

# AutoML: Introduction

## Risks of AutoML

Bernd Bischl   Frank Hutter   Lars Kotthoff  
Marius Lindauer   Joaquin Vanschoren

# Risks of AutoML

- ➊ Users apply AutoML **without understanding** anything.
  - ▶ Users might wonder why (Auto-)ML does not perform well after they passed in poor data.

# Risks of AutoML

- ② Users trust AutoML too much.
  - ▶ humans might not use human reasoning skills and do not second guess machine decisions

# Risks of AutoML

- ③ We enable non-ML experts to use ML  
without knowing the risks and consequences of ML.
  - ▶ E.g., bias in data and trained models

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- ④ Could result in deployment of ...

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  - ▶ inaccurate models due to lack of understanding of statistical concepts, e.g., sampling bias, overfitting, concept drift, ...

# Risks of AutoML

## ④ Could result in deployment of ...

- ▶ **inaccurate models** due to lack of understanding of statistical concepts, e.g., sampling bias, overfitting, concept drift, ...
- ▶ **biased and unfair models** due to lack of understanding ethical practices and use of features such as gender and race for predicting outcomes

# Mitigating the Risks

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  - ~~ Future research topics (as of March 2020)

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  - ~~ Future research topics (as of March 2020)
- ➌ Can we automatically find ML systems that are less prone to such risks?
  - ~~ Future research topics (as of March 2020)

# AutoML: Introduction

## How is Everything connected?

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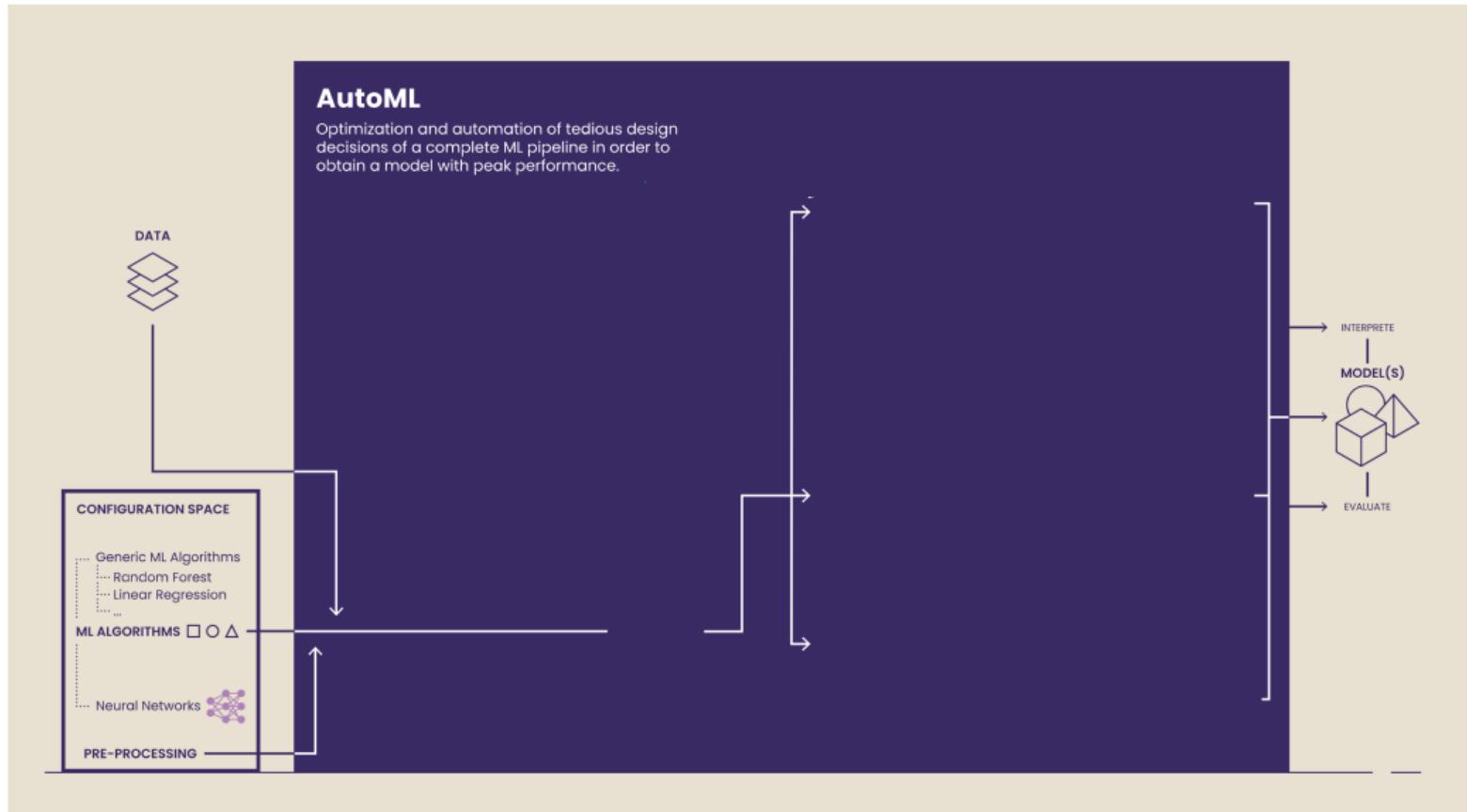
# Building a Successful AutoML Tool

~~ There is not a single way for building successful AutoML tools,  
but there are well established ideas.

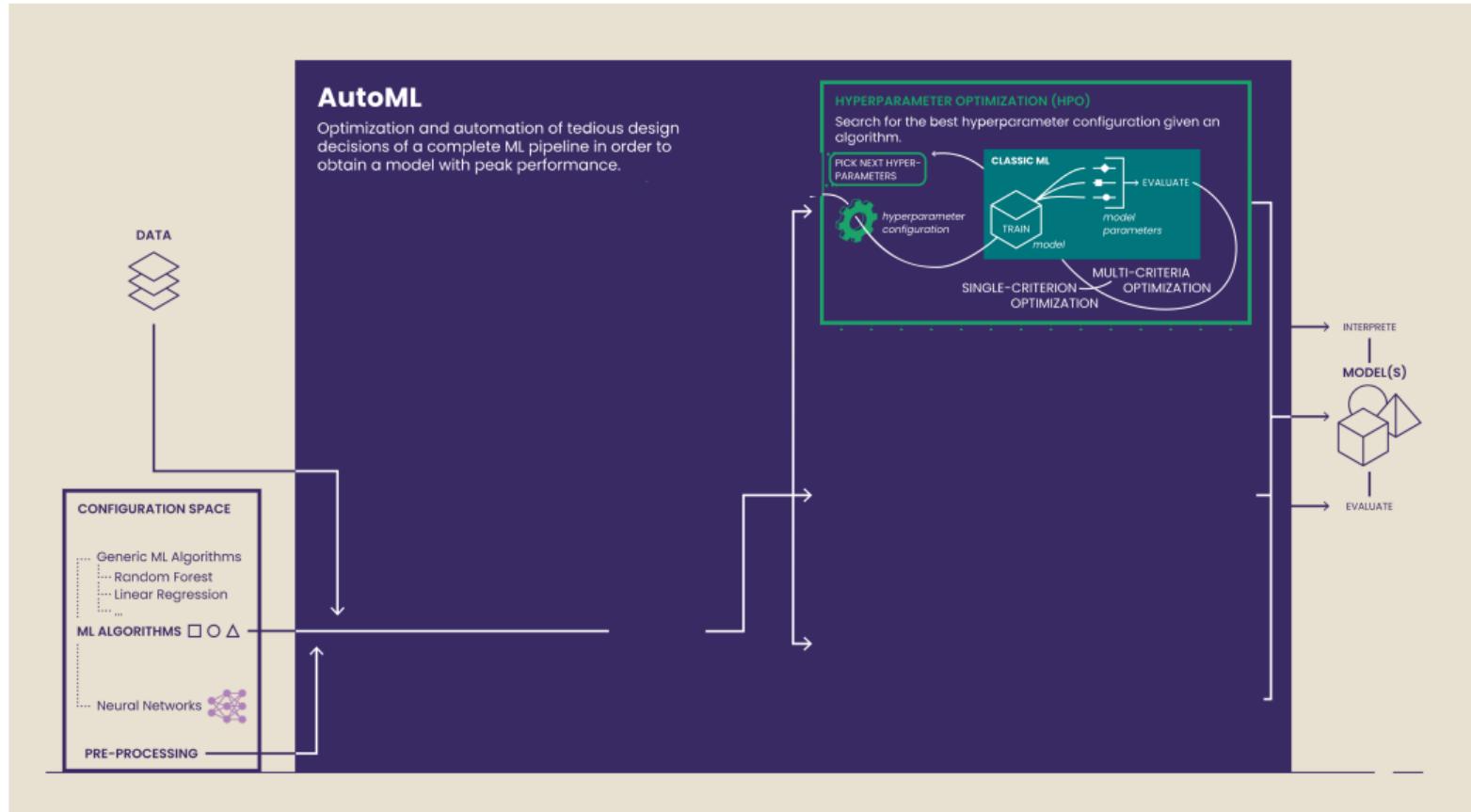
- Hyperparameter optimization
- Neural architecture search
- Model and algorithm selection
- Dynamic approaches

~~ But how can we combine all of these?

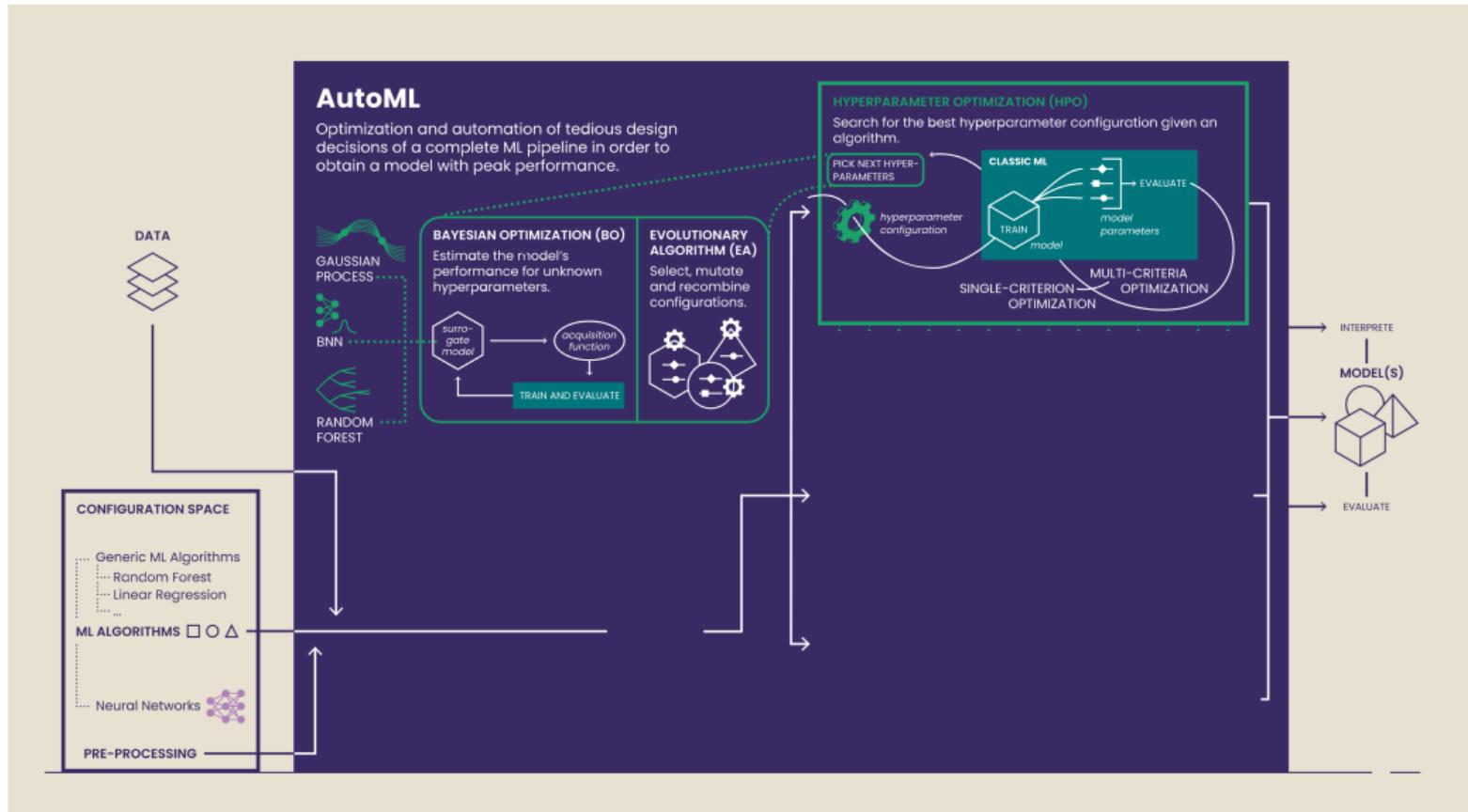
AutoML



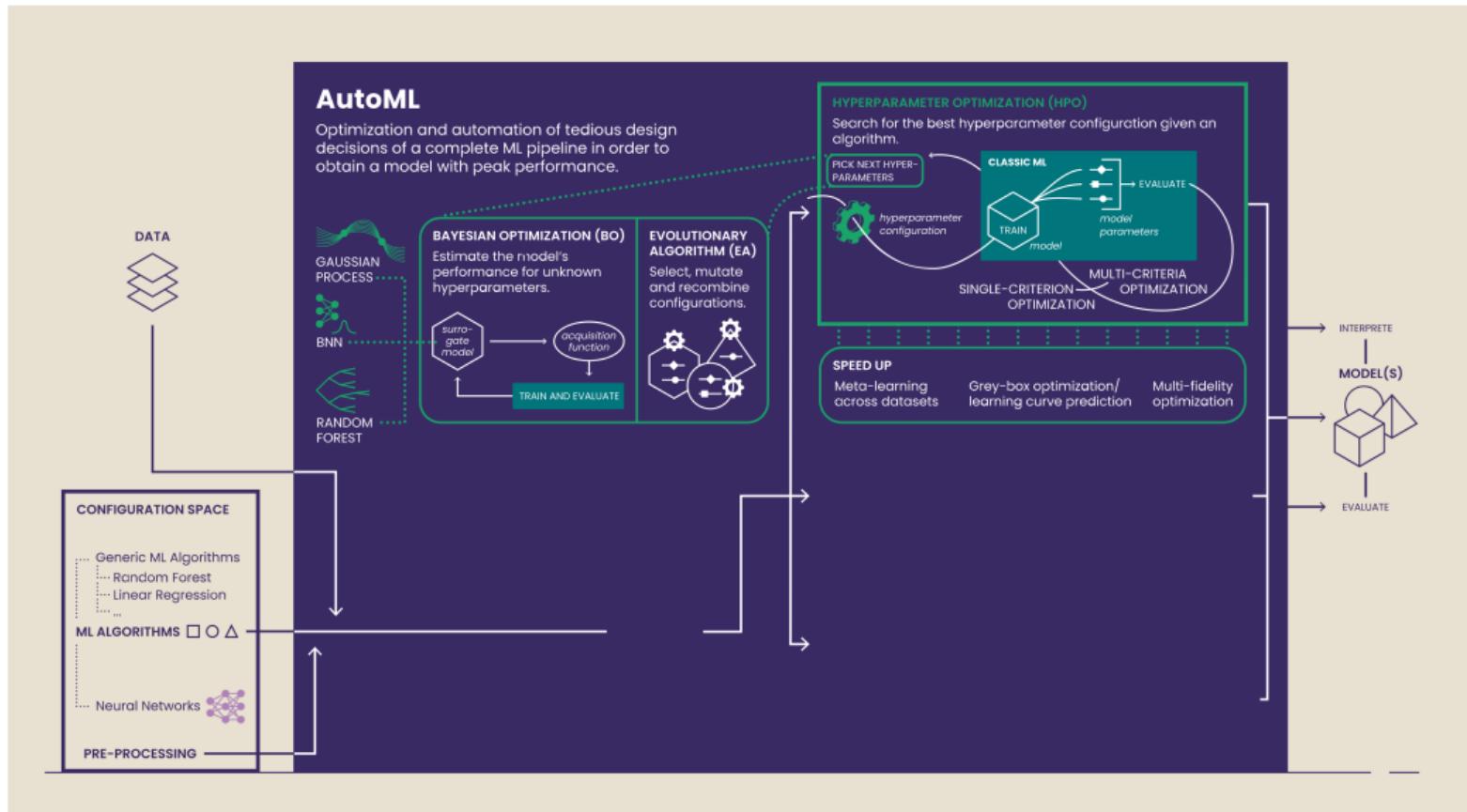
# AutoML + HPO



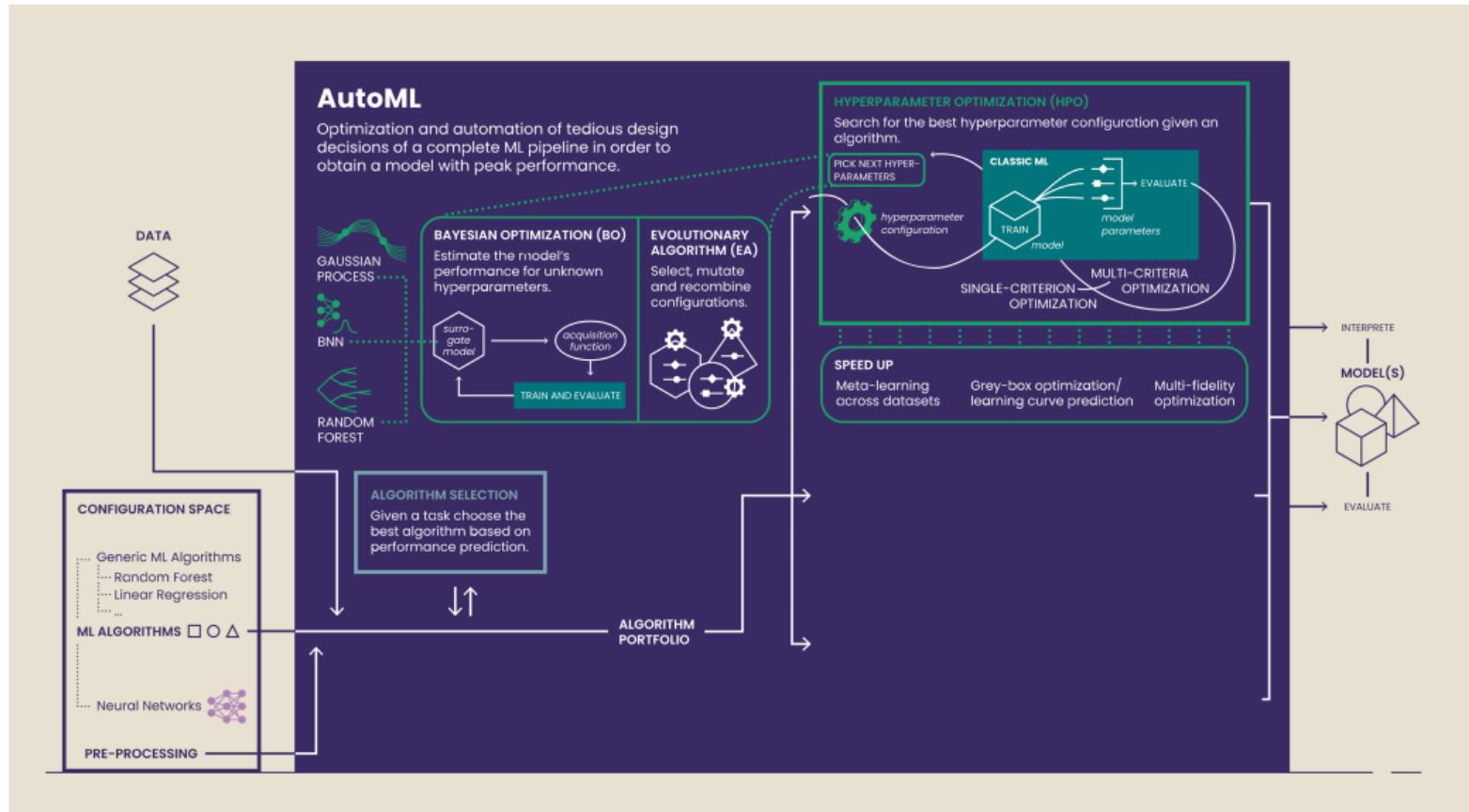
# AutoML + HPO + BO



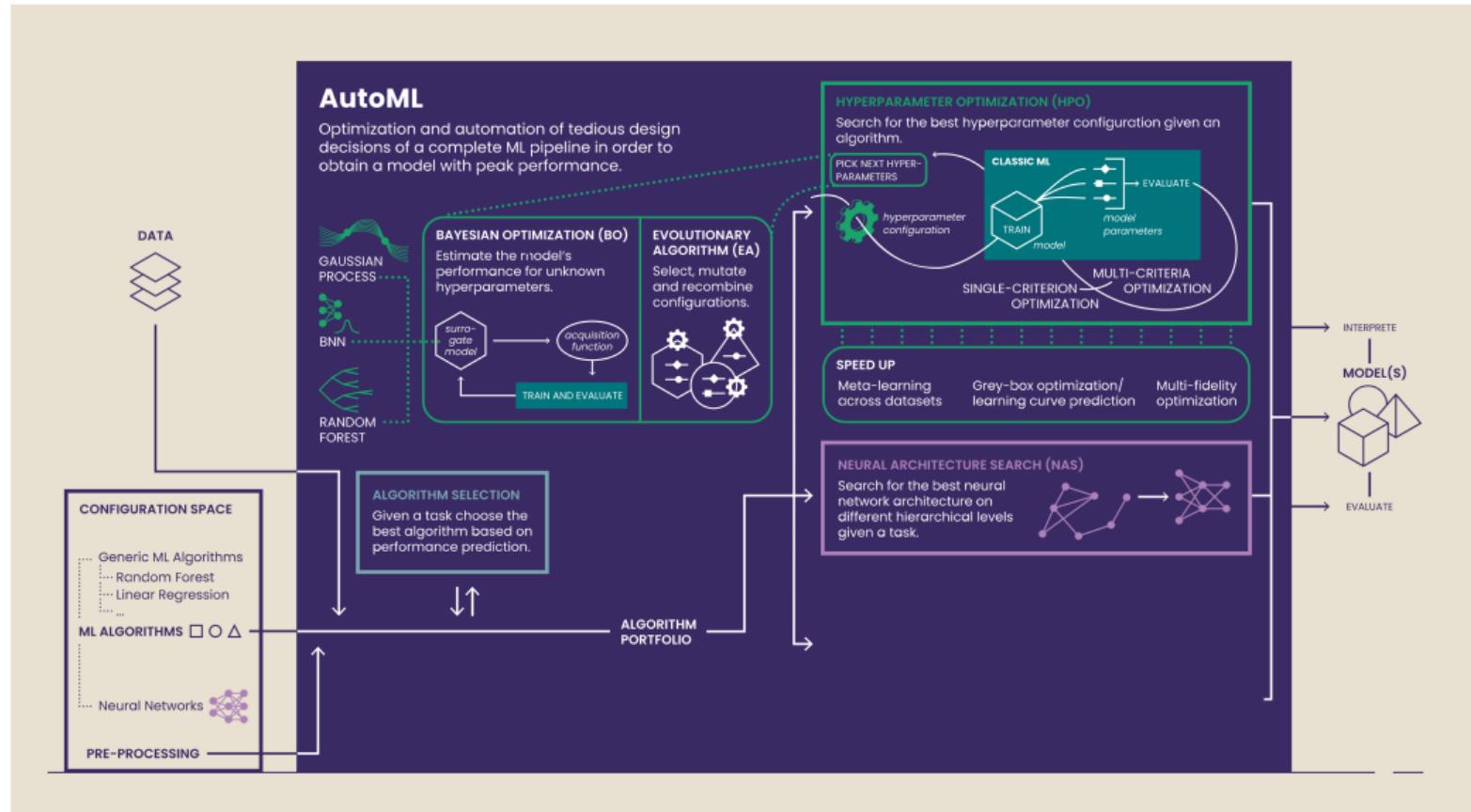
# AutoML + HPO + BO + Speed up



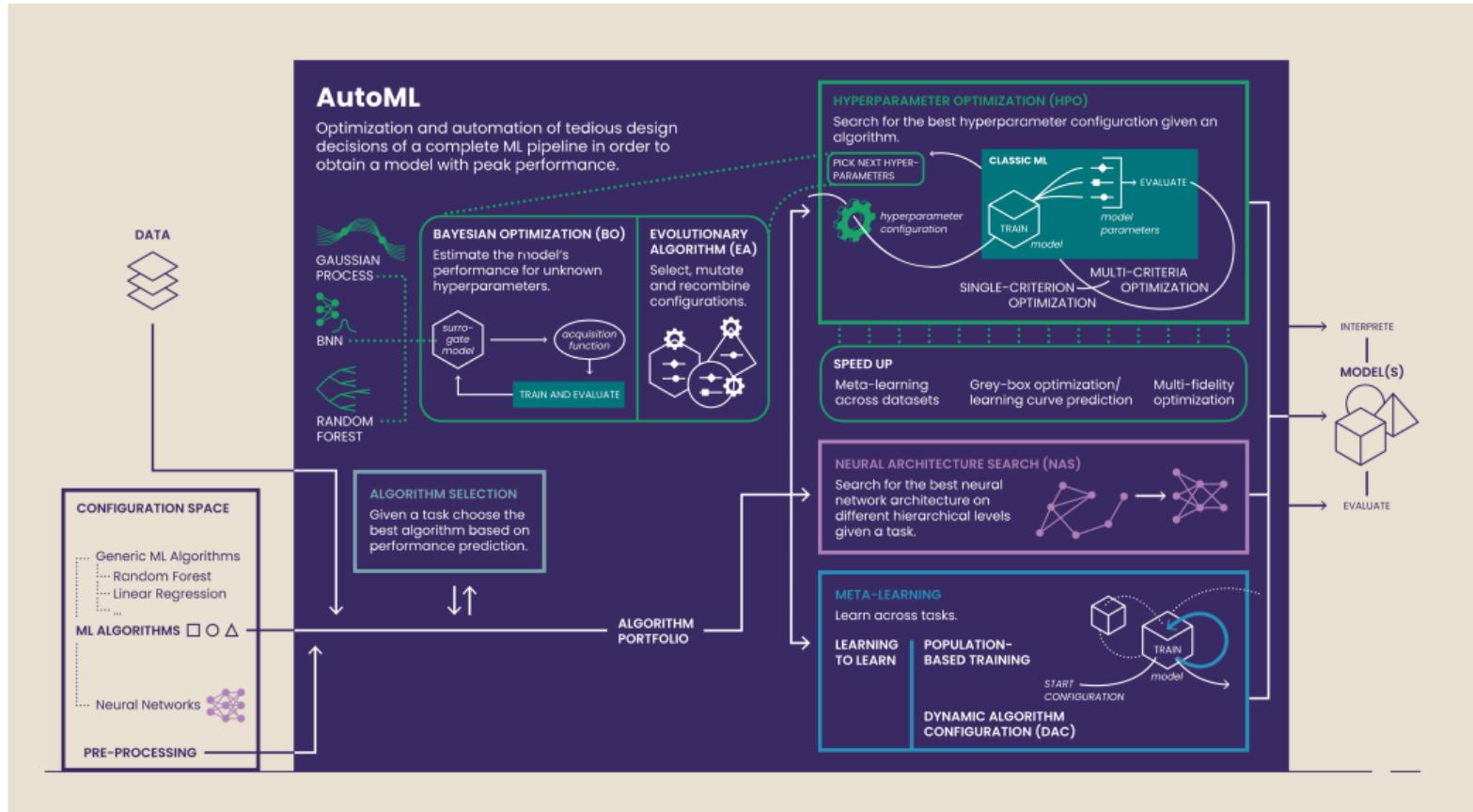
# AutoML + HPO + BO + Speed up + AS



# AutoML + HPO + BO + Speed up + AS + NAS



# AutoML + HPO + BO + Speed up + AS + NAS + Dynamic



# AutoML: Introduction

## The Big Picture

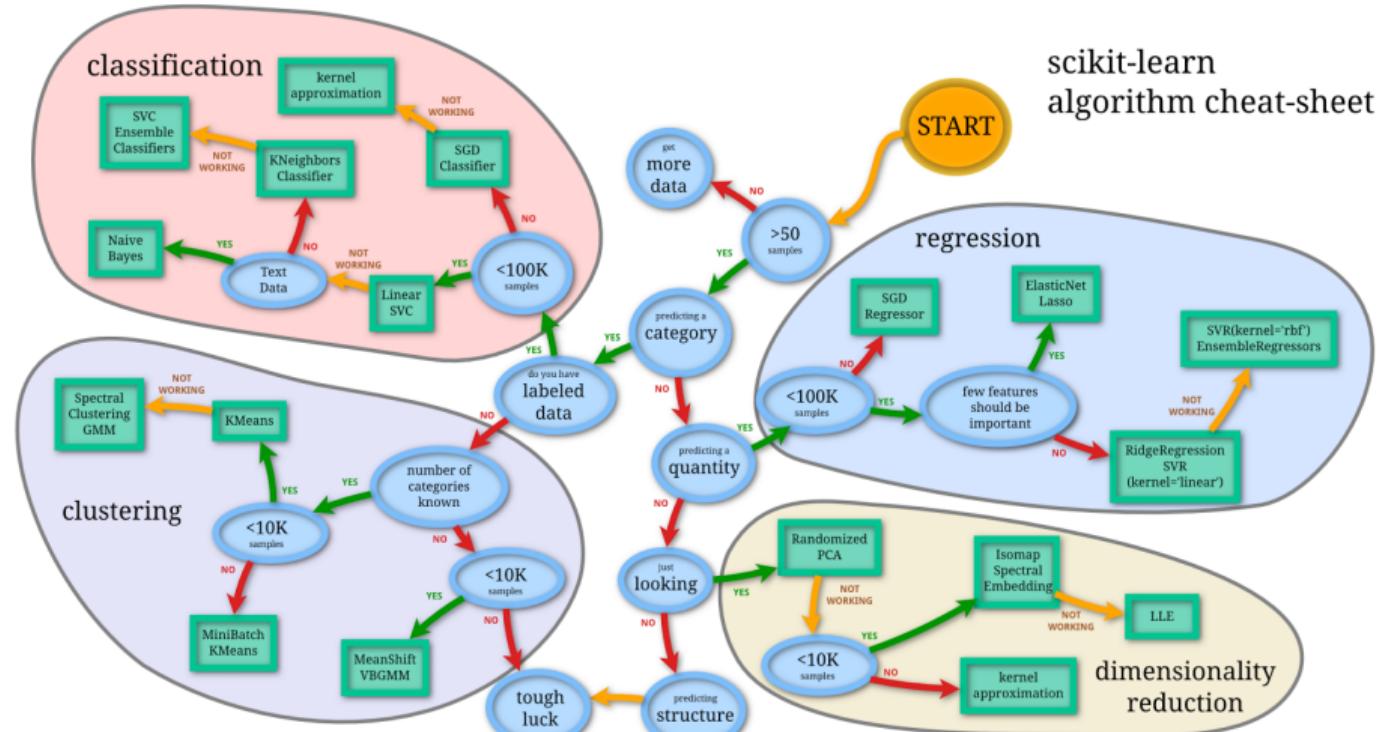
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# Machine Learning

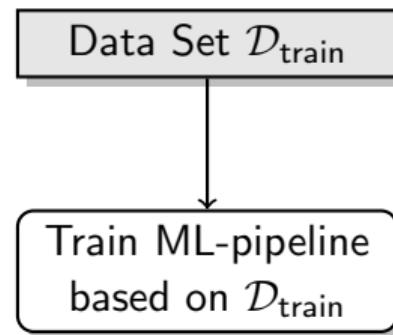
*“Machine learning is the science of getting computers to act without being explicitly programmed.”*

by Andrew Ng

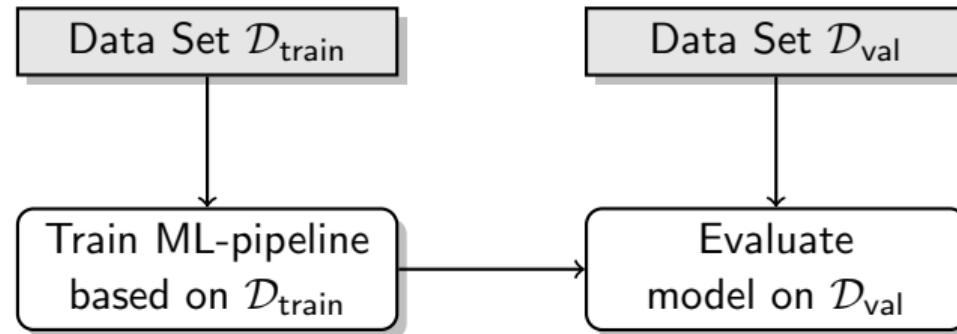
# Machine Learning requires many design decisions



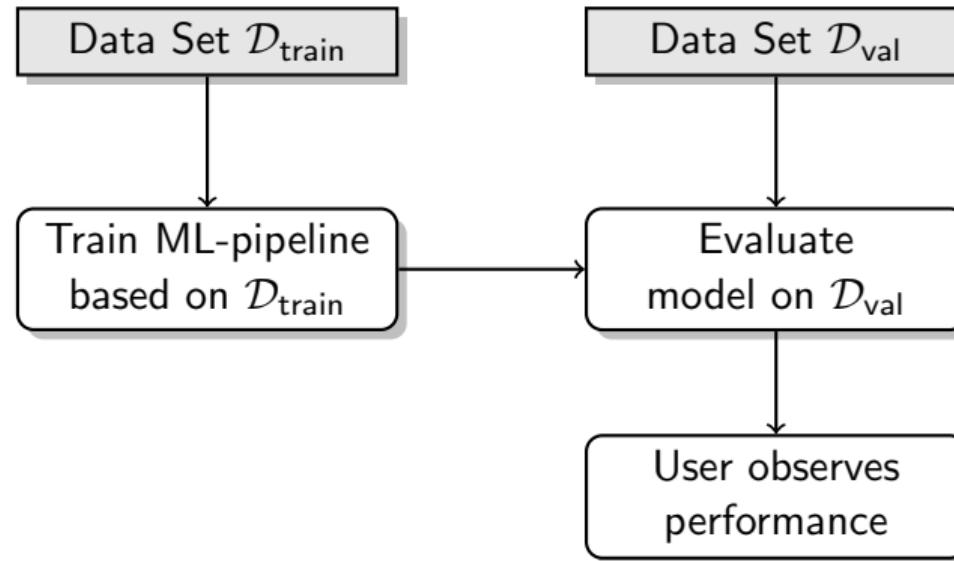
# Machine Learning Workflow



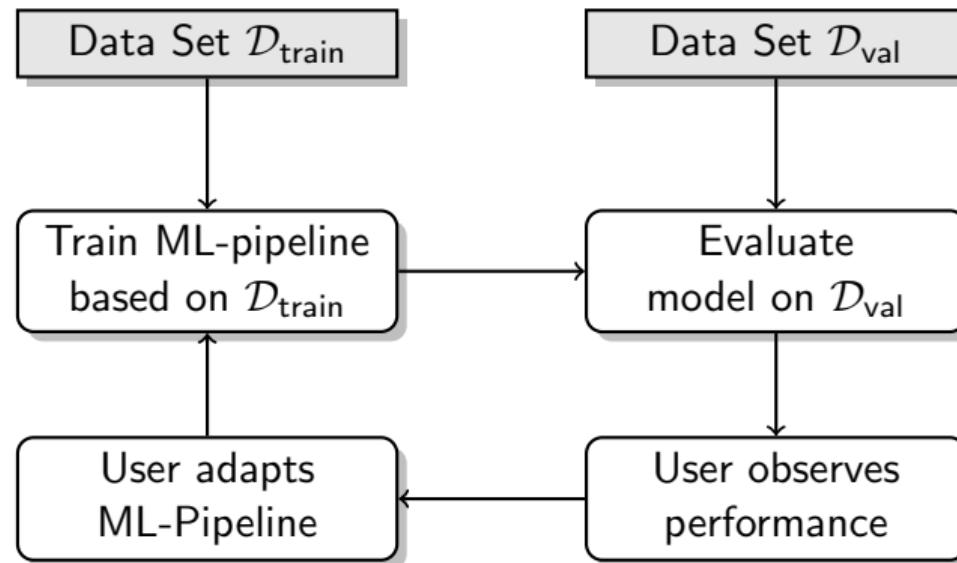
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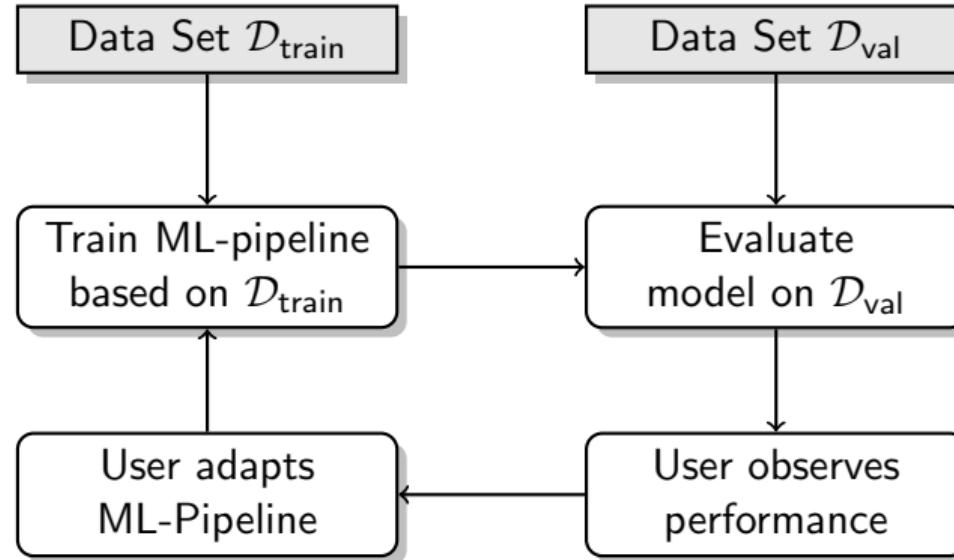
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~ Users indirectly teach machines how to learn.

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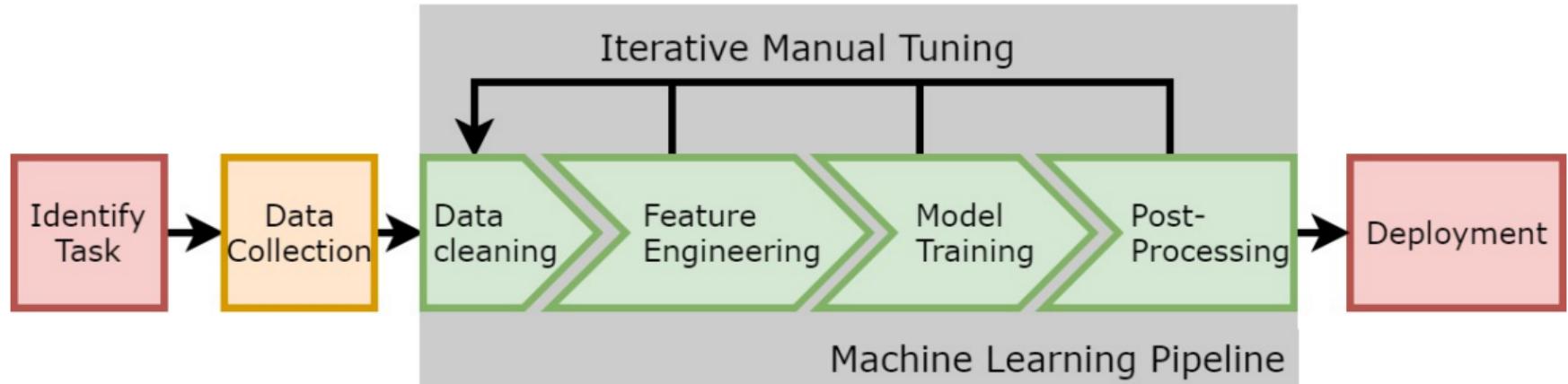
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Zoubin Ghahramani said that he often heard that:

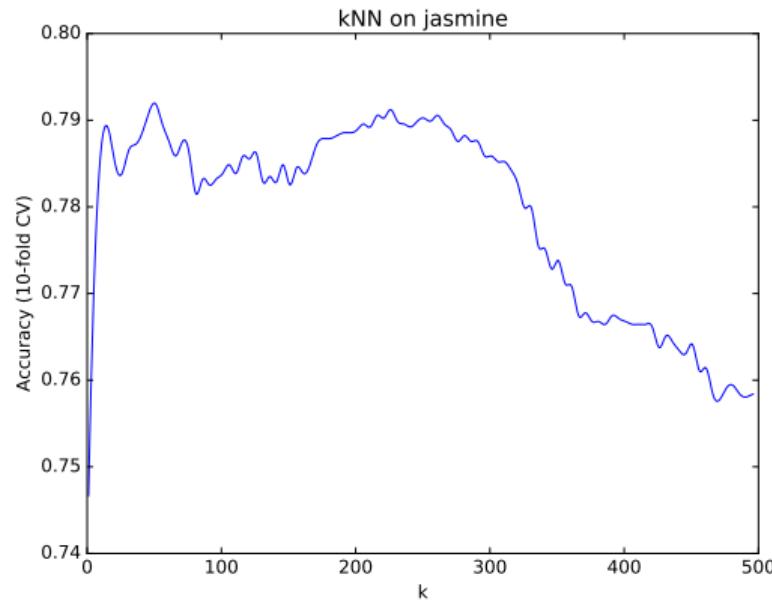
*"I'd like to use machine learning, but I can't invest much time."*

# Why does ML development take a lot of time?



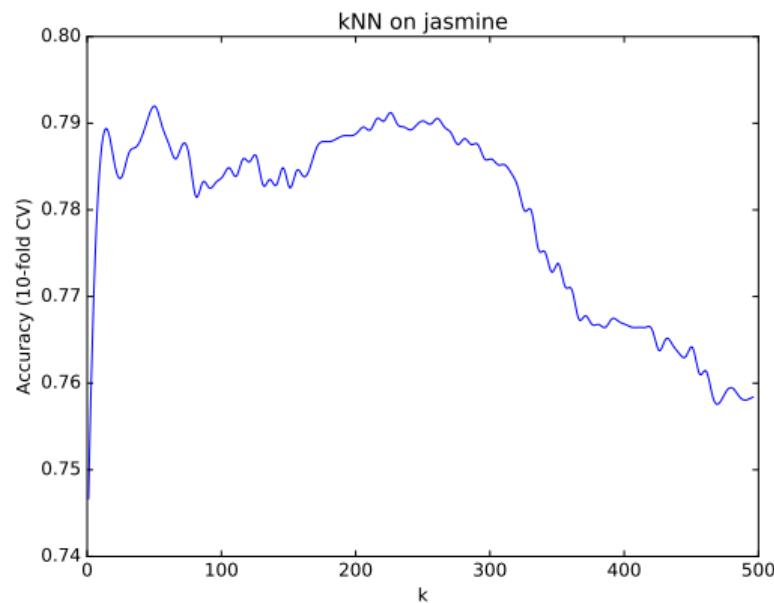
~~ To achieve state-of-the-art performance,  
this manual tuning has to be done for each new dataset again.

## A Simple Example with $k$ -NN



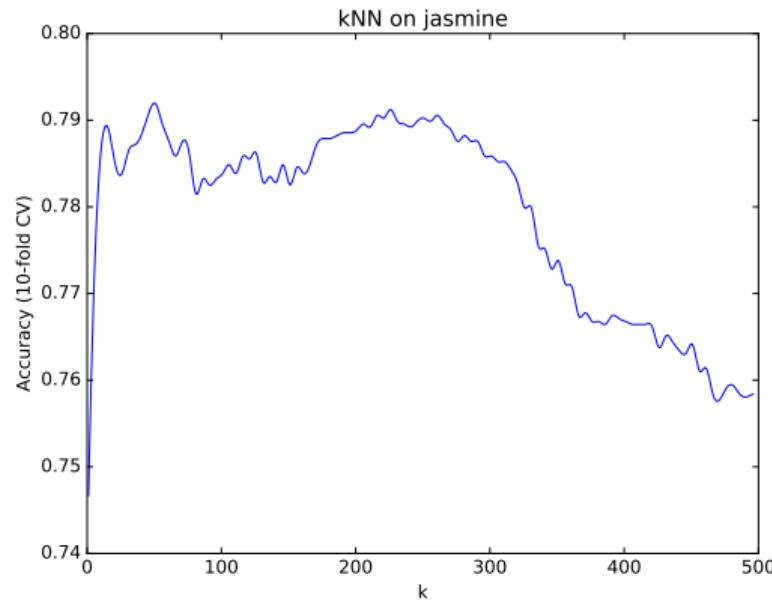
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- Size of neighbourhood ( $k$ ) is very important for its performance
- The performance function depending on  $k$  is quite complex (not at all convex)

# Goal of AutoML

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The goal of AutoML is to automate all parts of machine learning (as needed) to *support* users efficiently building their ML-applications.

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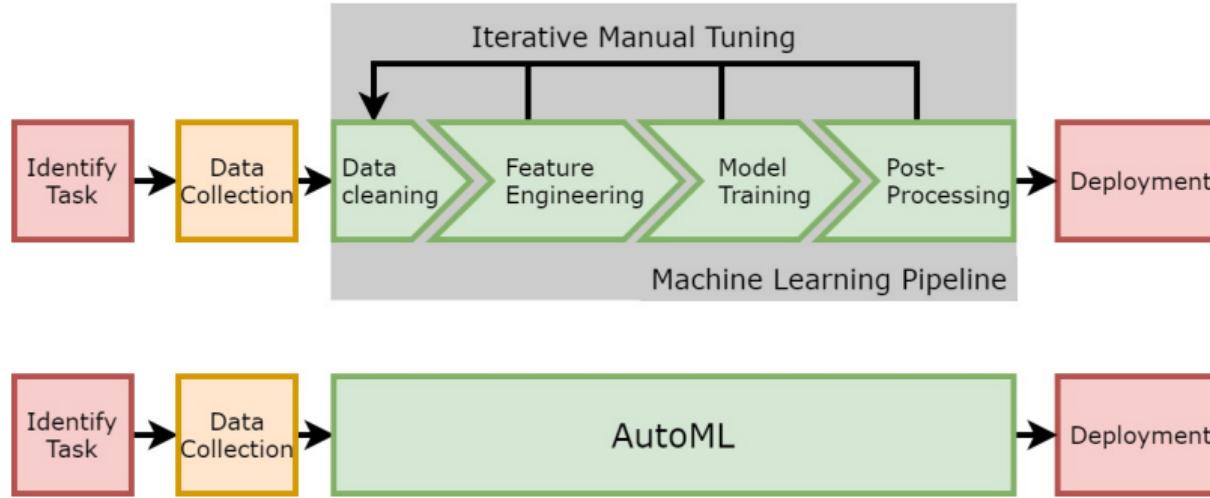
## Informal Definition: AutoML System

Given

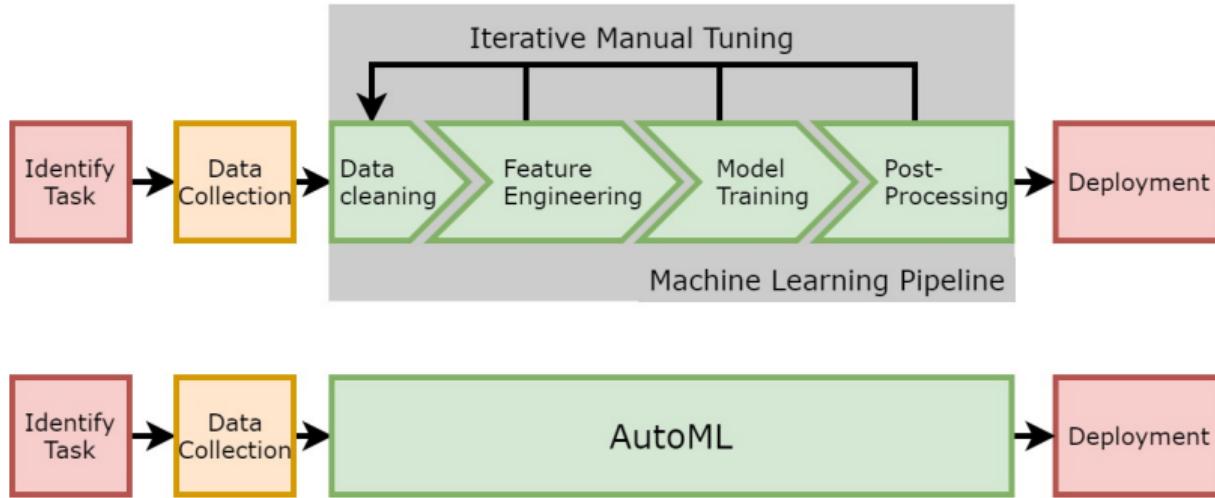
- a dataset
- a task (e.g., regression or classification)
- a cost metric (e.g., accuracy or RMSE)

an AutoML system automatically determines the approach that performs best for this particular application.

# ML vs AutoML



# ML vs AutoML



With AutoML, we ...

- support ML users
- improve the efficiency of developing new ML applications
- reduce the required ML-expertise
- might achieve better performance than developers w/o AutoML

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AutoML enables:

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  - ▶ AutoML has shown on subproblems to outperform human experts

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but AutoML is systematic
- ④ broader use of ML also in other disciplines
  - ▶ ML should not be limited to computer scientists;
  - ▶ the most amazing applications of ML are often done  
by either interdisciplinary teams or even non-computer scientists

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- ③ the mathematical relation between design decisions and performance is (often) unknown
  - ▶ gradient-based optimization is not directly possible
- ④ optimization in highly complex spaces
  - ▶ incl. categorical choices, continuous parameters, conditional dependencies

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## Overview of AutoML Problems

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Different metrics to measure the success of ML and AutoML:

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- ~~~ AutoML optimizes an arbitrary cost function, denoted as  $c$ .
- ~~~  $c(\cdot)$  can also return several cost metrics

# Hyperparameters of an SVM



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Previous  
sklearn.svm.  
...  
Next  
sklearn.svm.  
SVR  
Up  
API  
Reference

scikit-learn v0.20.3

Other versions

Please cite us if you use  
the software.

sklearn.svm.SVC  
Examples using  
sklearn.svm.SVC

## sklearn.svm.SVC

```
class sklearn.svm.SVC (C=1.0, kernel='rbf', degree=3, gamma='auto_deprecated', coef0=0.0, shrinking=True,  
probability=False, tol=0.001, cache_size=200, class_weight=None, verbose=False, max_iter=-1,  
decision_function_shape='ovr', random_state=None)
```

[source]

C-Support Vector Classification.

The implementation is based on libsvm. The fit time complexity is more than quadratic with the number of samples which makes it hard to scale to dataset with more than a couple of 10000 samples.

The multiclass support is handled according to a one-vs-one scheme.

For details on the precise mathematical formulation of the provided kernel functions and how gamma, coef0 and degree affect each other, see the corresponding section in the narrative documentation: [Kernel functions](#).

Read more in the [User Guide](#).

**Parameters:** `C : float, optional (default=1.0)`

Penalty parameter C of the error term.

`kernel : string, optional (default='rbf')`

Specifies the kernel type to be used in the algorithm. It must be one of 'linear', 'poly', 'rbf', 'sigmoid', 'precomputed' or a callable. If none is given, 'rbf' will be used. If a callable is given it is used to pre-compute the kernel matrix from data matrices; that matrix should be an array of shape `(n_samples, n_samples)`.

`degree : int, optional (default=3)`

Degree of the polynomial kernel function ('poly'). Ignored by all other kernels.

`gamma : float, optional (default='auto')`

Kernel coefficient for 'rbf', 'poly' and 'sigmoid'.

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The *hyper-parameter optimization (HPO)* problem is to find a hyper-parameter configuration that minimizes this cost:

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Remarks:

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- Sometimes, we want to optimize for different metrics, instead of one
  - ↪ multi-objective optimization and Pareto fronts

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  - ▶ support vector machine
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- studied 179 classifiers on 121 datasets [Fernández-Delgado et al. 2015]
- In practice, we actually want to jointly choose the best ML-algorithm and its hyperparameters

# CASH: Combined Algorithm Selection and Hyperparameter Optimization

## Definition

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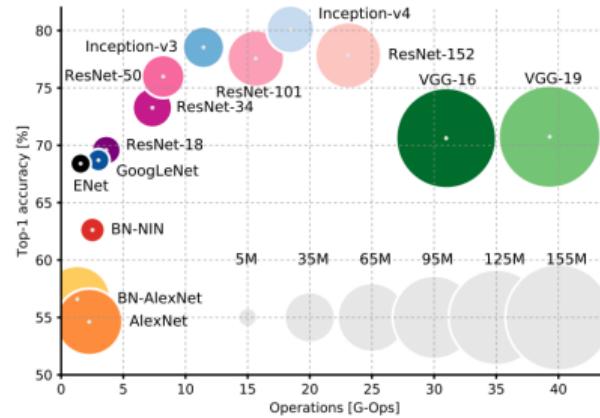
- $\mathbf{A} = \{\mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_k\}$  be a set of algorithms (a.k.a. portfolio)
- $\Lambda$  be a set of hyperparameters of each machine learning algorithm  $\mathcal{A}_i$
- $\mathcal{D}_{opt}$  be a dataset which is split into  $\mathcal{D}_{train}$  and  $\mathcal{D}_{valid}$
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we want to find the best combination of algorithm  $\mathcal{A} \in \mathbf{A}$  and its hyperparameter configuration  $\lambda \in \Lambda$  minimizing:

$$(\mathcal{A}^*, \lambda^*) \in \arg \min_{\mathcal{A} \in \mathbf{A}, \lambda \in \Lambda} c(\mathcal{A}_\lambda, \mathcal{D}_{train}, \mathcal{D}_{valid})$$

# Architectures of Neural Networks

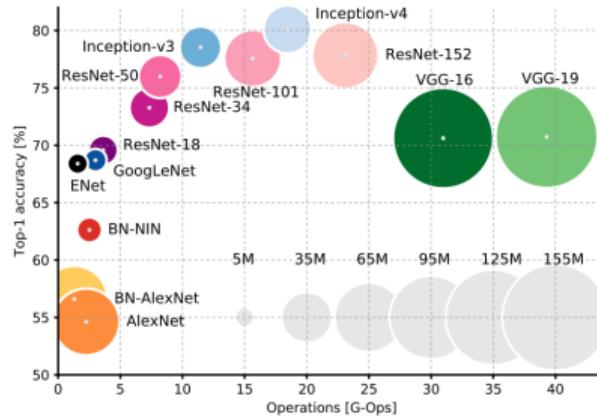
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on Imagenet [Canzian et al. 2017]

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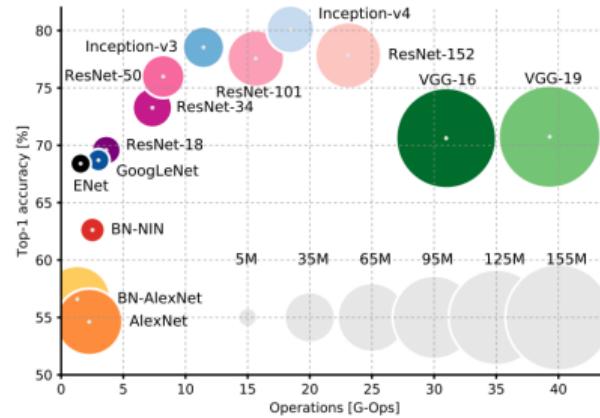


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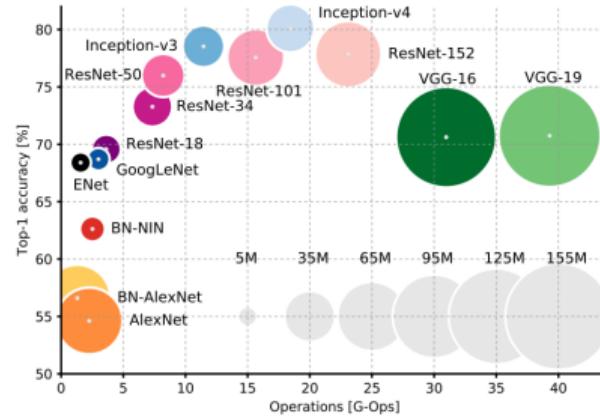


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- Already on a single dataset such as ImageNet, it is not obvious which architecture to choose
- For other datasets, you might need different architectures to achieve top-performance
  - ▶ For similar datasets, you might use scaled versions of known architectures (e.g., CIFAR10 and Imagenet)

# Neural Architecture Search (NAS)

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Remark:

- very similar to the HPO definition

# Neural Architecture Search (NAS)

## Definition

Let

- $\lambda$  be an architecture for a deep neural network  $N$  with domain  $\Lambda$ ,
- $\mathcal{D}_{opt}$  be a dataset which is split into  $\mathcal{D}_{train}$  and  $\mathcal{D}_{valid}$
- $c(N_\lambda, \mathcal{D}_{train}, \mathcal{D}_{valid})$  denote the cost of  $N_\lambda$  trained on  $\mathcal{D}_{train}$  and evaluated on  $\mathcal{D}_{valid}$ .

The *neural architecture search (NAS)* problem is to find an architecture that minimizes this cost:

$$\lambda^* \in \arg \min_{\lambda \in \Lambda} c(N_\lambda, \mathcal{D}_{train}, \mathcal{D}_{valid})$$

Remark:

- very similar to the HPO definition
- In practice, you want jointly optimize HPO and NAS [Zela et al. 2018]

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the *per-instance algorithm selection problem* is to obtain a mapping  $s : \mathcal{D} \mapsto \mathcal{A}$  such that

$$\arg \min_s \int_{\mathbf{D}} c(s(\mathcal{D}), \mathcal{D}) p(\mathcal{D}) d\mathcal{D}$$

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the *dynamic algorithm configuration problem (DAC)* is to obtain a configuration policy  $\pi^* : s_t \times \mathcal{D} \mapsto \lambda$  by optimizing its cost across a distribution of datasets:

$$\pi^* \in \arg \min_{\pi \in \Pi} \int_{\mathbf{D}} p(\mathcal{D}) c(\pi, \mathcal{D}) d\mathcal{D}$$

# Summary

**HPO** Search for the best hyperparameter configuration of a ML algorithm

**CASH** Search for the best combination of algorithm and hyperparameter configuration

**NAS** Search for the architecture of neural network

**Selection** Predict the best algorithm (and its hyperparameter configuration)

**DAC** Predict the best hyperparameter configuration for an algorithm state  
at a given time point

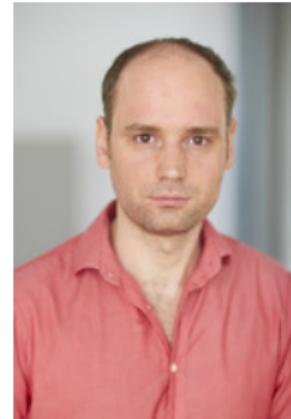
# AutoML: Introduction

## The Team

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# Bernd Bischl

- Professor at  
the Ludwig-Maximilians-University of Munich (Germany)
- Head of the statistical learning and data science group
- Co-Director of Munich Center for Machine Learning
- Founder of MLR (Machine Learning in R)
- Co-Founder of [www.openml.org](http://www.openml.org)
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(Configuration and Selection of Algorithms)



# Frank Hutter

- Professor at the University of Freiburg (Germany)
- Head of the machine learning lab
- Won 1st and 2nd international AutoML challenge
- Co-author of popular AutoML tools Auto-WEKA, Auto-sklearn, Auto-PyTorch
- Co-founder and co-organizer of AutoML workshop series at ICML (since 2014)
- Co-Editor of book on *Automated Machine Learning: Methods, Systems, Challenges*
- Co-Head of automl.org



# Lars Kotthoff

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- Organizer of competitions on algorithm selection
- Co-Editor of book on *Automated Machine Learning: Methods, Systems, Challenges*



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- Professor at  
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- Head of the machine learning group
- Won 1st and 2nd international AutoML challenge
- Co-author of popular AutoML tools Auto-sklearn &  
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- Co-Head of [automl.org](http://automl.org)
- Co-Founder and advisory board member of COSEAL  
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- Group Lead for AutoML & XAI at Fraunhofer IIS
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