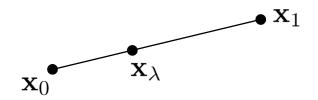
Learning from Data Convex Sets, Functions, and Optimization

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Convex Set

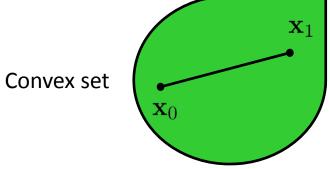
• Line-segment $[x_0, x_1]$ joining two points x_0 and x_1 in \mathbb{R}^d is given by:

$$\{x_{\lambda} = (1 - \lambda)x_0 + \lambda x_1, \lambda \in [0,1]\}$$



• Convex set: A set $C \subseteq \mathbb{R}^d$ is called convex if for any two points $x_0, x_1 \in C$, the line segment $[x_0, x_1]$ joining them also lies in C:

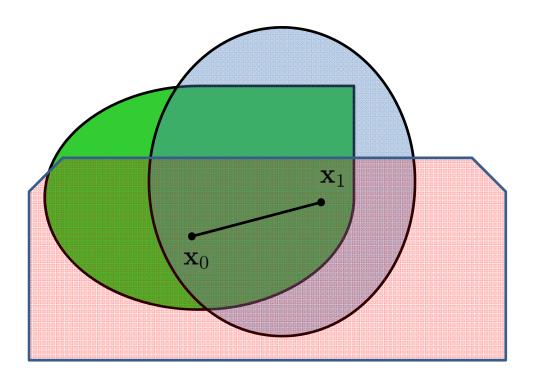




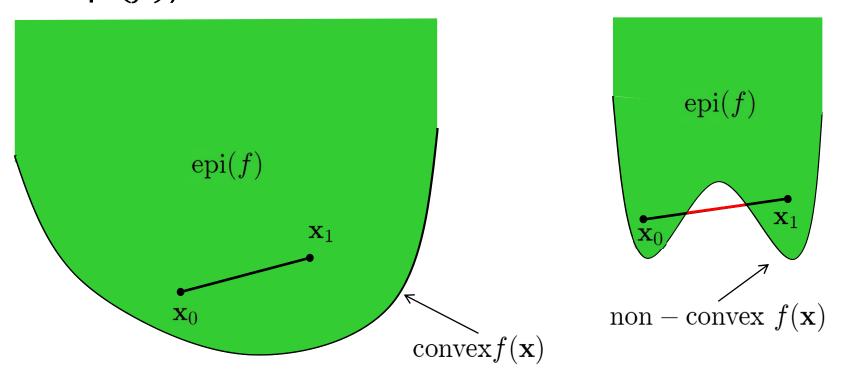


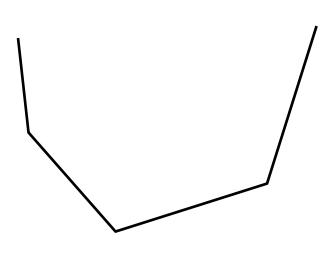
Convex Set

• The intersection of convex sets is convex

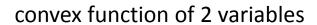


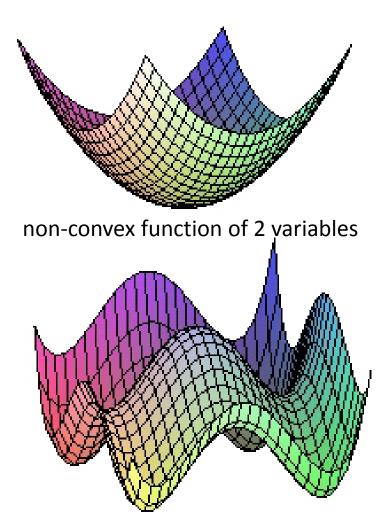
- Let C be a convex set and $f: C \to \mathbb{R}$ a real-valued function over C
- f is said to be a convex function over C if the region above the graph of the function (called its epigraph or epi(f)) is a convex set.





convex, but not differentiable everywhere

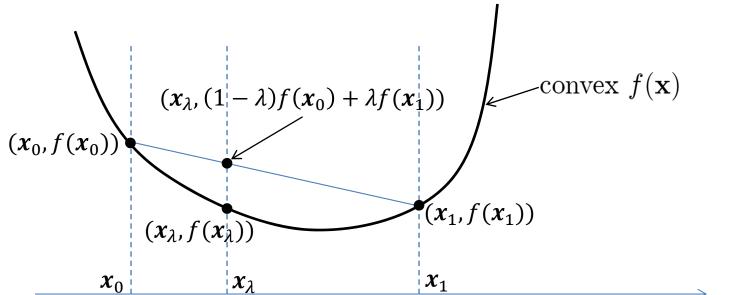




- Let C be a convex set and $f: C \to \mathbb{R}$ a real-valued function over C
- f is convex over $C \Leftrightarrow$ chord joining any two points on the graph, never goes below the graph:

$$\forall x_0, x_1 \in C, \forall \lambda \in [0,1],$$

$$f(\mathbf{x}_{\lambda}) = f((1-\lambda)\mathbf{x}_0 + \lambda\mathbf{x}_1) \le (1-\lambda)f(\mathbf{x}_0) + \lambda f(\mathbf{x}_1)$$



• f is convex over $C \Leftrightarrow$ all chords joining any two points on the graph, never go below the graph: $\forall x_0, x_1 \in C, \forall \lambda \in [0,1],$

$$f(\mathbf{x}_{\lambda}) = f((1-\lambda)\mathbf{x}_0 + \lambda\mathbf{x}_1) \le (1-\lambda)f(\mathbf{x}_0) + \lambda f(\mathbf{x}_1)$$

• If equality only when $x_0 = x_1$ or $\lambda = 0.1$ then f is strictly convex (no planar segments in graph)

convex, but not strictly convex $f(\mathbf{x})$ $(x_{\lambda}, f(x_{0}))$ $(x_{\lambda}, f(x_{\lambda}))$ $(x_{\lambda}, f(x_{\lambda}))$ $(x_{\lambda}, f(x_{\lambda}))$ $(x_{\lambda}, f(x_{\lambda}))$ $(x_{\lambda}, f(x_{\lambda}))$ $(x_{\lambda}, f(x_{\lambda}))$

Real-valued affine function

A real-valued function of the form:

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + b,$$

where $x, a \in \mathbb{R}^d$, $b \in \mathbb{R}$, is called a real-valued affine function over \mathbb{R}^d

 A real-valued affine function is a convex function, but it is not strictly convex

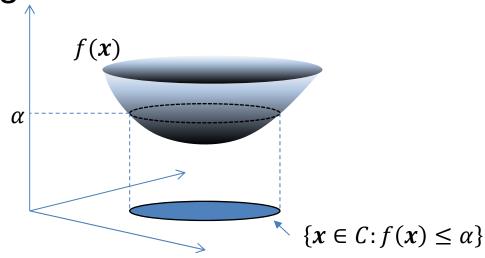
Sublevel sets of a convex function

The set of points of the form

$$\{x \in C: f(x) \le \alpha\}$$

is called the α -sublevel set of the function f with domain C

 If f is convex over a convex set C, then all its αsublevel sets are also convex. The reverse does not hold in general



Jensen's inequality for convex functions

- Let f be convex over a convex set C.
- Let X be any random vector whose probability distribution has a support contained in C
- Then,

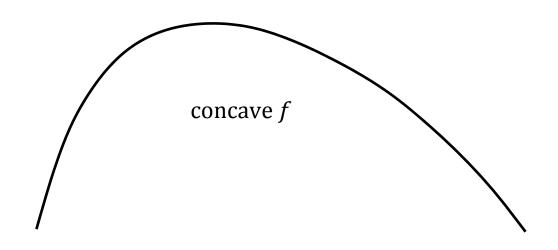
$$f(E[X]) \leq E[f(X)]$$

value at mean is not more than mean of values

If f is also strictly convex, then equality can be attained in Jensen's inequality, if, and only if,
 X = constant with probability one.

• f is concave over a convex set $C \Leftrightarrow -f$ is convex over C

• f is strictly concave over a convex set $C \Leftrightarrow -f$ is strictly convex over C



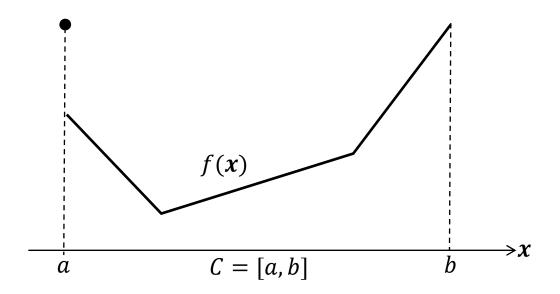
Operations that preserve convexity

- If f is convex, so is αf , for any $\alpha \geq 0$
- If $f_1, f_2, ..., f_k$ are each convex, then so is $f(x) = f_1(x) + f_2(x) + \cdots + f_k(x)$ The sum of convex functions is convex
- If $f_1, f_2, ..., f_k$ are each convex, then so is $f(x) = \max(f_1(x), f_2(x), ..., f_k(x))$ The maximum of convex functions is convex
- If f is convex and g is non-decreasing and convex, then h(x) = g(f(x)) is convex: a nondecreasing convex function of a convex function is convex
- If $f(x), x \in \mathbb{R}^d$, is convex, so is: h(z) = f(Az + b), for any $d \times k$ matrix $A, k \times 1$ vector variable z, and $d \times 1$ constant vector b: a convex function of an affine map is convex

Continuity of convex functions

- Let C be a convex set with a non-empty interior
- If f is convex over C then it is continuous over C's interior, but may have a jump discontinuity at C's boundary

f convex over [a, b]. It is continuous over (a, b), but discontinuous at a



Differentiable convex functions

• Let f is be differentiable over a convex set C with gradient vector of first-order partial derivatives:

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f}{\partial x_1}(\mathbf{x}), \dots, \frac{\partial f}{\partial x_d}(\mathbf{x})\right)^T$$

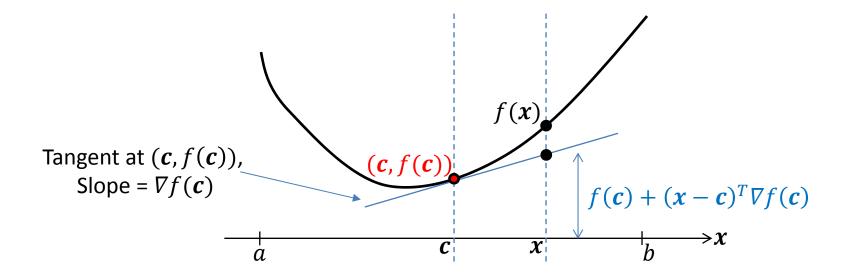
 Then f is convex over C, if, and only if, its graph never goes below the tangent plane constructed at any point:

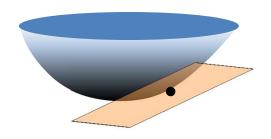
For all
$$x, c \in C$$
, $f(c) + (x - c)^T \nabla f(c) \le f(x)$

Differentiable convex functions

• For all $x, c \in C$, $f(c) + (x - c)^T \nabla f(c) \le f(x)$

f convex over C = [a, b] and differentiable over (a, b)





Twice-differentiable convex functions

• Let *f* is be twice-differentiable over a convex set *C* with a Hessian matrix of second-order partial derivatives:

$$\nabla^2 f(\mathbf{x}) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2}(\mathbf{x}) & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_d}(\mathbf{x}) \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_d \partial x_1}(\mathbf{x}) & \cdots & \frac{\partial^2 f}{\partial x_d^2}(\mathbf{x}) \end{pmatrix}$$

Then f is convex (strictly convex) over C, if, and only if,
 ∇²f(x) is positive semidefinite (positive definite) for all x ∈ C:

For all
$$x \in C$$
, $\nabla^2 f(x) \ge 0$

Examples

•
$$C = (0, \infty), f(x) = -\ln(x)$$

$$\frac{d^2 f(x)}{dx^2} = \frac{1}{x^2} > 0, \forall x \in C \Rightarrow f \text{ is (strictly) convex over } C$$

$$\Rightarrow \forall x \in C, f(1) + (x - 1)f'(1) \leq f(x)$$

$$\Rightarrow \forall x \in C, 0 + (x - 1)(-1) \leq -\ln(x)$$

$$\Rightarrow \forall x \in C, \ln(x) \leq x - 1$$

• $C = (-\infty, \infty), f(x) = e^x$ $\frac{d^2 f(x)}{dx^2} = e^x > 0, \forall x \in C \Rightarrow f \text{ is (strictly) convex over } C$ \Rightarrow By Jensen's inequality

$$f\left(\sum_{j=1}^{n} p_{j} x_{j}\right) = e^{\sum_{j=1}^{n} p_{j} x_{j}} \le \sum_{j=1}^{n} p_{j} f(x_{j}) = \sum_{j=1}^{n} p_{j} e^{x_{j}}$$

If for all j we set $c_j = e^{x_j}$, $p_j = \frac{1}{n}$, then we get the Geometric-Mean – Arithmetic-Mean (GM-AM) inequality for nonnegative numbers :

$$\left(\prod_{j=1}^{n} c_j\right)^{1/n} \le \frac{1}{n} \sum_{j=1}^{n} c_j$$

Examples

• $C = (0, \infty), f(x) = -\ln(x)$ $\frac{d^2 f(x)}{dx^2} = \frac{1}{x^2} > 0, \forall x \in C \Rightarrow f \text{ is (strictly) convex over } C$ $\Rightarrow \text{By Jensen's inequality, for any two pmfs } p_1, \dots, p_n \text{ and } q_1, \dots, q_n \text{ over } n \text{ values we have}$

$$f\left(\sum_{j=1}^{n} p_j \frac{q_j}{p_j}\right) = f(1) = 0 \le \sum_{j=1}^{n} p_j f\left(\frac{q_j}{p_j}\right) = \sum_{j=1}^{n} p_j \ln\left(\frac{p_j}{q_j}\right)$$

The quantity $\sum_{j=1}^{n} p_j \ln \left(\frac{p_j}{q_j} \right)$ is called the Kullack-Liebler (KL) divergence or relative entropy of pmf p with respect to pmf q and the above inequality shows that it is always nonnegative.

Convex optimization

• An optimization problem of the form $\min_{x \in C} f(x)$

in which:

- 1. the constraint set C over which a function f(x) is being minimized is a convex set and
- 2. the objective function f(x) that is being minimized is a convex function over C

is called a convex optimization problem. Here,

- if C is a closed set then a minimizer $x \in C$ is guaranteed to exist
- if C is a closed and f is strictly convex over C then the minimizer exists and is unique

Convex optimization

- Let $f, g_1, ..., g_n$ be real-valued convex functions over a convex subset $C \subseteq \mathbb{R}^d$
- Then the optimization problem:

$$\min_{\mathbf{x} \in C} f(\mathbf{x})$$

subject to:
$$g_j(x) \le 0, j \in [1, n]$$

is a convex optimization problem. This is also called the primal optimization problem (even if it is non-convex).

 Lagrange function or Lagrangian associated to the primal optimization problem is defined as:

$$\forall \mathbf{x} \in C, \forall \lambda_1, \dots, \lambda_n \ge 0,$$

$$L(\mathbf{x}, \lambda) \coloneqq f(\mathbf{x}) + \sum_{j=1}^n \lambda_j g_j(\mathbf{x})$$

• Here, $\lambda_1, \dots, \lambda_n$ are called Lagrange or dual variables or multipliers

Slater's condition or weak constraint qualification

- A set C together with functions g_1, \ldots, g_n are said to satisfy Slater's condition or weak constraint qualification if
 - 1. there exists a point \overline{x} in the interior of C such that
 - 2. for all $j \in [1, n]$, either
 - $g_i(\overline{x}) < 0$ or
 - $g_i(\overline{x}) = 0$ and g_i is an affine function

Karush-Kuhn-Tucker Theorem

- Let $f, g_1, ..., g_n$ be real-valued convex and differentiable functions over a convex subset $C \subseteq \mathbb{R}^d$ satisfying Slater's condition. Then \overline{x} is a solution of the primal optimization problem if, and only if, the following conditions hold:
 - Primal feasibility conditions:

$$\overline{x} \in C \text{ and } \forall j \in [1, n], g_j(\overline{x}) \leq 0$$

- Stationarity of Lagrangian: there exist $\lambda_1, ..., \lambda_n \ge 0$ such that

$$\nabla f(\overline{x}) + \sum_{j=1}^{n} \lambda_j \nabla g_j(\overline{x}) = 0,$$

– Complementary slackness conditions:

$$\forall j \in [1, n], \lambda_j g_j(\overline{x}) = 0$$

Dual optimization problem

 The Lagrange dual function associated to the primal optimization problem is defined by:

$$F(\lambda_1, ..., \lambda_n) = \inf_{\mathbf{x} \in C} L(\mathbf{x}, \lambda)$$
$$= \inf_{\mathbf{x} \in C} (f(\mathbf{x}) + \sum_{j=1}^n \lambda_j g_j(\mathbf{x}))$$

for all $\lambda_1, \dots, \lambda_n \geq 0$.

- If $\lambda := (\lambda_1, ..., \lambda_n)^T$, then $F(\lambda)$ is a concave function of λ
- The optimization problem:

$$\max_{\lambda \geq 0} F(\lambda)$$

is called the dual optimization problem associated to the primal optimization problem

Dual optimization problem

 If the conditions of the Karush-Kuhn-Tucker theorem are satisfied, then

$$\max_{\lambda \geq 0} F(\lambda) = \min_{x \in C} f(x)$$

subject to: $g_j(x) \leq 0, j \in [1, n]$

- Remarks: even if the primal problem is non-convex,
 - the dual function is concave
 - the dual function is never above the primal minimum
 - thus the dual maximum is never above the primal minimum
 - duality gap = (primal minimum) (dual maximum) ≥ 0
 - for a convex primal problem that is "regular" (Salter's conditions), the duality gap is zero