

# Combining $l^1$ Penalization with Higher Moment Constraints in Regression Models

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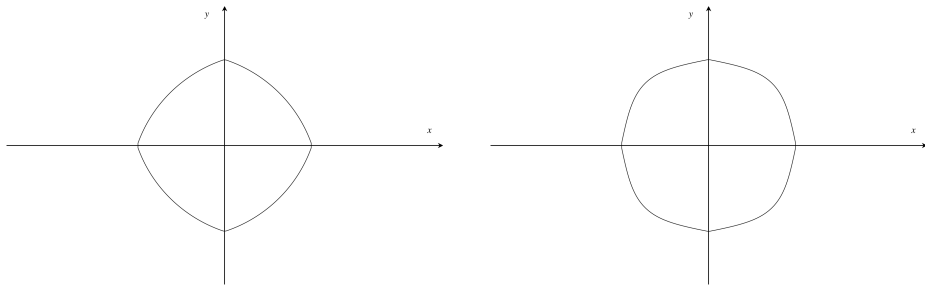
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# Motivation

- In statistics and probability theory it is common to impose moment assumptions on a random variable  $X : \Omega \rightarrow \mathbb{R}^n$  such as  $E(\|X\|^k) < \infty$  for  $k \in \mathbb{R}$ .
- These constraints correspond to the  $L^p$  spaces which allow control over the width and the height of such random variables. This can be interpreted as imposing "stability" on the random variable  $X$ .
- If statisticians so freely impose such constraints then we should build a tool to allow scientists and researchers to impose such constraints on their real problems.
- In this project, we build a package implements this idea. The goal is to build upon the "stability" property of ElasticNet [7] and create a tool available to scientists and researchers.

## Geometric Motivation

Consider for example an Elasticnet [7] penalty  $Q(x) = \frac{1}{2}|x| + \frac{1}{2}|y| + \frac{1}{2}|x|^2 + \frac{1}{2}|y|^2 \leq 1$  shown on the left. Extending this idea, a new penalty  $P(x) = \frac{1}{2}|x| + \frac{1}{2}|y| + \frac{1}{2}|x|^4 + \frac{1}{2}|y|^4 \leq 1$  shown on the right.



It seems reasonable that a scientist or researcher may want the option to "bow" out the feasible set even more.

# The Setup

Define a new penalty to try to impose more "stability" for scientists and researchers (try to extend the Elasticnet idea). Let

$$L_{\lambda}(\beta) = \frac{1}{2} \|y - X\beta\|_2^2 + \lambda P(\beta)$$

with penalty

$$\lambda P(\beta) = \lambda \alpha_0 \|\beta\|_1 + \lambda \sum_{k=1}^5 \alpha_k \|\beta\|_{2k}^{2k}$$

where  $y \in \mathbb{R}^n$ ,  $X \in M_{n \times p}(\mathbb{R})$ , and  $\beta \in \mathbb{R}^p$ ,  $\lambda \in \mathbb{R}_+$  and  $\alpha$ 's are convex combinations or use separate tuning parameters instead.

This is a convex, separable penalty separable, but the derivative is not Lipschitz.

# Algorithm Implementation 1

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**Algorithm 1:** Subgradient Coordinate Method

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Choose  $\beta^0 \in \mathbb{R}^p$  and tolerance  $\delta > 0$ ;

Set  $k \leftarrow 0$

**repeat**

    Set the step size  $h^k \leftarrow \frac{R}{\sqrt{1+k}}$  for some  $R > 0$  or use a constant step size.

    Permute  $I = \{1, \dots, p\}$

**for**  $i \in I$  **do**

        |  $\beta_i^{k+1} \leftarrow \beta_i^k - h^i g^i$  where  $g^i \in (\partial L)_i$

**end**

$k \leftarrow k + 1$

**until** *Until the loss difference  $\Delta L$  is less than  $\delta$ ;*

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# Drawbacks

- Not a descent method.
- No good stopping criterion.
- Convergence theory is worse.
- Tends to produce really small values instead of truly sparse solutions.

# A Much Better Algorithm

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**Algorithm 2:** Proximal Gradient Coordinate Descent

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Choose  $\beta^0 \in \mathbb{R}^p$  and tolerance  $\delta > 0$ ;

Set  $k \leftarrow 0$

**repeat**

    Set the step size  $h^k > 0$  with diminishing or line search.

    Randomly permute  $I = \{1, \dots, p\}$

**for**  $i \in I$  **do**

$\beta_i^{k+1} \leftarrow (\text{prox}_{h^k L})_i(\beta_i^k - h^k \langle X_i, y - X\beta \rangle)$

**end**

$k \leftarrow k + 1$

**until** *Until the Moreau-Yoshida mapping*  $M_{h_k, f} < \delta$ ;

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# Benefits

- A descent method, so can do line search.
- Good stopping criterion at  $O(p^2)$  flops.
- Convergence theory is unchanged from differentiable functions.



# Cross-Validation Implementation

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**Algorithm 3:** Warm Start Cross-Validation

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Choose a sequence of Lagrangian dual variables  $\lambda_1, \dots, \lambda_N$ , and initial value  $\beta^0$ .

Order  $\lambda_{(1)}, \dots, \lambda_{(N)}$  descending.

$\beta^{Warm} \leftarrow \beta^0$

**for**  $k \in 1, \dots, N$  **do**

$\beta^k \leftarrow$  by Cross-Validation with  $\lambda_{(k)}$  warm started with  $\beta^{Warm}$ .

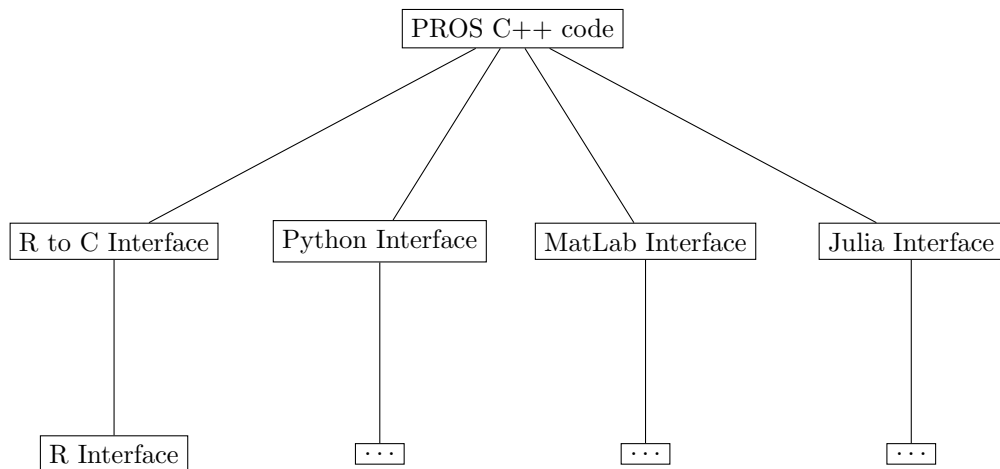
$\beta^{Warm} \leftarrow \beta^k$

**end**

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# Package Architecture

Written entirely in C++ for speed using Eigen [5] and can be interfaced to many other popular languages.



# Penalized Regression on Steroids

Installation:

```
> devtools::install_github("austindavidbrown/pros/R-package")
```

A single fit function with prediction

```
> fit <- pros(X, y, alpha, lambda)
> predict(fit, new_X)
```

A cross-validation fit function with prediction

```
> cv <- cv.pros(X, y, alpha)
> predict(cv, new_X)
```

There is even a [reference manual](#).

# The Prostate Cancer Dataset Analysis

This is a popular dataset from Stamey et al. [1] and analyzed in the ElasticNet paper Zou and Hastie [7]. There are 8 predictors and 1 response is the log of the prostate specific antigen.

- The data is split into a training set with 67 observations and a test set with 30 observations.
- The predictor data was standardized.
- 10-fold cross-validation and manual tuning due to time constraint of the project were used.
- The **glmnet** [6] library was used to fit and tune the Lasso and a naive un-tuned ElasticNet.
- **pros** [2] was used to fit the new penalty.
- This was not an extensive study due to time.

# The Prostate Cancer Dataset Results

Penalty	Tuning	Test MSE
Lasso Penalty (glmnet)	$\lambda = 0.001572009$	0.4558642
ElasticNet Penalty (glmnet)	$\alpha = (1/2, 1/2), \lambda = 0.01677868$	0.4539746
New Penalty (pros)	$\alpha = (1/3, 0, 0, 0, 0, 2/3, 0), \lambda = 20$	0.4443996
New Penalty (pros)	$\alpha = (1/5, 0, 1/5, 1/5, 1/5, 1/5, 0), \lambda = 50$	0.4479282

# Conclusion

- I would like to explore the remaining penalizations.

$$\lambda P'(\beta) = \lambda \alpha_1 \|\beta\|_1 + \lambda \alpha_2 \|\beta\|_\infty$$

$$\lambda P''(\beta) = \lambda \alpha_1 \|\beta\|_1 + \lambda \sum_{k=2}^{10} \alpha_k \|\beta\|_k$$

- Step size issue i.e. Find a fast line search.
- Look into convergence analysis.
- Most importantly, I think that we can bring new methods that may be useful to scientists and researchers and we can further study their properties.

# References

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- [2] PROS. [github.com/austindavidbrown/pros](https://github.com/austindavidbrown/pros)
- [3] Neal Parikh and Stephen Boyd. 2014. Proximal Algorithms. *Found. Trends Optim.* 1, 3 (January 2014), 127-239. DOI=10.1561/24000000003 <http://dx.doi.org/10.1561/24000000003>
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- [8] Yurii Nesterov. 2014. Introductory Lectures on Convex Optimization: A Basic Course (1 ed.). Springer Publishing Company, Incorporated.