

view_frames Result
Recorded at time: 1652005139.013

odom_aloam

Broadcaster: /odom_loam
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

base_link

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

d435_front_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

d435_rear_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

imu_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

inertial_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

rslidar

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

front_left_steer_link

front_left_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1652005139.000 (0.013 sec old)
Buffer length: 4.900 sec

front_right_steer_link

front_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1652005139.000 (0.013 sec old)
Buffer length: 4.900 sec

rear_left_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1652005139.000 (0.013 sec old)
Buffer length: 4.900 sec

rear_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1652005139.000 (0.013 sec old)
Buffer length: 4.900 sec

zed2i_base_link

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

zed2i_camera_center

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

zed2i_left_camera_frame

zed2i_imu_link

zed2i_left_camera_optical_frame

zed2i_temp_left_link

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

zed2i_baro_link

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

zed2i_mag_link

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec

zed2i_right_camera_frame

zed2i_right_camera_optical_frame

zed2i_temp_right_link

Broadcaster: /zed2i/zed2i_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1652005139.013 sec old)
Buffer length: 0.000 sec