

深度学习与迁移学习

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2017-07-30

主要内容

- 图像识别与定位
 - 思路1: 视作回归
 - 思路2: 借助图像窗口
- 物体识别
 - 边缘策略/选择性搜索 => R-CNN
 - R-CNN => Fast R-CNN
 - Fast R-CNN => Faster R-CNN
 - R-FCN简介
- 有监督到有监督的迁移学习
 - fine-tune 再优化
 - Multitask learning 多任务学习
- 有监督到无监督的迁移学习
 - 域对抗学习



卷积神经网络

□ 层次变深，效果变好

D	E
16 weight layers	19 weight layers
conv3-64 conv3-64	conv3-64 conv3-64
conv3-128 conv3-128	conv3-128 conv3-128
conv3-256 conv3-256 conv3-256	conv3-256 conv3-256 conv3-256
conv3-512 conv3-512 conv3-512	conv3-512 conv3-512 conv3-512
conv3-512 conv3-512 conv3-512	conv3-512 conv3-512 conv3-512
maxpool	
FC-4096	
FC-4096	
FC-1000	
soft-max	

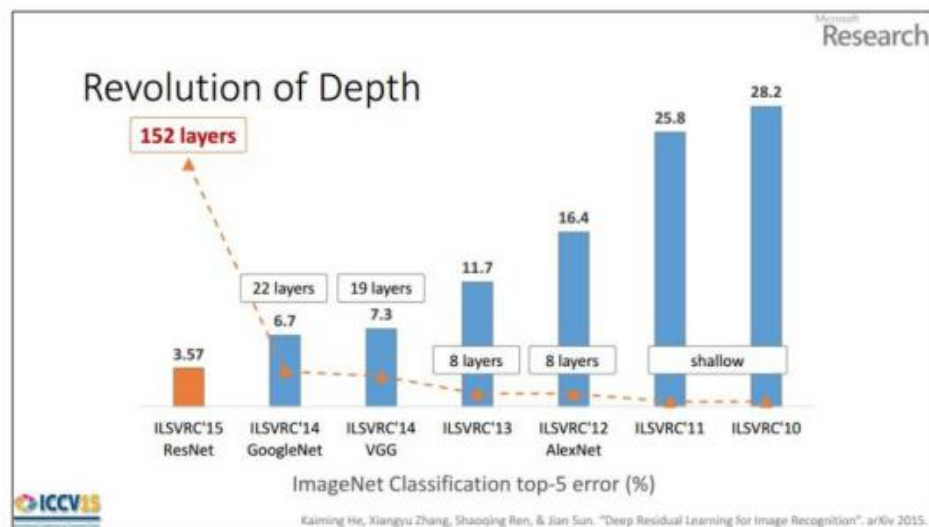
VGG
(2014)



GoogLeNet
(2014)



ResNet
(2015)



图像相关任务

图片识别



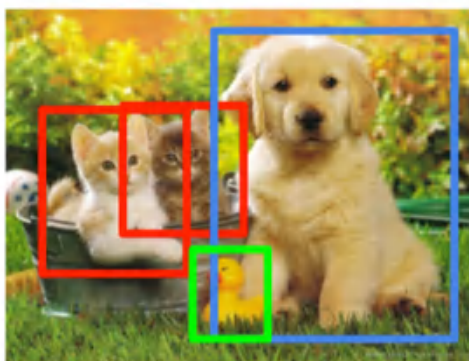
CAT

图片识别+定位



CAT

物体检测



CAT, DOG, DUCK

图像分割



CAT, DOG, DUCK

单物体

多物体



图像识别+定位

图像识别与定位

Classification: C个类别

Input: Image

Output: 类别标签

Evaluation metric: 准确率



CAT

Localization:

Input: Image

Output: 物体边界框 (x, y, w, h)

Evaluation metric: 交并准则



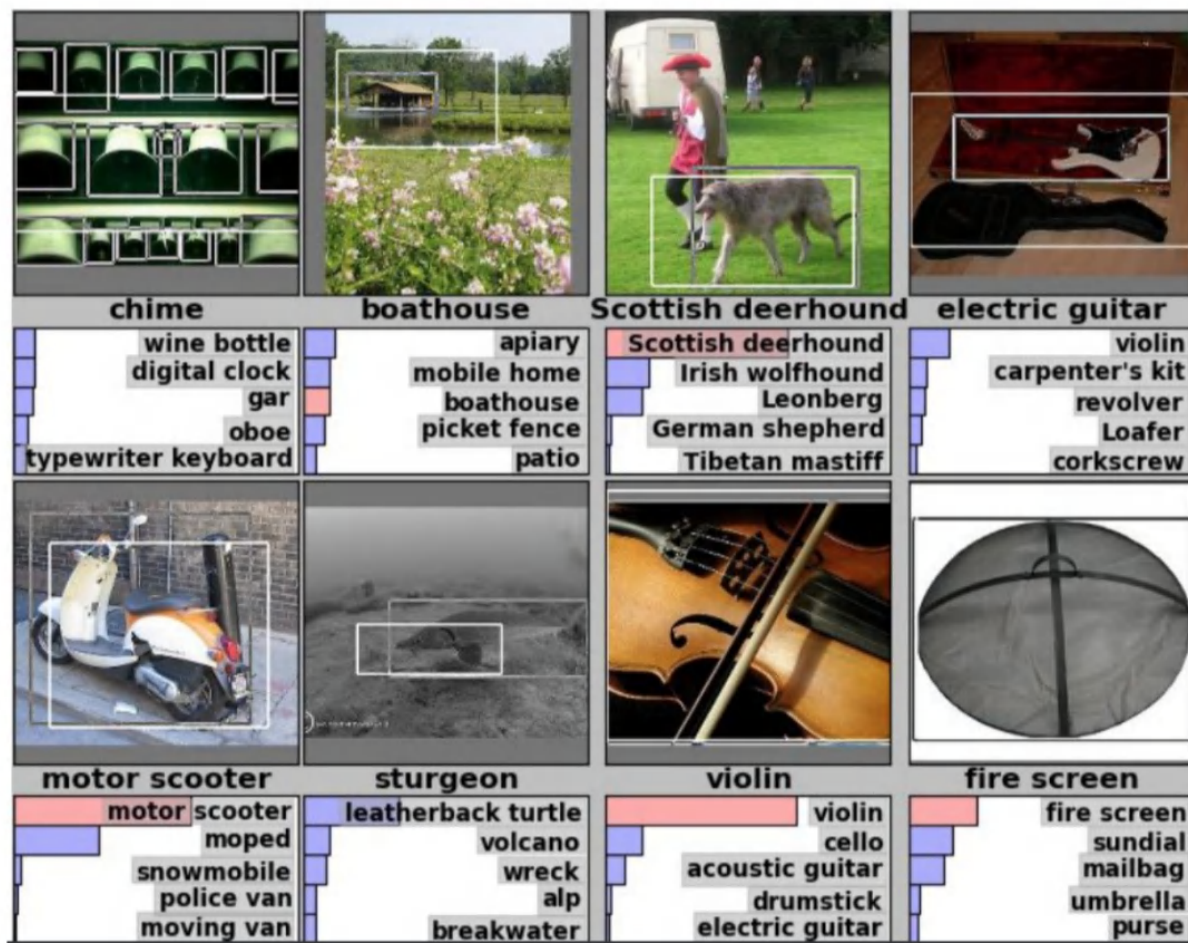
(x, y, w, h)

Classification + Localization: 识别主体+定位



ImageNet

□ 实际上有 识别+定位 2个任务



思路1：看作回归问题

□ 4个数字，用L2 loss/欧氏距离损失

Input: image



Neural Net



Output:

Box coordinates
(4 numbers)

Correct output:
box coordinates
(4 numbers)



Loss:
L2 distance

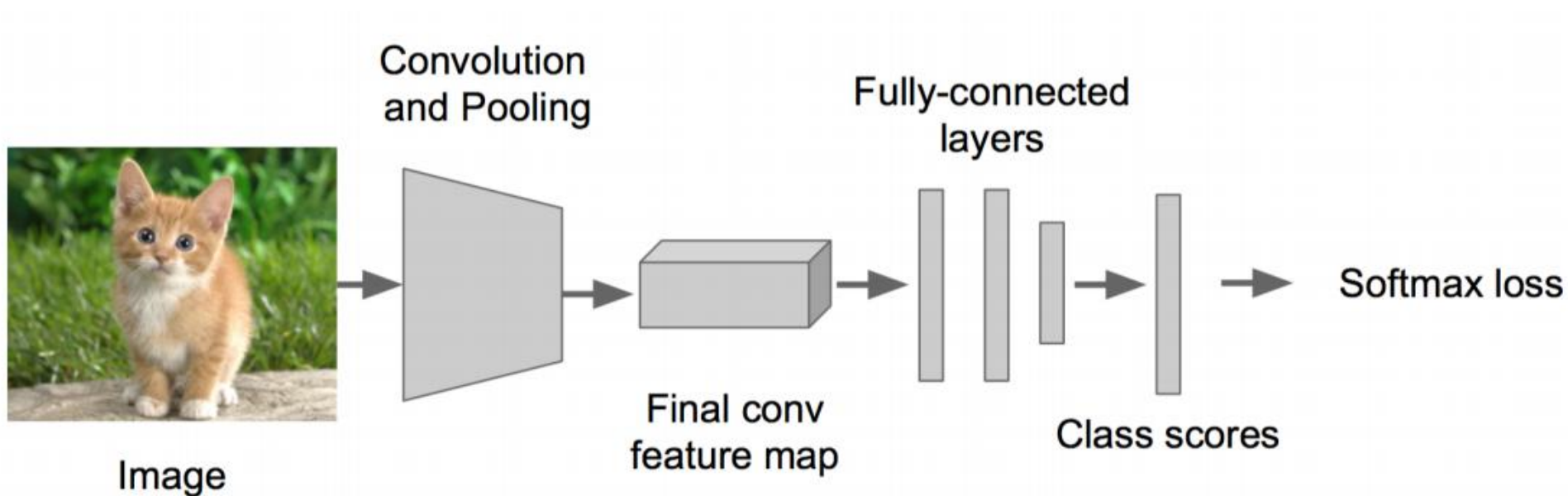
Only one object,
simpler than detection



思路1：看作回归问题

□ 步骤1:

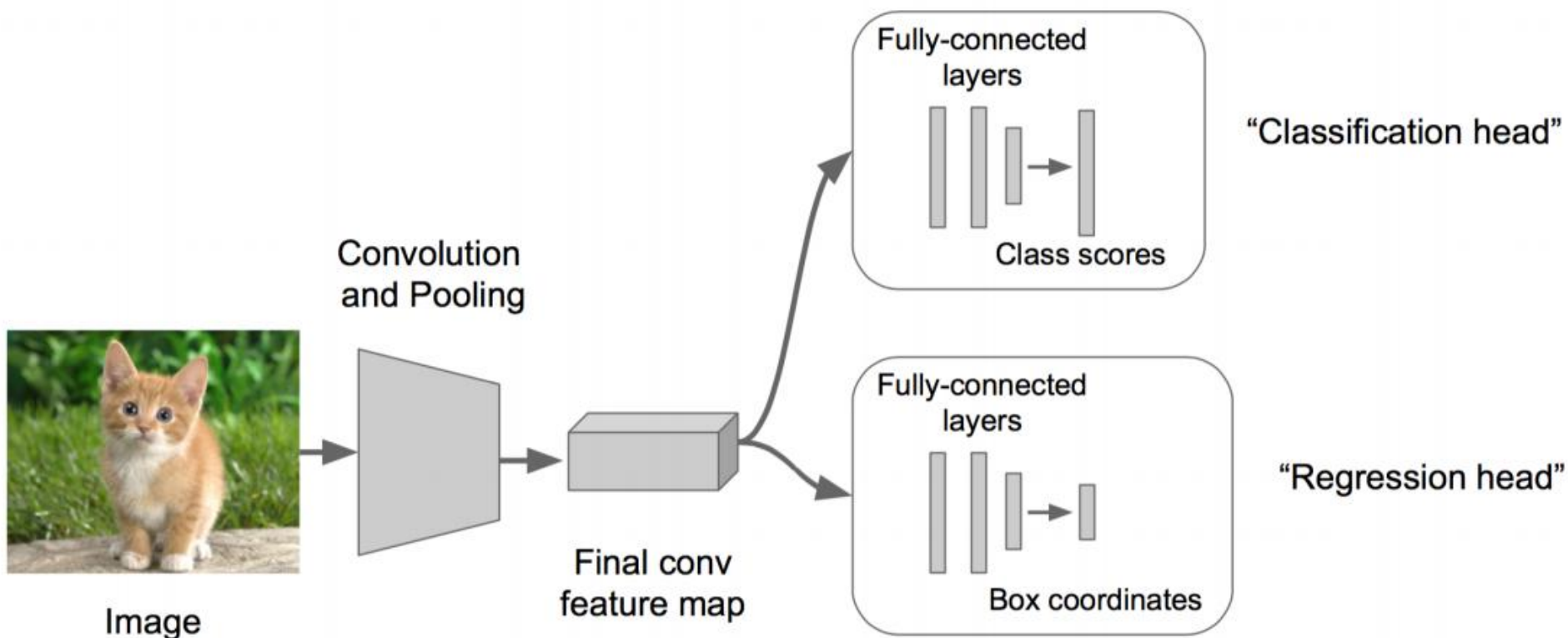
- 先解决简单问题，搭一个识别图像的神经网络
- 在AlexNet VGG GoogleLenet ResNet上fine-tune一下



思路1：看作回归问题

□ 步骤2:

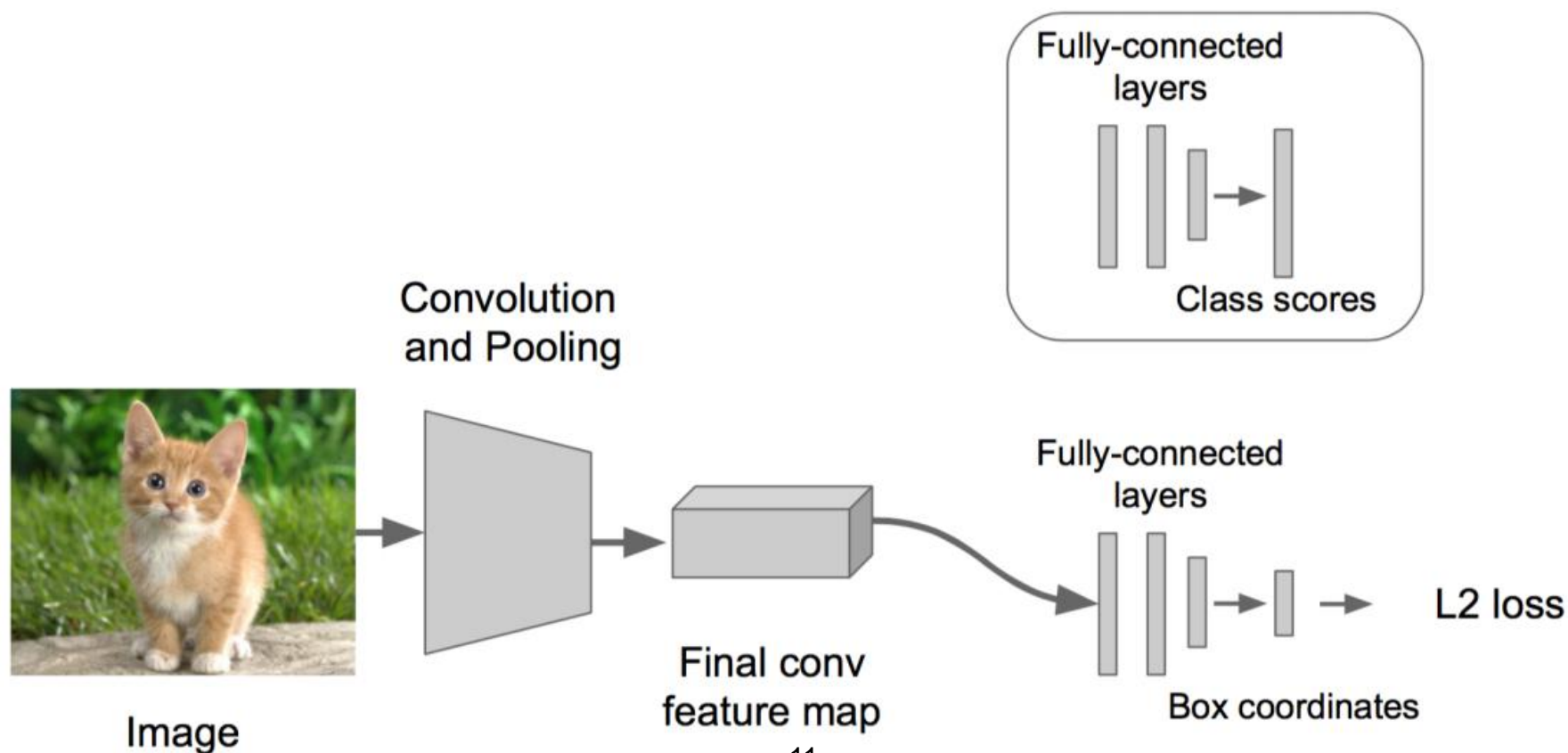
- 在上述神经网络的尾部展开
- 成为classification + regression模式



思路1：看作回归问题

□ 步骤3:

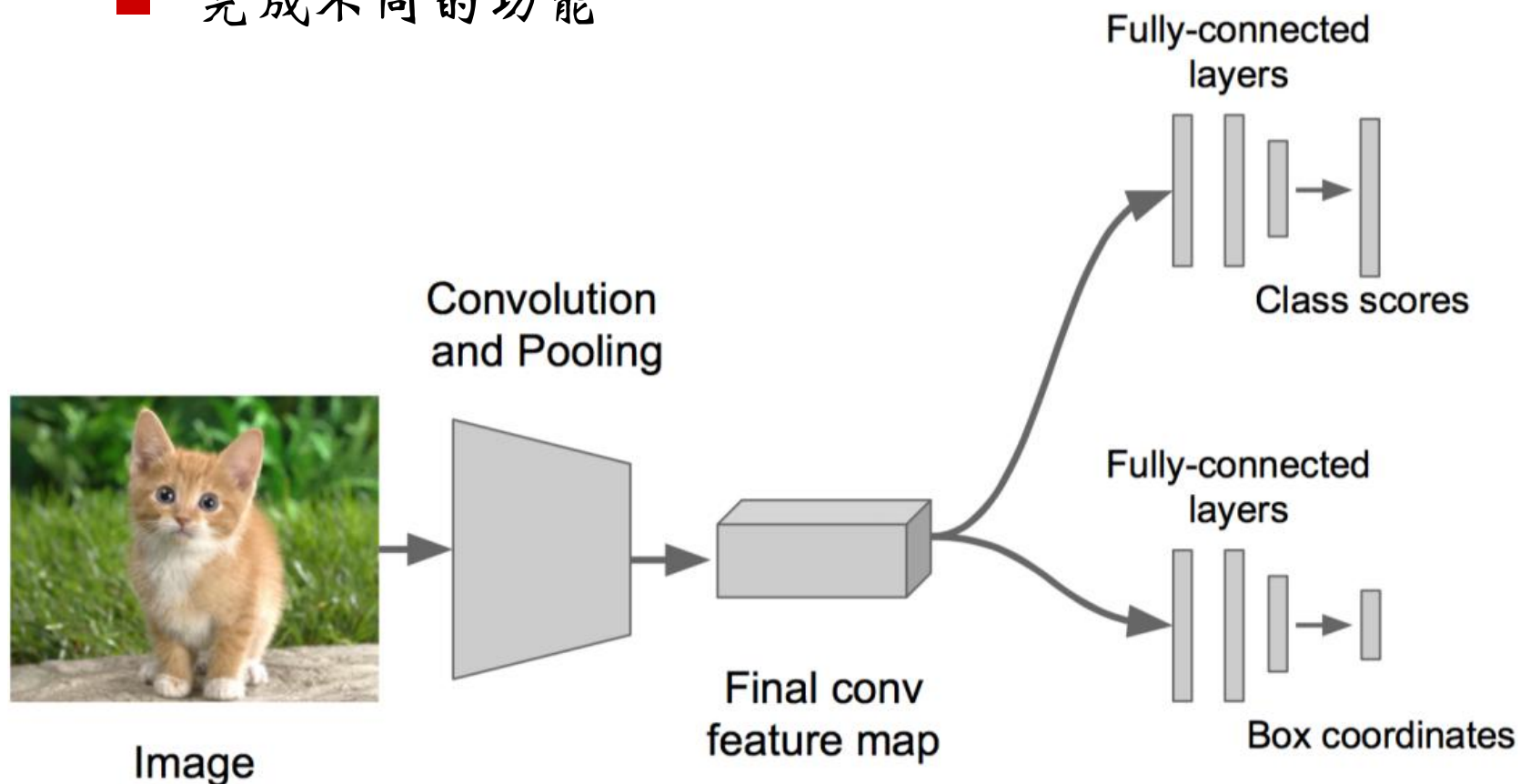
- Regression(回归)部分用欧氏距离损失
- 使用SGD训练



思路1：看作回归问题

□ 步骤4:

- 预测阶段把2个“头部”模块拼上
- 完成不同的功能

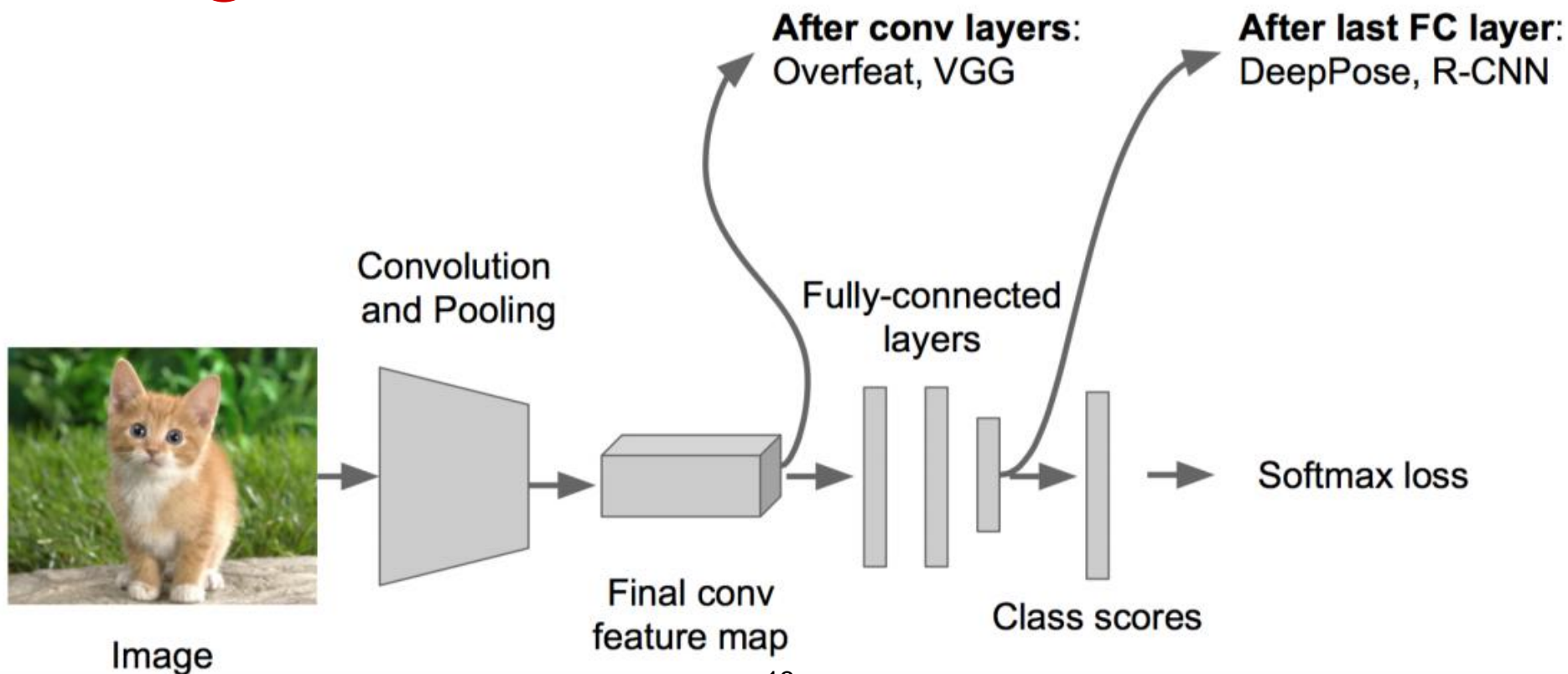


思路1：看作回归问题

□ Regression(回归)的模块部分加在什么位置？

① (最后的)卷积层后

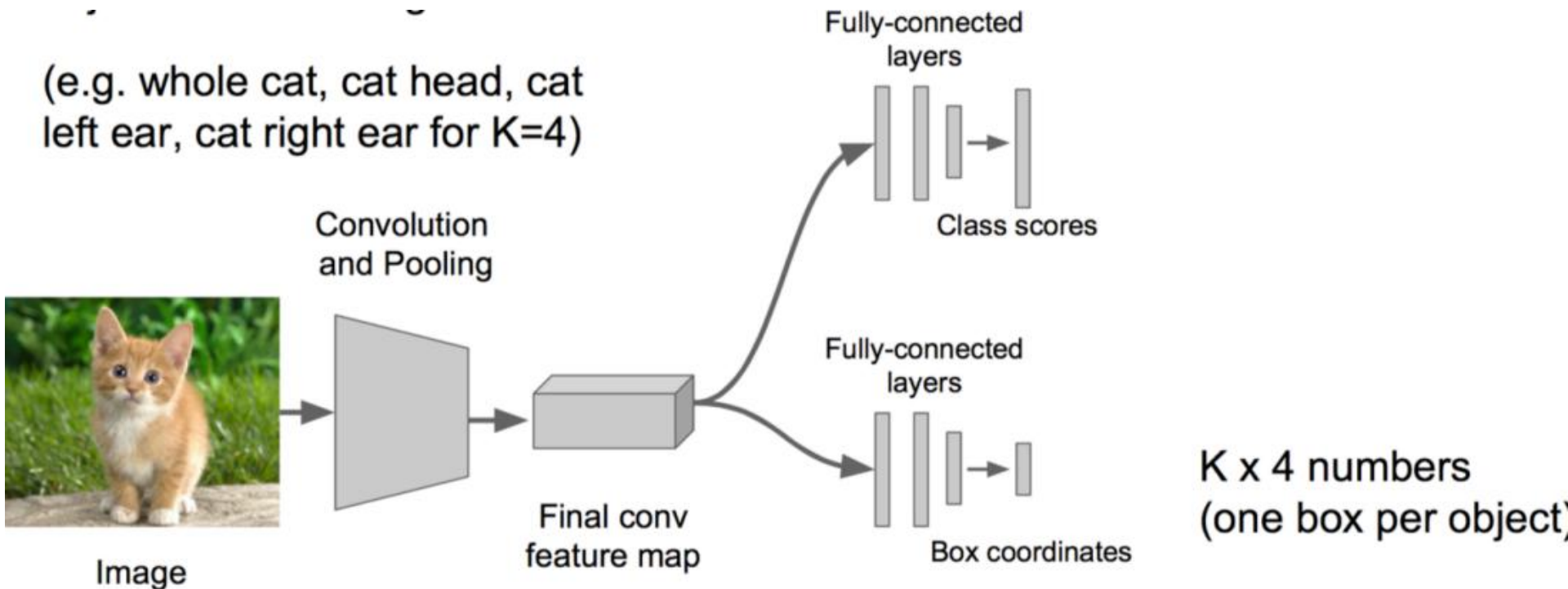
② 全连接层后



思路1：看作回归问题

- 能否对主体有更细致的识别？
 - 提前规定好有K个组成部分
 - 做成K个部分的回归

(e.g. whole cat, cat head, cat left ear, cat right ear for $K=4$)



思路1: 看作回归问题

□ 应用: 如何识别人的姿势?

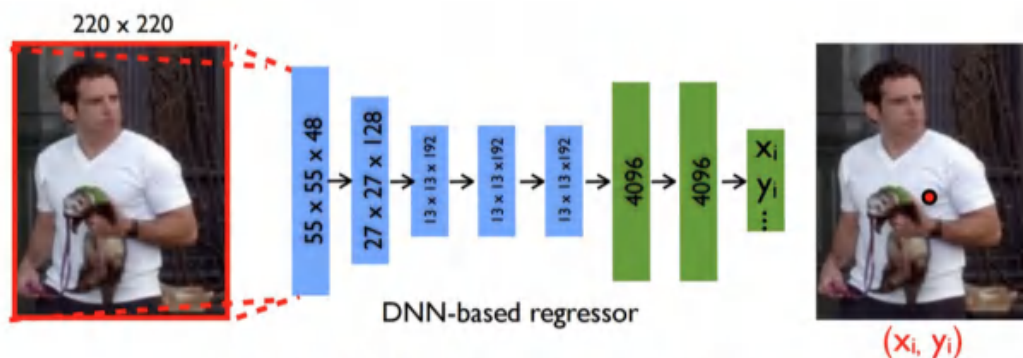
■ 每个人的组成部分是固定的

■ 对K个组成部分(关节)做回归预测 \Rightarrow 首尾相接的
线段

Represent a person by K joints

Regress (x, y) for each joint from
last fully-connected layer of
AlexNet

(Details: Normalized coordinates,
iterative refinement)



julyedu.com

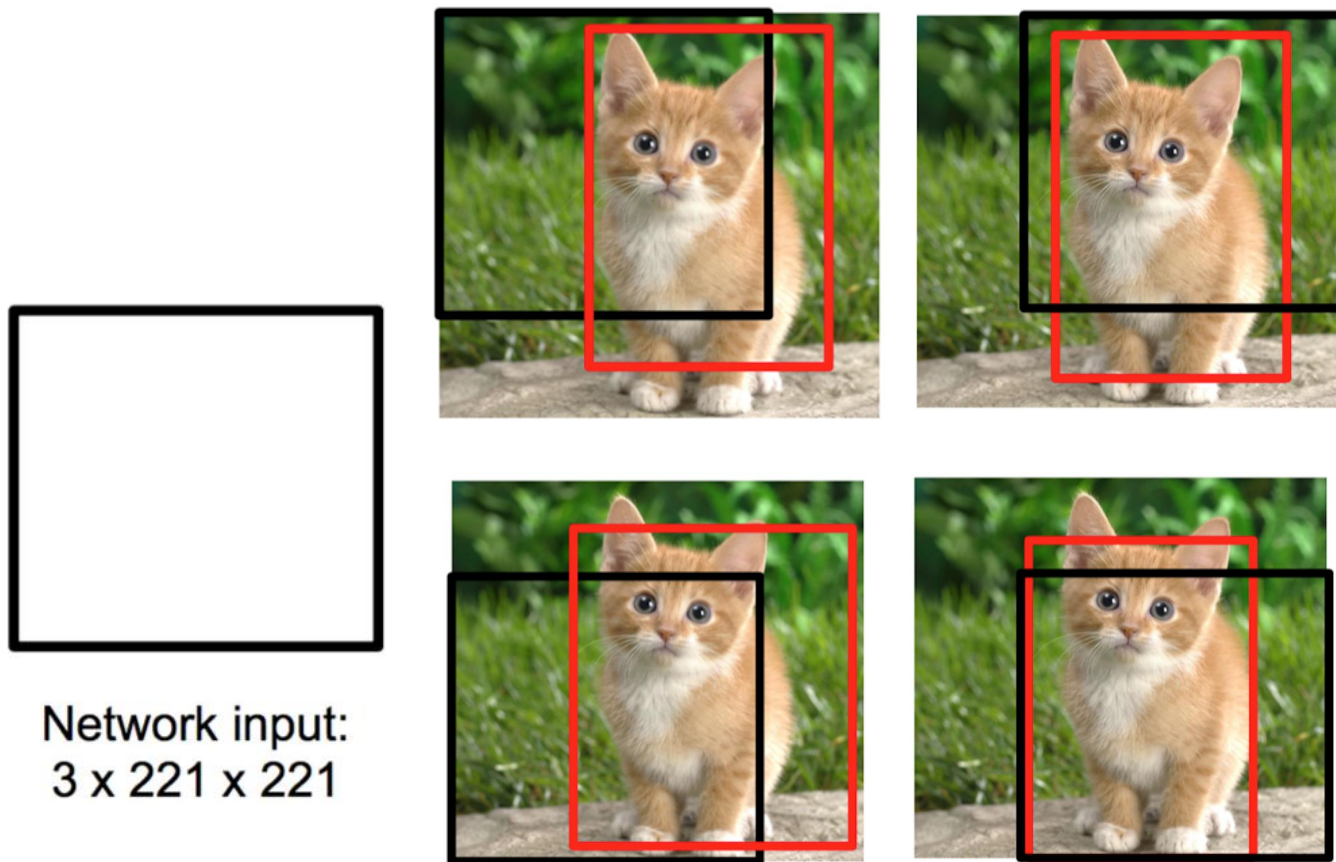


思路2: 图窗+识别与整合

- 类似刚才的classification + regression思路
- 咱们取不同的大小的“框”
- 让框出现在不同的位置
- 判定得分
- 按照得分高低对“结果框”做抽取和合并



思路2: 图窗+识别与整合



Network input:
 $3 \times 221 \times 221$

Larger image:
 $3 \times 257 \times 257$

0.5	0.75
0.6	0.8

Classification scores:
 $P(\text{cat})$



思路2: 图窗+识别与整合

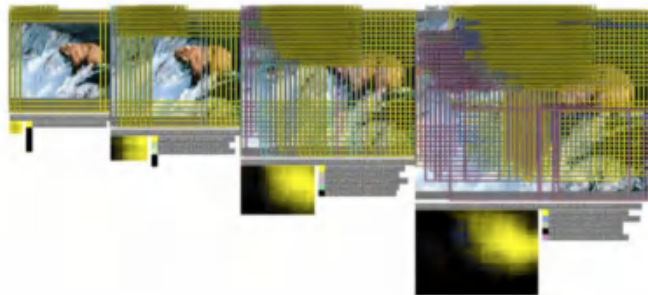
□ 实际应用时

- 尝试各种大小窗口

- 甚至会在窗口上再做一些“回归”的事情

In practice use many sliding window locations and multiple scales

Window positions + score maps



Box regression outputs

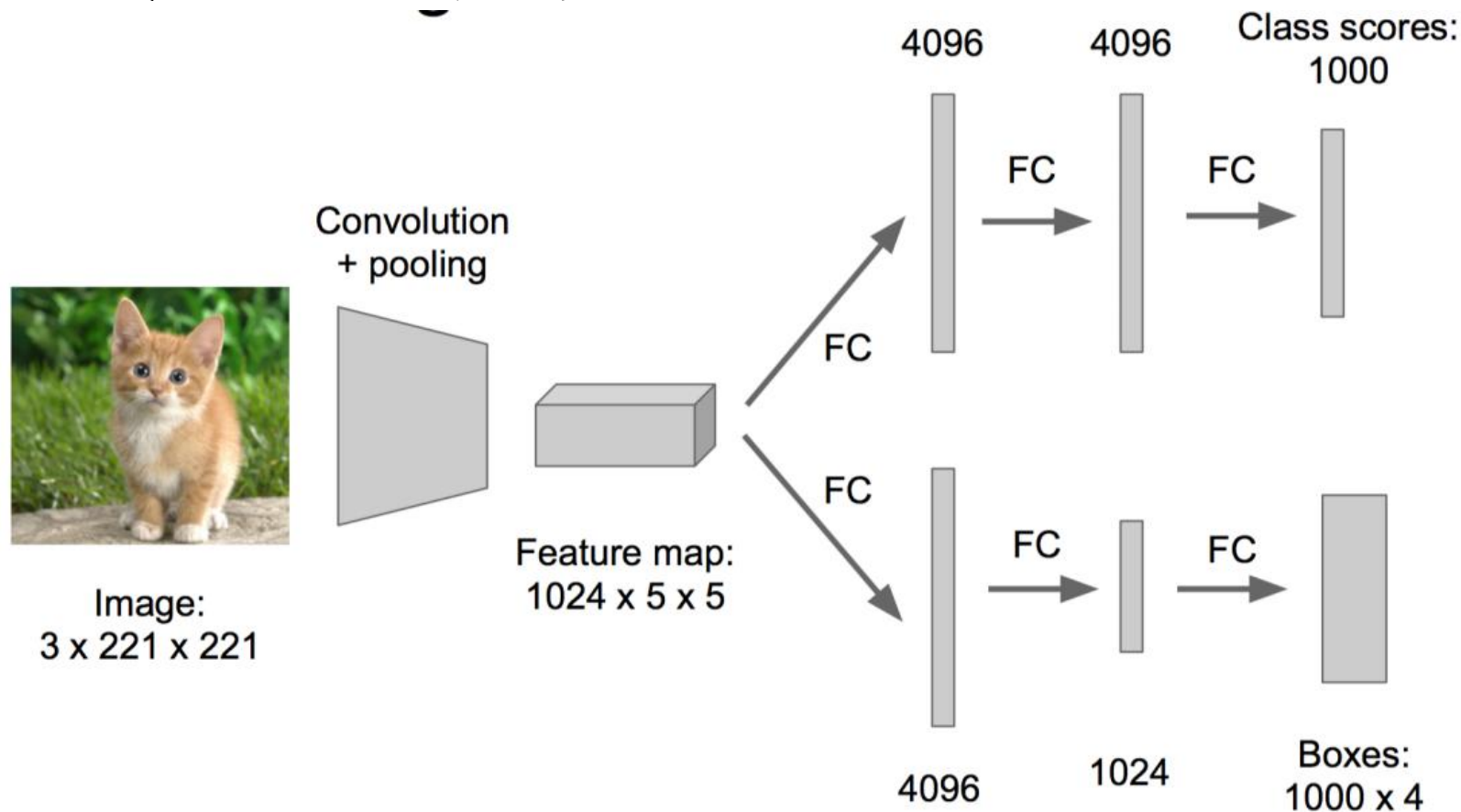


Final Predictions



思路2: 图窗+识别与整合

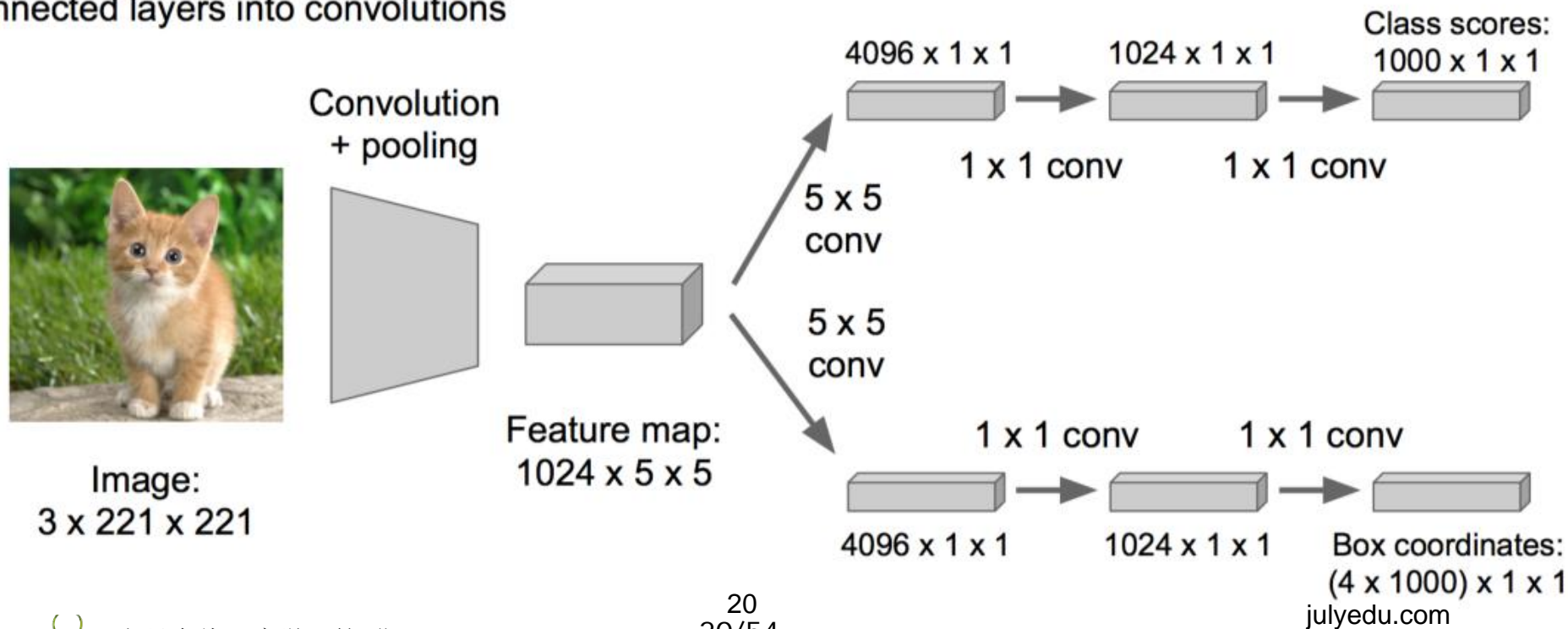
- 想办法克服一下过程中的“参数多”与“计算慢”
- 最初的形式如下



思路2: 图窗+识别与整合

- 想办法克服一下过程中的“参数多”与“计算慢”
 - 用多卷积核的卷积层 替换 全连接层
 - 降低参数量

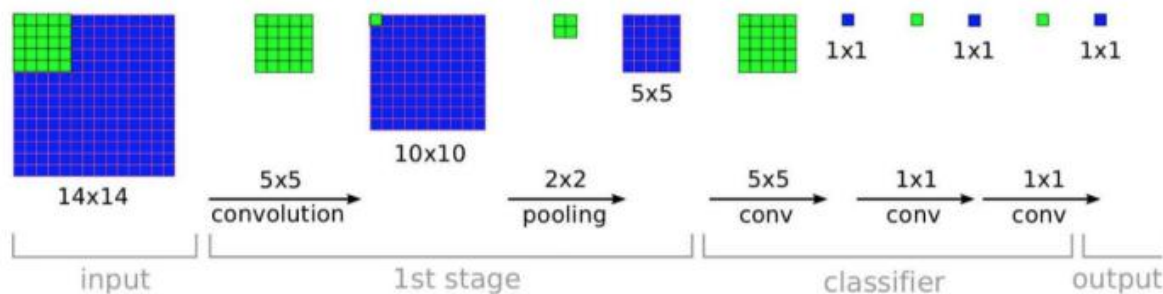
Efficient sliding window by converting fully-connected layers into convolutions



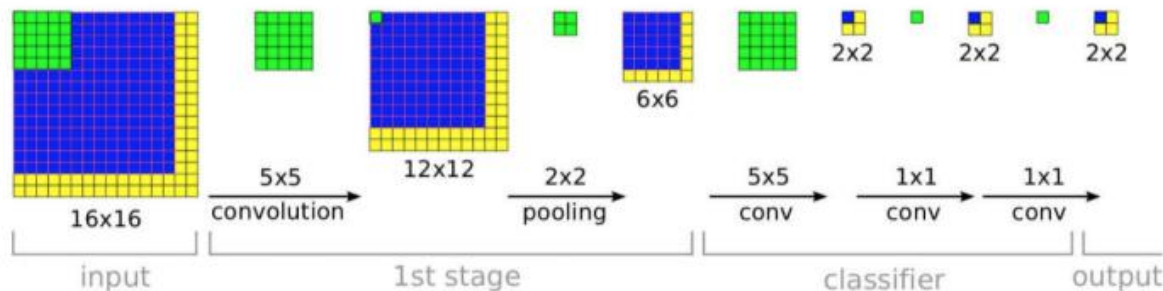
图像识别+定位

- 想办法克服一下过程中的“参数多”与“计算慢”
- 测试/识别阶段的计算是可复用的(小卷积)
- 加速计算

Training time: Small image, 1 x 1 classifier output



Test time: Larger image, 2 x 2 classifier output, only extra compute at yellow regions



Sermanet et al, "Integrated Recognition, Localization and Detection using Convolutional Networks", ICLR 2014



物体识别

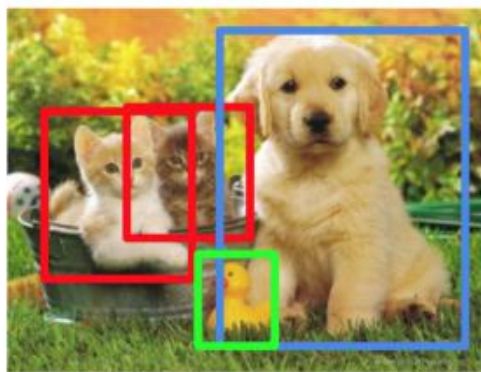
Classification



Classification
+ Localization



Object Detection



Instance
Segmentation



物体识别

□ 再次看做回归问题？



DOG, (x, y, w, h)
CAT, (x, y, w, h)
CAT, (x, y, w, h)
DUCK (x, y, w, h)

= 16 numbers



物体识别

□ 其实你不知道图上有多少个物体...



CAT, (x, y, w, h)
CAT, (x, y, w, h)
....
CAT (x, y, w, h)



物体识别

□ 试试看做分类问题？



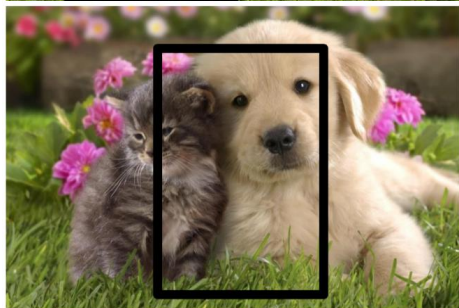
CAT? NO

DOG? NO



CAT? YES!

DOG? NO



CAT? NO

DOG? NO



物体识别

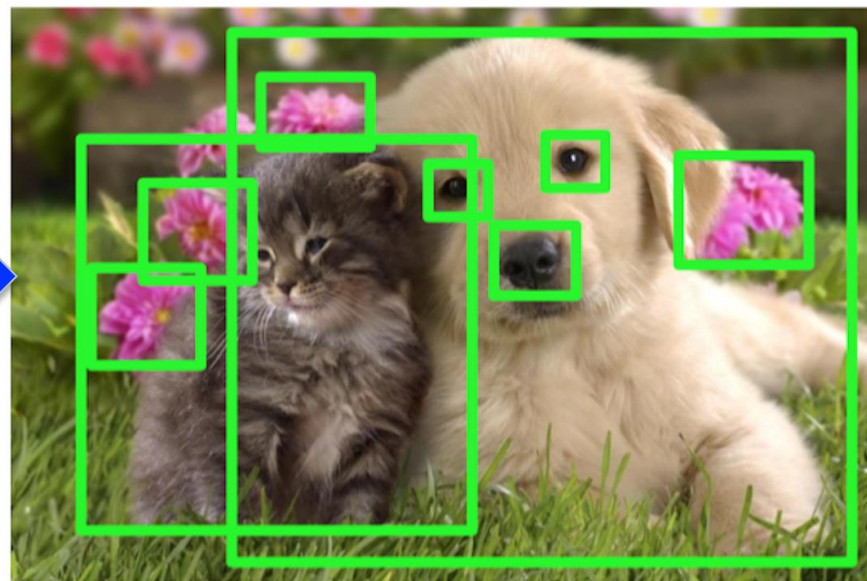
□ 看做分类问题，难点是？

- 你需要找“很多位置”，给“很多不同大小的框”
 - 你还需要对框内的图像分类(累计很多次)
 - 框的大小不一定对
 - ...
-
- 当然，如果你的GPU很强大，恩，那加油做吧...



物体识别：边缘策略

- 看做分类问题，有没有办法优化下？
 - 为什么要先给定“框”，能不能找到“候选框”？
 - 想办法先找到“可能包含内容的图框”

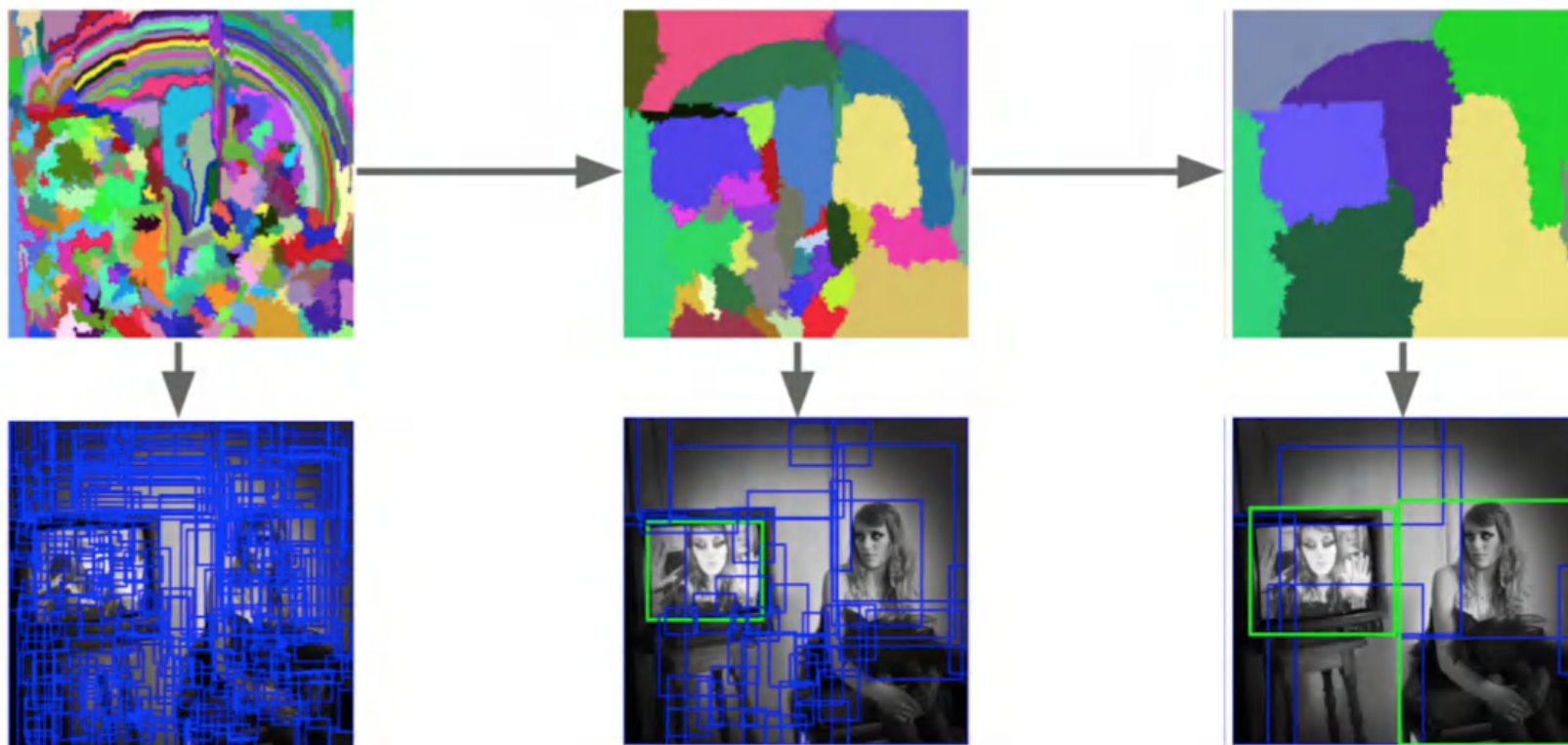


物体识别：选择性搜索

□ 关于“候选图框”识别，有什么办法？

■ 自下而上融合成“区域”

■ 将“区域”扩充为“图框”



Uijlings et al, "Selective Search for Object Recognition", IJCV 2013



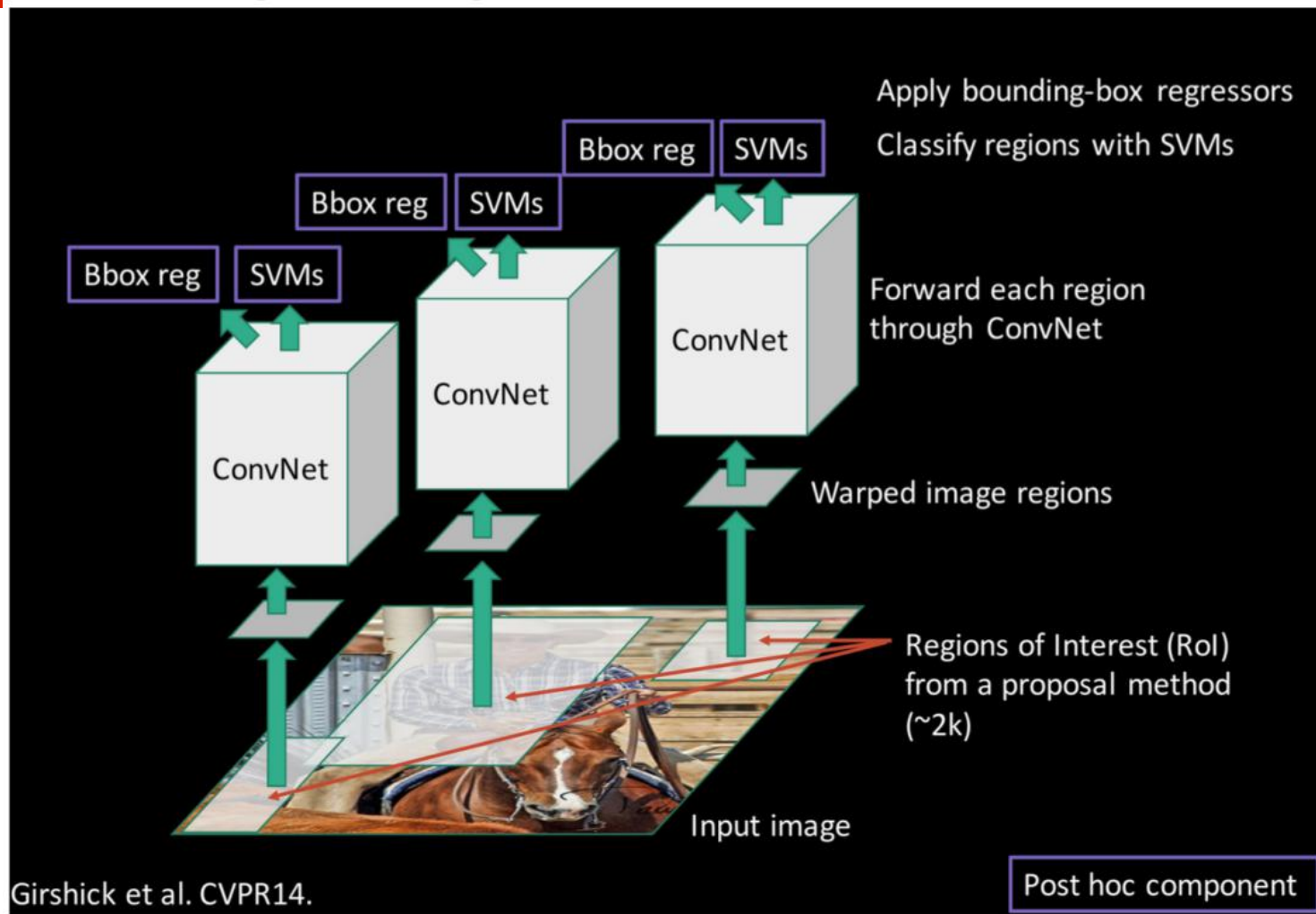
“图框” 候选： 其他方式？

Method	Approach	Outputs Segments	Outputs Score	Control #proposals	Time (sec.)	Repea- tability	Recall Results	Detection Results
Bing [18]	Window scoring		✓	✓	0.2	***	*	.
CPMC [19]	Grouping	✓	✓	✓	250	-	**	*
EdgeBoxes [20]	Window scoring		✓	✓	0.3	**	***	***
Endres [21]	Grouping	✓	✓	✓	100	-	***	**
Geodesic [22]	Grouping	✓		✓	1	*	***	**
MCG [23]	Grouping	✓	✓	✓	30	*	***	***
Objectness [24]	Window scoring		✓	✓	3	.	*	.
Rahtu [25]	Window scoring		✓	✓	3	.	.	*
RandomizedPrim's [26]	Grouping	✓		✓	1	*	*	**
Rantalankila [27]	Grouping	✓		✓	10	**	.	**
Rigor [28]	Grouping	✓		✓	10	*	**	**
SelectiveSearch [29]	Grouping	✓	✓	✓	10	**	***	***
Gaussian				✓	0	.	.	*
SlidingWindow				✓	0	***	.	.
Superpixels		✓			1	*	.	.
Uniform				✓	0	.	.	.

Hosang et al, “What makes for effective detection proposals?”, PAMI 2015



R-CNN

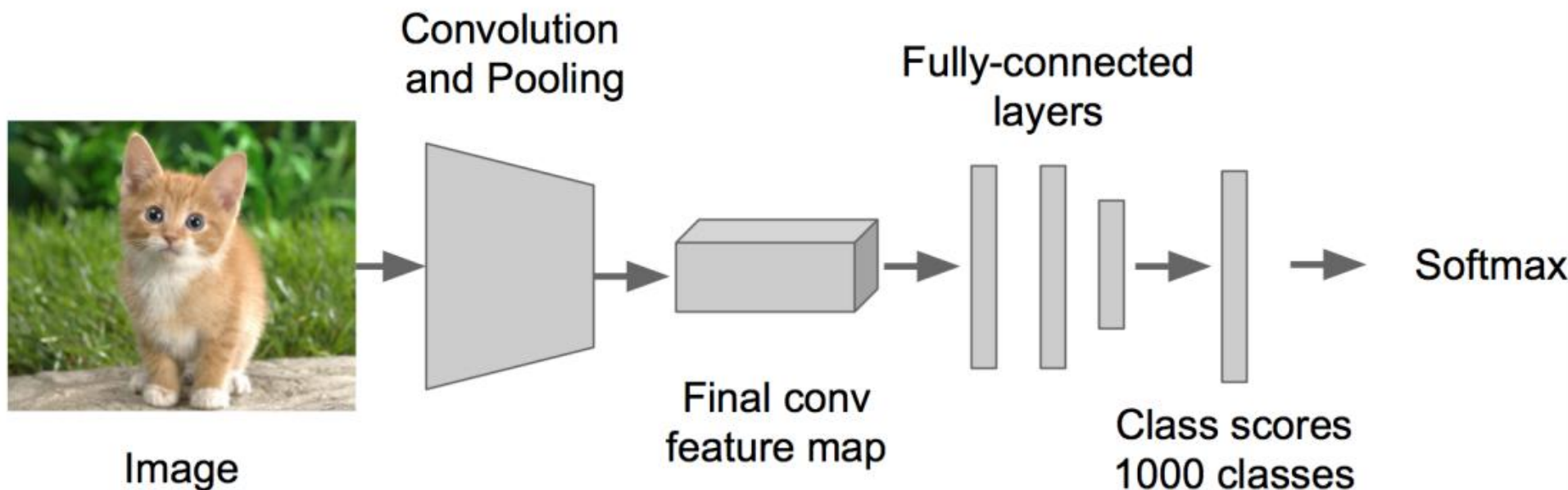


Girshick et al, "Rich feature hierarchies for accurate object detection and semantic segmentation", CVPR 2014



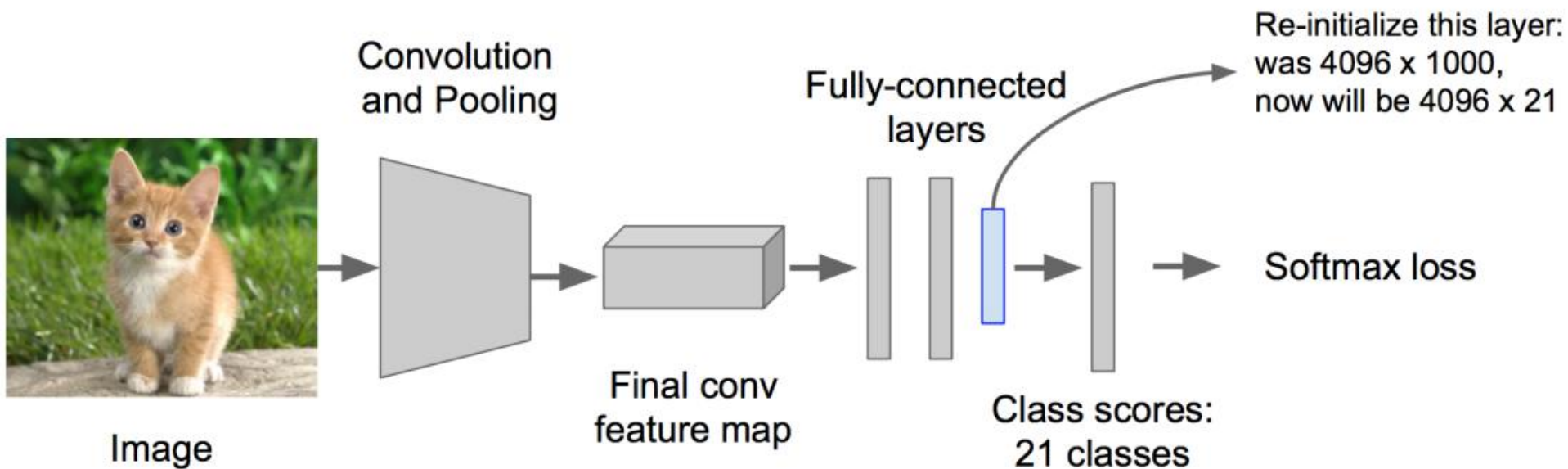
R-CNN

- 步骤1: 找一个预训练好的模型(Alexnet, VGG)
针对你的场景做fine-tune



R-CNN

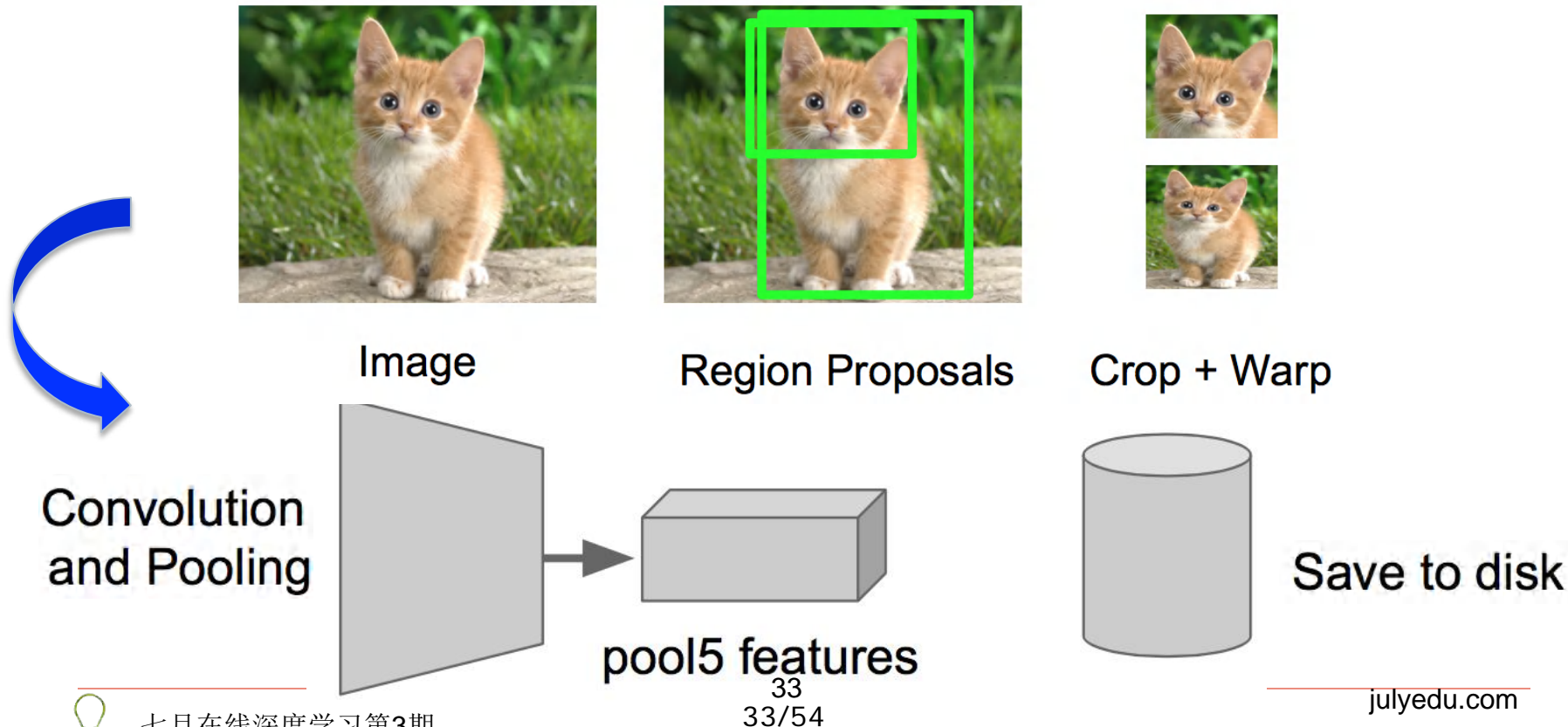
- 步骤2: fine-tuning模型
 - 比如20个物体类别+1个背景



R-CNN

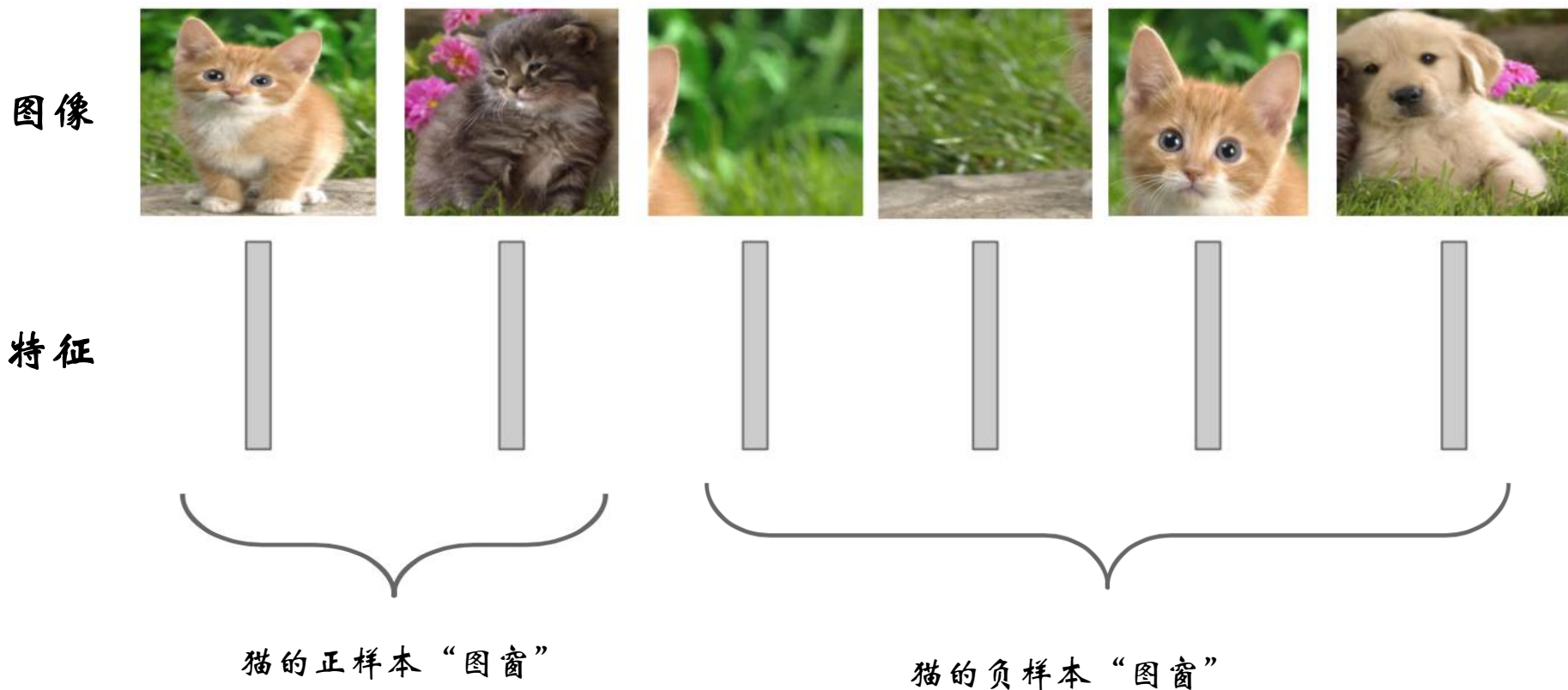
□ 步骤3：抽取图片特征

- 用“图框候选算法”抠出图窗
- Resize后用CNN做前向运算，取第5个池化层做特征
- 存储抽取的特征到硬盘/数据库上



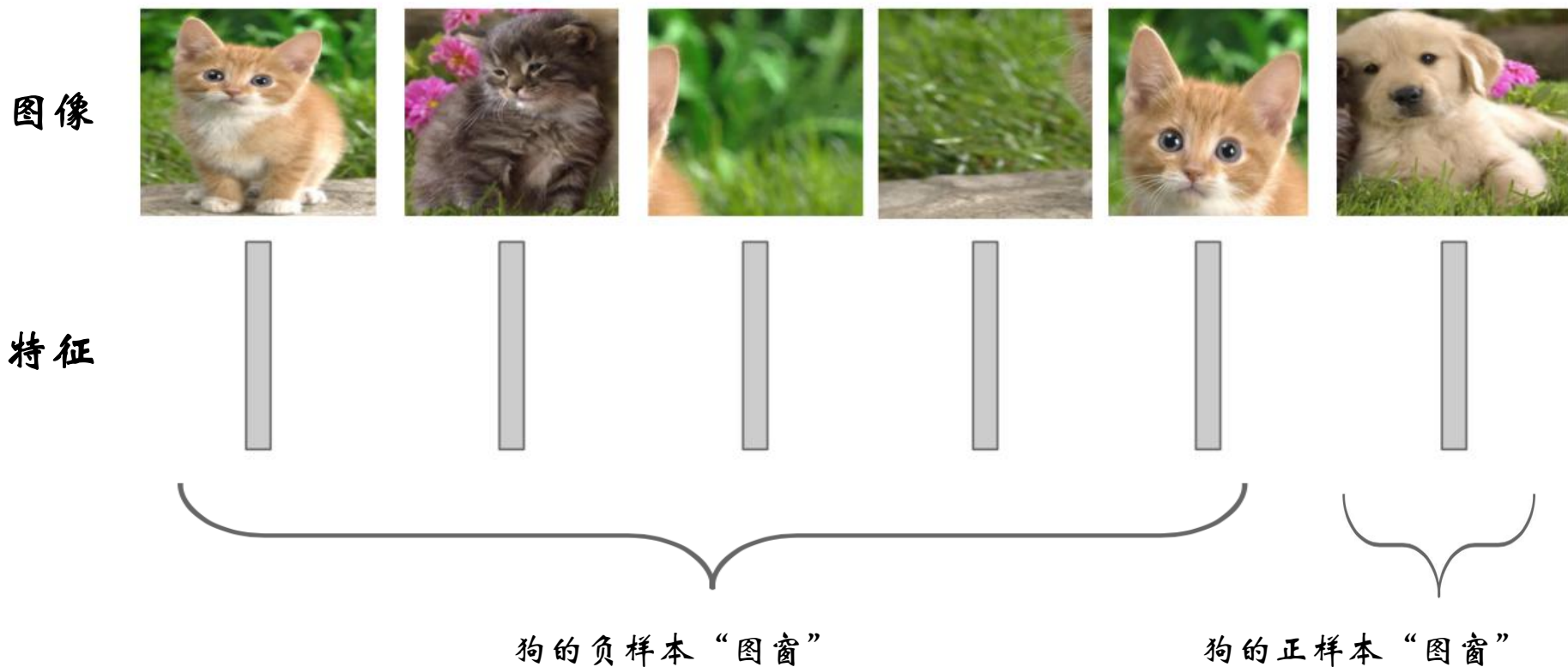
R-CNN

□ 步骤4：训练SVM识别是某个物体或者不是(2分类)



R-CNN

□ 步骤4：训练SVM识别是某个物体或者不是(2分类)



R-CNN

□ 步骤5: bbox regression

■ 微调图窗区域

图像



特征



回归得到
dx, dy, dw, dh
位置调整

$(0, 0, 0, 0)$
Proposal is good

$(.25, 0, 0, 0)$
Proposal too
far to left

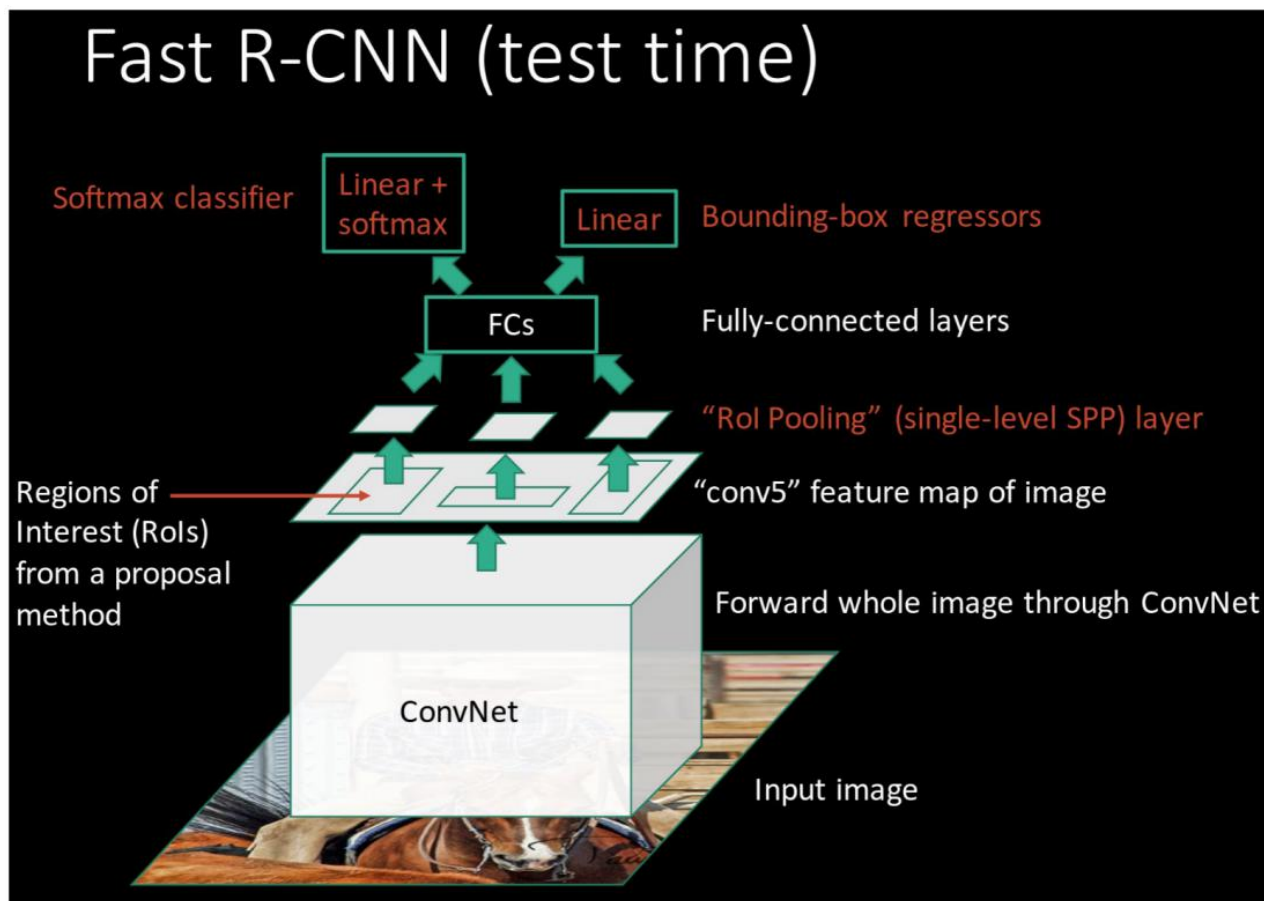
$(0, 0, -0.125, 0)$
Proposal too
wide



R-CNN => Fast-rcnn

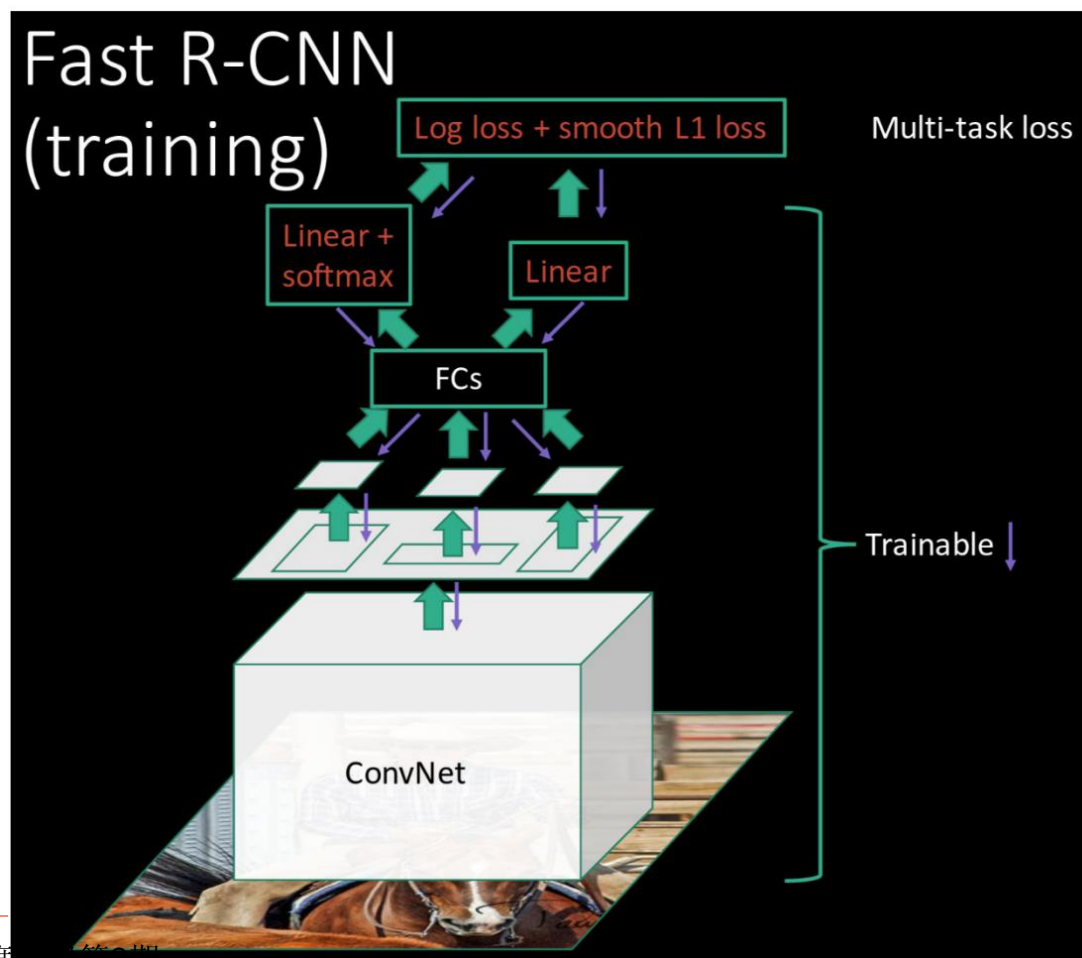
□ 针对R-CNN的改进1

■ 共享图窗计算，从而加速



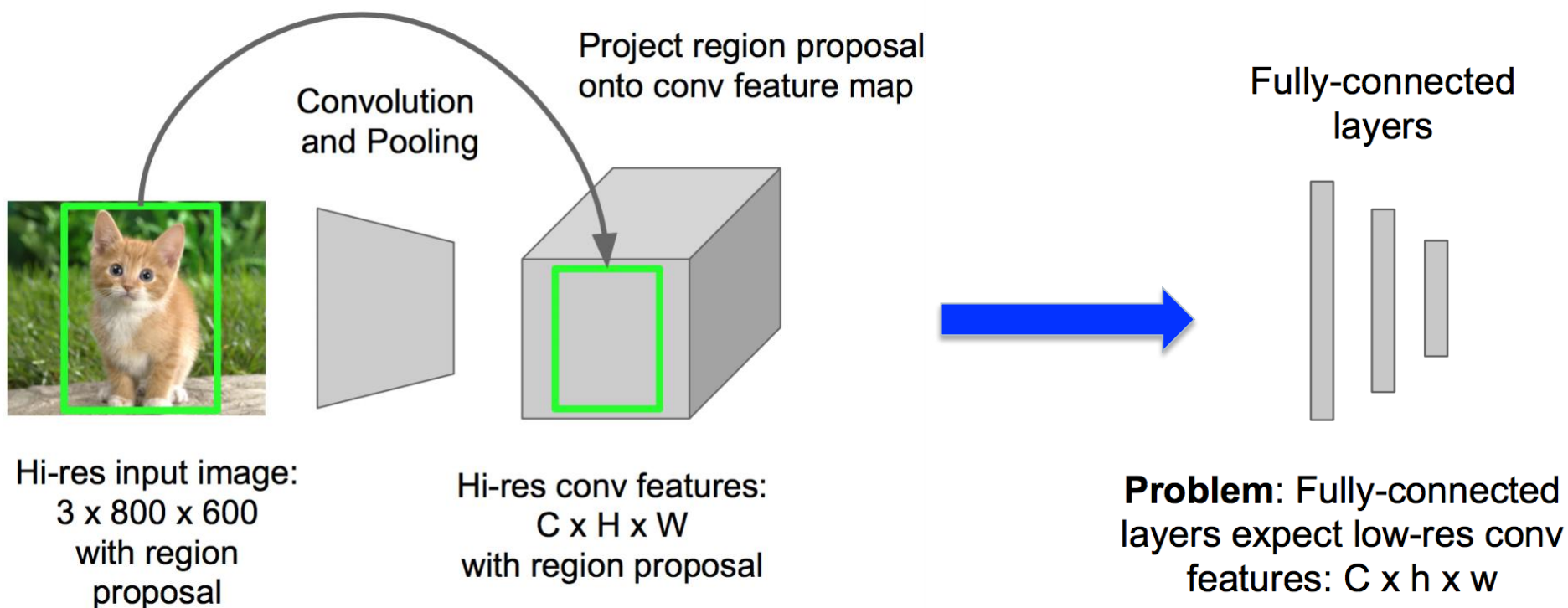
R-CNN => Fast-rcnn

- 针对R-CNN的改进2
 - 直接做成端到端的系统



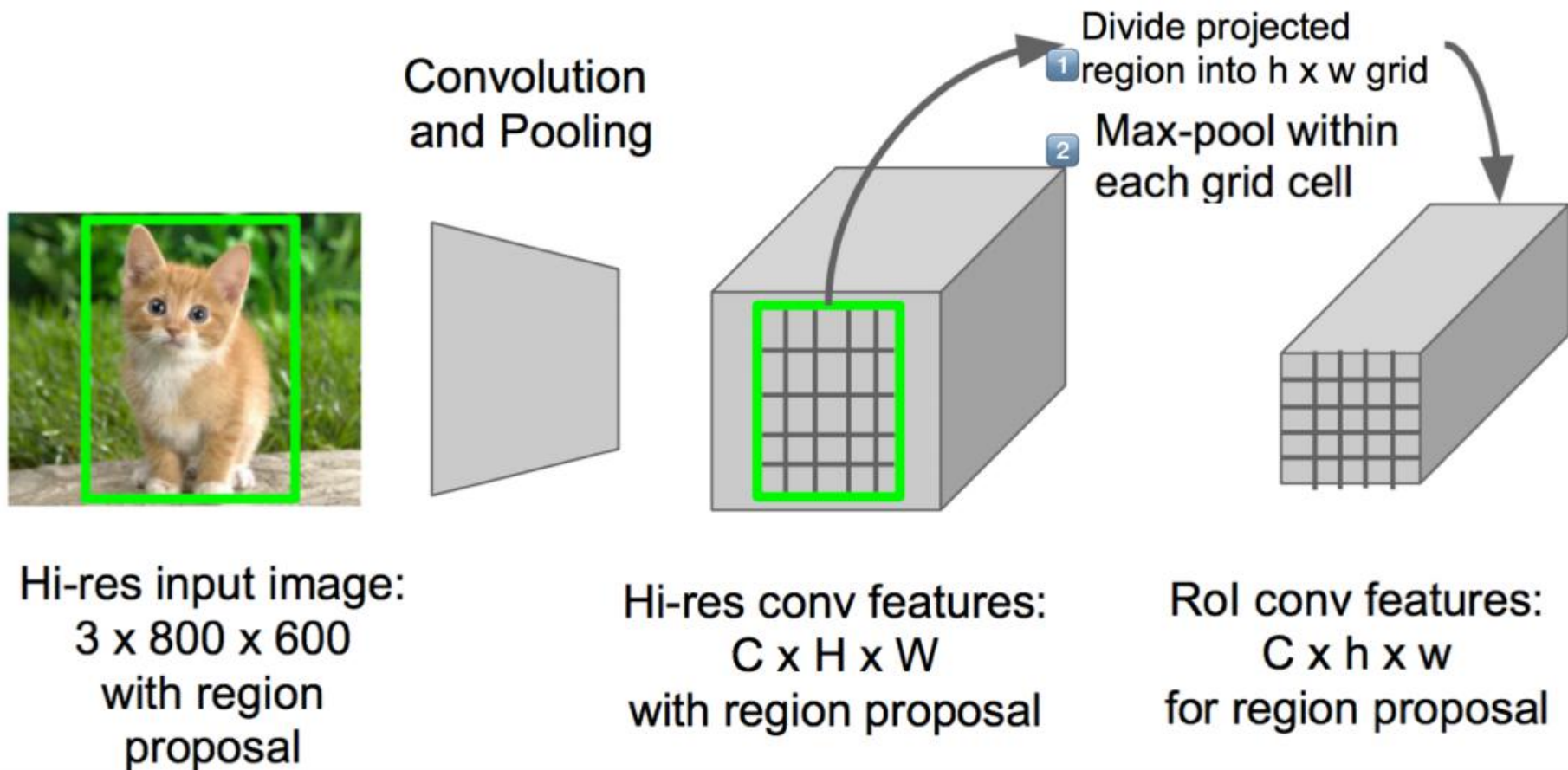
R-CNN => Fast-rcnn

□ 关于RIP: Region of Interest Pooling



R-CNN => Fast-rcnn

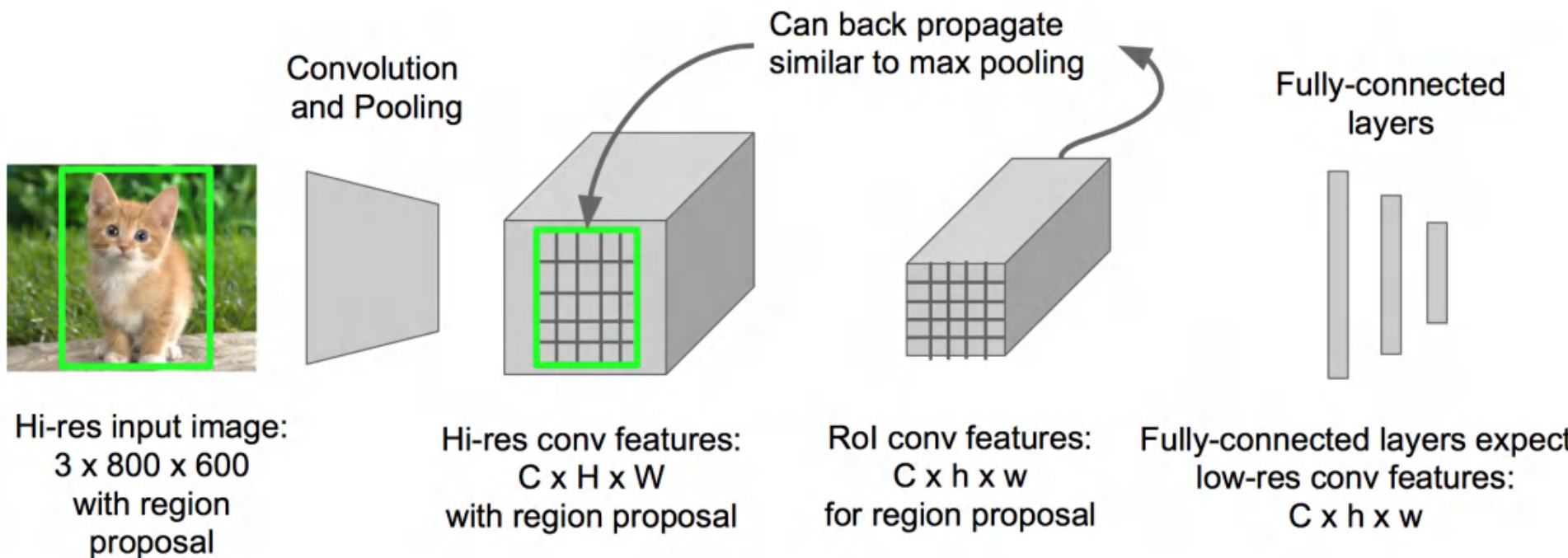
□ 维度不匹配怎么办：划分格子grid => 下采样



R-CNN => Fast-rcnn

□ RIP: Region of Interest Pooling

■ 映射关系显然是可以还原回去的



速度对比

	R-CNN	Fast R-CNN
Training Time:	84 hours	9.5 hours
(Speedup)	1x	8.8x
Test time per image	47 seconds	0.32 seconds
(Speedup)	1x	146x

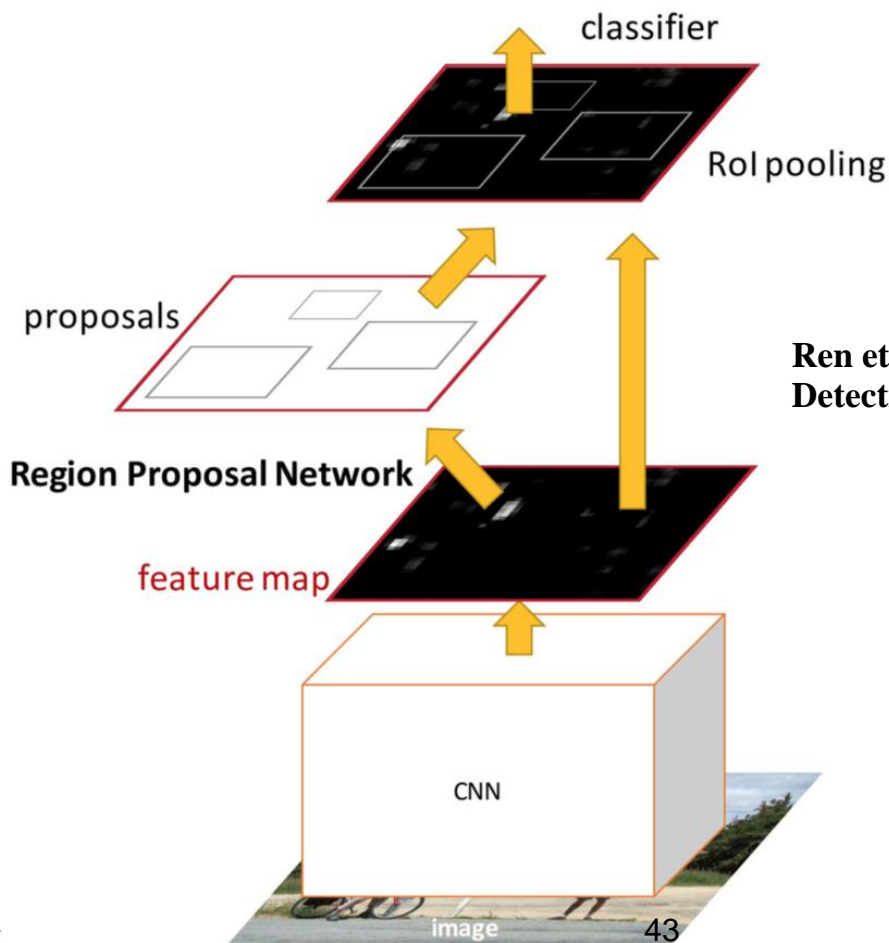
Faster!

FASTER!



Fast => Faster-rcnn

- Region Proposal(候选图窗)一定要另外独立做吗?
 - 一起用RPN做完得了!

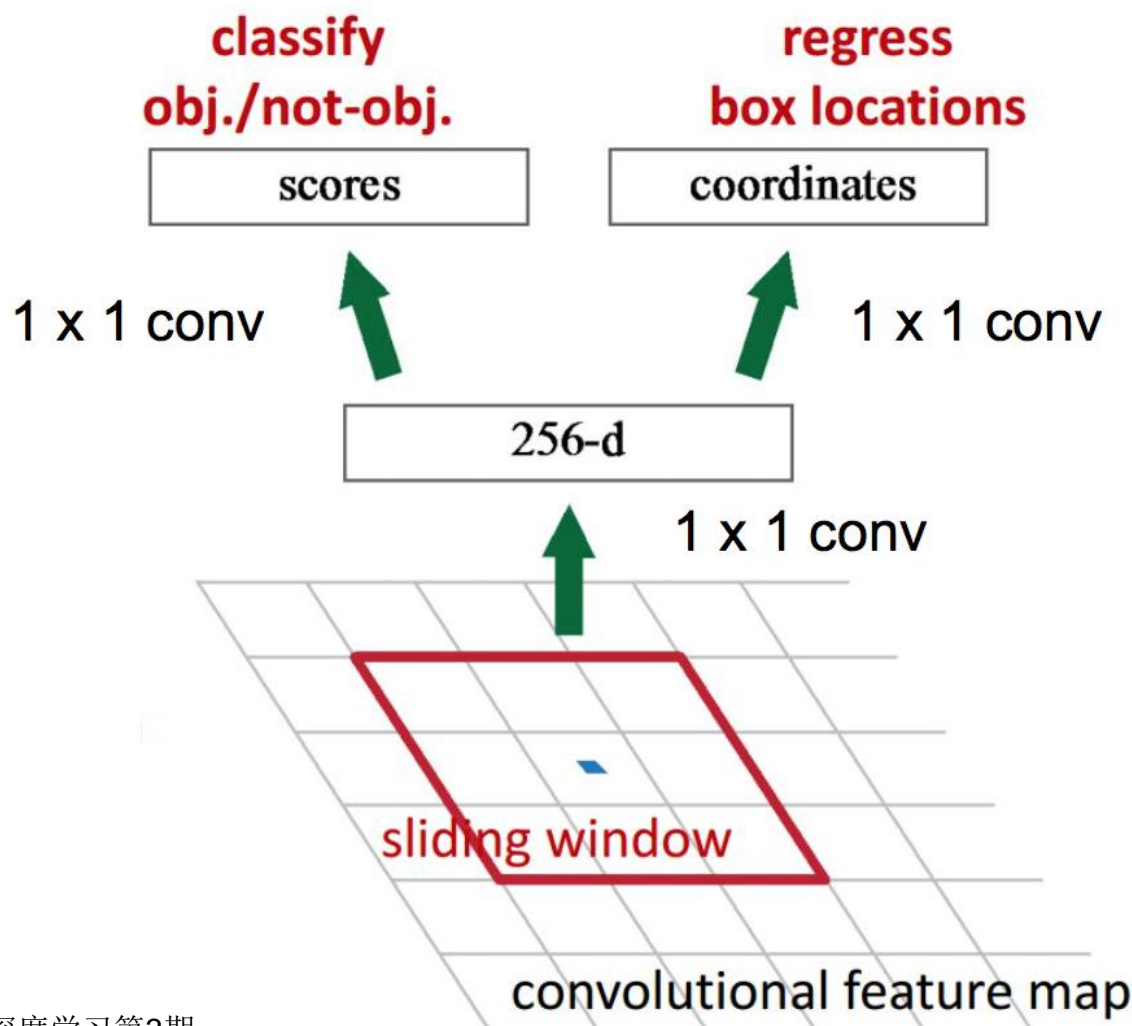


Ren et al, "Faster R-CNN: Towards Real-Time Object Detection with Region Proposal Networks", NIPS 2015



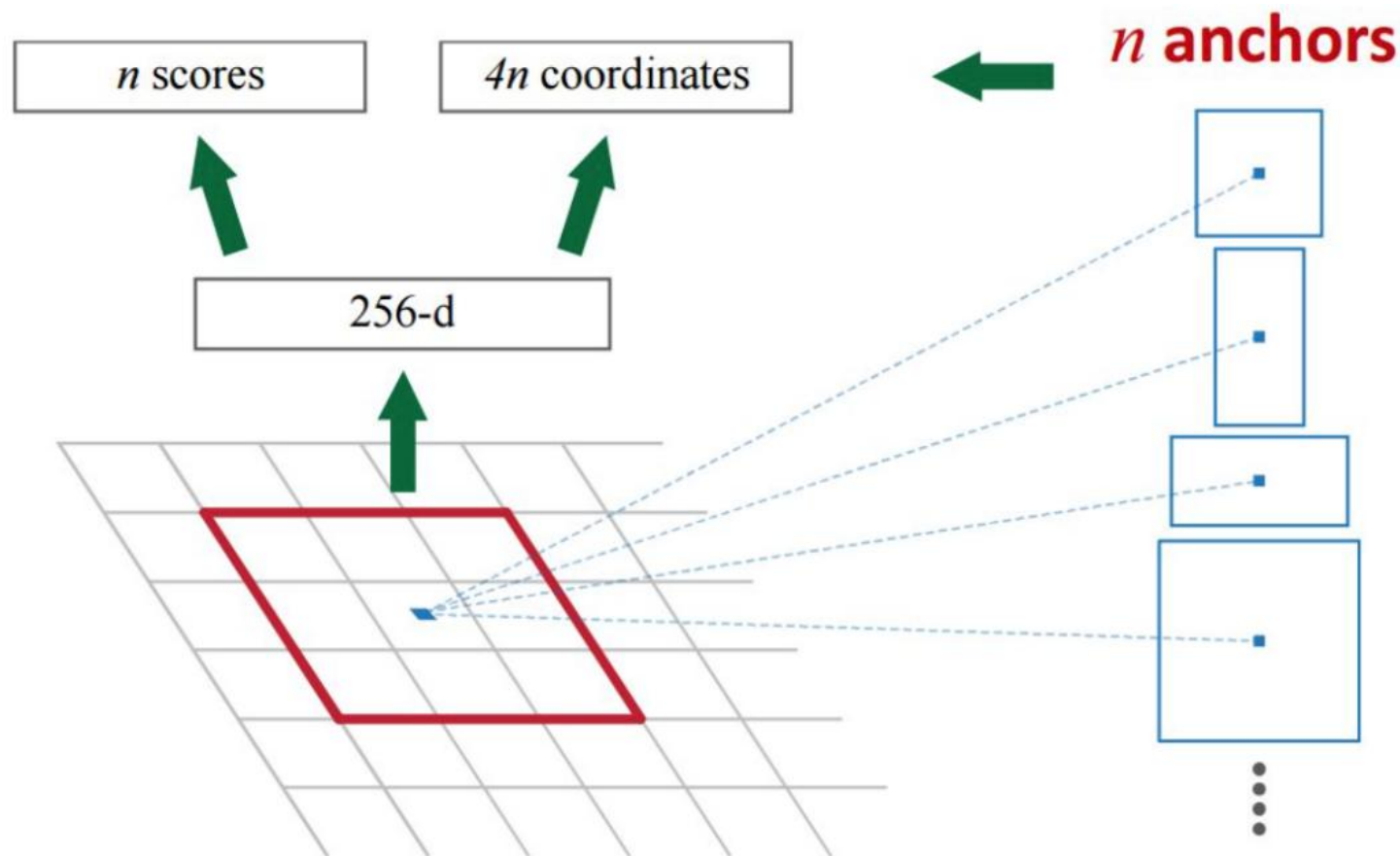
Fast => Faster-rcnn

□ 关于RPN: Region Proposal Network



Fast => Faster-rcnn

□ 关于RPN: Region Proposal Network



Faster-rcnn

□ 关于Faster R-CNN的整个训练过程

Faster R-CNN: Training

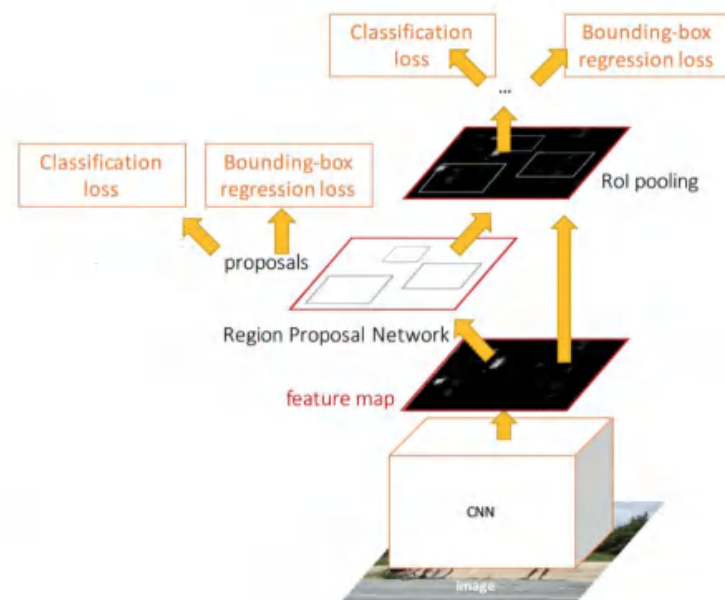
In the paper: Ugly pipeline

- Use alternating optimization to train RPN, then Fast R-CNN with RPN proposals, etc.
- More complex than it has to be

Since publication: Joint training!

One network, four losses

- RPN classification (anchor good / bad)
- RPN regression (anchor \rightarrow proposal)
- Fast R-CNN classification (over classes)
- Fast R-CNN regression (proposal \rightarrow box)



速度/准度对比

	R-CNN	Fast R-CNN	Faster R-CNN
Test time per image (with proposals)	50 seconds	2 seconds	0.2 seconds
(Speedup)	1x	25x	250x
mAP (VOC 2007)	66.0	66.9	66.9



部分代码与训练数据

R-CNN

(Caffe + MATLAB): <https://github.com/rbgirshick/rcnn> (非常慢, 参考)

Fast R-CNN

(Caffe + MATLAB): <https://github.com/rbgirshick/fast-rcnn> (非端到端)

Faster R-CNN

(Caffe + MATLAB): https://github.com/ShaoqingRen/faster_rcnn

(Caffe + Python): <https://github.com/rbgirshick/py-faster-rcnn>

SSD

(Caffe + Python) <https://github.com/weiliu89/caffe/tree/ssd>

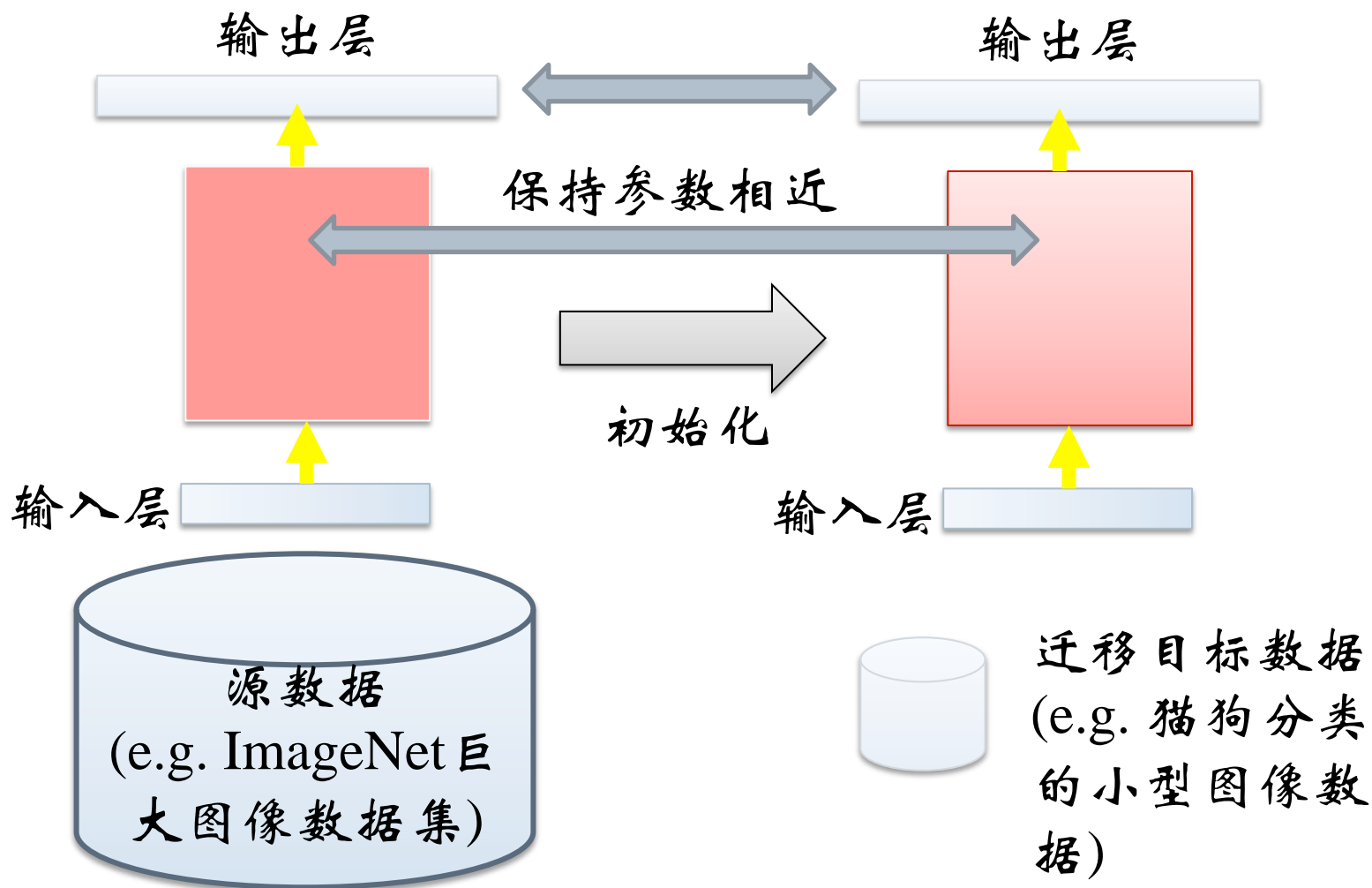
R-FCN

(Caffe + Matlab) <https://github.com/daijifeng001/R-FCN>

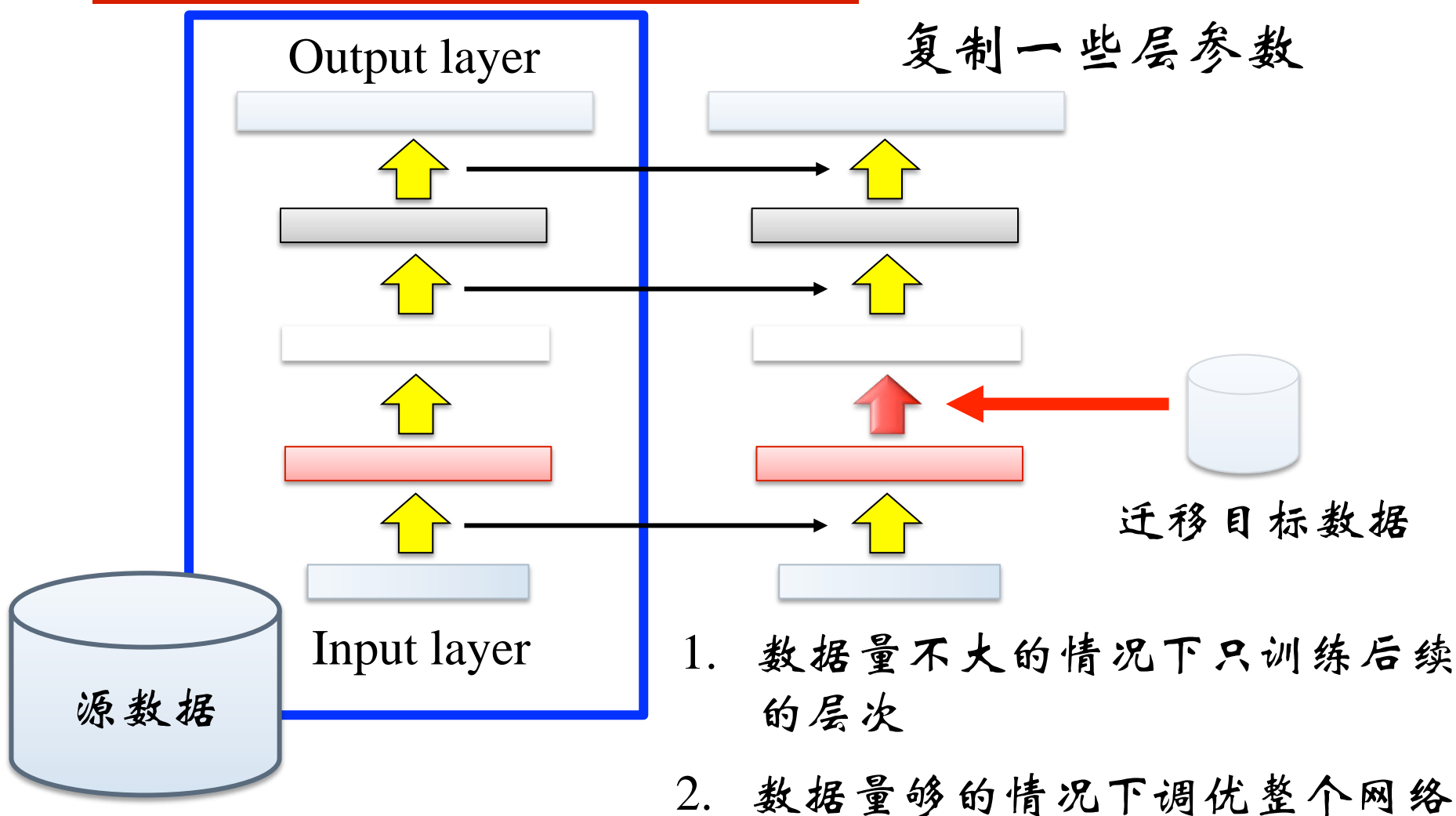
(Caffe + Python) <https://github.com/Orpine/py-R-FCN>



有监督到有监督: fine-tune

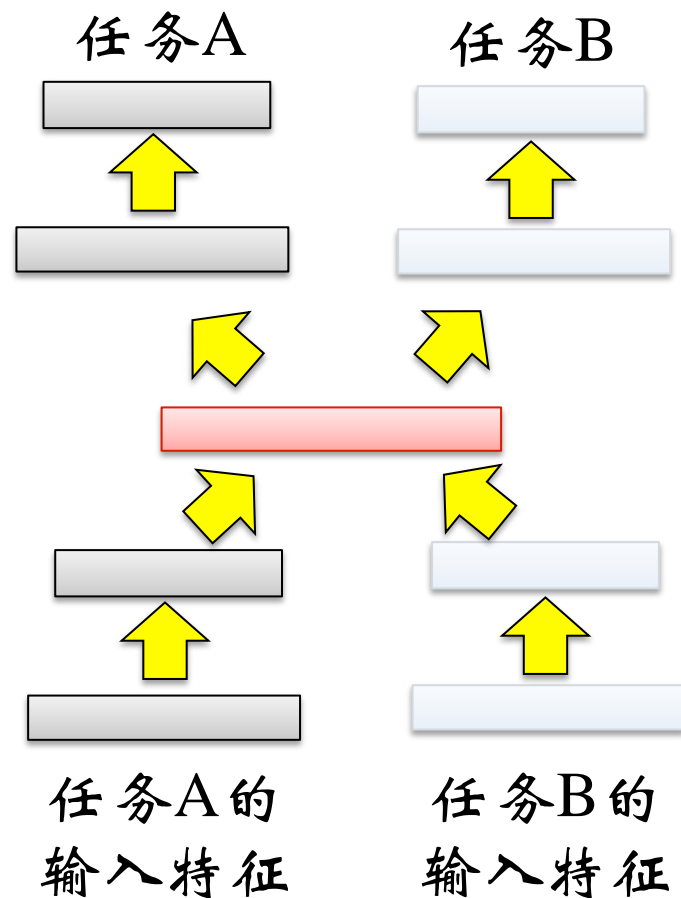
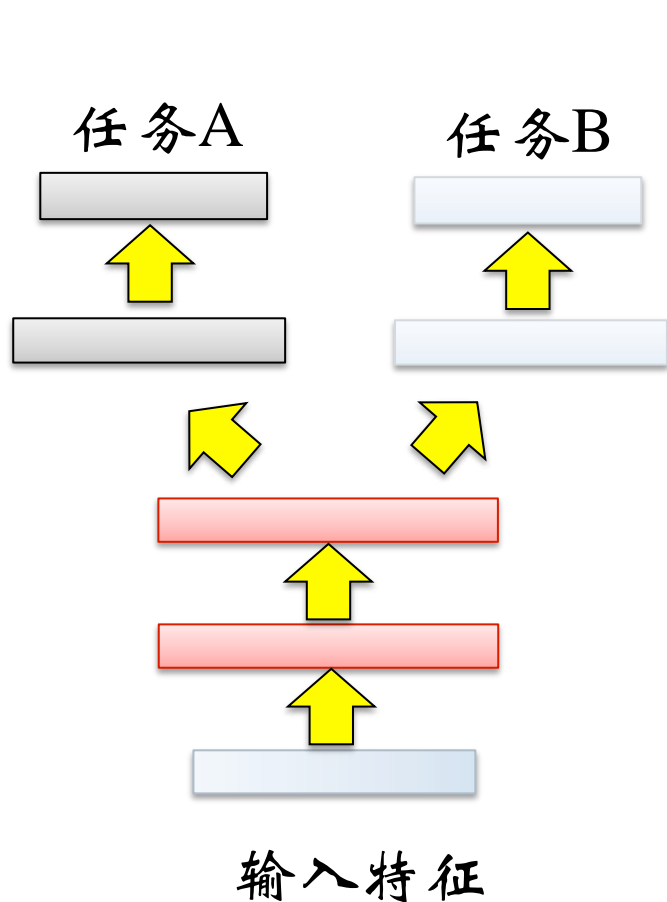


Layer Transfer

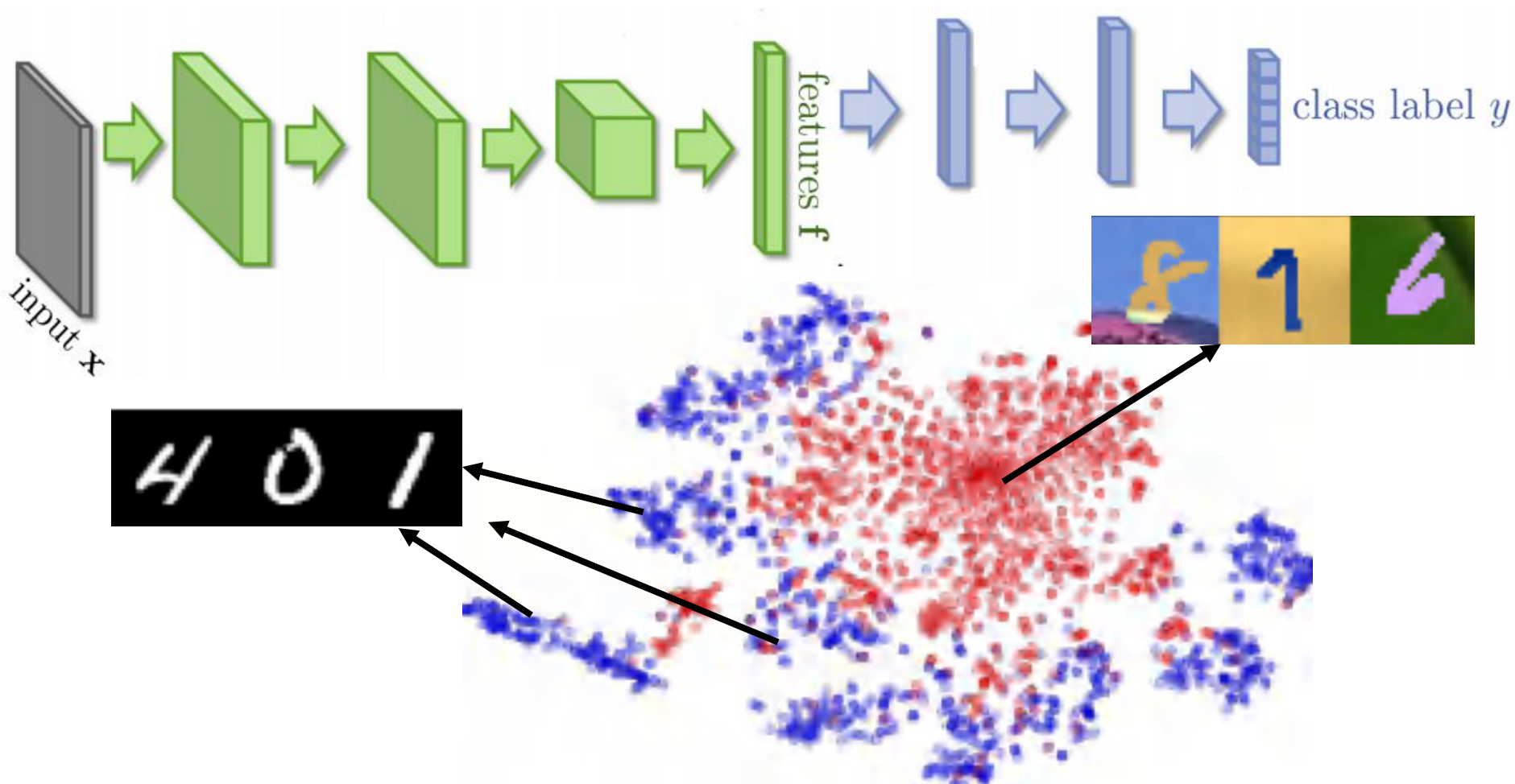


Multitask Learning

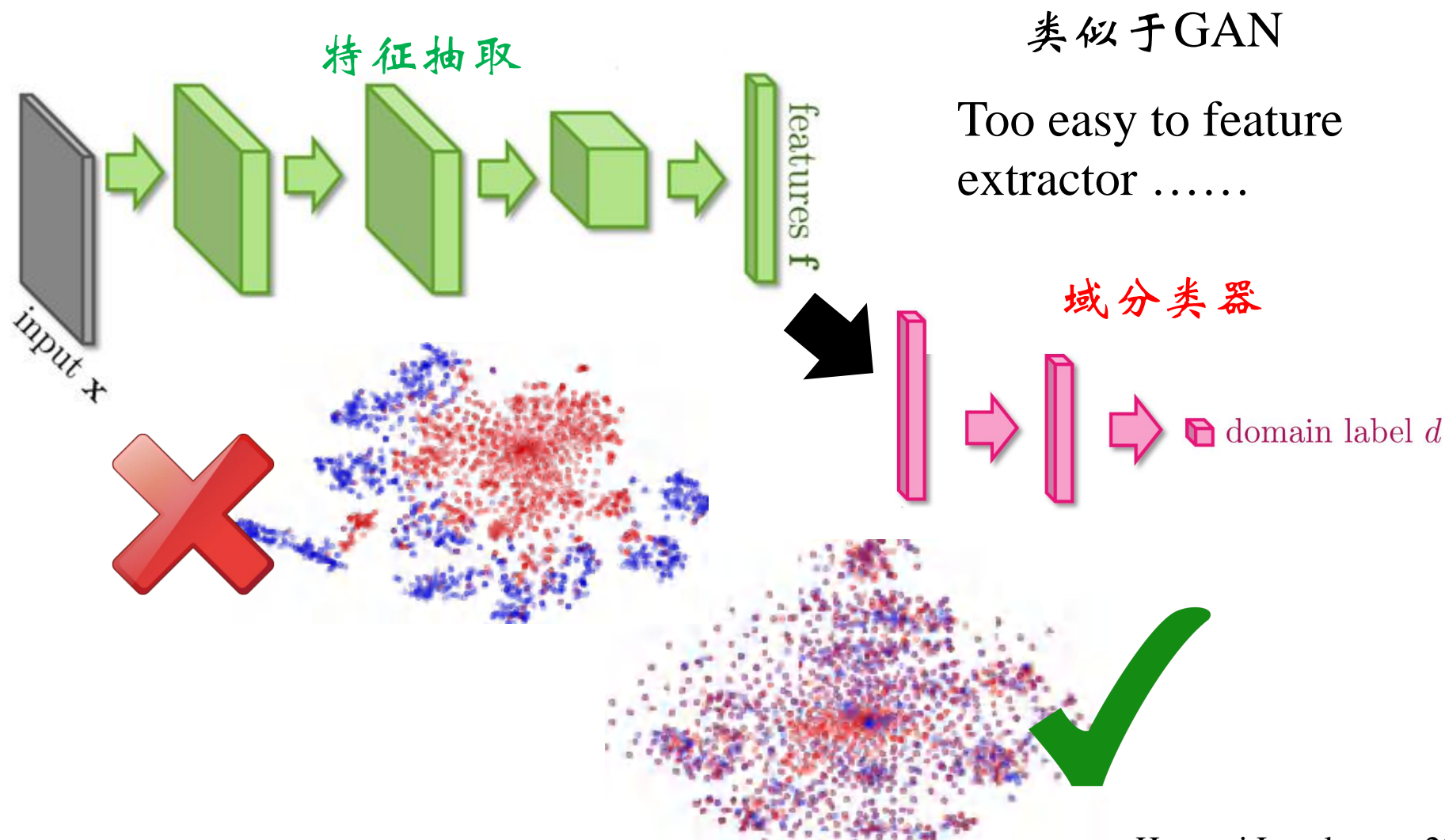
□ 神经网络是多层次的结构，适合多任务学习



有监督到无监督：域对抗学习



有监督到无监督：域对抗学习

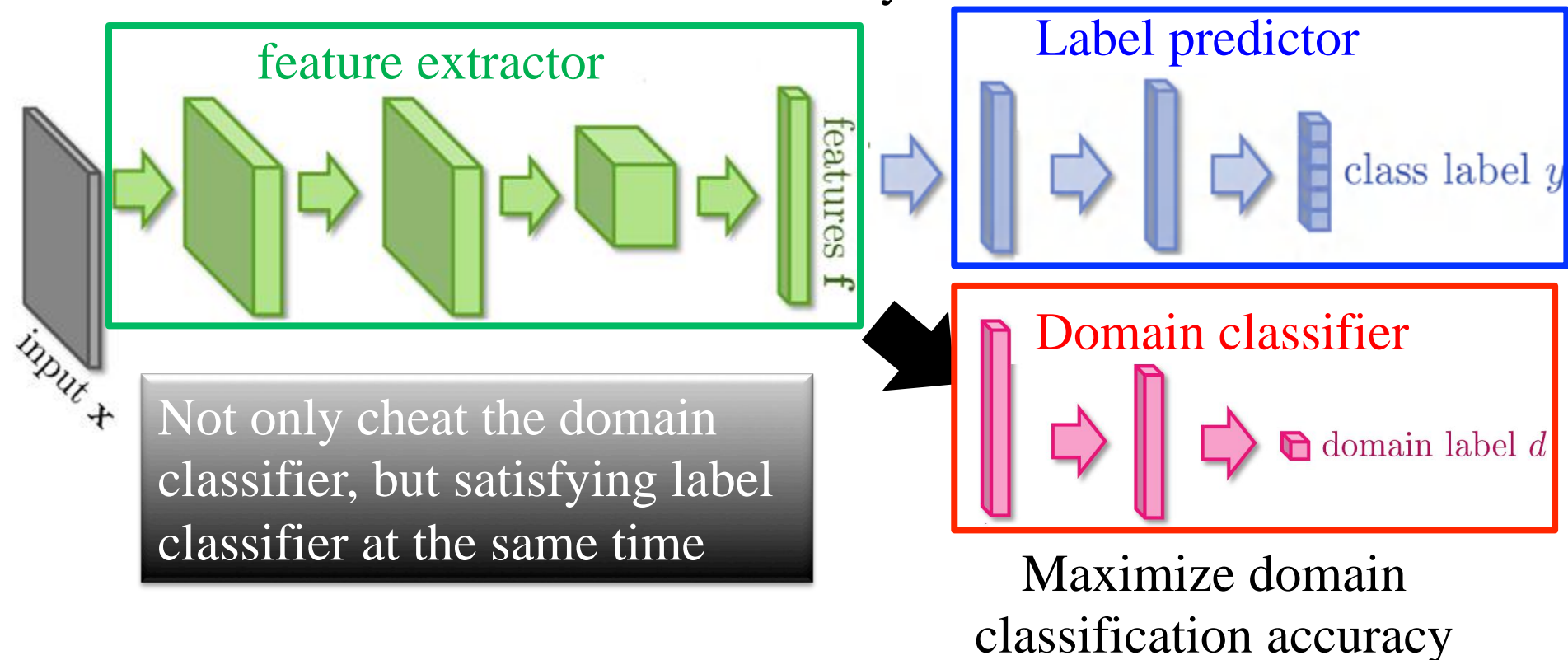


有监督到无监督：域对抗学习

Hung-yi Lee lecture 2017

Maximize label classification accuracy +
minimize domain classification accuracy

Maximize label
classification accuracy

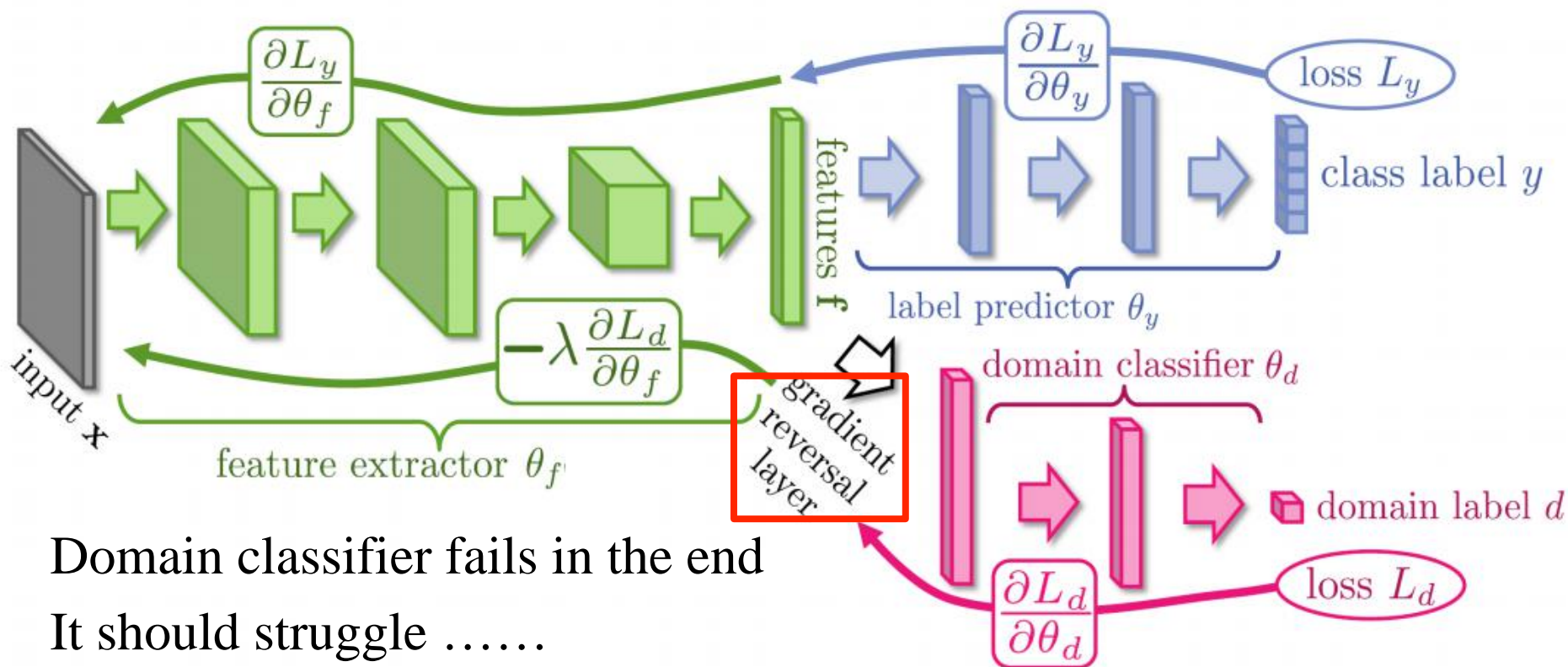


This is a big network, but different parts have different goals.



有监督到无监督：域对抗学习

Hung-yi Lee lecture 2017



Domain classifier fails in the end

It should struggle

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感谢大家！

恳请大家批评指正！

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