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CPE 434-01

4/1/2021

Lab 12

## Introduction

Compiler – used to translate a program from a high-level language to an assembly language. It checks for syntax errors.

Assembler – Translates assembly language into relocatable machine code. This is stored in an object file.

Linker – Takes all the object files and combines them to form an executable. It does this by combining all of the object files that are needed.

## Assignment

2.

It supports 4 UART serial ports.

The QEMU emulator supports the VersatilePB platform for other peripherals, four UART serial ports; the first serial port can be used when using the `-nographic` or `"-serial stdio"` device.

UARTDR is used to transmit and receive.

In more details, there is a register (UARTDR) that is used to transmit (when writing in the register) and receive (when reading) bytes; this register is placed at offset `0x0`, so I need to read and write at the beginning of the memory allocated for the UART0.

3.

```
volatile unsigned int * const UART0DR = (unsigned int *)0x101f1000;

void print_uart0(const char *s) {
    while(*s != '\0') { /* Loop until end of string */
        *UART0DR = (unsigned int)(*s); /* Transmit char */
        s++; /* Next char */
    }
}

void c_entry() {
    print_uart0("Hello world!\n");
}
```

```
odroid@odroid:~/lab12$ ^C
odroid@odroid:~/lab12$ arm-none-eabi-gcc -c -mcpu=arm926ej-s -g test.c -o test.o
odroid@odroid:~/lab12$
```

4.

```
odroid@odroid:~/lab12$ arm-none-eabi-as -mcpu=arm926ej-s -g startup.s -o startup.o
odroid@odroid:~/lab12$ |
```

5.

```
odroid@odroid:~/lab12$ arm-none-eabi-ld -T test.ld test.o startup.o -o test.elf
odroid@odroid:~/lab12$ |
```

6.

```
odroid@odroid:~/lab12$ arm-none-eabi-objcopy -O binary test.elf test.bin
odroid@odroid:~/lab12$ |
```

7.

```
Package qemu-kvm-extras is not available, but is referred to by another package.
This may mean that the package is missing, has been obsoleted, or
is only available from another source

E: Package 'qemu-kvm-extras' has no installation candidate
odroid@odroid:~/lab12$ qemu-system-arm -M versatilepb -m 128M -nographic -kernel test.bin
pulseaudio: set_sink_input_volume() failed
pulseaudio: Reason: Invalid argument
pulseaudio: set_sink_input_mute() failed
pulseaudio: Reason: Invalid argument
Hello world!
```

8.

The first step is to run `arm-none-eabi-gcc -c -mcpu=arm926ej-s -g test.c -o test.o`. This generates an object file of `test.c`. The next step is to run the same command but with `startup.s`. This checks for errors and assembles the files into object code.

The linker takes the code that I have written and combines it all together. This includes precompiled library code. The final command creates another executable of a different format.

## 8.2

```
Last login: Mon Apr  5 15:52:31 2021 from 172.22.0.6
odroid@odroid:~$ qemu-system-arm -M help
Supported machines are:
akita           Sharp SL-C1000 (Akita) PDA (PXA270)
borzoi          Sharp SL-C3100 (Borzoi) PDA (PXA270)
canon-a1100     Canon PowerShot A1100 IS
cheetah         Palm Tungsten|E aka. Cheetah PDA (OMAP310)
collie          Sharp SL-5500 (Collie) PDA (SA-1110)
connex          Gumstix Connex (PXA255)
cubieboard      cubietech cubieboard
highbank        Calxeda Highbank (ECX-1000)
imx25-pdk       ARM i.MX25 PDK board (ARM926)
integratorcp    ARM Integrator/CP (ARM926EJ-S)
kzm             ARM KZM Emulation Baseboard (ARM1136)
lm3s6965evb     Stellaris LM3S6965EVB
lm3s811evb      Stellaris LM3S811EVB
mainstone       Mainstone II (PXA27x)
midway          Calxeda Midway (ECX-2000)
musicpal        Marvell 88w8618 / MusicPal (ARM926EJ-S)
n800            Nokia N800 tablet aka. RX-34 (OMAP2420)
n810            Nokia N810 tablet aka. RX-44 (OMAP2420)
netduino2       Netduino 2 Machine
none            empty machine
nuri            Samsung NURI board (Exynos4210)
realview-eb     ARM RealView Emulation Baseboard (ARM926EJ-S)
realview-eb-mpcore ARM RealView Emulation Baseboard (ARM11MPCore)
realview-pb-a8  ARM RealView Platform Baseboard for Cortex-A8
realview-pbx-a9 ARM RealView Platform Baseboard Explore for Cortex-A9
smdkc210        Samsung SMDKC210 board (Exynos4210)
spitz           Sharp SL-C3000 (Spitz) PDA (PXA270)
sx1             Siemens SX1 (OMAP310) V2
sx1-v1          Siemens SX1 (OMAP310) V1
terrier         Sharp SL-C3200 (Terrier) PDA (PXA270)
tosa            Sharp SL-6000 (Tosa) PDA (PXA255)
verdex          Gumstix Verdex (PXA270)
versatileab     ARM Versatile/AB (ARM926EJ-S)
versatilepb     ARM Versatile/PB (ARM926EJ-S)
vexpress-a15    ARM Versatile Express for Cortex-A15
vexpress-a9     ARM Versatile Express for Cortex-A9
virt            ARM Virtual Machine
xilinx-zynq-a9  Xilinx Zynq Platform Baseboard for Cortex-A9
z2             Zipit Z2 (PXA27x)
```

```

odroid@odroid:~$ qemu-system-aarch64 -M help
Supported machines are:
akita          Sharp SL-C1000 (Akita) PDA (PXA270)
borzoi         Sharp SL-C3100 (Borzoi) PDA (PXA270)
canon-a1100    Canon PowerShot A1100 IS
cheetah        Palm Tungsten|E aka. Cheetah PDA (OMAP310)
collie         Sharp SL-5500 (Collie) PDA (SA-1110)
connex         Gumstix Connex (PXA255)
cubieboard     cubietech cubieboard
highbank       Calxeda Highbank (ECX-1000)
imx25-pdk      ARM i.MX25 PDK board (ARM926)
integratorcp   ARM Integrator/CP (ARM926EJ-S)
kzm            ARM KZM Emulation Baseboard (ARM1136)
lm3s6965evb    Stellaris LM3S6965EVB
lm3s811evb     Stellaris LM3S811EVB
mainstone      Mainstone II (PXA27x)
midway         Calxeda Midway (ECX-2000)
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realview-eb-mpcore ARM RealView Emulation Baseboard (ARM11MPCore)
realview-pb-a8 ARM RealView Platform Baseboard for Cortex-A8
realview-pbx-a9 ARM RealView Platform Baseboard Explore for Cortex-A9
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sx1-v1         Siemens SX1 (OMAP310) V1
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tosa           Sharp SL-6000 (Tosa) PDA (PXA255)
verdex         Gumstix Verdex (PXA270)
versatileab    ARM Versatile/AB (ARM926EJ-S)
versatilepb    ARM Versatile/PB (ARM926EJ-S)
vexpress-a15   ARM Versatile Express for Cortex-A15
vexpress-a9    ARM Versatile Express for Cortex-A9
virt           ARM Virtual Machine
xilinx-zynq-a9 Xilinx Zynq Platform Baseboard for Cortex-A9
xlnx-ep108     Xilinx ZynqMP EP108 board
z2             Zipit Z2 (PXA27x)

```

9.

Emulation requires a software bridge. VMs can access hardware directly. Because of this, emulators are faster. VMs are more completed to implement than an emulator is.

10.

Yes. Guest machines can run hypervisors, but they cannot perform full virtualization because they do not have full access to the system's hardware.