

CS 450 Module R3 Dispatching

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Goals

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- Support cooperative multitasking via `sys_req(IDLE)` and `sys_req(EXIT)`
- Implement commands to demonstrate processes loading, executing, and exiting properly
- Some Assembly required ;)

Background

Review: A Process is a Program in Execution

- The CPU has various registers – Most relevant here are the Instruction Pointer and the Stack Pointer
- Variables and the function call stack (list of future Instruction Pointers) are stored on the stack (on x86 – other architectures differ)
- Heaps come in R5
- Registers, stack, and heap are everything necessary to save, load, or fork a running process – collectively called the **context**

Context

Switch

- An event where one process gives up the CPU to another
 - Save the process *context* of the currently running process (we'll use the PCB stack space for this)
 - Move the pausing current process to the appropriate queue
 - Select the next process to execute
 - Load the new process's context
- Minimal Context on x86 (a struct should hold all of these registers):
 - Segment Registers: CS, DS, ES, FS, GS, SS
 - Status Control Registers: EIP, EFLAGS
 - General Purpose Registers: EAX, EBX, ECX, EDX, ESI, EDI, EBP, ESP

- More info: <http://flint.cs.yale.edu/cs422/doc/pc-arch.html>



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When to Context Switch in MPX

- MPX is *cooperatively* multitasking – processes willingly give up the CPU
- An MPX process yields the CPU by calling `sys_req(IDLE)`
- An MPX process terminates by calling `sys_req(EXIT)`
- You will implement support for both of these operations in this module

How C Functions Work (on 32-bit x86)

- Function parameters are *pushed* onto the stack, from right-to-left (i.e. the first parameter is pushed last)
- The compiler issues a call instruction with a function's address as its parameter
- The CPU pushes the address of the next instruction (the *return address*) onto the stack
- The CPU jumps to the address provided and executes until a ret instruction
- The CPU *pops* the return address from the stack and resumes execution there
- The *return value* of the previous function is in EAX

How Interrupts Work (on 32-bit x86)

- An `int` instruction is issued with a one-byte IRQ parameter
- The CPU *pushes* (in order) EFLAGS, CS, and EIP (*the return address*) onto the stack
- CPU examines the interrupt table and jumps to the Interrupt Service Routine (ISR) referenced by the IRQ in the interrupt table
- Execution continues until an `iret` instruction
- The CPU *pops* the EIP(*return address*), CS, and EFLAGS from the stack
- Ordinary execution resumes at the return address

Writing ISRs

ISR-> Interrupt Service Routine

- Requirements placed on an ISR
 - Save the contents of general purpose registers (e.g. push them onto the stack)
 - Service the interrupt
 - Restore the contents of the general purpose registers (e.g. pop them from the stack)
 - Return (with the `iret` instruction, **not** `ret`)
- Your ISR can use the stack space in each PCB for context switching
 - Reserve enough space at the top for register contents
 - YOUR **ISR** will push and pop from that space when switching

Intel Assembly

[Look at file sys_call_isr.s for a ISR stub](#)

- push – Push the specified value or register onto the stack
- pusha – Push all general purpose registers onto the stack
- pop – Pop the last value from the stack to the specified register
- popa – Pop all the general purpose registers from the stack
- mov – Copy data from one memory address or register to another memory address or register
- call – Call a function
- iret – Return from an ISR

Kernel Functions

ISR sys_call_isr (A stub is provided in
sys_call_isr.s

- Clang cannot directly generate complex ISRs, so at least some of the ISR must be written in Assembly
- You will probably find things easier to implement most of it in C (referred to here as `sys_call()`), and call that from the Assembly stub

ISR Assembly Outline

- Remember that the CPU pushes EFLAGS, CS, and EIP automatically (in that order)
- Push all general purpose registers and remaining segment registers onto the stack in the opposite order as they are defined in your context struct
- Push ESP – At this point, ESP is a pointer to a manually created context struct, and pushing it makes it a C function parameter
- Call your C function
- Set ESP based on the return value of your function (EAX)
- Pop registers in order of your struct
- Return from ISR

`struct context *sys_call(struct context *)`

- Take one parameter that is a pointer to a struct representing the context of the current process
- Return a pointer to the context of the process to be loaded
- You'll need a global PCB pointer representing the currently executing process – it should initially be NULL
- You'll also need a global or static context pointer representing the context from the first time `sys_call()` is entered
 - This should initially be NULL
 - If it is NULL, set it to point to the context provided as a parameter
 - When the last process issues an EXIT request, this is the context you will load

System Call Parameters and Return Value

- How do the parameters to `sys_req()` (e.g. IDLE) get to `sys_call()`?
- The interrupt convention doesn't place them on the stack, so MPX places them in registers EAX, EBX, ECX, and EDX (in that order)
- This is done by `sys_req`
- So, in the parameter to your C function, the EAX member will have the operation code (e.g. IDLE)
- Similarly, when your C function returns, it should set the EAX member to the return value that `sys_req()` will see and return
- **If the operation code is anything but IDLE or EXIT, do not load any new context and set the return value to -1**



System Call Operation: IDLE

- If there are any ready, non-suspended PCBs in the queue, remove the first from the queue and store it in a temporary variable as the next process
- Save the context of the current PCB by updating its stack pointer
- Add the current PCB back to the queue
- Return the context of the next process
- If the PCB queue is empty, or only consists of blocked or suspended PCBs, continue with the current process
- In all cases, ensure that the return value seen by sys_req() is 0

System Call Operation: EXIT

- Delete the currently running PCB
- If there are any ready, non-suspended PCBs in the queue, load the first as in IDLE
- If the PCB queue is empty, or only consists of blocked or suspended PCBs, load the original context
- In all cases, ensure that the return value seen by `sys_req()` is 0

User Commands

Yield

Pausing your command handler

- Cause Command Handler to yield the CPU
- If any processes are in queue, they will execute
- Literally a one-liner: `sys_req(IDLE);`

Load R3 -- there will be 3 versions

- LoadR3 -- Loads the R3 test processes from <processes.h>
- Each process (one per function) is loaded and queued in a non-suspended ready state, with a name and priority of your choosing
- Initialize and save the context for each process at the top of the PCB stack:
 - CS must be 0x08, all other segments 0x10
 - EBP must be the bottom of the PCB stack
 - ESP must be the top of the PCB stack
 - EIP must be a pointer to the function (the name of the function, without parenthesis, is a pointer to that function)
 - EFLAGS must be 0x0202
 - All other registers should be 0



- LoadR3Suspended –
 - Loads all R3 processes but sets the status to **ready suspended**
- LoadProcess <name> --
 - Loads a single process giving one of the process names
proc1 -> proc5
 - The process will be loaded as a ready **non-suspended process**
- Resume all -- resumes all ready suspended processes

Remove Command: Create PCB

- Disable the Create PCB Command completely

Final Notes

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- Remember to update:
 - Commands: Version and Help
 - Documentation: User's and Programmer's Manuals; Contributions
- Remember to set aside space for context in PCB stack – you may need to modify `setup_pcb()` to account for this
- Pay attention to compiler output to fix errors and warnings
- Use the debugger
- Don't confuse the members of your context struct with their use outside the struct
- This is the most difficult module – procrastination *will* negatively affect you