

CS 450 Module R2

PCB Operations

West Virginia University

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Goals

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- Establish Process Control Blocks (PCBs) for tracking and managing processes
- Emplace PCBs in queues to enable scheduling
- Implement commands for managing PCBs

Background

Process Control Blocks 1/2

- For multiprocessing, MPX needs to track processes with these attributes
- Name – A user readable string capable of storing at least 8 characters, unique to each process
 - Process names can have a limit, but that limit has to be at least 8 characters
 - This does **not** mean process names need to be at least 8 characters
- Class – Indicates whether a process us a user application or system process
- Priority – An integer between 0 (highest priority) and 9 (lowest priority)
- State – Two data points
 - Execution state – ready, running, or blocked
 - Dispatching state – suspended or not suspended

Process Control Blocks 2/2

- Stack – A process stack area of at least 1024 bytes
 - **Not** a separate data structure, just memory space for the CPU stack
 - The stack should initialized to all binary 0
- Stack Pointer – A pointer to the current location (in the Stack) used by CPU instructions
 - On x86, the CPU stack grows *down*, so stack pointer should initially point to the last few bytes (enough to hold a *void **) of the stack
- Related PCBs – For building queues, you'll likely want pointers for creating singly- or doubly-linked lists

Process Queues

- Used to track processes in similar states
- Ready processes should be sorted by priority (low-to-high), then FIFO (first in, first out) for PCBs of the same priority
- Blocked processes should be in simple FIFO order
- Implementation
 - Option 1: Ready and Blocked queues
 - Option 2: Ready, Blocked, Suspended-Ready, and Suspended-Blocked queues
 - Option 3: Everything in one big queue
 - Option 4: Surprise me

Kernel Functions

```
struct pcb* pcb_allocate(void);
```

- Uses `sys_alloc_mem()` to allocate memory for a new PCB, including the stack, and perform reasonable initialization
- Parameters:
 - None
- Returns:
 - A pointer to a newly allocated PCB on success
 - NULL on error during allocation or initialization

```
int pcb_free(struct pcb*);
```

- Uses sys_free_mem() to free all memory associated with a PCB, including the stack
- Parameters:
 - A pointer to the PCB to free
- Returns:
 - A code indicating success or error

```
struct pcb* pcb_setup(const char *, int, int);
```

- Allocates (via `allocate_pcb()`) a new PCB, initializes it with data provided, and sets the state to Ready, Not-suspended
- Parameters:
 - The process name
 - The process class (user application or system process)
 - The process priority (0-9)
- Returns:
 - A pointer to the initialized PCB on success
 - NULL on error allocating, initializing, or invalid parameter

```
struct pcb* pcb_find(const char *);
```

- Searches all process queues for a process with the provided name
- Parameters:
 - The name of the process to find
- Returns:
 - A pointer to the found PCB on success
 - NULL if the provided name was not found

```
void pcb_insert(struct pcb*);
```

- Inserts a PCB into the appropriate queue, based on state and (if Ready) priority
- Parameters:
 - A pointer to the PCB to enqueue
- Returns:
 - None

```
int pcb_remove(struct pcb*);
```

- Removes a PCB from its current queue, but does not free any associated memory or data structures
- Parameters:
 - A pointer to the PCB to unqueue
- Returns:
 - A success or error code

User Commands

Create PCB

- Calls `pcb_setup()` to create a PCB, then inserts it into the appropriate queue with `pcb_insert()`
- Parameters:
 - Process Name
 - Process Class
 - Process Priority
- Error Checking:
 - Name must be unique and valid
 - Class must be valid
 - Priority must be valid

Delete PCB

- Finds the requested process, removes it from its queue with `pcb_remove()`, and frees all associated memory with `pcb_free()`
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid
 - Must **not** be a System process

Block PCB

- Puts a process in the blocked state, and moves it the appropriate queue
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid

Unblock PCB

- Puts a process in the unblocked (ready) state, and moves it the appropriate queue
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid

Suspend PCB

- Puts a process in the suspended state, and moves it the appropriate queue
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid
 - Must **not** be a System process

Resume PCB

- Puts a process in the not suspended state, and moves it the appropriate queue
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid

Set PCB Priority

- Changes a process's priority, and moves it to the appropriate place in the appropriate queue
- Parameters:
 - Process Name
 - New Priority
- Error Checking:
 - Name must be valid
 - Priority must be valid (0-9)

Show PCB

- Displays a process's:
 - Name
 - Class
 - State
 - Suspended Status
 - Priority
- Parameters:
 - Process Name
- Error Checking:
 - Name must be valid

Show Ready

- For all processes in the Ready state, display the process's:
 - Name
 - Class
 - State
 - Suspended Status
 - Priority
- Parameters:
 - None
- Error Checking:
 - None

Show Blocked

- For all processes in the Blocked state, display the process's:
 - Name
 - Class
 - State
 - Suspended Status
 - Priority
- Parameters:
 - None
- Error Checking:
 - None

Show All

- For all processes (in any state), display the process's:
 - Name
 - Class
 - State
 - Suspended Status
 - Priority
- Parameters:
 - None
- Error Checking:
 - None

Final Notes

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- Remember to update:
 - Commands: Version and Help
 - Documentation: User's and Programmer's Manuals; Contributions
- Provide clear error messages – Referencing the manual should not be necessary to interpret errors
- Vary your testing – Don't simply repeat the exact same steps every time
- Pro tip: If your PCBs have pointers for a linked list, you don't need a separate data structure for queues
- Use the debugger