



School of Computer Science & Engineering  
**Trustworthy Systems Group**

# Provable Security for Autonomous Vehicles

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# Car Hacking Danger Is Likely Closer Than You Think

A Detroit Free Press report shows there were 150 automotive cybersecurity incidents in 2019 alone.

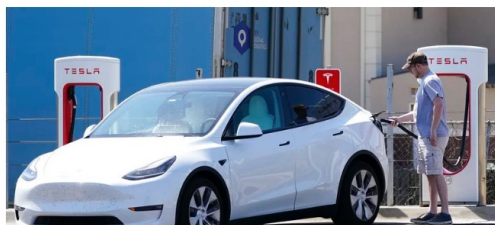


BY SEBASTIAN BLANCO PUBLISHED: SEP 4, 2021

NATIONAL

Nearly 400 car crashes in 11 months involved automated tech, companies tell regulators

June 15, 2022 · 1:26 PM ET  
By The Associated Press



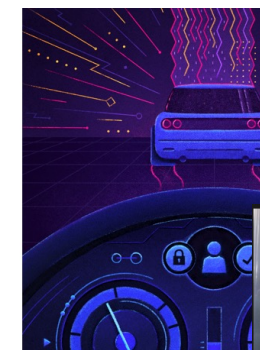
VULNERABILITIES

## Car Hacking Is Real. Here's How Manufacturers Can Combat It

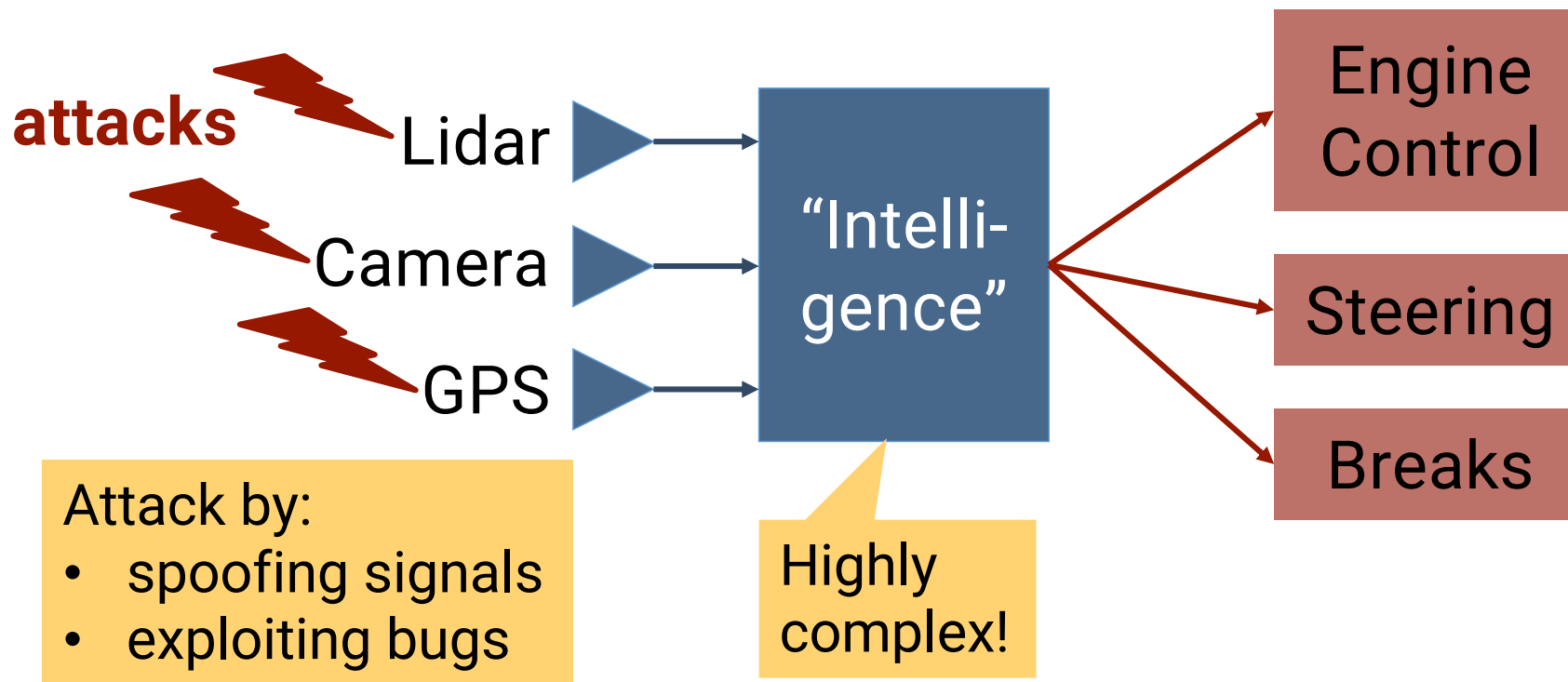
Sophisticated cars offer convenience for drivers but opportunities for hackers.



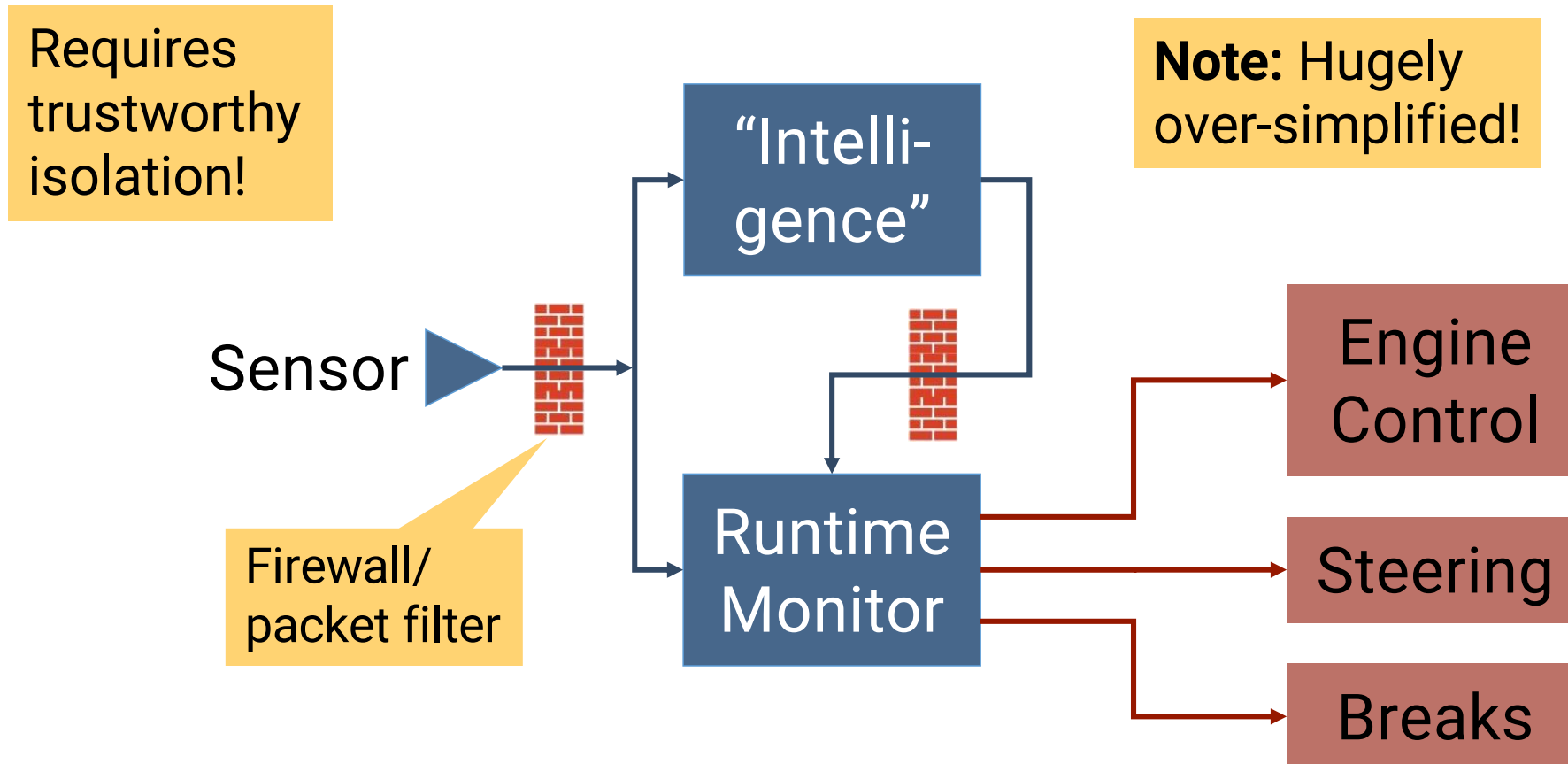
Diego Poza  
Head of Content



# Intelligent Vehicles: Hacker's Paradise!



# How Can We Protect Intelligent Vehicles?



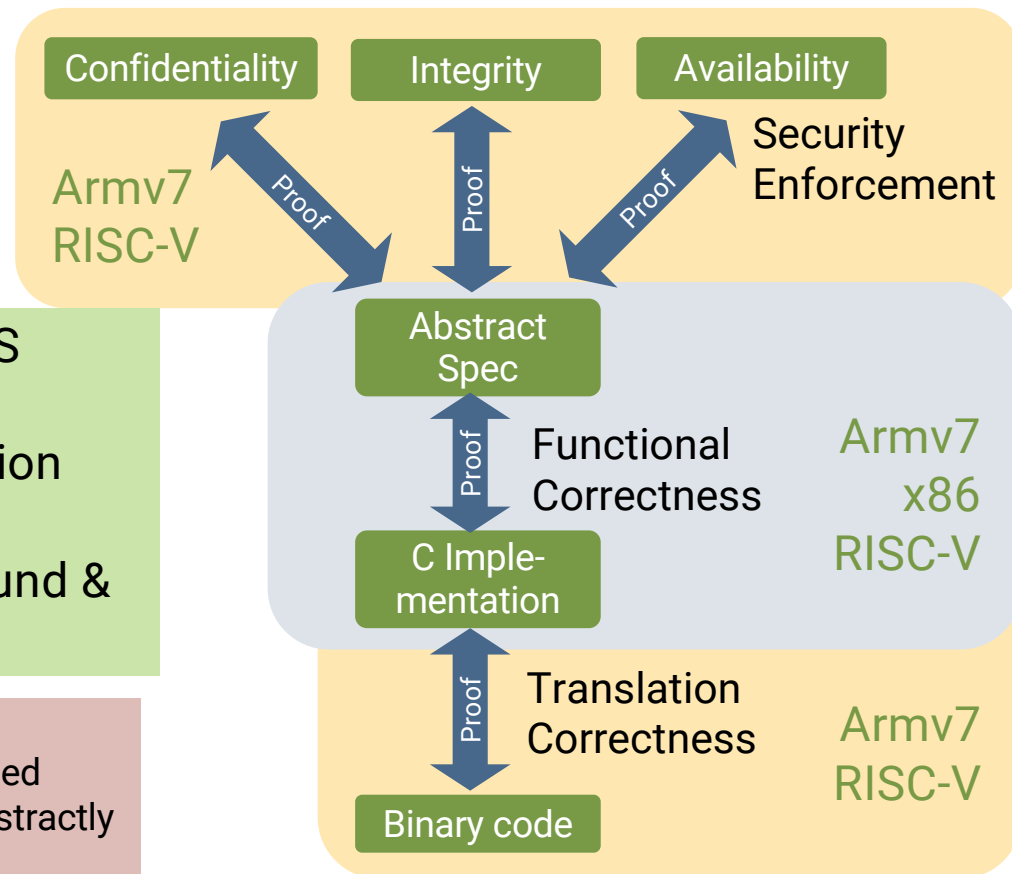
# seL4 Foundation for Truly Secure Systems

AArch64 in progress

- World's first correctness proof of OS
- Comprehensive formal verification
- Capabilities for fine-grained protection
- World's fastest microkernel
- Only protected-mode RTOS with sound & complete WCET analysis (Armv6)

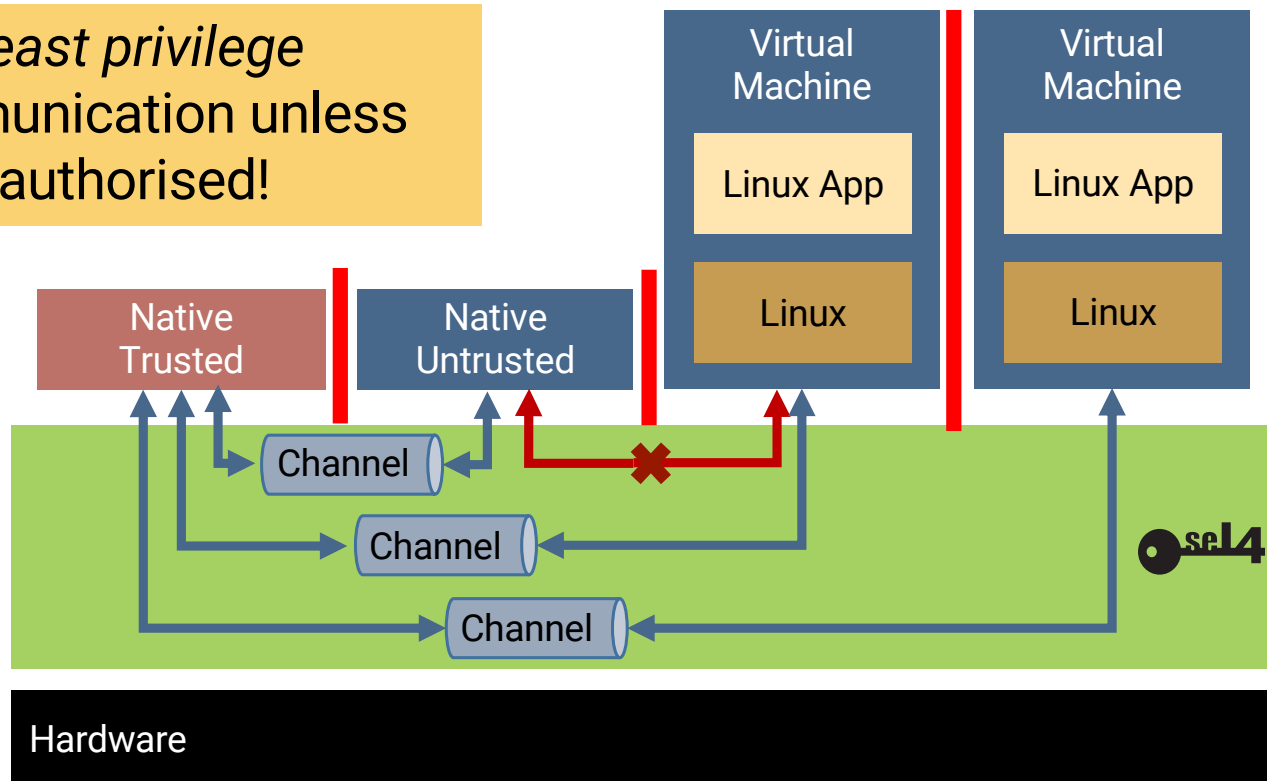
Present limitations

- initialisation code not verified
- MMU, caches modelled abstractly
- Multicore not yet verified



# sel4 Capabilities: Fine-Grained Protection

- Enforce *least privilege*
- No communication unless explicitly authorised!



# The Benchmark for Performance

Round-trip cross-address-space IPC on 64-bit Intel Skylake

Smaller  
is better

	seL4	Fiasco.OC L4Re	Zircon
Latency (cycles)	986	2717	8157
Mandatory HW cost* (cycles)	790	790	790
Overhead absolute (cycles)	196	1972	7367
Overhead relative	25%	240%	930%

World's fastest  
microkernel!

\*: The Cost of SYCALL + 2 × SWAPGS + SYSRET = 395 cycles, times 2 for round-trip

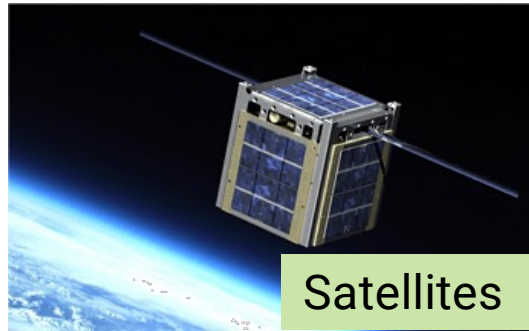
## Source:

Zeyu Mi, Dingji Li, Zihan Yang, Xinran Wang, Haibo Chen: "SkyBridge: Fast and Secure Inter-Process Communication for Microkernels", EuroSys, April 2019

# sel4 Made For Real-World Use



Autonomous vehicles



Satellites



Secure communication device  
In use in multiple defence forces

Laot: Critical  
infrastructure  
protection





# DARPA: World's Most Secure Drone



← Tweet



We brought a hackable quadcopter with defenses built on our HACMS program to [@defcon](#) [#AerospaceVillage](#). As program manager [@raymondrichards](#) reports, many attempts to breakthrough were made but none were successful. Formal methods FTW!



# seL4-based OS

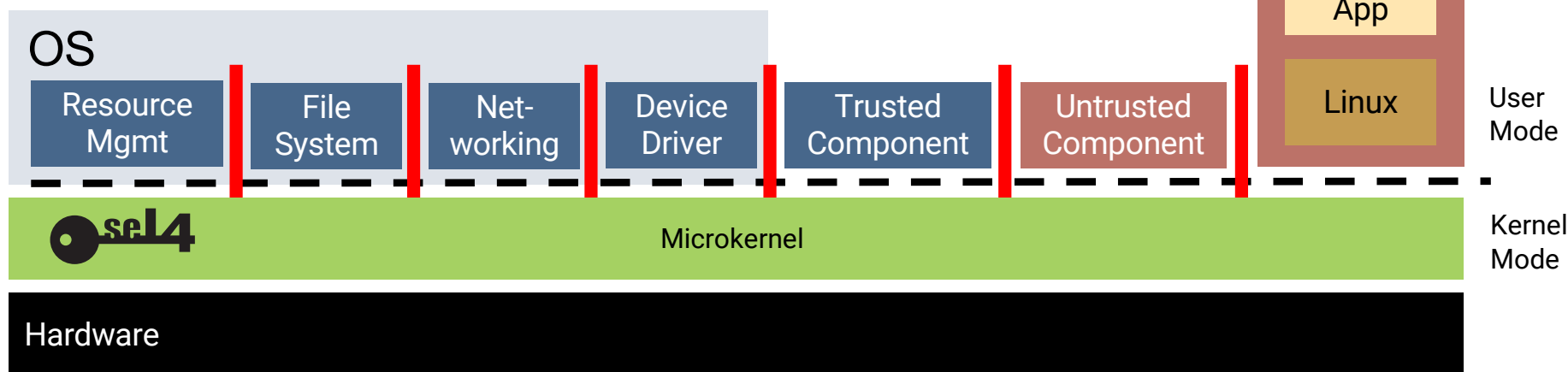
# Microkernel Is Not An OS

Modularisation: Separate components

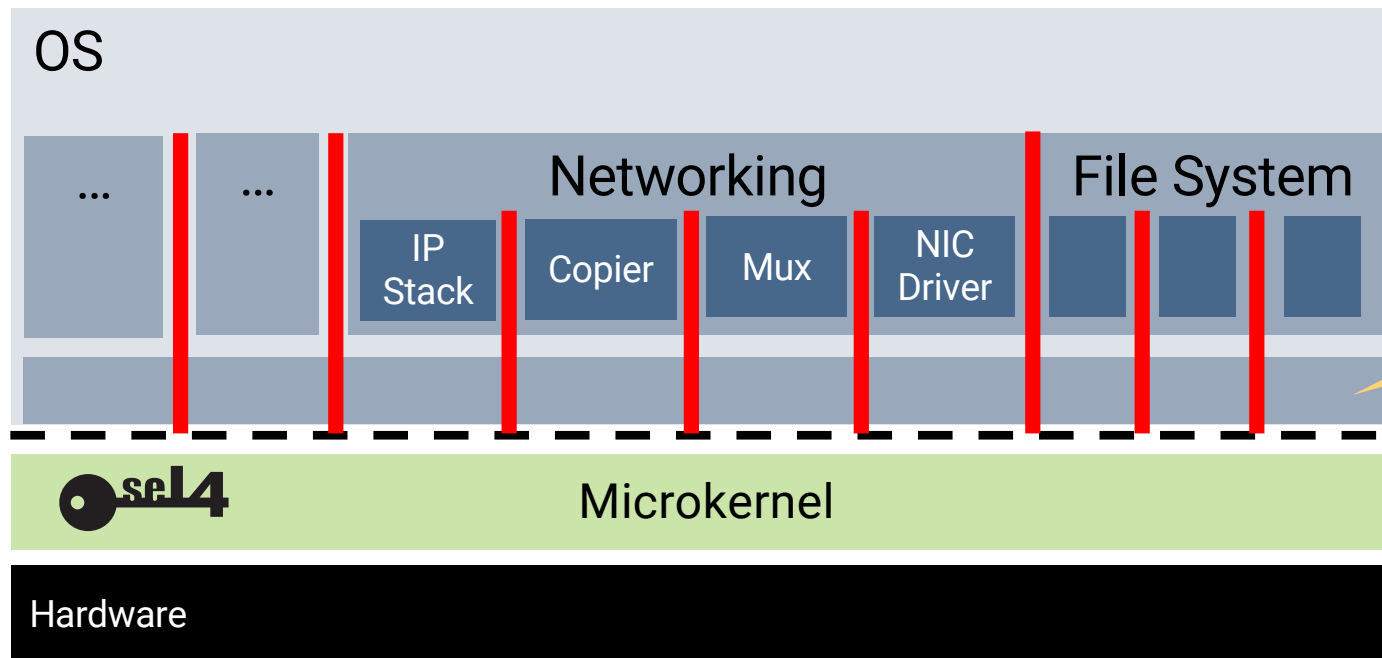
- operating-system services
- device drivers
- applications

Microkernel enforces isolation – bullet-proof

- kernel code reduced to minimum
- mediates hardware resources



# A Modular seL4 OS



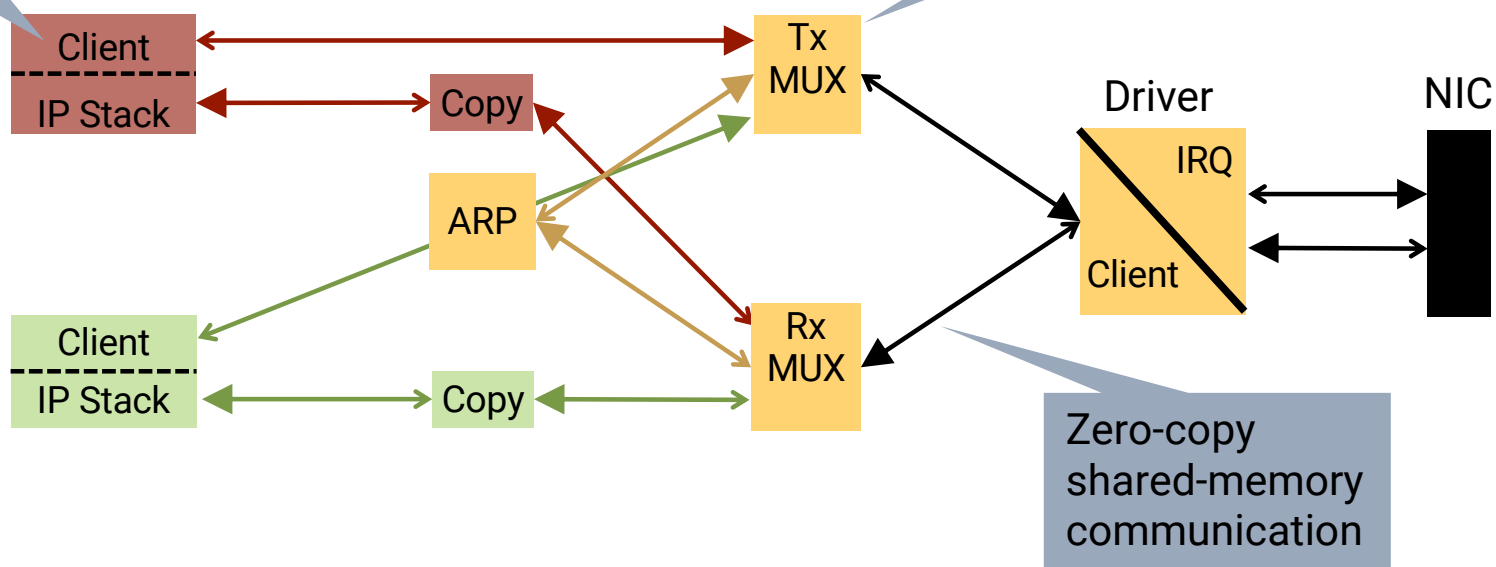
**seL4 Core Platform:**  
Thin abstraction layer

# Example: Networking

- Async I/O interface
- Optional Posix-like front-end

Strict separation of concerns: Large number of extremely simple components

Multiplexer for device sharing and traffic shaping

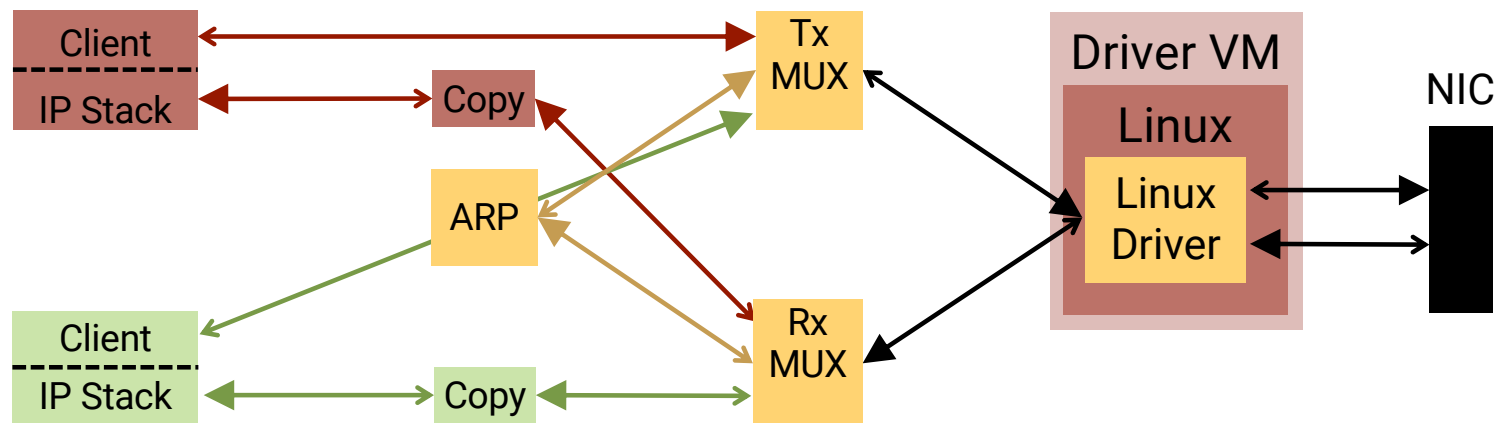


Zero-copy shared-memory communication

# Legacy Drivers?



Can use Linux drivers wrapped into individual driver VM



# Comparison to Linux



## Linux:

- NW driver: 4k lines
- NW system total: 1M lines

Performance?

Written by second-year student!

## KISS design:

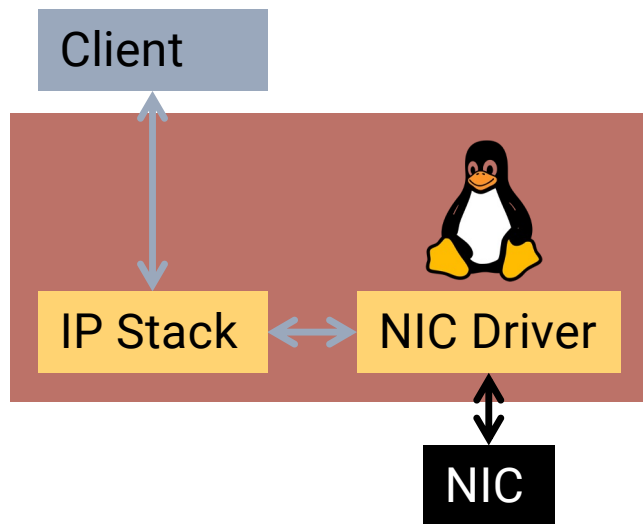
- NW driver: 700 lines
- MUX: 400 lines
- Copier: 200 lines
- IP stack: much simpler, client library
- shared NW system total < 2,000 lines

Simple enough to apply push-button verification!

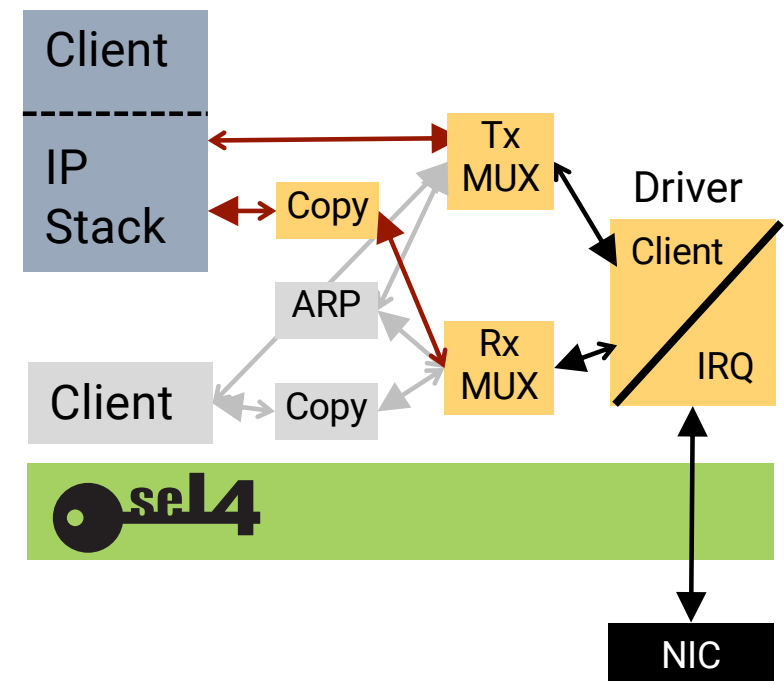
# Evaluation Setup



2 context switches per packet



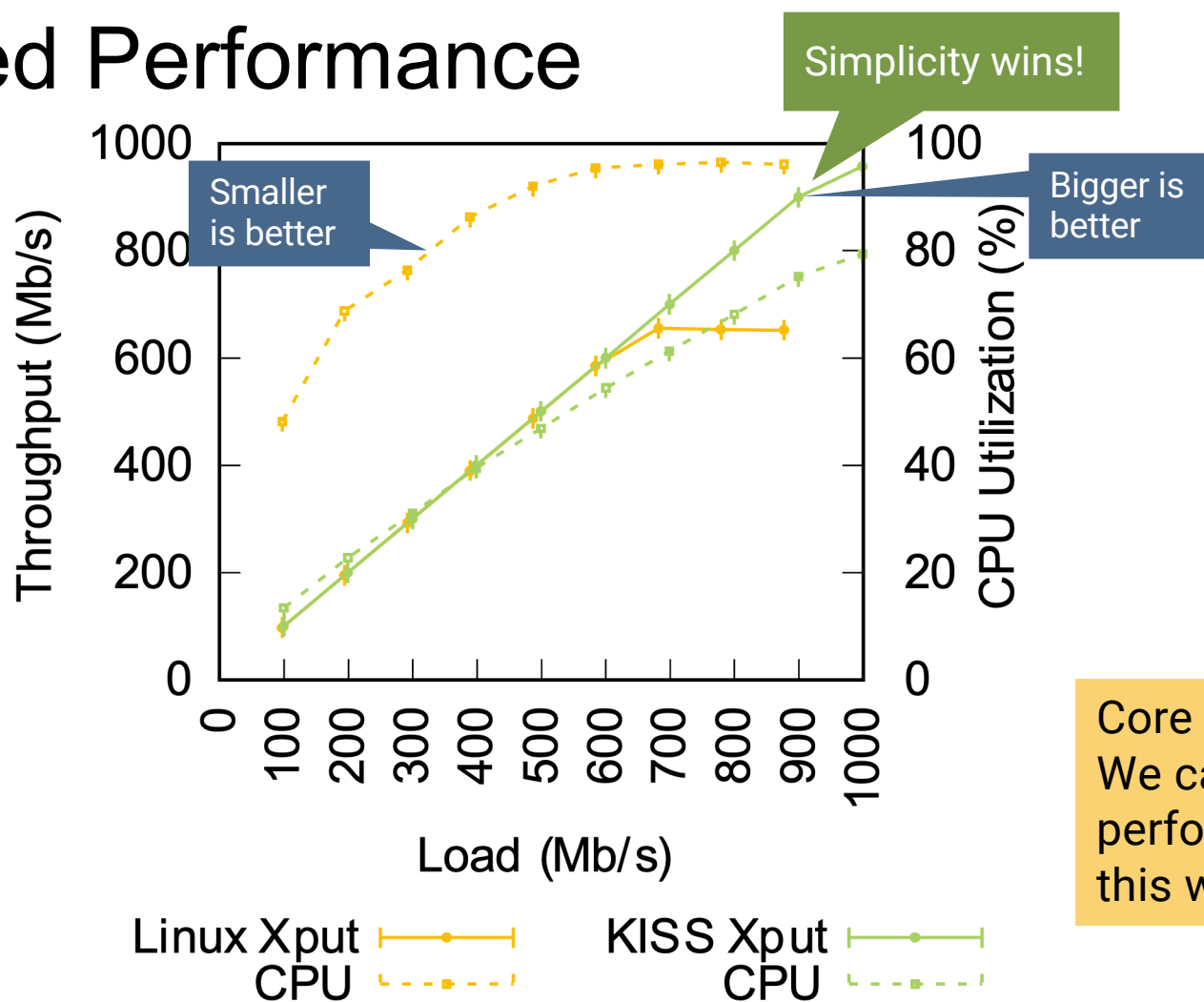
10 context switches per packet





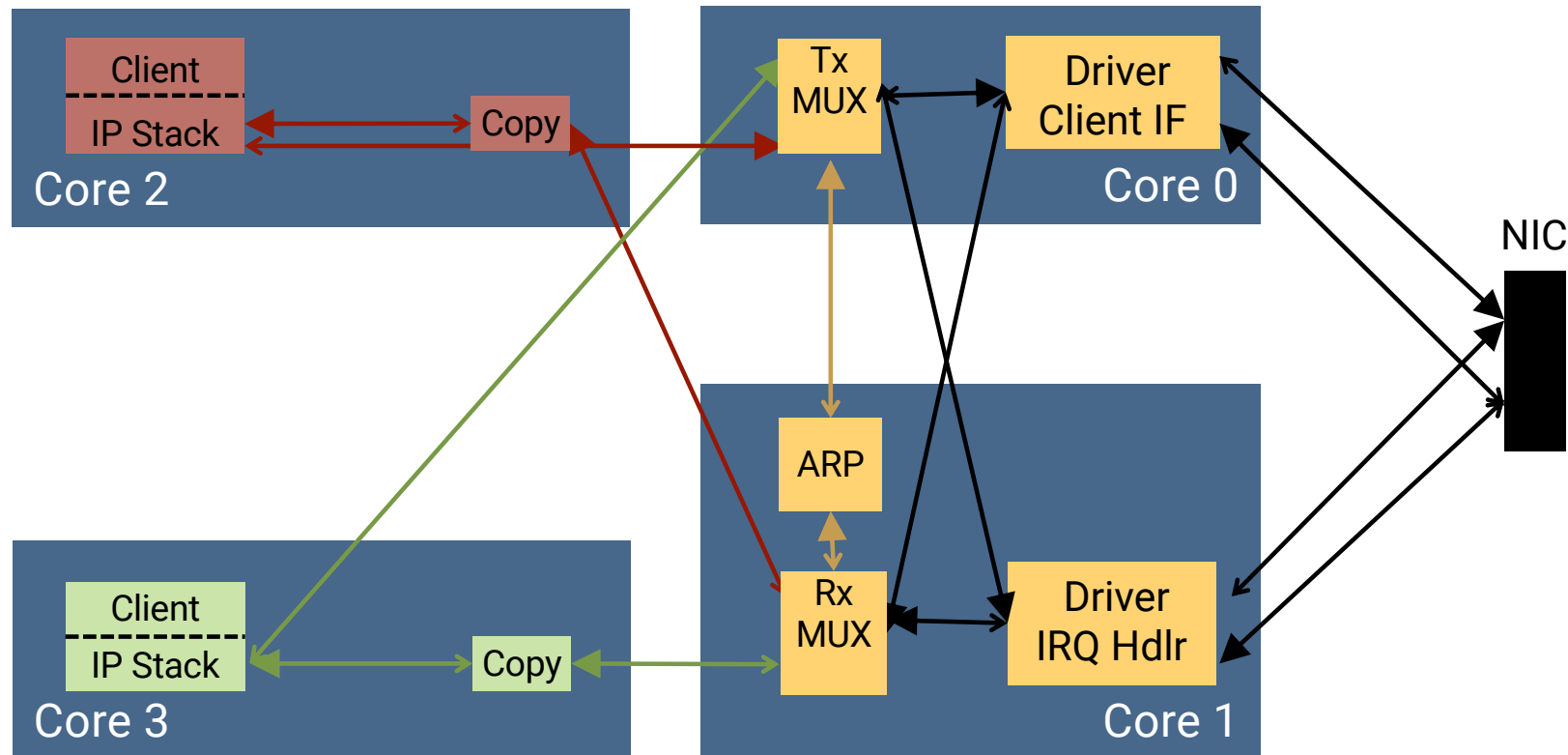
# Achieved Performance

- Gigabit Ethernet
- single core

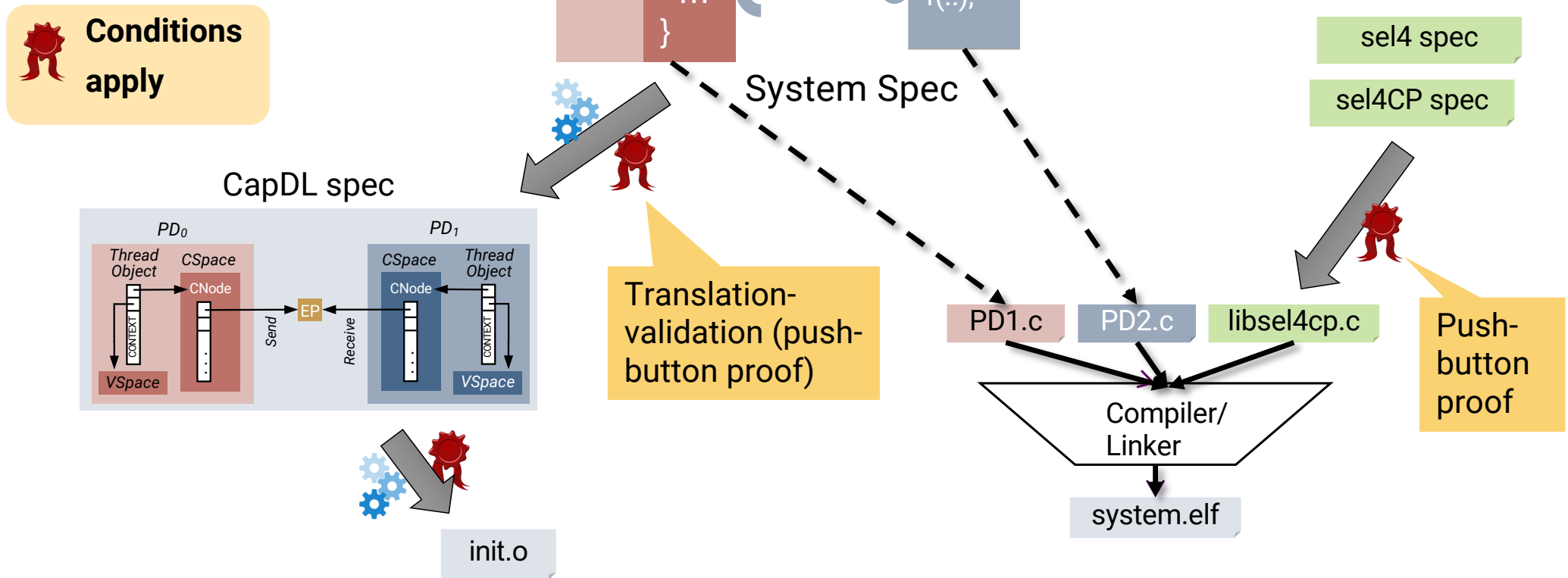


Core take-away:  
We can build a  
performant OS  
this way!

# Multicore Example



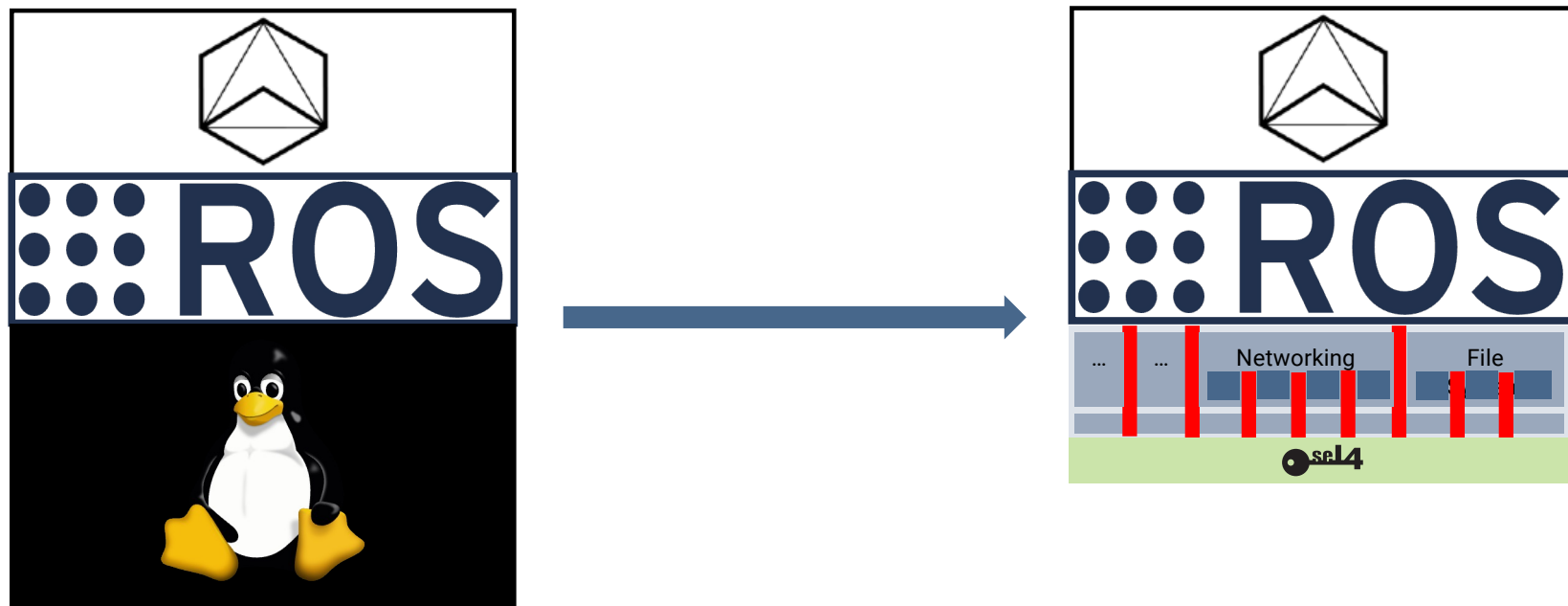
# OS Verification





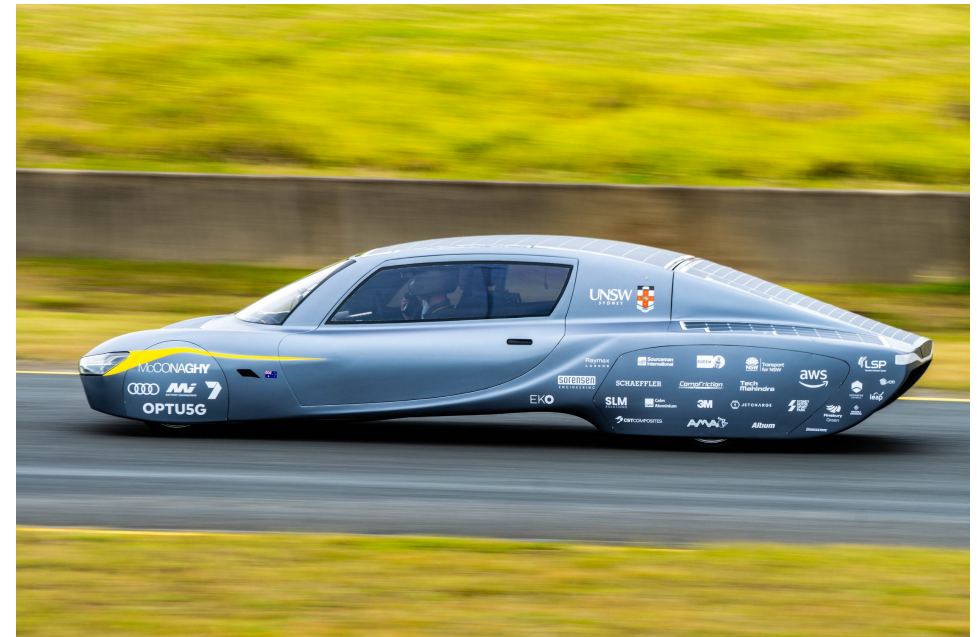
# seL4 and Autoware

# Autoware on seL4?



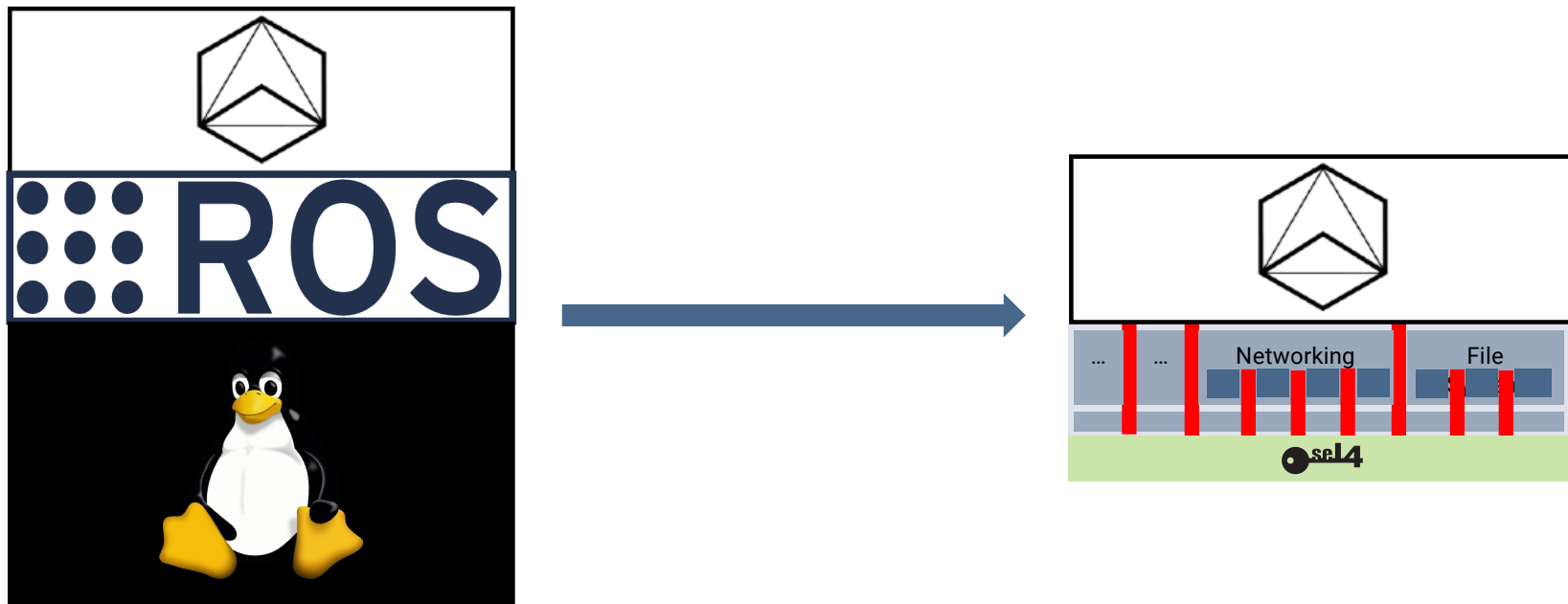
# Porting ROS 2: Initial Experience

- Current driver is UNSW's Sunswift Solar Racing Car
- In theory, ROS 2 has an OS abstraction layer:
  - ROS 2 Core Utilities
  - ROS 2 Runtime C
- In practice, ROS 2 implementation basically assumes Linux underneath
  - need to analyse more how a port could really work
  - stay tuned...



# Autoware on seL4 – Alternative Approach

To be investigated!





Security is no excuse  
for bad performance!



<https://trustworthy.systems>

