

# Combining $l^1$ Penalization with Higher Moment Stability Constraints in Regression Models

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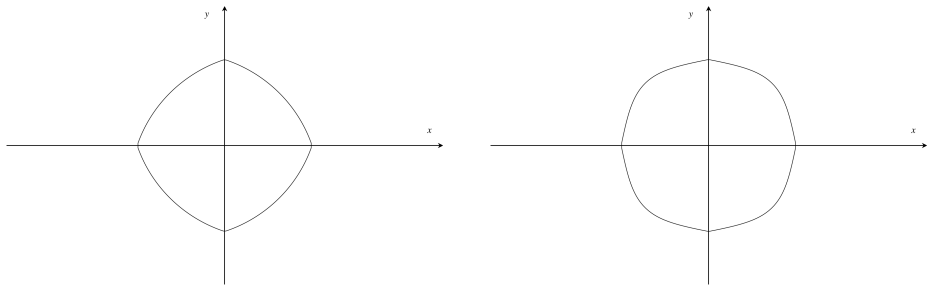
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# Motivation

- In statistics and probability theory it is common to impose moment assumptions on a random variable  $X : \Omega \rightarrow \mathbb{R}^n$  such as  $E(\|X\|^k) < \infty$  for  $k \in \mathbb{R}$ .
- These constraints correspond to the  $L^p$  spaces which allow control over the width and the height of such random variables. This can be interpreted as imposing "stability" on the random variable  $X$ .
- If statisticians so freely impose such constraints then we should build a tool to allow scientists and researchers to impose such constraints on their real problems.
- In this project, we build a package implements this idea. The goal is not to create the best predicting method, but instead build a tool that will allow researchers to explore stability and what a "stable" solution to their problem may look like.

## Geometric Motivation

Consider for example an Elasticnet [6] penalty  $Q(x) = \frac{1}{2}|x| + \frac{1}{2}|y| + \frac{1}{2}|x|^2 + \frac{1}{2}|y|^2 \leq 1$  shown on the left and a new penalty  $P(x) = \frac{1}{2}|x| + \frac{1}{2}|y| + \frac{1}{2}|x|^4 + \frac{1}{2}|y|^4 \leq 1$  shown on the right.



It seems reasonable that a scientist may want the option to "bow" out the feasible set even more.

# Penalizations

Define these penalizations to try to impose more "stability" for scientists and researchers (try to extend the Elasticnet idea)

$$P(\lambda) = \lambda \alpha_0 \|\beta\|_1 + \lambda \sum_{k=1}^5 \alpha_k \|\beta\|_{2k}^{2k}$$

$$P'(\lambda) = \lambda \alpha_1 \|\beta\|_1 + \lambda \alpha_2 \|\beta\|_\infty$$

$$P''(\lambda) = \lambda \alpha_1 \|\beta\|_1 + \lambda \sum_{k=2}^{10} \alpha_k \|\beta\|_k$$

where  $\lambda \in \mathbb{R}_+$  and  $\alpha$ 's are convex combinations or use separate tuning parameters instead. These are convex and  $P$  is uniformly convex!

# Objective

Let

$$L_{\lambda}(\beta) = \frac{1}{2} \|y - X\beta\|_2^2 + \lambda P(\beta)$$

be the objective with  $y \in \mathbb{R}^n$  centered,  $X \in M_{n \times p}(\mathbb{R})$  centered, and  $\beta \in \mathbb{R}^p$ .

- I only had time to do Euclidean loss but this can be extended.
- I only had time to implement the first penalization, so consider only the first one from here on out.
- I now know how to do the others actually.

# The Plan

- **glmnet** [5] uses coordinate descent, but the implementation cannot be used and a new algorithm needs to be used.

# Algorithm Implementation 1

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**Algorithm 1:** Subgradient Coordinate Method

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Choose  $\beta^0 \in \mathbb{R}^p$  and tolerance  $\delta > 0$ ;

Set  $k \leftarrow 0$

**repeat**

    Set the step size  $h^k \leftarrow \frac{R}{\sqrt{1+k}}$  for some  $R > 0$  or use a constant step size.

    Permute  $I = \{1, \dots, p\}$

**for**  $i \in I$  **do**

        |  $\beta_i^{k+1} \leftarrow \beta_i^k - h^i g^i$  where  $g^i \in (\partial L)_i$

**end**

$k \leftarrow k + 1$

**until** *Until the loss difference  $\Delta L$  is less than  $\delta$ ;*

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# Drawbacks

- Not a descent method.
- No good stopping criterion.
- The stopping criterion is also expensive at  $O(n^2)$  flops.
- Convergence theory is worse.
- Rarely produces sparse solutions really small values instead.



# A Much Better Algorithm

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**Algorithm 2:** Proximal Gradient Coordinate Descent

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Choose  $\beta^0 \in \mathbb{R}^p$  and tolerance  $\delta > 0$ ;

Set  $k \leftarrow 0$

**repeat**

    Set the step size  $h^k > 0$  with diminishing or line search.

    Randomly permute  $I = \{1, \dots, p\}$

**for**  $i \in I$  **do**

$\beta_i^{k+1} \leftarrow (\text{prox}_{h^k L})_i(\beta_i^k - h^k \langle X_i, y - X\beta \rangle)$

**end**

$k \leftarrow k + 1$

**until** *Until the Moreau-Yoshida mapping*  $M_{h_k, f} < \delta$ ;

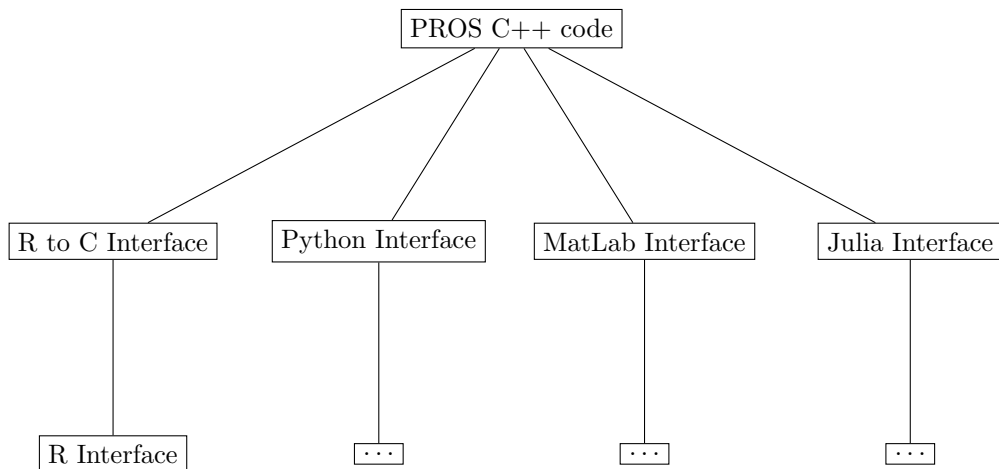
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# Benefits

- A descent method, so can do line search.
- Good stopping criterion at  $O(p^2)$  flops.
- Convergence theory is unchanged from differentiable functions.

# Architecture

Written entirely in C++ for speed using Eigen [4] and can be interfaced to many other popular languages.



# Simple, Familiar Interface and No Dependencies

A single fit function with prediction

```
> fit <- pros(X, y, alpha, lambda)
> predict(fit, new_X)
```

A cross-validation fit function with prediction

```
> cv <- cv.pros(X, y, alpha)
> predict(cv, new_X)
```

Ran out of time for plotting, but this would be cool.  
No dependencies! I did not use RCPP.

# Cross-Validation Implementation

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**Algorithm 3:** Warm Start Cross-Validation

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Choose a sequence of Lagrangian dual variables  $\lambda_1, \dots, \lambda_N$ , and initial value  $\beta^0$ .

Order  $\lambda_{(1)}, \dots, \lambda_{(N)}$  descending.

$\beta^{Warm} \leftarrow \beta^0$

**for**  $k \in 1, \dots, N$  **do**

$\beta^k \leftarrow$  by Cross-Validation with  $\lambda_{(k)}$  warm started with  $\beta^{Warm}$ .

$\beta^{Warm} \leftarrow \beta^k$

**end**

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# Penalized Regression on Steroids

## Penalized Regression on Steroids on Github

- The name doesn't fit really since I only implemented 1 penalization
- Talk about python prototype
- Show how to download
- Show the reference manual

# Open Questions

How to handle users and step sizes since we want to make it easy for users to use.  
Backtracking line search?

# References

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- [2] Neal Parikh and Stephen Boyd. 2014. Proximal Algorithms. *Found. Trends Optim.* 1, 3 (January 2014), 127-239. DOI=10.1561/2400000003 <http://dx.doi.org/10.1561/2400000003>
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- [4] Guennebaud, Gaël (2013). Eigen: A C++ linear algebra library (PDF). Eurographics/CGLibs.
- [5] Jerome Friedman, Trevor Hastie, Robert Tibshirani (2010). Regularization Paths for Generalized Linear Models via Coordinate Descent. *Journal of Statistical Software*, 33(1), 1-22. URL <http://www.jstatsoft.org/v33/i01/>.
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- [7] Yurii Nesterov. 2014. *Introductory Lectures on Convex Optimization: A Basic Course* (1 ed.). Springer Publishing Company, Incorporated.