Time Response to harmonic excitation

 $f(t) = \sin \omega t$   $\Rightarrow Sys.$   $x(t) = X \sin(\omega t + \varphi)$ 

One is interested in fineding how the system responds to harmonic excitation of different frequency values,  $\omega = 2\pi f$ 

Ex: For a 2 udorder système, one is concerned with avoiding resonance where the response may become very large X(0)

1 July f(t)= smot

2 F

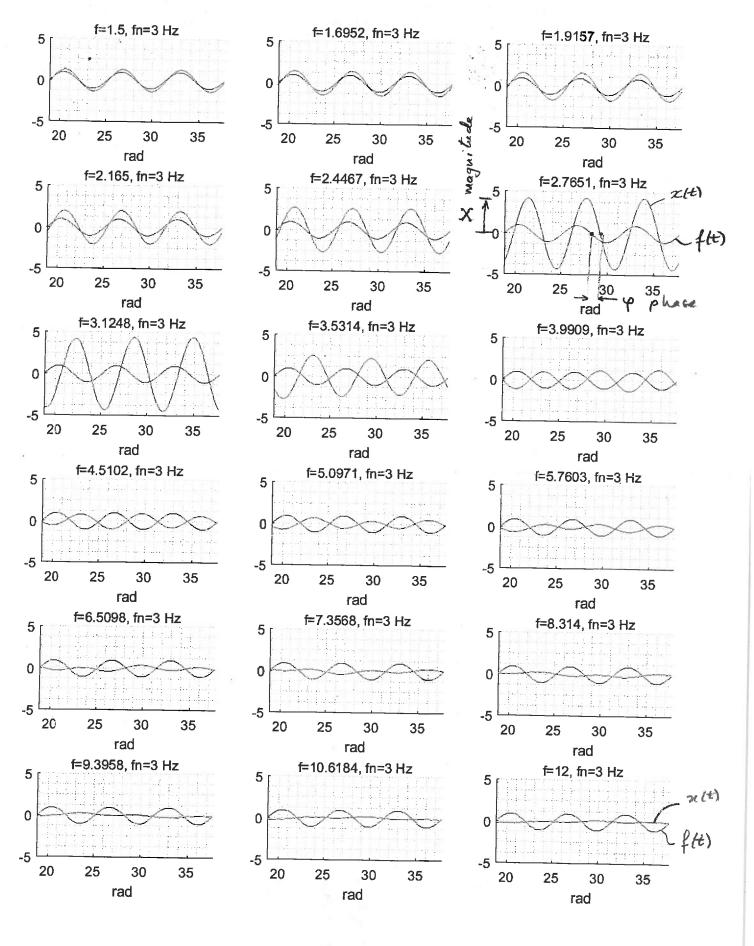
It (t) = X(w) sin (wt+ q(w))

 $\hat{J} = \frac{c}{2\sqrt{km}}, \quad \omega_n = \sqrt{\frac{k}{m}}.$ 

and = an /1-52

We notice that the amplitude and phose of the time response varies with excitation freez. W

## fire) = sin (wt), w = 2 Tif x(t) = 2 nd order system response to fix)



f(x) = sm wt = x(w) sin [wt + \( \psi \) [w] X(w) = magnitude of response 4(w) = phase of response Magnitude X and phase of vary with excitation Bode diagram plots: variation of X(w) & 4(w) 2nd order sys Bode diag. Magnitude (dB) -60 -80 -45 Phase (deg) -90 -135 -180 10<sup>0</sup> 101 10<sup>2</sup> 10<sup>3</sup> Frequency (rad/s) gis-re, lags behind the excitation. 294/523

## C:\Mydata\1 USC\c...\FRF 2ndOrderSys\_20161214.m

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```
1 % Amplitude_and_phase_2ndOrderSys.m
 2 % AMPLITUDE AND PHASE IN FREQUENCY RESPONSE
 3 clc
 4 clear
 5 close all
 6 s = tf('s');
 7 % f=input('f=');
 8 figure (1);
 9 %% 2nd order system
10 fn=3; z=10e-2; wn=2*pi*fn; G2=wn^2/(s^2+2*z*wn*s+wn^2);
11 M=6; N=3; Nplots=M*N;
12 fmin=fn/2; fmax=fn*4;
13 a=log10(fmin); b=log10(fmax); f=logspace(a,b,Nplots);
14 %% plotting setup
15 Na=1e3; amax=10*2*pi; da=amax/Na; angle=0:da:amax;
16 xmin=0.3*Na*da; xmax=0.6*Na*da;
17 %% plot respose at various frequencies
18 for i=1:Nplots
19 w=2*pi*f(i); % excitation frequency
20 t=angle/w;
                 % time steps at this excitation freq.
21 A=1; % forcing function amplitude
22 F=A*w/(s^2+w^2);
                        % Laplace transform of sine forcing function
23 fe=impulse(F,t); % time response of forcing function
24 X2=G2*F;
                   % Laplace transform of 2nd order system response
25 subplot(M,N,i);
26 x2=impulse(X2,t); % time response of 2nd order system
27 plot(angle,fe,angle,x2); hold on
28 title(['f=' num2str(f(i)) ', fn=' num2str(fn) ' Hz' ],...
     'FontSize', 10, 'FontWeight', 'normal')
30 xlabel('rad'); xlim([xmin xmax]); ylim([-5*A 5*A]);
31 % grid on
32 grid minor; box off
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## 

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```
33 end
34 %% FRF Bode plots
35 figure(2)
36 bode(G2); grid on; title('2nd order sys Bode diag.');
37 aw=log10(2*pi*fn/2); bw=log10(2*pi*fn*2); N=1e4; wBode=logspace(aw,bw,N);
38 figure(3)
39 bode(G2,wBode); grid on; title('zoom 2nd order sys Bode diag.' );
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