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VFB

2016/06/13

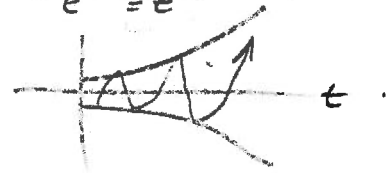
INSTABILITY SUPPRESSION WITH VELOCITY FEEDBACK

Assume a 2nd order system with negative damping, $\zeta < 0$. Hence, the response will be unstable:

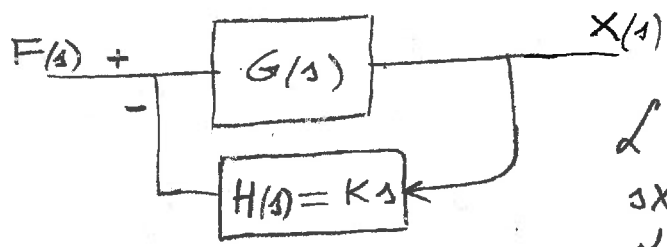
$$e^{-\zeta \omega_n t} = e^{|\zeta| \omega_n t}$$

$$\zeta < 0$$

$$-\zeta \omega_n = |\zeta| \omega_n$$



We can use FB to suppress this instability.



$\mathcal{L} \dot{x} = sX$
 sX is the LT of velocity!

$$G_{CL} = \frac{G}{1+GH} = \frac{\omega_n^2}{1 + \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} Ks}$$

$$= \frac{\omega_n^2}{s^2 + (2\zeta\omega_n + K\omega_n^2)s + \omega_n^2} \quad (1)$$

$$G_{CL} = \frac{\omega_n^2}{s^2 + 2\zeta_{CL}\omega_n s + \omega_n^2} \quad (2)$$

FB4
2018/022 (1)&(2):

$$2\zeta_{CL} = 2\zeta + K\omega_n$$

$$\zeta_{CL} = \zeta + \frac{K\omega_n}{2} \quad (3)$$

- 1) Velocity feedback increases damping.
- 2) If the initial system is unstable because it has -ve damping ($\zeta < 0$), then velocity feedback can give the CL system a positive damping, $\zeta_{CL} > 0$.

Solve Eq. (3) to get

$$K = \frac{2}{\omega_n} (\zeta_{CL} - \zeta) \quad (4)$$

Critical gain K_{cr} is the gain that makes $\zeta_{CL} = 0$.

Recall Eq (3) and set it to zero to get

$$\zeta + \frac{K\omega_n}{2} = 0 \rightarrow K_{cr} = -\frac{2\zeta}{\omega_n} \quad (5)$$

Example:

$$\zeta = -5\% = -0.05$$

$$f_n = 4 \text{ Hz}$$

$$\omega_n = 2\pi \times 4 = 8\pi \text{ rad/s}$$

$$K_{cr} = -\frac{2 \times (-0.05)}{8\pi} \approx 0.004$$

For $K > K_{cr}$ the system is stable ✓

FB4a
20/8/022

Calculation of FB gain K

Recall (4) $K = \frac{2}{\omega_n} (\zeta_{CL} - \zeta)$

Factor out ζ to get $K = -\frac{2\zeta}{\omega_n} \left(1 - \frac{\zeta_{CL}}{\zeta}\right)$

Recall (5) and write

$$K = K_{cr} \left(1 - \frac{\zeta_{CL}}{\zeta}\right) \quad (6)$$

Define ζ_{ratio} as

$$\zeta_{ratio} = \frac{\zeta_{CL}}{\zeta} \quad (7)$$

(7) \rightarrow (6):

$$K = K_{cr} (1 - \zeta_{ratio}) \quad (8)$$

Eg (8) gives the FB gain K as a function of ζ_{ratio}

Gain ratio K_{ratio}

Divide Eg (8) by K_{cr} to get

$$K_{ratio} = 1 - \zeta_{ratio} \quad (9)$$

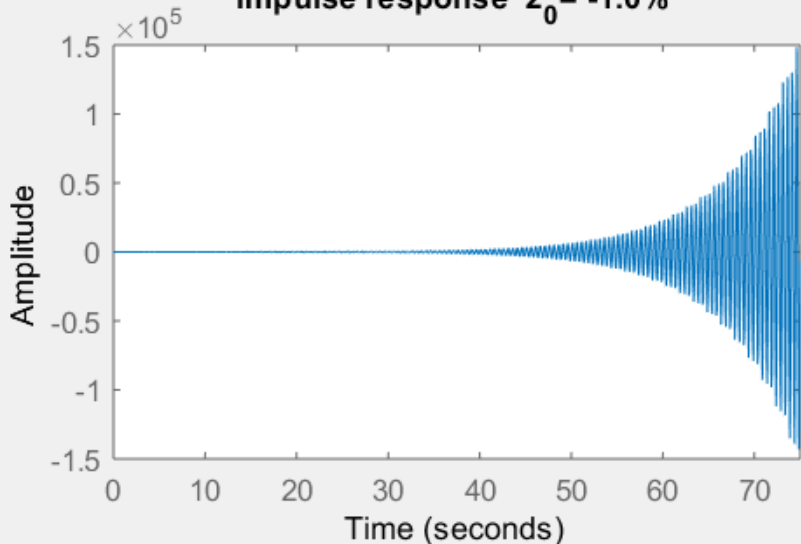
Discussion of Eg. (8)

(a) if $\zeta < 0$, then $\zeta_{ratio} < 0$, $K_{cr} > 0 \rightarrow \boxed{K > 0}$

(b) if $0 < \zeta < \zeta_{CL}$, then $K_{cr} < 0$, $\zeta_{ratio} > 1$, $(1 - \zeta_{ratio}) < 0$, $\boxed{K > 0}$

(c) $\zeta < \zeta_{CL}$, then $K_{cr} < 0$, $\zeta_{ratio} < 1$, $1 - \zeta_{ratio} > 0$, $\boxed{K < 0}$
reduce ζ_{CL}

impulse response $z_0 = -1.0\%$



FB Impulse response, $z_{CL} = 3\%$, $K=0.0063662$

$K_{ratio}=4$, $z_0 = -1.0\%$

