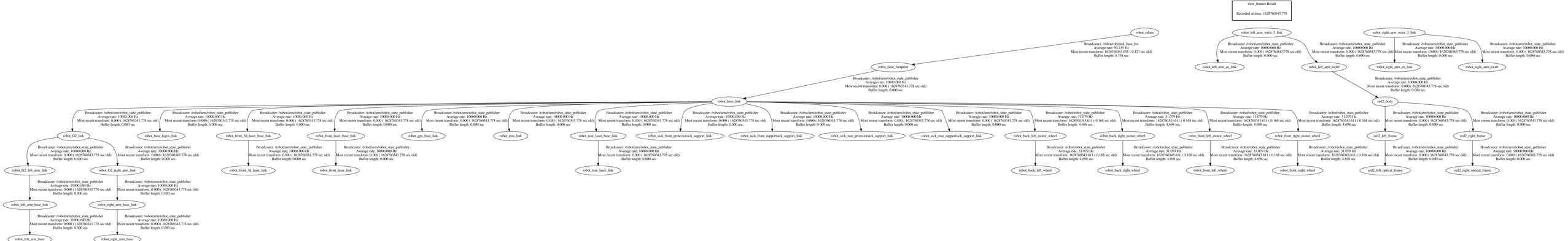
view_frames Result
Recorded at time: 1628760343.778
robot_odom
Broadcaster: /robot/robotnik_base_hw
Average rate: 30.235 Hz
Most recent transform: 1628760343.651 (0.127 sec old)
Buffer length: 4.738 sec
robot_base_footprint
Broadcaster: /robot/arm/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1628760343.778 sec old)
Buffer length: 0.000 sec
robot_base_link
robot_left_arm_wrist_3_link
robot_left_arm_ee_link
robot_left_arm_tool0
robot_right_arm_wrist_3_link
robot_right_arm_ee_link
robot_right_arm_tool0
zed2_body
zed2_left_frame
zed2_left_optical_frame
zed2_right_frame
zed2_right_optical_frame
robot_G2_link
robot_G2_left_arm_link
robot_G2_right_arm_link
robot_left_arm_base_link
robot_right_arm_base_link
robot_left_arm_base
robot_right_arm_base
robot_base_logos_link
robot_front_3d_laser_base_link
robot_front_3d_laser_link
robot_front_laser_base_link
robot_front_laser_link
robot_gps_base_link
robot_imu_link
robot_rear_laser_base_link
robot_rear_laser_link
robot_sick_front_protectorsick_support_link
robot_sick_front_supportsick_support_link
robot_sick_rear_protectorsick_support_link
robot_sick_rear_supportsick_support_link
robot_back_left_motor_wheel
robot_back_left_wheel
robot_back_right_motor_wheel
robot_back_right_wheel
robot_front_left_motor_wheel
robot_front_left_wheel
robot_front_right_motor_wheel
robot_front_right_wheel