()

```
void StartPWM11 (
     void )
```

4.31.1.19 StartTIM2()

```
void StartTIM2 (
     void )
```

4.31.1.20 StopPWM11()

```
void StopPWM11 (
     void )
```

4.31.1.21 transferData()

4.32 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/temperature_handler.c File Reference

```
#include <string.h>
#include "temperature_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

- int32_t GetTemperature (void)
- TemperatureRange_e GetTemperatureRange (void)

Variables

```
• const int32_t ThermistorTodCelcius = (1)
```

- const int32 t dCelciusToThermistor = (1)
- const int32_t HeatingThreshold1_dC = (1000)
- const int32 t HeatingThreshold2 dC = (1200)
- const int32_t CoolingThreshold1_dC = (800)
- const int32_t CoolingThreshold2_dC = (1000)

4.32.1 Function Documentation

4.32.1.1 GetTemperature()

4.32.1.2 GetTemperatureRange()

4.32.2 Variable Documentation

4.32.2.1 CoolingThreshold1_dC

```
const int32_t CoolingThreshold1_dC = (800)
```

4.32.2.2 CoolingThreshold2_dC

```
const int32_t CoolingThreshold2_dC = (1000)
```

4.32.2.3 dCelciusToThermistor

```
const int32_t dCelciusToThermistor = (1)
```

4.32.2.4 HeatingThreshold1_dC

```
const int32_t HeatingThreshold1_dC = (1000)
```

4.32.2.5 HeatingThreshold2_dC

```
const int32_t HeatingThreshold2_dC = (1200)
```

4.32.2.6 ThermistorTodCelcius

```
const int32_t ThermistorTodCelcius = (1)
```

C:/Users/agreen/Documents/Projects/Aveo/CH-53K LED ← 4.33 Controller/Core/Src/voltage handler.c File Reference

```
#include <stdio.h>
#include "voltage_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

- uint16_t GetVoltage (void)
- VoltageRange_e GetVoltageRange (void)

Variables

- const uint16 t RawTodColts = (1)
- const uint16 t dColtsToRaw = (1)
- const uint16_t VoltageErrorLowThreshold_dV = 240u
- const uint16 t VoltageLowThreshold dV = 260u
- const uint16_t VoltageHighThreshold_dV = 300u
- const uint16_t VoltageErrorHighThreshold_dV = 320u

4.33.1 Function Documentation

4.33.1.1 GetVoltage()

```
uint16_t GetVoltage (
             void )
```

4.33.1.2 GetVoltageRange()

```
VoltageRange_e GetVoltageRange (
             void )
```

4.33.2 Variable Documentation

4.33.2.1 dColtsToRaw

```
const uint16_t dColtsToRaw = (1)
```

4.33.2.2 RawTodColts

```
const uint16_t RawTodColts = (1)
```

4.33.2.3 VoltageErrorHighThreshold_dV

```
const uint16_t VoltageErrorHighThreshold_dV = 320u
```

4.33.2.4 VoltageErrorLowThreshold_dV

```
const uint16_t VoltageErrorLowThreshold_dV = 240u
```

4.33.2.5 VoltageHighThreshold_dV

```
const uint16_t VoltageHighThreshold_dV = 300u
```

4.33.2.6 VoltageLowThreshold_dV

```
const uint16_t VoltageLowThreshold_dV = 260u
```

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