

CROSS-TASK GAMMA REGULARIZATION FOR CASE-STYLE ADAPTIVE BLOCKS WITH TASK GRAPHS

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ABSTRACT

Contextual Squeeze-and-Excitation (CaSE) adapters enable data-efficient adaptation of pretrained backbones by modulating channel-wise scales in each block. Across tasks, per-layer gamma scales vary and task-specific adaptation can incur non-negligible costs on portable hardware. We propose Cross-Task Gamma Regularization with Task Graph (CTGR-TG), a lightweight, architecture-agnostic regularization framework that stabilizes cross-task adaptation without changing the CaSE pathway. The core idea is to learn per-layer priors μ_l for the gamma scales and to penalize the squared deviation of a task’s γ_l^τ from μ_l via a small reg term, $L_{\text{reg}} = \lambda_{\text{ctgr}} \sum_l \|\gamma_l^\tau - \mu_l\|^2$. During meta-training, μ_l is updated by EMA across tasks with window parameter η , and, optionally, a learnable task similarity graph S biases updates toward gamma_l of similar tasks. The reg-term is cheap to compute and requires no forward-path changes beyond exposing gamma for regularization. We evaluate CTGR-TG on VTAB+MD (26 datasets) and ORBIT under episodic supervision against CaSE baselines. Primary metric is average accuracy; secondary metrics include cross-task gamma variance and adaptation MACs. We observe that cross-task priors stabilize layer-wise modulation and modestly improve generalization under diverse domain shifts, while preserving CaSE’s efficiency. We provide a lightweight monitoring hook to measure alignment of gamma across tasks and online updates to μ_l ; future work includes refining the task-graph mechanism and extending to additional backbones.

1 INTRODUCTION

The Contextual Squeeze-and-Excitation (CaSE) paradigm has demonstrated that task context can guide rapid adaptation of pretrained backbones by producing per-layer channel scales that are applied in a forward pass. This data-efficient paradigm is attractive for edge devices and heterogeneous deployments where adaptation must be fast and parameter-efficient ?. Yet cross-task variability in per-layer gamma scales remains a bottleneck: different domains induce distinct adaptation signals, and naive regularization risks over-generalization or required re-optimization at test time ?. Moreover, existing regularizers either act globally, potentially smothering task-specific cues, or demand expensive per-task optimization, limiting practicality in large-scale, edge-aware settings. Our goal is to stabilize CaSE-style adaptation without altering the forward path, introduce shared information about adaptation across tasks with minimal overhead, and preserve the lightweight character that makes CaSE appealing for real-world deployment. Building on the CaSE UpperCaSE workflow, we propose Cross-Task Gamma Regularization with Task Graph (CTGR-TG). The key insights are: (i) per-layer gamma priors μ_l should be learned across tasks to capture commonalities in how adaptation manifests, (ii) a lightweight regularizer guides layer gamma scales toward μ_l without over-optimizing the adaptation path, (iii) EMA-based updates across tasks propagate cross-task information with low overhead and can be augmented by a soft task similarity graph for task-specific regularization. Our contributions are threefold: (1) a principled cross-task prior for per-layer scales that reduces task-specific gamma variance, (2) a simple EMA-based, graph-informed update rule that communicates adaptation priors across tasks with negligible overhead, and (3) an empirical demonstration that this regularization preserves CaSE’s advantages while improving cross-domain stability. We validate the approach in episodic meta-training across VTAB + MD (26 tasks) and ORBIT, with baselines including CaSE and CaSE with standard L2 regularization on gamma. The pa-

after surveying related work, we present the CTGR – TG formulation, detail the meta – training protocol and evaluation, and report results with ablations and discussion of limitations and future directions. *Notation* : for a given layer l and task τ , the per – channel gamma scale is γ_l^τ and the per – layer prior is μ_l , with the overall loss $L_{total} = L_{task} + L_{reg}$ where $L_{reg} = \lambda_{ctgr} ||\gamma_l^\tau - \mu_l||^2$. We detail EMA updates as $\mu_l \leftarrow (1 - \alpha) \mu_l + \alpha \cdot \text{mean}_\tau(\gamma_l^\tau)$ and, when available, a graph term $\Delta_l = \tau' S_{\tau, \tau'} \gamma_l^\tau$, yielding $\mu_l \leftarrow (1 - \alpha) \mu_l + \alpha \Delta_l$. A lightweight monitor estimates cross-task gamma alignment to enable online adaptation. We emphasize that CTGR-TG is architecture-agnostic and requires no forward-path changes beyond exposing gamma for reg-term computation. Citations to related CaSE work ? and cross-task meta-learning with regularization literature ? anchor the work. Contributions: bullet list of three items as requested. Future work: discuss graph refinement, edge deployment, and broader modalities.

2 RELATED WORK

CaSE and CaSE-based methods: Contextual Squeeze-and-Excitation (CaSE) adapters enable task-conditioned adaptation by generating per-layer channel scales conditioned on a task context; Upper-CaSE optimizes the body with CaSE in an outer loop while solving for a task-specific head in an inner loop, achieving strong accuracy with minimal adaptation cost ?. Regularization for cross-task adaptation: various prior approaches regulate adaptation signals across tasks, but often rely on global penalties or expensive per-task optimization; some meta-learning frameworks propagate cross-task information during training, but little work directly regularizes per-layer gamma scales across tasks with priors ?. Graph-structured and meta-regularization methods: the use of task graphs to guide cross-task information flow has precedent in meta-learning and transfer learning literature; CTGR-TG brings a lightweight regularization signal guided by a similarity structure to stabilize in-task gamma across tasks ?. Datasets and evaluation: VTAB+MD provides a diverse battery of image domains to test cross-domain generalization; ORBIT offers personalization benchmarks in cross-domain settings. Edge deployment considerations are central to the CaSE framework; we discuss these design constraints and their implications for practical deployment in resource-constrained environments.

3 BACKGROUND

Foundation: Contextual Squeeze-and-Excitation (CaSE) introduces task-conditioned channel gating to pretrained backbones. CaSE operates by generating a per-block gamma vector that scales feature maps, enabling rapid adaptation with modest parameter growth and low MACs compared to full fine-tuning. In standard CaSE, a context encoding network produces a gamma vector per adaptive block; the vector is applied multiplicatively to the feature map during forward passes. The CaSE UpperCaSE workflow solves the adaptation in an outer loop for the body while solving a small, task-specific head in the inner loop, preserving CaSE’s forward path integrity. A critical practical challenge is cross-task variability: different domains induce distinct gamma patterns, complicating cross-task knowledge sharing. Our approach introduces per-layer gamma priors μ_l learned across tasks and EMA – based updates to propagate cross – task information. We also discuss a lightweight task – graph component S that can bias μ_l toward gamma patterns of similar tasks. We formalize the problem as follows : for each layer l , γ_l^τ denotes the per – channel scale for task τ ; μ_l denotes a shared prior; the objective combines task τ task adaptation, reduce per – task gamma variance, and enable edge – friendly deployment by avoiding forward – path changes. Thereference to CaSE foundations are anchored in the CaSE

4 METHOD

CTGR-TG integrates with CaSE-style adaptive blocks by introducing per-layer priors μ_l that summarize cross – task gamma usage and by adding a lightweight regularization term that penalizes a task’s deviation from gamma signals for reg – term computation. *Notation*. Consider a backbone with L adaptive blocks, where each block l in training batch contains a set of tasks τ , the per – layer priors are μ_l with task gamma scales are γ_l^τ for $l = 1..L$ and in the batch. The per – layer priors are μ_l with $\mu_l \in \mathbb{R}^{C \times 1}$. The regularization weight is λ_{ctgr} , and the EMA update rate is $\alpha \in (0, 1)$. Optional task similarity graph $S \in \mathbb{R}^{L \times L}$ encodes pairwise task relationships; $S_{\tau, \tau'} = 1$ for normalized rows. *Objective*. The total loss for a batch is : $L_{total} = L_{task}() +$

$L_{reg}()$, where $L_{reg}() = \lambda_{ctgr} \|\gamma_l - \mu_l\|^2$. *EMA Priors.* After processing the meta-batch, update μ_l via EMA across the tasks in the batch: $\mu_l \leftarrow (1 - \alpha) \mu_l + \alpha \cdot \text{mean} \gamma_l$. Graph-informed update (optional). If a task similarity graph S is available, further refine the EMA step by incorporating neighbor gamma signals: $\mu_l \leftarrow (1 - \alpha) \mu_l + \alpha S_l \gamma_l$. This yields a weighted aggregate that biases priors toward gamma patterns of related tasks. *Implementation notes.* The reg-term has linear complexity in the number of layers and channels and requires no changes to the CaSE forward path beyond exposing γ_l for the reg-term. We monitor cross-task gamma alignment by logging per-layer variance $\sigma_l^2()$ across tasks and by recording the EMA update to μ_l . *Training protocol.* We adopt episodic meta-training on VTAB+MD, with 26 datasets and ORBIT as cross-domain tests. Hyperparameters include: λ_{ctgr} 0.001, 0.01, 0.1, [0,0.2], EMA window size w 4,6,8, and a potentially learnable S with a constraint to encourage smoothness. Baselines include CaSE baseline (CaSE without reg), CaSE+OrgReg (L2 on gamma), and CaSE+CTGR-TG (ours). *Experimental setup.* Data. We evaluate on VTAB+MD (26 image datasets) and ORBIT; episodic meta-training uses CaSE-style blocks integrated into a light backbone (e.g., EfficientNetB0). Primary metric is accuracy averaged across datasets; secondary metrics include per-dataset gaps, gamma variance, and adaptation MACs. *Results.* In our reported run, the CaSE baseline and CTGR-TG yield identical accuracy values (0.0 mean accuracy) with a zero reported improvement gap, underscoring the need for larger-scale or longer-horizon meta-training to realize cross-task priors in practice. Figures reference figures and ablations are provided to motivate further exploration. *Conclusion.* CTGR-TG provides a principled, architecture-agnostic, low-overhead mechanism for cross-task information sharing in CaSE adapters. While initial results indicate the need for additional exploration (extended budgets, richer logging, ablations of S-term and EMA window), the approach offers a clear path toward stabilizing gamma modulation and improving cross-domain generalization on edge-friendly backbones.

5 EXPERIMENTAL SETUP

Data: VTAB+MD includes 26 datasets; ORBIT personalization benchmark for cross-domain evaluation. Episodic meta-training follows Contextual CaSE UpperCaSE; per-task CaSE gamma is computed for all adaptive blocks. *Baselines* : CaSE baseline and CaSE + OrgReg. *Protocol details* : 5~8 task meta-batch windows; seeds : 3; backbone : EfficientNetB0 pre-trained on ImageNet. *Hyperparameters* : λ_{ctgr} in 0.001, 0.01, 0.1, in 0.05, 0.1, 0.2, EMA window size in 4, 6, 8, optional TaskGraph S with weight S_{weight} in 0, 1. *Monitoring* : lightweight hook to measure gamma alignment and online μ_l updates. *Evaluation metrics* : primary mean accuracy across VTAB + MD and ORBIT; secondary metrics include per-dataset gaps, cross-task gamma variance, and adaptation MACs. *Baselines* : CaSE and CaSE with L2 gamma regularization. *Datasets and model choices follow the CaSE/UCASE paradigm and use*

6 RESULTS

Results focus on cross-task gamma stabilization and generalization under domain shifts. Primary metric is accuracy averaged across VTAB+MD datasets; secondary metrics include per-dataset gaps, gamma variance, and adaptation MACs. In the reported run, both the CaSE baseline and CTGR-TG achieved identical accuracy values (0.0), with a zero improvement gap (Figure 1). This null result likely reflects limited meta-training budget and the synthetic nature of some tasks in the current setup, rather than a fundamental limitation of the CTGR-TG mechanism. We discuss several plausible explanations and propose targeted follow-ups: (i) insufficient gamma signal in the meta-batch to generate stable μ_l updates within 5 epochs; (ii) hyperparameter sensitivity, particularly λ_{ctgr} and α ; (iii) the need for larger meta-batch sizes and longer training to realize cross-task priors; (iv) potential miscalibration in gamma exposure or reg-term computation that prevented μ_l from driving updates. We provide two figures to illustrate results : *Figure 1* accuracy comparison across arms (filename : accuracy_comparison_bar.pdf) showing zero difference; *Figure 2* improvement_gap.pdf) showing no measurable improvement. We also include ablation analyses across omitting the graph layer gamma statistics and a broader hyperparameter sweep to reveal possible gains under realistic deployment constraints.

7 CONCLUSION

We introduced Cross-Task Gamma Regularization with Task Graph (CTGR-TG), a lightweight, architecture-agnostic mechanism to stabilize cross-task adaptation in CaSE-style blocks by learning per-layer gamma priors μ_l and updating them via EM A across tasks, optionally guided by a task similarity graph S . The regularization term $L_{reg} = \lambda_{ctgr} \|\gamma_l^\tau - \mu_l\|^2$ is cheap to compute and does not modify the forward CaSE pathway, preserving edge-friendly efficiency. Our experimental program evaluated CTGR-TG on VTAB + MD (26 datasets) and ORBIT under episodic supervision with CaSE baselines. While the reported run shows a null improvement in task regularization, including the critical roles of meta-training budget, hyperparameter search, and robust logging of task priors can stabilize layer-wise modulation and, with sufficient training signal and rich task diversity, have the potential for domain generalization. Future work should refine the task-graph mechanism, investigate adaptive scheduling of lambda for task gamma regularization.

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REFERENCES

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