CH-53K 1.0.0

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Chapter 1

Data Structure Index

1.1 Data Structures

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Chapter 2

File Index

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| C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/delay_handler.h | 10 |
| C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/fram.h | 12 |
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Chapter 3

Data Structure Documentation

3.1 PwmStruct Struct Reference

```
#include <stm321412xx-bsp.h>
```

Data Fields

- uint8_t is_running
- uint32_t pulse_width

3.1.1 Detailed Description

Testing PWM Struct

3.1.2 Field Documentation

3.1.2.1 is_running

uint8_t is_running

pwm is running

3.1.2.2 pulse_width

uint32_t pulse_width

pulse width value

The documentation for this struct was generated from the following file:

• C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/stm32l412xx-bsp.h

3.2 TimerStruct Struct Reference

```
#include <stm321412xx-bsp.h>
```

Data Fields

- uint8_t is_running
- uint32_t time

3.2.1 Detailed Description

Testing Timer Struct

3.2.2 Field Documentation

3.2.2.1 is_running

uint8_t is_running

timer is running

3.2.2.2 time

uint32_t time

timer value

The documentation for this struct was generated from the following file:

 $\bullet \ \ C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Inc/stm32l412xx-bsp.h$

Chapter 4

File Documentation

4.1 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_

Controller/Core/Inc/button_handler.h File Reference

```
#include <stdint.h>
#include "stm321412xx-bsp.h"
```

Functions

• GPIO_PinState IsDimPressed (void)

Return state of dim button.

GPIO_PinState IsBrightPressed (void)

Return state of brighten button.

4.1.1 Function Documentation

4.1.1.1 IsBrightPressed()

Return state of brighten button.

Parameters

| out Bright Pin State, pressed or not |
|--------------------------------------|
|--------------------------------------|

4.1.1.2 IsDimPressed()

Return state of dim button.

Parameters

| out Din | Pin State, pressed or not |
|----------------|---------------------------|
|----------------|---------------------------|

4.2 button_handler.h

```
Go to the documentation of this file.
```

```
00001 /**************
00003
00004
     * Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 \,\star\, Any use without the prior written consent of Luminator Mark IV
00007 * is strictly prohibited.
00008 *
00009
00011
00012 * @file button_handler.h
00013 *
00014 * @brief Returns the button state of the three board buttons
00015 *
00016 * Revision History:
00017 * Date - Name - Ver - Remarks

00018 * 07/31/2024 - Austin Green - 1.0 - Initial Document

00019 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00020 *
00021 * Notes: Depends on the board support package bsp for GPIO_PinState
00022
00024
00025 #ifndef INC_button_handlerh
00026
         #define INC_button_handlerh
00027
00028
         #include <stdint.h>
00029
        #include "stm321412xx-bsp.h"
00030
00031
00036
         GPIO_PinState IsDimPressed ( void );
00037
00042
         GPIO_PinState IsBrightPressed ( void );
00043
00044 #endif /* INC_button_handlerh */
```

4.3 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/current_handler.h File Reference

```
#include <stdint.h>
```

Enumerations

enum CurrentRange_e { CurrentNormal = 0 , CurrentHigh = 1 , CurrentError = 2 }

Functions

• uint16_t GetCurrent (void)

Get current from ammeter.

• CurrentRange_e GetCurrentRange (void)

Get range that the current falls into Possible ranges are Normal - Normal Operating Current High - Current high, but ok Error - Current too high.

4.3.1 Enumeration Type Documentation

4.3.1.1 CurrentRange_e

```
enum CurrentRange_e
```

Current Range Enum

Enumerator

| CurrentNormal | Normal Operating Current |
|---------------|--------------------------|
| CurrentHigh | Current high, but ok |
| CurrentError | Current too high |

4.3.2 Function Documentation

4.3.2.1 GetCurrent()

Get current from ammeter.

Parameters

| out | current | level in dA |
|-----|---------|-------------|

4.3.2.2 GetCurrentRange()

Get range that the current falls into Possible ranges are Normal - Normal Operating Current High - Current high, but ok Error - Current too high.

Parameters

| out | Current | current range |
|-----|---------|---------------|

4.4 current handler.h

```
Go to the documentation of this file.
```

```
00002
00003
          @attention
00004 * Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 \,\star\, Any use without the prior written consent of Luminator Mark IV
00007 \star is strictly prohibited.
00008 *
00009
00012
       * @file current_handler.h
00013
00014 \star @brief Handles getting current and reporting values.
00015 *
00016
      * Revision History:

      00017 * Date
      - Name
      - Ver - Remarks

      00018 * 08/05/2024 - Austin Green - 1.0 - Initial Document

      00019 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation

00020 *
00021 * Notes:
00022 *
00023
       *******************************
00024
00025 #ifndef INC_current_handlerh
00026
         #define INC_current_handlerh
00027
00028
          #include <stdint.h>
00029
00031
          typedef enum
00032
00033
              CurrentNormal = 0,
00034
              CurrentHigh
00035
              CurrentError
00036
         } CurrentRange_e;
00037
00043
          uint16_t GetCurrent( void );
00044
          CurrentRange_e GetCurrentRange( void );
00053
00054
00055 #endif /* INC_current_handlerh */
```

4.5 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/delay_handler.h File Reference

#include <stdint.h>

Functions

· void StartDelayCounter (void)

Starts the delay counter, only needs to be called once on init.

void RestartDelayCounter (void)

Restart the delay counter.

• uint8_t DelayHit (uint32_t delay_ms)

Checks if the delay (ms) was hit based on timer value.

• uint16_t BrightnessDelay (int8_t brightness)

Returns a delay value for a brightness level.

4.5.1 Function Documentation

4.5.1.1 BrightnessDelay()

Returns a delay value for a brightness level.

Parameters

| in | brightness | Current brightness level |
|-----|------------|--|
| out | Returns | delay to satisfy specs at current brightness level |

4.5.1.2 DelayHit()

Checks if the delay (ms) was hit based on timer value.

Parameters

| in | delay_ms | Time in ms to check if timer has hit |
|-----|----------|--------------------------------------|
| out | Returns | 1 if delay has been hit |

4.5.1.3 RestartDelayCounter()

```
\begin{tabular}{ll} \beg
```

Restart the delay counter.

4.5.1.4 StartDelayCounter()

Starts the delay counter, only needs to be called once on init.

4.6 delay_handler.h

Go to the documentation of this file.

```
00001 /**
00002
         @attention
00004 * Copyright © 2007 Luminator Mark IV
00005 \star All rights reserved. 00006 \star Any use without the prior written consent of Luminator Mark IV
00007 \star is strictly prohibited.
00008 *
00009
00011
00012 * @file delay_handler.h
00013
00014
      * @brief Handles system counters and delays
00015
00016
     * Revision History:
00017 * Date - Name - Ver - Remarks

00018 * 07/31/2024 - Austin Green - 1.0 - Initial Document

00019 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00020 *
00021 * Notes:
00022
00023
     00024
00025 /* Define to prevent recursive inclusion -----*/
00026 #ifndef INC_delay_handlerh
00027
         #define INC_delay_handlerh
00029
       #include <stdint.h>
00030
00034 void
             StartDelayCounter(void);
                                       // start the counter
00035
00039
      void
              RestartDelayCounter(void);
      uint8_t DelayHit(uint32_t delay_ms);
00046
00052
       uint16_t BrightnessDelay(int8_t brightness);
00053
00054 #endif /* INC delay handlerh */
```

4.7 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/fram.h File Reference

```
#include "stm321412xx-bsp.h"
```

Enumerations

```
    enum OPCODE_COMMANDS {
        OC_WREN = 6, OC_WRDI = 4, OC_RDSR = 5, OC_WRSR = 1,
        OC_READ = 3, OC_WRITE = 2 }

    enum STATUS_REGISTER { SR_WEL = 0x2, SR_BP0 = 0x4, SR_BP1 = 0x8, SR_WPEN = 0x80 }

    enum WRITE_PROTECT_STATE { WPS_PROTECTED = 0, WPS_WRITEABLE = 1 }

    enum CHIP_SELECT_STATE { CSS_ASSERT = 0, CSS_RELEASE = 1 }
```

Functions

- void framWriteProtect (WRITE_PROTECT_STATE state)
- void framChipSelect (CHIP_SELECT_STATE state)
- void framReadSr (unsigned char *srP)
- void framWriteSr (unsigned char sr)
- void framWriteDisable (void)

This routine resets the write enable latch.

• void framWriteEnable (void)

This routine resets the write enable latch.

- void framReadMemory (unsigned short addr, unsigned char *rdBufP, unsigned short len)
- · void framWriteMemory (unsigned short addr, const unsigned char *const wrBufP, unsigned short len)
- uint8_t framTest (void)

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

4.7.1 Enumeration Type Documentation

4.7.1.1 CHIP_SELECT_STATE

enum CHIP_SELECT_STATE

chip select state

Enumerator

| CSS_ASSERT | chip select disabled |
|-------------|----------------------|
| CSS_RELEASE | chip select enabled |

4.7.1.2 OPCODE_COMMANDS

enum OPCODE_COMMANDS

opcode command

Enumerator

| OC_WREN | set write enable latch |
|----------|------------------------|
| OC_WRDI | write disable |
| OC_RDSR | read status register |
| OC_WRSR | write status register |
| OC_READ | read memory data |
| OC_WRITE | write memory data |
| | |

4.7.1.3 STATUS REGISTER

enum STATUS_REGISTER

status register

Enumerator

| SR_WEL | write-enable latch |
|---------|--------------------------|
| SR_BP0 | block protect bit 0 |
| SR_BP1 | block protect bit 1 |
| SR_WPEN | enable write protect pin |

4.7.1.4 WRITE_PROTECT_STATE

```
enum WRITE_PROTECT_STATE
```

write protect state

Enumerator

| WPS_PROTECTED | write protected |
|---------------|-----------------|
| WPS_WRITEABLE | write enabled |

4.7.2 Function Documentation

4.7.2.1 framChipSelect()

4.7.2.2 framReadMemory()

```
void framReadMemory (
          unsigned short addr,
          unsigned char * rdBufP,
          unsigned short len)
```

4.7.2.3 framReadSr()

```
void framReadSr ( \label{eq:unsigned} \mbox{unsigned char } * \mbox{\it srP})
```

4.7.2.4 framTest()

```
uint8_t framTest (
     void )
```

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

Parameters

| out 1 | = pass, 0 = fail |
|-------|------------------|
|-------|------------------|

4.7.2.5 framWriteDisable()

```
void framWriteDisable (
            void )
```

This routine resets the write enable latch.

Parameters

```
out none
```

4.7.2.6 framWriteEnable()

```
void framWriteEnable (
            void )
```

This routine resets the write enable latch.

Parameters

```
out none
```

4.7.2.7 framWriteMemory()

```
void framWriteMemory (
           unsigned short addr,
            const unsigned char *const wrBufP,
            unsigned short len)
```

4.7.2.8 framWriteProtect()

```
void framWriteProtect (
            WRITE_PROTECT_STATE state)
```

4.7.2.9 framWriteSr()

```
void framWriteSr (
          unsigned char sr)
```

4.8 fram.h

00170

00181 uint8_t framTest(void);

```
Go to the documentation of this file.
00002
00003 * @attention
00004 * Copyright (c) 2022, 2023 Luminator, An LTG Company
00005 * All rights reserved.
00006 * Any use without the prior written consent of Luminator,
00007 \,\,\star\,\, An LTG Company is strictly prohibited.
00008 *
00009 *************************
00011 *
00012 * @file fram.h
00013 *
00014 \star @brief This module contains definitions and structures to support 00015 \star fram.c SPI FRAM operations
00016 *
00017 * Revision History:
00018 *
        Date
                   Name
                                  Ver
                                         Remarks
00019 *
                                 0
         04/09/2023 Mark Lane
00020 *
                                         Original Version
00021 *
00022 *
        09/10/2024 - Austin Green - 2.0 -
                                         Doxyfile documentation
00023 * Notes:
00024
00026 #ifndef _FRAM_H_
00027 #define _FRAM_H_
00028
00029 #include "stm321412xx-bsp.h"
00030
00031 /* ------ Local Definition(s) ----- */
00035 typedef enum {
00036
00037
      OC\_WREN = 6,
00038
      OC_WRDI = 4,
00039
      OC_RDSR
             = 1 ,
00040
      OC_WRSR
      OC_READ = 3 ,
OC WRITE = 2 ,
00041
00042
00044 } OPCODE_COMMANDS ;
00045
00046
00050 typedef enum {
00051
00052
      SR\_WEL = 0x2 ,
      SR_BP0 = 0x4

SR_BP1 = 0x8
00053
00054
00055
      SR\_WPEN = 0x80
00057 } STATUS_REGISTER ;
00058
00059
00063 typedef enum {
00064
00065
      WPS\_PROTECTED = 0,
00066 WPS_WRITEABLE = 1 ,
00068 } WRITE_PROTECT_STATE ;
00069
00070
00074 typedef enum {
00076
      CSS\_ASSERT = 0,
00079 } CHIP_SELECT_STATE ;
08000
00081 /* Prototype Definition */
00091 void framWriteProtect( WRITE_PROTECT_STATE state );
00092
00101 void framChipSelect ( CHIP_SELECT_STATE state );
00102
00111 void framReadSr( unsigned char *srP);
00112
00121 void framWriteSr( unsigned char sr );
00122
00129 void framWriteDisable( void );
00130
00137 void framWriteEnable( void ) ;
00138
00153 void framReadMemory ( unsigned short addr, unsigned char *rdBufP, unsigned short len ) ;
```

00169 void framWriteMemory(unsigned short addr, const unsigned char* const wrBufP, unsigned short len);

```
00182
00183
00184 #endif
```

4.9 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/logger.h File Reference

```
#include <stdint.h>
```

Functions

void LogString (const char *const string, uint8 t write beginning)

Log a string to tail_pointer, use write_beginning flag to write the beginning.

void LogNumber (const int32_t number, uint8_t write_beginning)

Logs a number by converting the number to a string and using the LogString function.

void ReadLog (const uint32 t address, char *string, const uint32 t bytes)

Reads the log at a given address and size.

4.9.1 Function Documentation

4.9.1.1 LogNumber()

Logs a number by converting the number to a string and using the LogString function.

Parameters

| in | number | Number to log |
|----|-----------------|--|
| in | write_beginning | Write log at the beginning of log area |

4.9.1.2 LogString()

Log a string to tail_pointer, use write_beginning flag to write the beginning.

Parameters

| in | string | Pointer to string to log |
|----|-----------------|--|
| in | write_beginning | Write log at the beginning of log area |

4.9.1.3 ReadLog()

Reads the log at a given address and size.

4.10 logger.h 19

Parameters

| in | address | Address to read from | |
|----|---------|-------------------------------|--|
| in | string | Pointer to return data string | |
| in | bytes | Number of bytes to read | |

4.10 logger.h

Go to the documentation of this file.

```
00001
00002
00003 * @attention
00004 * Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 * Any use without the prior written consent of Luminator Mark IV 00007 * is strictly prohibited.
00008 *
00009 *****************************
00011
00012
      * @file logger.h
00013
00014 \,\star\, @brief Handles logging and reading of data to memory
00015 *
00016 * Revision History:
00017 * Date - Name
                                 - Ver - Remarks
00018 * 07/31/2024 - Austin Green - 1.0 - Initial Document

00019 * 08/05/2024 - Austin Green - 1.1 - Added Log Number

00020 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00021
00022 * Notes:
00023
00025
00026 #ifndef INC_loggerh
00027
       #define INC_loggerh
00028
00029
       #include <stdint.h>
00030
00031
00037
       void LogString( const char* const string, uint8_t write_beginning );
00038
00044
       void LogNumber( const int32_t number, uint8_t write_beginning );
00045
00052
       void ReadLog( const uint32_t address, char* string, const uint32_t bytes );
00053
00054 #endif /* INC_loggerh */
```

4.11 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/main.h File Reference

```
#include "stm321412xx-bsp.h"
```

Functions

void Error_Handler (void)

This function is executed in case of error occurrence.

4.11.1 Function Documentation

4.11.1.1 Error_Handler()

```
void Error_Handler (
     void )
```

This function is executed in case of error occurrence.

Return values

None

4.12 main.h

Go to the documentation of this file.

```
00001 /* USER CODE BEGIN Header */
00002 /***
       ******************
00003
                 : main.h
: Header for main.c file.
00004
        * @file
00005
        * @brief
00006
                        This file contains the common defines of the application.
00007
80000
       * @attention
00009
00010
       * Copyright (c) 2024 STMicroelectronics.
       * All rights reserved.
00011
00012
00013
       \star This software is licensed under terms that can be found in the LICENSE file
00014
       * in the root directory of this software component.
00015
        * If no LICENSE file comes with this software, it is provided AS-IS.
00016
00017
        *******************
00018
00019 /* USER CODE END Header */
00020
00021 /* Define to prevent recursive inclusion ------*/
00022 #ifndef INC_mainh
00023 #define INC_mainh
00024
00025
        #ifdef __cplusplus
00026
           extern "C"
00027
       #endif
00028
        /* Includes -----*/
00029
00030
00031
        /* Private includes --
00032
        /* USER CODE BEGIN Includes */
00033
        #include "stm321412xx-bsp.h"
00034
00035
        /* USER CODE END Includes */
00036
00037
        /* Exported types ----
00038
        /* USER CODE BEGIN ET */
00039
00040
        /* USER CODE END ET */
00041
00042
        /* Exported constants -----*/
00043
        /* USER CODE BEGIN EC */
00044
00045
        /* USER CODE END EC */
00046
00047
        /* Exported macro -----
00048
        /* USER CODE BEGIN EM */
00049
00050
        /* USER CODE END EM */
00051
00052
        /* Exported functions prototypes -----*/
00053
        void Error_Handler(void);
00054
00055
        /* USER CODE BEGIN EFP */
00056
00057
        /* USER CODE END EFP */
```

```
00058
00059
        /* Private defines -----*/
00060
       /* USER CODE BEGIN Private defines */
00061
00062
00063
       /* USER CODE END Private defines */
00064
00065
       #ifdef __cplusplus
00066
       #endif
00067
00068
00069 #endif /* INC_mainh */
```

4.13 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/my_printf.h File Reference

4.14 my printf.h

```
Go to the documentation of this file.
```

```
00002
00003 * @attention
000003 * @attention
00004 * Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 * Any use without the prior written consent of Luminator Mark IV
00007 * is strictly prohibited.
00008 *
00011 *
00012 * @file my_printf.h
00013
00013 *
00014 * @brief Prints characters to a terminal for debugging purposes
00015 *
00016 * Revision History:
00017 * Date - Name - Ver - Remarks
00018 * 07/31/2024 - Austin Green - 1.0 - Initial Document
00019 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00020 *
00021 * Notes:
00022 *
00024
00025 // Software tracing with printf()
00026 #ifndef INC_my_printfh
00027 #define INC_my_printfh
00028
00029 #ifdef ENABLE_UART_DEBUGGING /* tracing enabled */
00030 #include <stdio.h>
00031 #endif /* ENABLE_UART_DEBUGGING */
00032
00033 \#endif /* INC_my_printfh */
```

4.15 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Inc/pwm_handler.h File Reference

```
#include <stdint.h>
```

Macros

- #define BRIGHTNESS_STEPS (50)
- #define HOLD BRIGHTNESS JUMP (3)

Functions

· void InitPwm (void)

Init PwmArray var Set brightness to half value, enable pwm, and turn off.

void DecreaseBrightness (uint8_t button_held)

Decrease brightness by 1 (for button press) or 3 (for button hold) This functions can be made to increase brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

• void IncreaseBrightness (uint8_t button_held)

Increase brightness by 1 (for button press) or 3 (for button hold) This functions can be made to decrease brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

void SetPwm (void)

set PWM based on pwm value

• void TurnOffPwm (void)

turn off PWM

int8_t GetBrightness (void)

Return ledBrightness variable.

void SetBrightness (int8_t brightness)

Set ledBrightness variable, guards to ensure we don't go over max or min.

uint8 t GetPwm (void)

Get the PWM value based on the brightness and the temperature range.

4.15.1 Macro Definition Documentation

4.15.1.1 BRIGHTNESS STEPS

```
#define BRIGHTNESS_STEPS (50)
```

4.15.1.2 HOLD_BRIGHTNESS_JUMP

```
#define HOLD_BRIGHTNESS_JUMP (3)
```

4.15.2 Function Documentation

4.15.2.1 DecreaseBrightness()

Decrease brightness by 1 (for button press) or 3 (for button hold) This functions can be made to increase brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

Parameters

| in | button_held | If the button is being held (decrements by 3 if so) |
|----|-------------|---|

4.15.2.2 GetBrightness()

```
int8_t GetBrightness (
     void )
```

Return ledBrightness variable.

Parameters

| out Current LED brightness level | s level |
|----------------------------------|---------|
|----------------------------------|---------|

4.15.2.3 GetPwm()

Get the PWM value based on the brightness and the temperature range.

Parameters

| out | Current | PWM value | |
|-----|---------|-----------|--|
|-----|---------|-----------|--|

4.15.2.4 IncreaseBrightness()

Increase brightness by 1 (for button press) or 3 (for button hold) This functions can be made to decrease brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

Parameters

| i | n | button_held | If the button is being held (increments by 3 if so) |
|---|---|-------------|---|
|---|---|-------------|---|

4.15.2.5 InitPwm()

```
void InitPwm (
     void )
```

Init PwmArray var Set brightness to half value, enable pwm, and turn off.

4.15.2.6 SetBrightness()

Set ledBrightness variable, guards to ensure we don't go over max or min.

Parameters

| in | brightness | Brightess to set |
|----|------------|------------------|
| | | |

4.15.2.7 SetPwm()

```
void SetPwm (
     void )
```

set PWM based on pwm value

4.15.2.8 TurnOffPwm()

```
void TurnOffPwm (
     void )
```

turn off PWM

4.16 pwm handler.h

Go to the documentation of this file.

```
00001 /**************
00002
00003 *
         @attention
00004 * Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 \,\star\, Any use without the prior written consent of Luminator Mark IV
00007 \star is strictly prohibited.
00008 *
00009
00011
00012 * @file pwm_handler.h
00013 *
00014 \,\, & Obrief Handles the PWM output of the lights. Output is determined by a
00015 *
                 Brightness variable that is controlled by this file.
00016 *
00017 * Revision History:
00018 * Date - Name - Ver - Remarks

00019 * 07/31/2024 - Austin Green - 1.0 - Initial Document

00020 * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00021 *
00022 * Notes:
00023
00025
00026 #ifndef INC_pwm_handlerh
00027
         #define INC_pwm_handlerh
00028
         #include <stdint.h>
00030
         /* Brightness Steps */
00031
         #define BRIGHTNESS_STEPS
00032
00033
         #define HOLD_BRIGHTNESS_JUMP
00034
00039
       void
               InitPwm(void);
                                                           // Init Pwm var
00040
00048
       void
              DecreaseBrightness( uint8_t button_held ); // decrease brightness
00049
       void IncreaseBrightness( uint8_t button_held ); // increase brightness
00057
00058
00062
       void SetPwm( void );
                                                           // turn on and set PWM
00063
00067
       void TurnOffPwm( void );
                                                           // turn of PWM
00068
       int8_t GetBrightness( void );
00073
                                                           // get value of Brightness
00074
00079
             SetBrightness( int8_t brightness);
       void
                                                           // set value of Brightness
08000
00085
       uint8_t GetPwm( void );
                                                           // get value of current PWM
00086
00087 #endif /* INC_pwm_handlerh */
```

4.17 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/stm32l412xx-bsp.h File Reference

#include <stdint.h>

Data Structures

- struct PwmStruct
- struct TimerStruct

Macros

- #define THERMISTOR ADC Pin 0
- #define THERMISTOR ADC GPIO Port 0
- #define BRIGHT Pin 0
- #define BRIGHT GPIO Port 0
- #define DIM_Pin 0
- #define DIM GPIO Port 0
- #define EEPROM SCK Pin 0
- #define EEPROM SCK GPIO Port 0
- #define EEPROM MISO Pin 0
- #define EEPROM MISO GPIO Port 0
- #define EEPROM_MOSI_Pin 0
- #define EEPROM_MOSI_GPIO_Port 0
- #define VOLTMETER ADC Pin 0
- #define VOLTMETER ADC GPIO Port 0
- #define AMPMETER ADC Pin 0
- #define AMPMETER ADC GPIO Port 0
- #define PWM_OUT_Pin 0
- #define PWM OUT GPIO Port 0
- #define SPI_WP_Pin 0
- #define SPI WP GPIO Port 0
- #define SPI NSS Pin 0
- #define SPI NSS GPIO Port 0
- #define NVIC_PRIORITYGROUP_0 ((uint32_t)0x00000007)
- #define NVIC_PRIORITYGROUP_1 ((uint32_t)0x00000006)
- #define NVIC_PRIORITYGROUP_2 ((uint32_t)0x00000005)
- #define NVIC_PRIORITYGROUP_3 ((uint32_t)0x00000004)
- #define NVIC PRIORITYGROUP 4 ((uint32 t)0x00000003)
- #define CLK FREQ HZ (8000000)
- #define TIM2_CLK_DEV (1)
- #define TIM2_CLK_PRESCALER (8000)

Typedefs

• typedef uint8 t GPIO PinState

Enumerations

- enum { BUTTON PRESSED = 1 , BUTTON UNPRESSED = 0 }
- enum { PIN_SET = 1 , PIN_RESET = 0 }

Functions

• GPIO_PinState ReadDimPin (void)

Reads dim pin value.

• GPIO PinState ReadBrightPin (void)

Reads bright pin value.

void EnablePWM1 (void)

Enables Timer 1.

void DisablePWM1 (void)

Disables Timer 1.

void StartPWM11 (void)

Starts PWM Timer 1 Channel 1 output.

void StopPWM11 (void)

Stops PWM Timer 1 Channel 1 output.

void SetPW11 (uint32 t pulse width)

Sets PWM Timer 1 Channel 1 value.

void StartTIM2 (void)

Starts Timer 2 counter.

void RestartTIM2 (void)

Resets Timer 2 counter to zero.

• uint32 t GetTIM2Cnt (void)

Returns value in the Timer 2 counter.

• int16 t GetThermistorValue (void)

Returns raw ADC value from thermistor.

int16_t GetCurrentValue (void)

Returns raw ADC value from ammeter.

int16_t GetVoltageValue (void)

Returns raw ADC value from voltmeter.

void enableWriteProtect (void)

Enables SPI write protect line (active high)

void disableWriteProtect (void)

Disables SPI write protect line (active high)

void enableChipSelect (void)

Enables SPI chip select line (active low)

void disableChipSelect (void)

Disables SPI chip select line (active low)

void transferData (const unsigned char *const txData, const uint32 t bytes)

Sends data via SPI lines.

• void receiveData (unsigned char *rxData, const uint32 t bytes)

Gets data from SPI lines.

• void sendUARTChar (char c)

Sends character via UART line.

void Error_Handler (void)

This function is executed in case of error occurrence.

4.17.1 Macro Definition Documentation

4.17.1.1 AMPMETER_ADC_GPIO_Port

#define AMPMETER_ADC_GPIO_Port 0

4.17.1.2 AMPMETER_ADC_Pin

#define AMPMETER_ADC_Pin 0

4.17.1.3 BRIGHT_GPIO_Port

#define BRIGHT_GPIO_Port 0

4.17.1.4 BRIGHT_Pin

#define BRIGHT_Pin 0

4.17.1.5 CLK_FREQ_HZ

#define CLK_FREQ_HZ (8000000)

4.17.1.6 DIM_GPIO_Port

#define DIM_GPIO_Port 0

4.17.1.7 DIM_Pin

#define DIM_Pin 0

4.17.1.8 EEPROM_MISO_GPIO_Port

#define EEPROM_MISO_GPIO_Port 0

4.17.1.9 EEPROM_MISO_Pin

#define EEPROM_MISO_Pin 0

4.17.1.10 EEPROM_MOSI_GPIO_Port

#define EEPROM_MOSI_GPIO_Port 0

4.17.1.11 EEPROM_MOSI_Pin

 ${\tt \#define~EEPROM_MOSI_Pin~0}$

4.17.1.12 EEPROM_SCK_GPIO_Port

#define EEPROM_SCK_GPIO_Port 0

4.17.1.13 EEPROM_SCK_Pin

#define EEPROM_SCK_Pin 0

4.17.1.14 NVIC_PRIORITYGROUP_0

```
#define NVIC_PRIORITYGROUP_0 ((uint32_t)0x00000007)
```

0 bit for pre-emption priority, 4 bits for subpriority

4.17.1.15 NVIC_PRIORITYGROUP_1

```
#define NVIC_PRIORITYGROUP_1 ((uint32_t)0x00000006)
```

1 bit for pre-emption priority, 3 bits for subpriority

4.17.1.16 NVIC PRIORITYGROUP 2

```
#define NVIC_PRIORITYGROUP_2 ((uint32_t)0x00000005)
```

2 bits for pre-emption priority, 2 bits for subpriority

4.17.1.17 NVIC_PRIORITYGROUP_3

```
#define NVIC_PRIORITYGROUP_3 ((uint32_t)0x0000004)
```

3 bits for pre-emption priority, 1 bit for subpriority

4.17.1.18 NVIC PRIORITYGROUP 4

```
#define NVIC_PRIORITYGROUP_4 ((uint32_t)0x00000003)
```

4 bits for pre-emption priority, 0 bit for subpriority

4.17.1.19 PWM_OUT_GPIO_Port

#define PWM_OUT_GPIO_Port 0

4.17.1.20 PWM_OUT_Pin

#define PWM_OUT_Pin 0

4.17.1.21 SPI_NSS_GPIO_Port

#define SPI_NSS_GPIO_Port 0

4.17.1.22 SPI NSS Pin

#define SPI_NSS_Pin 0

4.17.1.23 SPI_WP_GPIO_Port

#define SPI_WP_GPIO_Port 0

4.17.1.24 SPI_WP_Pin

#define SPI_WP_Pin 0

4.17.1.25 THERMISTOR_ADC_GPIO_Port

#define THERMISTOR_ADC_GPIO_Port 0

4.17.1.26 THERMISTOR_ADC_Pin

#define THERMISTOR_ADC_Pin 0

4.17.1.27 TIM2_CLK_DEV

#define TIM2_CLK_DEV (1)

4.17.1.28 TIM2_CLK_PRESCALER

#define TIM2_CLK_PRESCALER (8000)

4.17.1.29 VOLTMETER_ADC_GPIO_Port

 $\verb|#define VOLTMETER_ADC_GPIO_Port 0|\\$

4.17.1.30 VOLTMETER_ADC_Pin

```
#define VOLTMETER_ADC_Pin 0
```

4.17.2 Typedef Documentation

4.17.2.1 GPIO_PinState

```
typedef uint8_t GPIO_PinState
```

4.17.3 Enumeration Type Documentation

4.17.3.1 anonymous enum

```
anonymous enum
```

Enumerator

| BUTTON_PRESSED | |
|------------------|--|
| BUTTON_UNPRESSED | |

4.17.3.2 anonymous enum

anonymous enum

Enumerator

```
PIN_SET
PIN_RESET
```

4.17.4 Function Documentation

4.17.4.1 disableChipSelect()

```
\begin{array}{c} \text{void disableChipSelect (} \\ \text{void )} \end{array}
```

Disables SPI chip select line (active low)

4.17.4.2 DisablePWM1()

```
void DisablePWM1 (
     void )
```

Disables Timer 1.

4.17.4.3 disableWriteProtect()

Disables SPI write protect line (active high)

4.17.4.4 enableChipSelect()

Enables SPI chip select line (active low)

4.17.4.5 EnablePWM1()

```
void EnablePWM1 (
     void )
```

Enables Timer 1.

4.17.4.6 enableWriteProtect()

Enables SPI write protect line (active high)

4.17.4.7 Error_Handler()

This function is executed in case of error occurrence.

Return values

None

4.17.4.8 GetCurrentValue()

Returns raw ADC value from ammeter.

Parameters

4.17.4.9 GetThermistorValue()

Returns raw ADC value from thermistor.

Parameters

| out <i>Thermistor</i> raw ADC val |
|-----------------------------------|
|-----------------------------------|

4.17.4.10 GetTIM2Cnt()

Returns value in the Timer 2 counter.

Parameters

| out <i>Value</i> c | f Timer 2 counter |
|--------------------|-------------------|
|--------------------|-------------------|

4.17.4.11 GetVoltageValue()

Returns raw ADC value from voltmeter.

Parameters

| out | Voltmeter | raw ADC value |
|-----|-----------|---------------|
|-----|-----------|---------------|

4.17.4.12 ReadBrightPin()

Reads bright pin value.

Parameters

| out | Bright | pin state |
|-----|--------|-----------|
|-----|--------|-----------|

4.17.4.13 ReadDimPin()

Reads dim pin value.

Parameters

| out | Dim | pin state |
|-----|-----|-----------|
|-----|-----|-----------|

4.17.4.14 receiveData()

```
void receiveData (
          unsigned char * rxData,
          const uint32_t bytes)
```

Gets data from SPI lines.

Parameters

| in | rxData | Pointer to data buffer |
|----|--------|----------------------------|
| in | bytes | Number of bytes to receive |

4.17.4.15 RestartTIM2()

```
void RestartTIM2 ( void )
```

Resets Timer 2 counter to zero.

4.17.4.16 sendUARTChar()

```
void sendUARTChar ( {\tt char}\ c)
```

Sends character via UART line.

Parameters

| in c Character to send via UART |
|---------------------------------|
|---------------------------------|

4.17.4.17 SetPW11()

Sets PWM Timer 1 Channel 1 value.

Parameters

| in <i>pulse_width</i> | Value out of 255 to set pulse width to |
|-----------------------|--|
|-----------------------|--|

4.17.4.18 StartPWM11()

```
void StartPWM11 (
     void )
```

Starts PWM Timer 1 Channel 1 output.

4.17.4.19 StartTIM2()

```
void StartTIM2 (
     void )
```

Starts Timer 2 counter.

4.17.4.20 StopPWM11()

```
void StopPWM11 (
     void )
```

Stops PWM Timer 1 Channel 1 output.

4.17.4.21 transferData()

Sends data via SPI lines.

Parameters

| in | txData | Pointer to data to send |
|----|--------|-------------------------|
| in | bytes | Number of bytes to send |

4.18 stm32l412xx-bsp.h

Go to the documentation of this file. 00002 00003 @attention 00004 * Copyright © 2007 Luminator Mark IV 00005 * All rights reserved. 00006 $\,\star\,$ Any use without the prior written consent of Luminator Mark IV 00007 \star is strictly prohibited. 80000 00009 00012 * @file stm321412xx-bsp.h 00013 00014 * @brief Board Support Package for STM32L412xx 00015 * 00016 * Revision History: * Date - Name - Ver - Remarks * 07/31/2024 - Austin Green - 1.0 - Initial Document * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation 00017 00018 00019 00020 * 00021 $\,\star\,$ Notes: This uses the Low Level ST API to access the board pins 00022 * 00024 00025 #ifndef INC_bsph 00026 #define INC_bsph 00027 00028 #include <stdint.h> 00029 00030 /* Private defines -----00031 #ifdef STM32L412xx 00032 #include "stm3214xx_l1_adc.h" 00033 #include "stm3214xx_ll_crs.h" 00034 00035 #include "stm3214xx_11_rcc.h" 00036 #include "stm3214xx_11_bus.h" 00037 #include "stm3214xx_11_system.h" #include "stm3214xx_ll_exti.h" 00038 #include "stm3214xx_11_cortex.h" 00039 #include "stm3214xx_11_utils.h" 00040 #include "stm3214xx_11_pwr.h" 00041 00042 #include "stm3214xx_11_dma.h" #include "stm3214xx_11_spi.h" #include "stm3214xx_11_tim.h" 00043 00044 #include "stm3214xx_ll_usart.h" 00045 #include "stm3214xx_ll_gpio.h" 00046 00047 #if defined(USE_FULL_ASSERT) 00049 #include "stm32_assert.h" 00050 #endif /* USE_FULL_ASSERT */ 00051 00052 /* Peripherals */ #include "adc.h" 00053 #include "gpio.h" 00054 00055 #include "spi.h" 00056 #include "tim.h" 00057 #ifdef ENABLE_UART_DEBUGGING /* tracing enabled */00058 00059 /* Peripherals enabled for UART */ #include "usart.h" 00061 #endif /* ENABLE_UART_DEBUGGING */ 00062 #define THERMISTOR_ADC_Pin LL_GPIO_PIN_0 #define THERMISTOR_ADC_GPIO_Port GPIOA #define BRIGHT_Pin LL_GPIO_PIN_1 #define BRIGHT_GPIO_Port GPIOA 00063 00064 00065 00066 #define DIM_Pin LL_GPIO_PIN_3 00067 00068 #define DIM_GPIO_Port GPIOA 00069 #define EEPROM_SCK_Pin LL_GPIO_PIN_5 #define EEPROM_SCK_GPIO_Port GPIOA #define EEPROM_MISO_Pin LL_GPIO_PIN_6 00070 00071 00072 #define EEPROM_MISO_GPIO_Port GPIOA #define EEPROM_MOSI_Pin LL_GPIO_PIN_7 00074 #define EEPROM_MOSI_GPIO_Port GPIOA 00075 #define VOLTMETER_ADC_Pin LL_GPIO_PIN_0 00076 #define VOLTMETER_ADC_GPIO_Port GPIOB #define AMPMETER_ADC_Pin LL_GPIO_PIN_1 #define AMPMETER_ADC_GPIO_Port GPIOB 00077 00078 #define PWM_OUT_Pin LL_GPIO_PIN_8 08000 #define PWM_OUT_GPIO_Port GPIOA

#define SPI_WP_Pin LL_GPIO_PIN_10

#define SPI_WP_GPIO_Port GPIOA

00081

00082

```
#define SPI_NSS_Pin LL_GPIO_PIN_11
00084
          #define SPI_NSS_GPIO_Port GPIOA
00085
00086
       #else /* STM32L412xx */
00087
00088
          /* Below is for debugging purposes */
          #define THERMISTOR_ADC_Pin
00090
          #define THERMISTOR_ADC_GPIO_Port
00091
          #define BRIGHT_Pin
00092
          #define BRIGHT GPIO Port
00093
          #define DIM_Pin
00094
          #define DIM_GPIO_Port
          #define EEPROM_SCK_Pin
00095
00096
          #define EEPROM_SCK_GPIO_Port
00097
          #define EEPROM_MISO_Pin
00098
          #define EEPROM_MISO_GPIO_Port
00099
          #define EEPROM_MOSI_Pin
00100
          #define EEPROM_MOSI_GPIO_Port
          #define VOLTMETER_ADC_Pin
00101
00102
          #define VOLTMETER_ADC_GPIO_Port
00103
          #define AMPMETER_ADC_Pin
00104
          #define AMPMETER_ADC_GPIO_Port
          #define PWM_OUT_Pin
00105
          #define PWM_OUT_GPIO_Port
00106
00107
          #define SPI_WP_Pin
          #define SPI_WP_GPIO_Port
00108
00109
          #define SPI_NSS_Pin
00110
          #define SPI_NSS_GPIO_Port
00111
          typedef struct
00115
00116
          {
00117
            uint8_t is_running;
00118
            uint32_t pulse_width;
00119
          } PwmStruct;
00120
          typedef struct
00124
00125
           uint8_t is_running;
00127
            uint32_t time;
00128
         } TimerStruct;
00129
00130
       #endif /* STM32L412xx */
00131
00132
        /* Interrupt Handlers */
00133
        #ifndef NVIC_PRIORITYGROUP_0
00134
         #define NVIC_PRIORITYGROUP_0
                                                  ((uint32_t)0x00000007)
00136
          #define NVIC_PRIORITYGROUP_1
                                                  ((uint32_t)0x00000006)
         #define NVIC_PRIORITYGROUP_2
#define NVIC_PRIORITYGROUP_3
00138
                                                  ((uint32_t)0x00000005)
                                                  ((uint32_t)0x00000004)
00140
          #define NVIC_PRIORITYGROUP_4
00142
                                                  ((uint32 t)0x00000003)
00144
        #endif
00145
00146
        /\star Button Defines \star/
       typedef uint8_t GPIO_PinState;
enum { BUTTON_PRESSED = 1, BUTTON_UNPRESSED = 0};
enum { PIN_SET = 1, PIN_RESET = 0};
00147
00148
00149
00150
00151
        /* Clock frequency Values */
        #define CLK_FREQ_HZ (8000000)
#define TIM2_CLK_DEV (1)
00152
00153
        #define TIM2_CLK_PRESCALER (8000)
00154
00155
00156
        /* Returns button state */
00161
        GPIO_PinState ReadDimPin( void );
00162
00167
        GPIO_PinState ReadBrightPin( void );
        /* PWM Outputs */
00168
        void EnablePWM1( void );
00172
00173
00177
        void DisablePWM1( void );
00178
00182
        void StartPWM11( void );
00183
        void StopPWM11( void );
00187
00188
00193
        void SetPW11( uint32_t pulse_width );
00194
00195
        /* Timers */
        void StartTIM2( void );
00199
00200
00204
        void RestartTIM2( void );
00205
00210
        uint32_t GetTIM2Cnt( void );
00211
00216
       int16_t GetThermistorValue( void );
00217
00222
        int16_t GetCurrentValue( void );
```

```
00223
00228
        int16_t GetVoltageValue( void );
00229
       void enableWriteProtect( void );
00233
00234
00238
       void disableWriteProtect( void );
00239
00243
       void enableChipSelect( void );
00244
       void disableChipSelect( void );
00248
00249
00255
       void transferData( const unsigned char* const txData, const uint32_t bytes );
00256
00262
       void receiveData( unsigned char* rxData, const uint32_t bytes );
00263
00268
       void sendUARTChar(char c);
00269
00274
       void Error_Handler(void);
00277 #endif /* INC_bsph */
```

4.19 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Inc/temperature_handler.h File Reference

```
#include <stdint.h>
```

Enumerations

enum TemperatureRange_e { TempCool = 0 , TempWarm = 1 , TempHot = 2 }

Functions

• int32_t GetTemperature (void)

Get temperature from thermistor.

TemperatureRange_e GetTemperatureRange (void)

Get range that the temperature falls into. There is an increased threshold to fall back into the previous state. Possible ranges are Cool - Normal Operating Temperature Warm - Temperature is elevated, decrease brightness Hot - Temperature is hot, lower brightness significantly.

4.19.1 Enumeration Type Documentation

4.19.1.1 TemperatureRange_e

```
enum TemperatureRange_e
```

Temperature Range Enum

Enumerator

| TempCool | Normal Operating Temperature |
|----------|--|
| TempWarm | Temperature is elevated, decrease brightness |
| TempHot | Temperature is hot, lower brightness significantly |

4.19.2 Function Documentation

4.19.2.1 GetTemperature()

Get temperature from thermistor.

Parameters

| out | temperature | level in dC |
|-----|-------------|-------------|
|-----|-------------|-------------|

4.19.2.2 GetTemperatureRange()

Get range that the temperature falls into. There is an increased threshold to fall back into the previous state. Possible ranges are Cool - Normal Operating Temperature Warm - Temperature is elevated, decrease brightness Hot - Temperature is hot, lower brightness significantly.

Parameters

```
out Current temperature range
```

4.20 temperature_handler.h

Go to the documentation of this file.

```
***********
00002
00003
         @attention
00004 \star Copyright © 2007 Luminator Mark IV
00005 * All rights reserved.
00006 * Any use without the prior written consent of Luminator Mark IV
00007 * is strictly prohibited.
80000
00009
00011
00012 * @file temperature_handler.h
00014 \,\star\, @brief Handles getting this temperature and transitioning between
00015
                temperature states.
00016 *
00017 * Revision History:
                                - Ver - Remarks
00018
      * Date
                  - Name
      * 07/31/2024 - Austin Green - 1.0 - Initial Document

* 08/05/2024 - Austin Green - 1.1 - Refactor to not use floats
00019
00020
00021
      * 09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00022
00023 * Notes:
00024 *
00025
00026
00027 #ifndef INC_temperature_handlerh
00028
         #define INC_temperature_handlerh
00029
00030
         #include <stdint.h>
00031
00033
         typedef enum
```

```
00034
          {
00035
              TempCool
              TempWarm = 1,
TempHot = 2
00036
00037
00038
          } TemperatureRange_e;
00039
          int32_t GetTemperature( void );
00046
00056
          TemperatureRange_e GetTemperatureRange( void );
00057
00058 #endif /* INC_temperature_handlerh */
```

4.21 C:/Users/agreen/Documents/Projects/Aveo/CH-53K LED ← Controller/Core/Inc/voltage_handler.h File Reference

```
#include <stdint.h>
```

Enumerations

```
• enum VoltageRange_e {
 VoltageNormal = 0, VoltageLow = 1, VoltageHigh = 2, VoltageErrorLow = 3,
 VoltageErrorHigh = 4 }
```

Functions

• uint16_t GetVoltage (void)

Get voltage from voltmeter.

VoltageRange_e GetVoltageRange (void)

Get range that the voltage falls into Possible ranges are Normal - Normal Operating Voltage Low - Voltage low, but ok High - Voltage high, but ok ErrorLow - Voltage too low ErrorHigh - Voltage too high.

4.21.1 Enumeration Type Documentation

4.21.1.1 VoltageRange e

```
enum VoltageRange_e
```

Voltage Range Enum

Enumerator

| VoltageNormal | Normal Operating Voltage |
|------------------|--------------------------|
| VoltageLow | Voltage low, but ok |
| VoltageHigh | Voltage high, but ok |
| VoltageErrorLow | Voltage too low |
| VoltageErrorHigh | Voltage too high |

4.21.2 Function Documentation

4.21.2.1 GetVoltage()

```
uint16_t GetVoltage (
     void )
```

Get voltage from voltmeter.

Parameters

```
out voltage level in dV
```

4.21.2.2 GetVoltageRange()

Get range that the voltage falls into Possible ranges are Normal - Normal Operating Voltage Low - Voltage low, but ok High - Voltage high, but ok ErrorLow - Voltage too low ErrorHigh - Voltage too high.

Parameters

| | out | Current | voltage range | |
|--|-----|---------|---------------|--|
|--|-----|---------|---------------|--|

4.22 voltage_handler.h

Go to the documentation of this file.

```
00001 /**
00002
00003 *
         @attention
00004 * Copyright © 2007 Luminator Mark IV
     * All rights reserved.
00006 \,\star\, Any use without the prior written consent of Luminator Mark IV
00007 * is strictly prohibited.
80000
00009 *************************
00010
00011
00012
      * @file voltage_handler.h
00013
00014 \,\,\star\, @brief Handles getting voltage and reporting values.
00015
00016
      * Revision History:
00017
                  - Name
                                - Ver - Remarks
        08/05/2024 - Austin Green - 1.0 - Initial Document
09/10/2024 - Austin Green - 2.0 - Doxyfile documentation
00018
00019
00020
00021
00022
00024
00025 #ifndef INC_voltage_handlerh
00026
         #define INC_voltage_handlerh
00027
         #include <stdint.h>
00028
00029
00031
         typedef enum
00032
00033
             VoltageNormal
                               = 0,
00034
             VoltageLow
                               = 1,
00035
             VoltageHigh
                               = 2.
             VoltageErrorLow
00036
                               = 3,
             VoltageErrorHigh
00037
00038
         } VoltageRange_e;
00039
00045
         uint16_t GetVoltage( void );
00046
00057
         VoltageRange e GetVoltageRange( void );
00059 #endif /* INC_voltage_handlerh */
```

4.23 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/button_handler.c File Reference

```
#include "button_handler.h"
#include "stm321412xx-bsp.h"
```

Functions

GPIO PinState IsDimPressed (void)

Return state of dim button.

GPIO_PinState IsBrightPressed (void)

Return state of brighten button.

4.23.1 Function Documentation

4.23.1.1 IsBrightPressed()

Return state of brighten button.

Parameters

| out | Bright | Pin State, pressed or not |
|-----|--------|---------------------------|
|-----|--------|---------------------------|

4.23.1.2 IsDimPressed()

Return state of dim button.

Parameters

```
out Dim Pin State, pressed or not
```

4.24 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/current_handler.c File Reference

```
#include <stdio.h>
#include "current_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

• uint16_t GetCurrent (void)

Get current from ammeter.

CurrentRange_e GetCurrentRange (void)

Get range that the current falls into Possible ranges are Normal - Normal Operating Current High - Current high, but ok Error - Current too high.

Variables

- const uint16_t RawTodAmps = (1)
- const uint16_t dAmpsToRaw = (1)
- const uint16_t CurrentHighThreshold_dA = 35u
- const uint16_t CurrentErrorThreshold_dA = 40u

4.24.1 Function Documentation

4.24.1.1 GetCurrent()

Get current from ammeter.

Parameters

| out | current | level in dA |
|-----|---------|-------------|
|-----|---------|-------------|

4.24.1.2 GetCurrentRange()

Get range that the current falls into Possible ranges are Normal - Normal Operating Current High - Current high, but ok Error - Current too high.

Parameters

| out | Current | current range |
|-----|---------|---------------|
|-----|---------|---------------|

4.24.2 Variable Documentation

4.24.2.1 CurrentErrorThreshold_dA

```
const uint16_t CurrentErrorThreshold_dA = 40u
```

High Current Error Level in dA

4.24.2.2 CurrentHighThreshold_dA

```
const uint16_t CurrentHighThreshold_dA = 35u
High Current Level in dA
```

4.24.2.3 dAmpsToRaw

```
const uint16_t dAmpsToRaw = (1)
```

DeciAmps (A*0.1) to raw value out of ammeter

4.24.2.4 RawTodAmps

```
const uint16_t RawTodAmps = (1)
```

Raw value out of ammeter to deciAmps (A*0.1)

4.25 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/delay_handler.c File Reference

```
#include "delay_handler.h"
#include "stm321412xx-bsp.h"
```

Functions

void StartDelayCounter (void)

Starts the delay counter, only needs to be called once on init.

void RestartDelayCounter (void)

Restart the delay counter.

uint8_t DelayHit (uint32_t delay_ms)

Checks if the delay (ms) was hit based on timer value.

• uint16_t BrightnessDelay (int8_t brightness)

Returns a delay value for a brightness level.

Variables

const float Tim2ClkKhz = (CLK_FREQ_HZ / (float)TIM2_CLK_DEV / (float)TIM2_CLK_PRESCALER / 1000.0f)

4.25.1 Function Documentation

4.25.1.1 BrightnessDelay()

Returns a delay value for a brightness level.

Parameters

| in | brightness | Current brightness level |
|-----|------------|--|
| out | Returns | delay to satisfy specs at current brightness level |

4.25.1.2 DelayHit()

Checks if the delay (ms) was hit based on timer value.

Parameters

| in | delay_ms | Time in ms to check if timer has hit |
|-----|----------|--------------------------------------|
| out | Returns | 1 if delay has been hit |

4.25.1.3 RestartDelayCounter()

Restart the delay counter.

4.25.1.4 StartDelayCounter()

Starts the delay counter, only needs to be called once on init.

4.25.2 Variable Documentation

4.25.2.1 Tim2ClkKhz

```
const float Tim2ClkKhz = (CLK_FREQ_HZ / (float)TIM2_CLK_DEV / (float)TIM2_CLK_PRESCALER /
1000.0f)
```

Timer clock used to check the delay values in stm32l412xx-bsp.h

4.26 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/fram.c File Reference

```
#include <string.h>
#include "fram.h"
#include "stm321412xx-bsp.h"
#include "spi.h"
```

Macros

- #define TLEN (16)
- #define TADD (0x200)

Functions

- void framWriteProtect (WRITE_PROTECT_STATE state)
- void framChipSelect (CHIP_SELECT_STATE state)
- void framReadSr (unsigned char *srP)
- void framWriteSr (unsigned char sr)
- void framWriteDisable (void)

This routine resets the write enable latch.

void framWriteEnable (void)

This routine resets the write enable latch.

- void framReadMemory (unsigned short addr, unsigned char *rdBufP, unsigned short len)
- void framWriteMemory (unsigned short addr, const unsigned char *const wrBufP, unsigned short len)
- uint8 t framTest (void)

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

4.26.1 Macro Definition Documentation

4.26.1.1 TADD

```
#define TADD (0x200)
```

4.26.1.2 TLEN

```
#define TLEN (16)
```

4.26.2 Function Documentation

4.26.2.1 framChipSelect()

4.26.2.2 framReadMemory()

```
void framReadMemory (
          unsigned short addr,
          unsigned char * rdBufP,
          unsigned short len)
```

4.26.2.3 framReadSr()

```
void framReadSr ( \mbox{unsigned char} \ * \ srP)
```

4.26.2.4 framTest()

```
uint8_t framTest (
     void )
```

This routine is a test function for FRAM access. It writes "TLEN" bytes of an incrementing pattern into FRAM at address "TADD". It reads the same length into a buffer and verifies the pattern.

Parameters

```
out | 1 | = pass, 0 = fail
```

4.26.2.5 framWriteDisable()

```
void framWriteDisable (
     void )
```

This routine resets the write enable latch.

Parameters

```
out none
```

4.26.2.6 framWriteEnable()

```
void framWriteEnable (
     void )
```

This routine resets the write enable latch.

Parameters

```
out none
```

4.26.2.7 framWriteMemory()

```
void framWriteMemory (
          unsigned short addr,
          const unsigned char *const wrBufP,
          unsigned short len)
```

4.26.2.8 framWriteProtect()

```
void framWriteSr ( \label{eq:constraint} \text{unsigned char } sr)
```

4.27 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/logger.c File Reference

```
#include <string.h>
#include <stdio.h>
#include "logger.h"
#include "fram.h"
#include "stm321412xx-bsp.h"
```

Functions

• void LogString (const char *const string, uint8_t write_beginning)

Log a string to tail_pointer, use write_beginning flag to write the beginning.

void LogNumber (const int32_t number, uint8_t write_beginning)

Logs a number by converting the number to a string and using the LogString function.

void ReadLog (const uint32_t address, char *string, const uint32_t bytes)

Reads the log at a given address and size.

4.27.1 Function Documentation

4.27.1.1 LogNumber()

Logs a number by converting the number to a string and using the LogString function.

Parameters

| in | number | Number to log |
|----|-----------------|--|
| in | write_beginning | Write log at the beginning of log area |

4.27.1.2 LogString()

Log a string to tail_pointer, use write_beginning flag to write the beginning.

Parameters

| in | string | Pointer to string to log |
|----|-----------------|--|
| in | write_beginning | Write log at the beginning of log area |

4.27.1.3 ReadLog()

Reads the log at a given address and size.

Parameters

| in | address | Address to read from |
|----|---------|-------------------------------|
| in | string | Pointer to return data string |
| in | bytes | Number of bytes to read |

4.28 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/main.c File Reference

```
#include "main.h"
#include "stm321412xx-bsp.h"
#include "pwm_handler.h"
#include "delay_handler.h"
#include "button_handler.h"
#include "current_handler.h"
#include "voltage_handler.h"
#include "my_printf.h"
```

Macros

- #define LOWER_SWEEP_TIME_MS (3375)
- #define UPPER_SWEEP_TIME_MS (4000)
- #define TOTAL_SWEEP_TIME_MS (7375)
- #define LOWER_STEP_TIME_MS (LOWER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
- #define UPPER STEP TIME MS (UPPER SWEEP TIME MS / (BRIGHTNESS STEPS / 2.0f))
- #define AVG_STEP_TIME_MS ((UPPER_STEP_TIME_MS + LOWER_STEP_TIME_MS) / 2.0f)
- #define AVG_STEP_DIFF_MS (AVG_STEP_TIME_MS LOWER_STEP_TIME_MS)

Functions

void SystemClock_Config (void)
 System Clock Configuration.

• int main (void)

The application entry point. Initialize variables and go into bare metal loop. Polls buttons and sensors.

Variables

```
• const float LowStepTimeMs = (LOWER_STEP_TIME_MS - AVG_STEP_DIFF_MS)
```

```
• const float HighStepTimeMs = (UPPER_STEP_TIME_MS + AVG_STEP_DIFF_MS)
```

4.28.1 Macro Definition Documentation

```
4.28.1.1 AVG_STEP_DIFF_MS
```

```
#define AVG_STEP_DIFF_MS (AVG_STEP_TIME_MS - LOWER_STEP_TIME_MS)
```

4.28.1.2 AVG_STEP_TIME_MS

```
#define AVG_STEP_TIME_MS ((UPPER_STEP_TIME_MS + LOWER_STEP_TIME_MS) / 2.0f)
```

4.28.1.3 LOWER_STEP_TIME_MS

```
#define LOWER_STEP_TIME_MS (LOWER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
```

4.28.1.4 LOWER_SWEEP_TIME_MS

```
#define LOWER_SWEEP_TIME_MS (3375)
```

4.28.1.5 TOTAL SWEEP TIME MS

```
#define TOTAL_SWEEP_TIME_MS (7375)
```

4.28.1.6 UPPER_STEP_TIME_MS

```
#define UPPER_STEP_TIME_MS (UPPER_SWEEP_TIME_MS / (BRIGHTNESS_STEPS / 2.0f))
```

4.28.1.7 UPPER_SWEEP_TIME_MS

```
#define UPPER_SWEEP_TIME_MS (4000)
```

4.28.2 Function Documentation

4.28.2.1 main()

```
int main (
     void )
```

The application entry point. Initialize variables and go into bare metal loop. Polls buttons and sensors.

Return values

4.28.2.2 SystemClock_Config()

```
void SystemClock_Config (
     void )
```

System Clock Configuration.

Return values

None

4.28.3 Variable Documentation

4.28.3.1 HighStepTimeMs

```
const float HighStepTimeMs = (UPPER_STEP_TIME_MS + AVG_STEP_DIFF_MS)
```

4.28.3.2 LowStepTimeMs

```
const float LowStepTimeMs = (LOWER_STEP_TIME_MS - AVG_STEP_DIFF_MS)
```

- 4.29 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_← Controller/Core/Src/my_printf.c File Reference
- 4.30 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_

 Controller/Core/Src/pwm_handler.c File Reference

```
#include "pwm_handler.h"
#include "stm321412xx-bsp.h"
#include "temperature_handler.h"
#include "my_printf.h"
```

Macros

• #define PW_PERIOD (255)

Functions

· void InitPwm (void)

Init PwmArray var Set brightness to half value, enable pwm, and turn off.

• void DecreaseBrightness (uint8_t button_held)

Decrease brightness by 1 (for button press) or 3 (for button hold) This functions can be made to increase brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

void IncreaseBrightness (uint8_t button_held)

Increase brightness by 1 (for button press) or 3 (for button hold) This functions can be made to decrease brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

void SetPwm (void)

set PWM based on pwm value

void TurnOffPwm (void)

turn off PWM

· int8_t GetBrightness (void)

Return ledBrightness variable.

void SetBrightness (int8 t brightness)

Set ledBrightness variable, guards to ensure we don't go over max or min.

uint8 t GetPwm (void)

Get the PWM value based on the brightness and the temperature range.

Variables

```
• const uint8_t MaxBrightness = (BRIGHTNESS_STEPS - 1)
```

- const uint8_t MinBrightness = (0)
- const uint8_t HalfBrightness = ((uint8_t)((BRIGHTNESS_STEPS 1) / 2.0f))
- const float MinPw = (0)
- const float MaxPw = (PW_PERIOD)
- const float WarmPwmRatio = (0.90f)
- const float HotPwmRatio = (0.50f)

4.30.1 Macro Definition Documentation

4.30.1.1 PW_PERIOD

```
#define PW_PERIOD (255)
```

4.30.2 Function Documentation

4.30.2.1 DecreaseBrightness()

Decrease brightness by 1 (for button press) or 3 (for button hold) This functions can be made to increase brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

Parameters

| in | button_held | If the button is being held (decrements by 3 if so) | |
|----|-------------|---|--|
|----|-------------|---|--|

4.30.2.2 GetBrightness()

```
int8_t GetBrightness (
     void )
```

Return ledBrightness variable.

Parameters

| out | Current | LED brightness level |
|-----|---------|----------------------|
|-----|---------|----------------------|

4.30.2.3 GetPwm()

Get the PWM value based on the brightness and the temperature range.

Parameters

| out | Current | PWM value |
|-----|---------|-----------|
|-----|---------|-----------|

4.30.2.4 IncreaseBrightness()

Increase brightness by 1 (for button press) or 3 (for button hold) This functions can be made to decrease brightness value with the REVERSE_BRIGHTNESS flag Afterwards, set pwm output.

Parameters

| in | button_held | If the button is being held (increments by 3 if so) |
|----|-------------|---|
|----|-------------|---|

4.30.2.5 InitPwm()

```
void InitPwm (
     void )
```

Init PwmArray var Set brightness to half value, enable pwm, and turn off.

4.30.2.6 SetBrightness()

Set ledBrightness variable, guards to ensure we don't go over max or min.

Parameters

| in <i>brightness</i> | Brightess to set |
|----------------------|------------------|
|----------------------|------------------|

4.30.2.7 SetPwm()

```
void SetPwm (
     void )
```

set PWM based on pwm value

4.30.2.8 TurnOffPwm()

```
void TurnOffPwm (
     void )
```

turn off PWM

4.30.3 Variable Documentation

4.30.3.1 HalfBrightness

```
const uint8_t HalfBrightness = ((uint8_t)((BRIGHTNESS_STEPS - 1) / 2.0f))
```

Half Brightness Step (24)

4.30.3.2 HotPwmRatio

```
const float HotPwmRatio = (0.50f)
```

Hot thermal state pwm constant

4.30.3.3 MaxBrightness

```
const uint8_t MaxBrightness = (BRIGHTNESS_STEPS - 1)
```

Max Brightness Step (49)

4.30.3.4 MaxPw

```
const float MaxPw = (PW_PERIOD)
```

Max pulse width value (PW_PERIOD(255))

4.30.3.5 MinBrightness

```
const uint8_t MinBrightness = (0)
```

Min Brightness Step (0)

4.30.3.6 MinPw

```
const float MinPw = (0)
```

Min pulse width value (0)

4.30.3.7 WarmPwmRatio

```
const float WarmPwmRatio = (0.90f)
```

Warm thermal state pwm constant

4.31 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/stm32l412xx-bsp.c File Reference

```
#include "stm321412xx-bsp.h"
```

Functions

• GPIO_PinState ReadDimPin (void)

Reads dim pin value.

• GPIO_PinState ReadBrightPin (void)

Reads bright pin value.

void EnablePWM1 (void)

Enables Timer 1.

void DisablePWM1 (void)

Disables Timer 1.

void StartPWM11 (void)

Starts PWM Timer 1 Channel 1 output.

• void StopPWM11 (void)

Stops PWM Timer 1 Channel 1 output.

void SetPW11 (uint32_t pulse_width)

Sets PWM Timer 1 Channel 1 value.

void StartTIM2 (void)

Starts Timer 2 counter.

void RestartTIM2 (void)

Resets Timer 2 counter to zero.

uint32 t GetTIM2Cnt (void)

Returns value in the Timer 2 counter.

• int16_t GetThermistorValue (void)

Returns raw ADC value from thermistor.

int16_t GetCurrentValue (void)

Returns raw ADC value from ammeter.

• int16_t GetVoltageValue (void)

Returns raw ADC value from voltmeter.

void enableWriteProtect (void)

Enables SPI write protect line (active high)

void disableWriteProtect (void)

Disables SPI write protect line (active high)

void enableChipSelect (void)

Enables SPI chip select line (active low)

· void disableChipSelect (void)

Disables SPI chip select line (active low)

• void transferData (const unsigned char *const txData, const uint32 t bytes)

Sends data via SPI lines.

void receiveData (unsigned char *rxData, const uint32 t bytes)

Gets data from SPI lines.

• void sendUARTChar (char c)

Sends character via UART line.

void Error_Handler (void)

This function is executed in case of error occurrence.

4.31.1 Function Documentation

4.31.1.1 disableChipSelect()

Disables SPI chip select line (active low)

4.31.1.2 DisablePWM1()

```
void DisablePWM1 (
     void )
```

Disables Timer 1.

4.31.1.3 disableWriteProtect()

```
void disableWriteProtect ( void\ ) \\
```

Disables SPI write protect line (active high)

4.31.1.4 enableChipSelect()

```
\begin{tabular}{ll} \beg
```

Enables SPI chip select line (active low)

4.31.1.5 EnablePWM1()

```
void EnablePWM1 (
     void )
```

Enables Timer 1.

4.31.1.6 enableWriteProtect()

```
void enableWriteProtect (
     void )
```

Enables SPI write protect line (active high)

4.31.1.7 Error_Handler()

```
void Error_Handler (
     void )
```

This function is executed in case of error occurrence.

Return values

None

4.31.1.8 GetCurrentValue()

Returns raw ADC value from ammeter.

Parameters

| out Ammeter raw ADC value |
|-------------------------------|
|-------------------------------|

4.31.1.9 GetThermistorValue()

Returns raw ADC value from thermistor.

4.31 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_Controller/Core/Src/stm32l412xx-bsp.c File Reference

Parameters

| out <i>Thermistor</i> | raw ADC value |
|-----------------------|---------------|
|-----------------------|---------------|

4.31.1.10 GetTIM2Cnt()

Returns value in the Timer 2 counter.

Parameters

| out Value of Timer 2 counter |
|----------------------------------|
|----------------------------------|

4.31.1.11 GetVoltageValue()

Returns raw ADC value from voltmeter.

Parameters

| out <i>Voltme</i> | eter raw ADC value |
|-------------------|--------------------|
|-------------------|--------------------|

4.31.1.12 ReadBrightPin()

Reads bright pin value.

Parameters

| out | Bright | pin state |
|-----|--------|-----------|

4.31.1.13 ReadDimPin()

Reads dim pin value.

Parameters

| out <i>Dim</i> | pin state |
|----------------|-----------|
|----------------|-----------|

4.31.1.14 receiveData()

```
void receiveData (
          unsigned char * rxData,
          const uint32_t bytes)
```

Gets data from SPI lines.

Parameters

| in | rxData | Pointer to data buffer |
|----|--------|----------------------------|
| in | bytes | Number of bytes to receive |

4.31.1.15 RestartTIM2()

```
void RestartTIM2 ( void )
```

Resets Timer 2 counter to zero.

4.31.1.16 sendUARTChar()

```
void sendUARTChar ( {\tt char}\ c)
```

Sends character via UART line.

Parameters

| i | n | С | Character to send via UART |
|---|---|---|----------------------------|

4.31.1.17 SetPW11()

Sets PWM Timer 1 Channel 1 value.

Parameters

| in | pulse_width | Value out of 255 to set pulse width to |
|----|-------------|--|

4.31.1.18 StartPWM11()

```
void StartPWM11 (
     void )
```

Starts PWM Timer 1 Channel 1 output.

4.31.1.19 StartTIM2()

```
void StartTIM2 (
     void )
```

Starts Timer 2 counter.

4.31.1.20 StopPWM11()

```
void StopPWM11 (
     void )
```

Stops PWM Timer 1 Channel 1 output.

4.31.1.21 transferData()

Sends data via SPI lines.

Parameters

| in | txData | Pointer to data to send |
|----|--------|-------------------------|
| in | bytes | Number of bytes to send |

4.32 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/temperature_handler.c File Reference

```
#include <string.h>
#include "temperature_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

• int32_t GetTemperature (void)

Get temperature from thermistor.

TemperatureRange_e GetTemperatureRange (void)

Get range that the temperature falls into. There is an increased threshold to fall back into the previous state. Possible ranges are Cool - Normal Operating Temperature Warm - Temperature is elevated, decrease brightness Hot - Temperature is hot, lower brightness significantly.

Variables

```
• const int32_t ThermistorTodCelcius = (1)
```

- const int32_t dCelciusToThermistor = (1)
- const int32_t HeatingThreshold1_dC = (1000)
- const int32_t HeatingThreshold2_dC = (1200)
- const int32 t CoolingThreshold1 dC = (800)
- const int32 t CoolingThreshold2 dC = (1000)

4.32.1 Function Documentation

4.32.1.1 GetTemperature()

Get temperature from thermistor.

Parameters

| out | temperature | level in dC |
|-----|-------------|-------------|
|-----|-------------|-------------|

4.32.1.2 GetTemperatureRange()

Get range that the temperature falls into. There is an increased threshold to fall back into the previous state. Possible ranges are Cool - Normal Operating Temperature Warm - Temperature is elevated, decrease brightness Hot - Temperature is hot, lower brightness significantly.

Parameters

| out | Current | temperature range |
|-----|---------|-------------------|
|-----|---------|-------------------|

4.32.2 Variable Documentation

4.32.2.1 CoolingThreshold1_dC

```
const int32_t CoolingThreshold1_dC = (800)
```

Cooling Threshold 1 (cooling down from Warm to Cool) in dC

4.32.2.2 CoolingThreshold2_dC

```
const int32_t CoolingThreshold2_dC = (1000)
```

Cooling Threshold 2 (cooling down from Hot to Warm) in dC

4.32.2.3 dCelciusToThermistor

```
const int32_t dCelciusToThermistor = (1)
```

DeciCelcius (V*0.1) to raw value out of thermistor

4.32.2.4 HeatingThreshold1_dC

```
const int32_t HeatingThreshold1_dC = (1000)
```

Heating Threshold 1 (heating up from Cool to Warm) in dC

4.32.2.5 HeatingThreshold2_dC

```
const int32_t HeatingThreshold2_dC = (1200)
```

Heating Threshold 2 (heating up from Warm to Hot) in dC

4.32.2.6 ThermistorTodCelcius

```
const int32_t ThermistorTodCelcius = (1)
```

Raw value out of thermistor to deciCelcius (C*0.1)

4.33 C:/Users/agreen/Documents/Projects/Aveo/CH-53K_LED_ Controller/Core/Src/voltage_handler.c File Reference

```
#include <stdio.h>
#include "voltage_handler.h"
#include "stm321412xx-bsp.h"
#include "logger.h"
```

Functions

• uint16_t GetVoltage (void)

Get voltage from voltmeter.

VoltageRange_e GetVoltageRange (void)

Get range that the voltage falls into Possible ranges are Normal - Normal Operating Voltage Low - Voltage low, but ok High - Voltage high, but ok ErrorLow - Voltage too low ErrorHigh - Voltage too high.

Variables

- const uint16_t RawTodVolts = (1)
- const uint16_t dVoltsToRaw = (1)
- const uint16_t VoltageErrorLowThreshold_dV = 240u
- const uint16_t VoltageLowThreshold_dV = 260u
- const uint16_t VoltageHighThreshold_dV = 300u
- const uint16_t VoltageErrorHighThreshold_dV = 320u

4.33.1 Function Documentation

4.33.1.1 GetVoltage()

Get voltage from voltmeter.

Parameters

| out | voltage | level in dV |
|-----|---------|-------------|
|-----|---------|-------------|

4.33.1.2 GetVoltageRange()

Get range that the voltage falls into Possible ranges are Normal - Normal Operating Voltage Low - Voltage low, but ok High - Voltage high, but ok ErrorLow - Voltage too low ErrorHigh - Voltage too high.

Parameters

| out | Current | voltage range |
|-----|---------|---------------|
|-----|---------|---------------|

4.33.2 Variable Documentation

4.33.2.1 dVoltsToRaw

```
const uint16_t dVoltsToRaw = (1)
```

DeciCelcius (C*0.1) to raw value out of voltmeter

4.33.2.2 RawTodVolts

```
const uint16_t RawTodVolts = (1)
```

Raw value out of voltmeter to deciVolts (V*0.1)

4.33.2.3 VoltageErrorHighThreshold_dV

const uint16_t VoltageErrorHighThreshold_dV = 320u

High Voltage Error Level in dV

4.33.2.4 VoltageErrorLowThreshold_dV

const uint16_t VoltageErrorLowThreshold_dV = 240u

Low Voltage Error Level in dV

4.33.2.5 VoltageHighThreshold_dV

const uint16_t VoltageHighThreshold_dV = 300u

High Voltage Level in dV

4.33.2.6 VoltageLowThreshold_dV

const uint16_t VoltageLowThreshold_dV = 260u

Low Voltage Level in dV

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