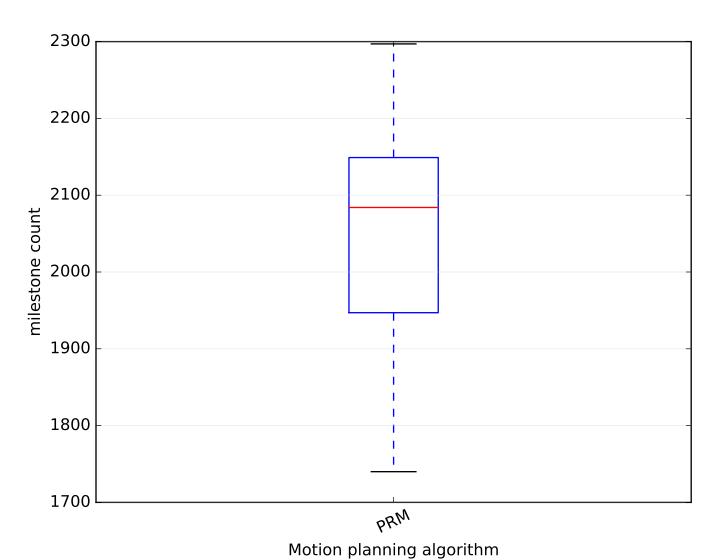
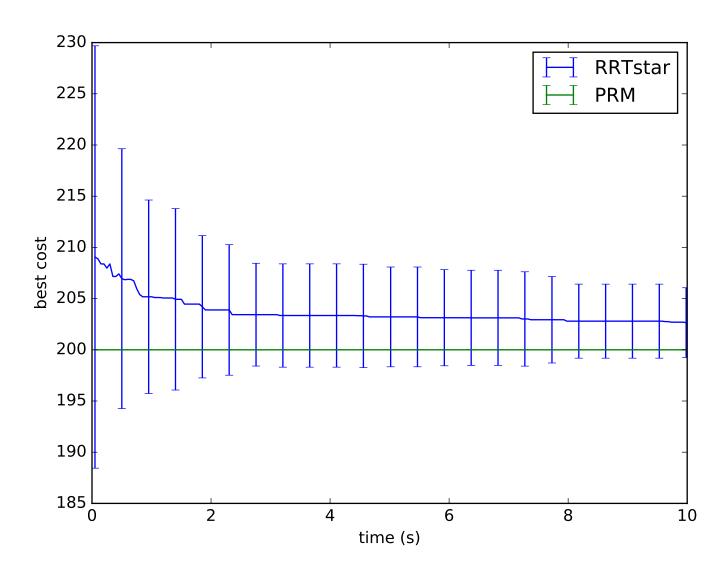
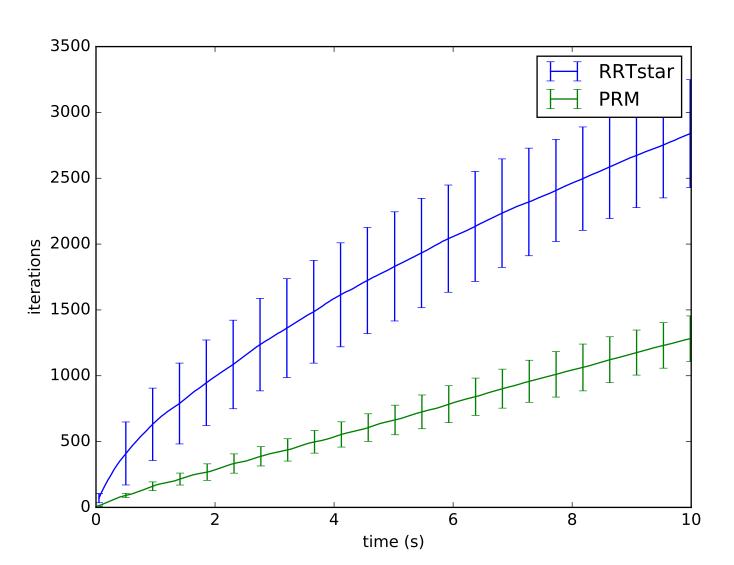
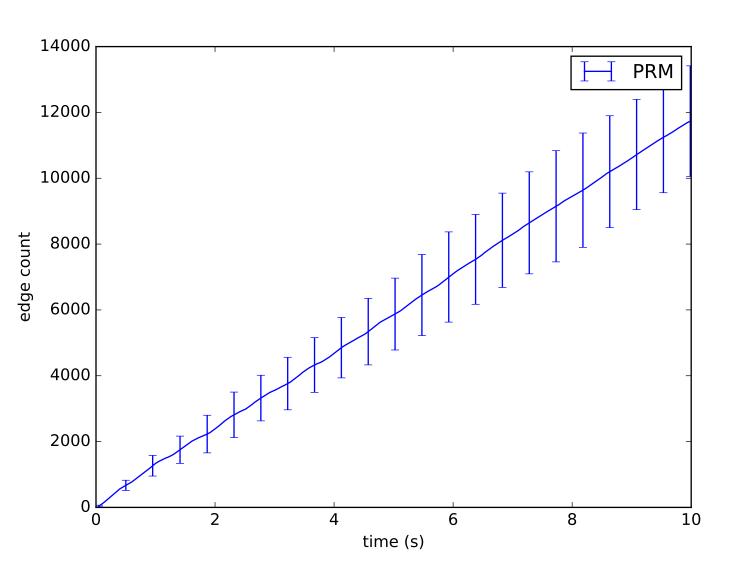


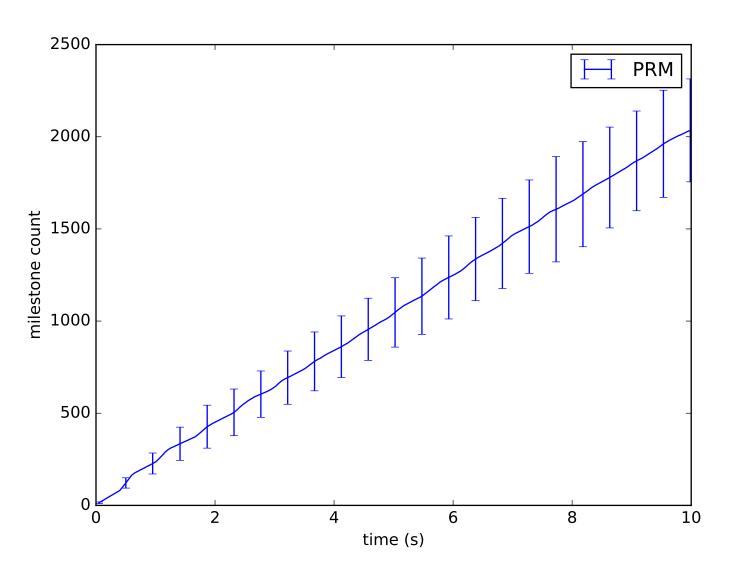
Motion planning algorithm











Experiment "quadrotor\_uniform\_sampler"

Number of averaged runs: 25

Time limit per run: 10 seconds

Memory limit per run: 10000 MB