





# Linux Systems and Open Source Software

Basics of Performance Analysis
Part I



















## **Outline**

- What is Performance?
- Time Measurement for Performance Analysis
- Standard Time Measurement (POSIX)
- Native Linux Time Measurement
- Time Measurement for x86 Platforms













## WHAT IS PERFORMANCE?













# Define Performance

Plane	Speed	DC to Paris time	Passengers	Throughput (p x mph)
Boeing 747	610 mph	6.5 hours	470	286,700
Concorde	1350 mph	3 hours	132	178,200

### Choose an airplane with better *performance*

- To pick a fastest airplane?
- To pick a high-throughput airplane?













## Define Performance (Cont'd)

Plane	Speed	DC to Paris time	Passengers	Throughput (p x mph)
Boeing 747	610 mph	6.5 hours	470	286,700
Concorde	1350 mph	3 hours	132	178,200

- Time to do the task
  - Execution time, response time, latency
- Tasks per day, hour, week, sec, ns. ..
  - Throughput, bandwidth















## Performance Measurement

- In CS, when talk about **performance**, we should note...
- What is the **goal** here?
  - A well-tweaked program?
  - A fast machine?
  - ?

- **How** is performance measured?
  - Manually or automatically; will discussed in this course
- Example:

How to **choose** amongst different machines?

- Cost: price, technology metrics
- Performance
  - Metrics: time and processing speed; indicate relative performance
  - E.g., run time or X's per second





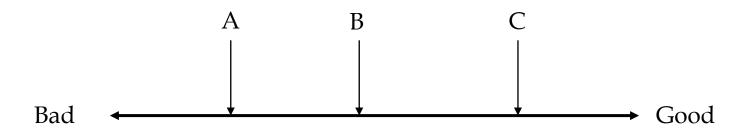








## **Performance Metrics**



- What is a **metric**?
  - Basis for measuring
  - Basis for comparison
- Metric varies across different situations
  - Job: Salary, Responsibilities; School: Grades;
  - Mutual Funds: Total Return, Risk
  - Cars: Top speed, Acceleration, Impact test
- Metrics are used to Order and Compare
- Many metrics are possible, many used















## **Computer Performance Metrics**

- Execution Time
  - CPU time, wall clock time
- Millions of Instructions Per Second (MIPS)
  - Machine instructions small primitive units generated by the compiler
- Cycles Per Instruction (CPI)
  - Fixed length time periods, normalization for technology
- Clock Rate (Megahertz)
  - Millions of cycles per second
- => Many metrics are used
  - Some better, some worse
- **Goal**: use metrics which **reflect performance** delivered by the underlying machine to real user programs, real applications
  - Quantize the combined effect of the application (SW) and machine (HW)













## **Measuring Execution Time**

- Steps
  - 1. Select a program
  - 2. Execute the program
  - 3. Measure the CPU time, or the wall clock (stopwatch) time

- Performance = 1 / (Execution time)
  - Smaller execution time -> better performance
  - Larger execution time -> worse performance
- Questions?
  - What to be compared? (the performance of different programs?)
  - How to measure time?















## Programs under Test (What)

- Target program
  - Would like to run EXACTLY the **same program**, but...
  - Programs are large and unwieldy, input data is critical, and they and their usage would change over time
  - Need to run entire application programs at full data set sizes to get good performance information
  - Best **predictors**, tricky, difficult, sometimes misleading
- "Benchmarking"
  - How applications will really run
  - Lies? and Benchmarks
  - Common benchmark programs are used to evaluate the performance amongst *commercial machines*
    - <u>SPEC</u>, TPC, Dhrystones, <u>Antutu</u>, etc.













## Time Measurement (How)

- How to measure execution time?
  - Watch (start/stop the meter; wall clock)
  - Computer timing: User (processor time) + System (operating system -- I/O, etc.)
    - Compare based on processor time for processor performance
    - Important, but of decreasing importance for SYSTEM performance
  - Concurrent users? Measurement errors?(Involves What to measure!!!)
- Usually, you should know What and then you will know How















## Time

- CPU Execution Time
  - = CPU clock cycles \* Clock cycle time
  - = CPU clock cycles / Clock rate
- Elapsed time (or wall-clock time)
  - It is the actual time taken between the start and the end of the task
- CPU Execution Time does not necessarily mean the wall-clock time
  - I.e., the elapsed time for running the program may be different from the time that CPU spent on the program
- Every conventional processor has a clock with an associated clock cycle time or clock rate
- Every program runs in an integer number of clock cycles x MHz = x millions of cycles/second (clock rate)
   1/ (x MHz) = cycle time; 1/(500 MHz) = 2 ns













### MIPS and MFLOPS

- MIPS and MFLOPS are common metrics for describing the capabilities of the machines
  - But, are they suitable for comparing performance of different machines all the time?
- MIPS: million instructions per second
  - =(number of **instructions** executed in program)/ ( execution time in seconds \* 10<sup>6</sup>)
- MFLOPS: million floating point operations per second
  - =(number of **floating point operations** executed in program)/( execution time in seconds \* 10<sup>6</sup>)















# A Benchmarking Example

- Pentium III 2.5Ghz system, Microsoft C++ compiler
  - Compile the program, execute, count instructions
  - Measured at <u>2,100 MIPs</u>
- What does this tell you about performance?
- Compile again, this time with optimization ON!
  - Compilation takes a lot longer, execute, count instructions
  - Measured performance at **1,600 MIPs**
- Intuitively, the optimized version should be faster than the original version (and in fact, the optimized version takes less time)
- But, the MIPS of the former is less than that of the latter. What happened?











# A Benchmarking Example (Cont'd)

# of Inst\_A / ExecTime\_A

# of Inst\_B /

ExecTime\_B

- There are **fewer instructions** executed in the optimized program!
  - And the optimized program takes less time
- MIPS rating depends on compiler
  - Quality of generated code
  - Optimized for instruction execution time, not MIPS rating
  - Compilers are always benchmarked with the machine
- How could you "cheat" to get a high MIPS rating?















## **Another Benchmarking Example**

- Power Macintosh, 1Ghz, PowerPC G4
  - Compile same program, "optimized"
  - Execute, assuming no obvious cheating
  - Experiment produces 1,500 MIPS rating
  - Is this faster than the Pentium III?
- => There's no easy way to tell from this information!
- Why?
  - The **unit of work** has changed.
  - Pentium Instruction != PowerPC instruction
- Hard to compare MIPS across architectures
  - MIPS is of little use for comparing architectures
  - Resort to execution time













## Another Benchmarking Example (Cont'd)

- Unit of work
  - **The real target** when we try to benchmark a program/system
  - E.g., Instructions, Floating Point Operations, Window updates, etc.
- The benchmarking result can be considered as <u>the time taken for executing the works</u>, which are affected by different factors:
  - Instructions: compiler, architecture
  - Floating Point operations: compiler, algorithm
  - Window updates: algorithm
- That is, the benchmarking result is the combined effect of the HW and SW environment
  - Depends on compiler, architecture, algorithm, implementation, execution environment, etc.











## **Example: Unit of Work**

- Floating Point Operations
- Window Updates
- Frames/Polygons (rendering)
- Megabytes (communication)
- Limitations of each of these?
- How can you cheat/reduce each of these?
  - → Time to finish a fixed amount of work
  - → Ratio of the finished amount of work per time unit















## Summary

- Architecture involves a tension of programmability, compilers, implementability, and technology
  - Optimize the design given these ever changing constraints
- Many possible measures of work / performance metrics
- Choosing is rife with potential errors
- Because it includes everything, execution time is the safest choice
- Still need to analyze the other influences carefully before you can draw any conclusions about the causes











# TIME MEASUREMENT FOR PERFORMANCE ANALYSIS









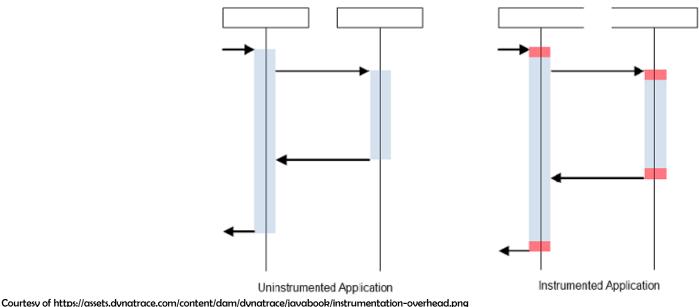


## Instrumentation-based Time Measurement

- Code instrumentation
  - Inject the *time functions* into the target application
  - It can be done manually or automatically in the source or binary program

#### Example

Insert *time* at the prolog and epilog of each function to get the elapsed times of the functions







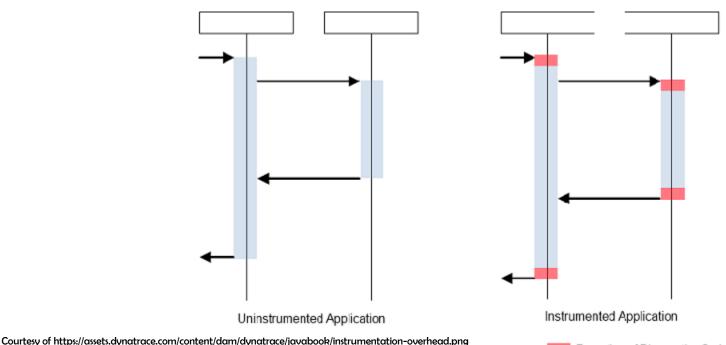






## Watch Out for Its Overhead

- Code instrumentation overhead
  - The red blocks refer to the overhead incurred by the time functions
  - The overhead is often ignored; but, you should pay attention to it
  - Here, we assume it is negligible compared with the **targets** (e.g., the functions to be analyzed)
- Instrumentation always:
  - introduces overhead (low or high)
  - alters the program execution

















## Measurement of *Time* Overhead

- It is crucial to understand the **cost** of the time measurement
- You may use the following simple method to get the overhead of the time function you used
  - Example below shows the averaged time required by each time() function invocation
- Note: **one million** is a magic number

```
start = time();
for i= 1 ~ 1,000,000
    time();
end = time();
```















## Note

 The following methods are simple and good for the sequential programs

- As for **parallel programs**, you should consider the concurrency issues
  - E.g., Lock and Wait
  - In this case, performance profiling tools should be used to characterize the runtime activities of multiple threads













# STANDARD TIME MEASUREMENT















### Be Careful

- The length of code for time measurement
- Unit & Resolution
  - Minute, seconds, microseconds
  - Length of code vs. Time Resolution
- Variables to hold the time values
  - Each time function has its own rules and way to *represent* the time
  - Types/Formats of the variables are important
- *Clock source* of the time function
  - System-wide, per-process, per-thread
- Code portability
  - Is the time measurement code portable across HW platforms?
  - E.g., Windows system has its time functions















## time()

- Get time in seconds
  - Return the current calendar time or -1 if there is an error
  - If the argument time is given, then the current time is stored in time
  - Only measure the time up to seconds

```
#include <ctime>
time_t time( time_t *time );
```















## clock()

- Determine processor time (clocks)
  - Return the processes CPU time (time since the program started)
  - Return -1 if that information is not available
- Conversion to seconds by division by CLOCKS\_PER\_SEC
  - Note: if your compiler is POSIX compliant, then CLOCKS\_PER\_SEC is always defined as 1,000,000
  - On a 32-bit system where CLOCKS\_PER\_SEC equals 1000000 this function will return the same value approximately every 72 minutes
  - For improved accuracy, since glibc 2.18, it is implemented on top of clock\_gettime(2) (using the CLOCK\_PROCESS\_CPUTIME\_ID clock)

#include <ctime>

clock\_t clock( void );





#include <ctime>







## Example: Time Measurement using clock()

```
// Time stamp before the computations
clock t start = clock();
... /* Computations to be measured */
// Time stamp after the computations
clock t end = clock();
double cpu time = static cast<double>( end - start ) /
                       Report the elapsed time for the code section
CLOCKS PER SEC;
                       enclosed by the two clock functions
```

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## clock\_gettime()

- High Precision Event Timer
- The functions **clock\_gettime()** and **clock\_settime()** retrieve and set the time of the specified clock
- The function **clock\_getres()** finds the resolution (precision) of the specified clock **clk\_id** (should also consider the incurred overhead)

```
#include <time.h>
int clock_gettime(clockid_t clk_id, struct timespec *tp);
struct timespec {
    time_t tv_sec; /* seconds */
    long tv_nsec; /* nanoseconds */
}
```











# Supported Clocks for clock\_gettime()

- The **clk\_id** argument is the identifier of the particular clock on which to act
- Sufficiently recent versions of GNU libc and the Linux kernel support the following clocks:
  - CLOCK\_REALTIME
     System-wide wall-clock clock. Set this clock requiring appropriate privileges
  - CLOCK\_MONOTONIC
     Clock that cannot be set and represents monotonic time since some unspecified starting point
     Good for total elapsed time, including I/O & block overhead
  - CLOCK\_PROCESS\_CPUTIME\_ID
     High-resolution per-process timer from the CPU (not for block/sleep code)
  - CLOCK\_THREAD\_CPUTIME\_ID
     Thread-specific CPU-time clock













# NATIVE LINUX TIME MEASUREMENT











# gettimeofday()

Used for measuring wall clock time

```
#include <sys/time.h>
#include <sys/types.h>
struct timeval tp;
double sec, usec, start, end;
// Time stamp before the computations
gettimeofday( &tp, NULL );
sec = static_cast<double>( tp.tv_sec );
usec = static_cast<double>( tp.tv_usec )/1E6;
start = sec + usec:
// Computations to be measured
// Time stamp after the computations
gettimeofday( &tp, NULL );
sec = static_cast<double>( tp.tv_sec );
usec = static cast<double>( tp.tv usec )/1E6;
end = sec + usec;
// Time calculation (in seconds)
double time = end - start:
```



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# TIME MEASUREMENT FOR X86 PLATFORMS















## Read Time Stamp Counter (RDTSC)

- Time Stamp Counter (TSC)
  - Record CPU clock cycles
  - Monotonically increase for each CPU clock
  - Accessed by the Read Time Stamp Counter (**RDTSC**) instruction introduced in Pentium processors
- Simple and neat to use the Time Stamp Counter for time measurement
  - by calling the inline function below to get the current timestamp (in cycles)
  - Need to translate the cycles into the actual time

```
/* assembly code to read the TSC */
static inline uint64_t RDTSC()
 unsigned int hi, lo;
   asm__ volatile("rdtsc" : "=a" (lo), "=d" (hi));
 return ((uint64_t)hi << 32) | lo;
```











# Why RDTSC?

- Compared with clock\_gettime()
  - Higher resolution
    - We can get the resolution through the API **clock\_getres()**
    - On the Dell XPS 1530 with Intel core2duo T7500 CPU running Ubuntu 10.04, it has a resolution of 1 nanosecond
    - On the other hand, RDTSC instruction can have resolution of up to a CPU clock time
    - On the 2.2 GHz CPU that means resolution is 0.45 nanoseconds

#### - Low cost

- Measure the time taken for 1 million calls to both HPET and RDTSC
- HPET: 1 s 482 ms 188 us 38 ns
- RDTSC: 0 s 103 ms 311 us 752 ns
- RDTSC is 14x faster than HPET











# Be Careful for the Following Situations!!!

- The per-CPU TSC value may not the same across CPU cores
  - Multiple cores having different TSC values
  - One should bind the process to same CPU
  - Invariant TSC support for ensuring consistent across multiple cores; but, one should pay attention to multi-CPUs
- CPU frequency scaling for power saving
  - Fixed CPU power governor policy, e.g., high performance
- Hibernation of system will reset TSC value
  - Disable the hibernate; or, check the TSC values
- Impact on portability due to varying implementation of CPUs
  - Fixed Intel CPUs with same settings
- Out-of-order execution of code
  - Use the instruction, e.g., CPUID, for serializing instructions
  - Please refer to the document













# **QUESTIONS?**



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