AVA CHEN

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EDUCATION

Columbia University	$2019-{ m present}$
Ph.D in Mechanical Engineering, expected Spring 2025	$New\ York,\ NY$
M.S. in Mechanical Engineering, conferred Feb. 2021	
Advisor: Matei Ciocarlie	
Massachusetts Institute of Technology (MIT)	2013 - 2017
B.S. in Mechanical Engineering	$Cambridge,\ MA$

HONORS

NIH Ruth L. Kirschstein National Research Service Award (NRSA) F31 – NICHD	2023 - 2025
Robotics: Science & Systems (RSS) Pioneer	$\boldsymbol{2024}$
Columbia Center for the Integration of Research, Teaching and Learning (CIRTL) Fellow	2023 - 2024
Columbia University Presidential Distinguished Fellowship	2019 - 2023
Rising Star in ME 2022 at Stanford University	$\boldsymbol{2022}$
Honorable Mention, MIT MechE deFlorez Design Competition	2016

PUBLICATIONS

Peer-Reviewed Journal Articles

[* indicates equal contribution]

- [J.4] L. Winterbottom*, A. Chen*, R. Mendonca, D.M. Nilsen, M. Ciocarlie, and J. Stein. "Clinician perceptions of a novel wearable robotic hand orthosis for post-stroke hemiparesis." *Disability and Rehabilitation*, 1–10. (2024)
- [J.3] J. Palacios*, A. Deli-Ivanov*, A. Chen*, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie, "Grasp Force Assistance via Throttle-based Wrist Angle Control on a Robotic Hand Orthosis for C6-C7 Spinal Cord Injury." IEEE Transactions on Medical Robotics and Bionics, in press. (2024)
- [J.2] A. Chen, L. Winterbottom, S. Park, J. Xu, D. M. Nilsen, J. Stein, and M. Ciocarlie, "Thumb Stabilization and Assistance in a Robotic Hand Orthosis for Post-Stroke Hemiparesis." *IEEE Robotics and Automation Letters*, 7, 8276-8282. (2022)
 - Presented in 2022 IEEE RAS/EMBS Intl. Conference on Biomedical Robotics and Biomechatronics (BioRob). Finalist, BioRob2022 Best Paper Award
- [J.1] A. Chen, K. Kim, and P.S. Shamble. "Rapid mid-jump production of high-performance silk by jumping spiders." Current Biology, 31, R1422-R1423. (2021)

Peer-Reviewed Conference Papers

- [C.5] P. L. La Rotta*, J. Xu*, A. Chen, L. Winterbottom, W. Chen, D. M. Nilsen, J. Stein, and M. Ciocarlie, "Meta-Learning for Fast Adaptation in Intent Inferral on a Robotic Hand Orthosis for Stroke." In 2024 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS).
- [C.4] A. Chen*, K. Lee*, L. Winterbottom, J. Xu, C. Lee, G. Munger, A. Deli-Ivanov, D. M. Nilsen, J. Stein, and M. Ciocarlie, "Volitional Control of the Paretic Hand Post-Stroke Increases Finger Stiffness and Resistance to Robot-Assisted Movement." In 2024 IEEE RAS/EMBS Intl. Conference on Biomedical Robotics and Biomechatronics (BioRob).
- [C.3] A. Chen, L. Winterbottom, K. O'Reilly, S. Park, D. M. Nilsen, J. Stein, and M. Ciocarlie. "Design of Spiral-Cable Forearm Exoskeleton to Provide Supination Adjustment for Hemiparetic Stroke Subjects." In 2022 IEEE Intl. Conference on Rehabilitation Robotics (ICORR).
- [C.2] J. Xu, C. Meeker, A. Chen, L. Winterbottom, M. Fraser, S. Park, L. M. Weber, M. Miya, D. M. Nilsen, J. Stein, and M. Ciocarlie. "Adaptive Semi-Supervised Intent Inferral to Control a Powered Hand Orthosis for Stroke." In 2022 IEEE Intl. Conference on Robotics and Automation (ICRA).
- [C.1] T. Cervantes, W.E. Byun*, A. Chen*, K. Kim*, K. Nealon*, J. Connor, and A. Slocum. "A Device for Quantitative Analysis of the Thumb Ulnar Collateral Ligament." ASME. Frontiers in Biomedical Devices, 2018 ASME Design of Medical Devices Conference.

Submitted for Publication

[S.1] J. Xu*, R. Wang*, S. Shang*, A. Chen, L. Winterbottom, L. Hsu, W. Chen, K. Ahmed, P. L. La Rotta, X. Zhu, D. M. Nilsen, J. Stein, and M. Ciocarlie, "ChatEMG: Synthetic Data Generation to Control a Robotic Hand Orthosis for Stroke." (2024, submitted.)

Workshop and Symposium Contributions

- [W.7] L. Winterbottom, A. Chen, D. M. Nilsen, R. Mendonca, J. Xu, K. Lee, M. Ciocarlie, and J. Stein. "Motor learning techniques to enhance training with robotic hand orthoses for stroke survivors: challenges and opportunities." Submitted to American Occupational Therapy Association (AOTA) INSPIRE 2025.
- [W.6] A. Chen. "Assisting Impaired Dexterity with User-Driven Robotic Hand Exoskeletons." In Robotics: Science and Systems (RSS) workshop: RSS Pioneers 2024.
- [W.5] A. Chen, J. Xu, K. Lee, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie. "Bidirectional Human-Robot Feedback and Physical Effects of Assisted Manipulation with a Robotic Hand Orthosis for Stroke." In New England Manipulation Symposium (NEMS) 2024.
- [W.4] L. Winterbottom, D. Nilsen, R. Mendonca, A. Chen, S. Lin, K. Carroll, J. Xu, M. Ciocarlie, and J. Stein. "Collaboration between Occupational Therapists, Engineers, and People with Neurological Conditions in the Development of Wearable Robotic Devices." In American Occupational Therapy Association (AOTA) INSPIRE 2024.
- [W.3] J. Palacios*, A. Deli-Ivanov*, A. Chen, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie. "Towards Tenodesis-Modulated Control of an Assistive Hand Exoskeleton for SCI." In 2023 IEEE/RSJ Intl. Conf. on Intelligent Robots and Systems (IROS) workshop: Assistive Robotics for Citizens.
- [W.2] L. Winterbottom, K. Carroll, S. Lin, A. Chen, R. Mendonca, D. M. Nilsen, M. Ciocarlie, and J. Stein. "Stroke Survivors' Perspectives on the Design of a Novel Wearable Robotic Hand Brace." In 2022 Janet Falk-Kessler Distinguished Lectureship and Day of Scholarship.
- [W.1] L. Winterbottom, D. Nilsen, R. Mendonca, A. Chen, J. Xu, M. Ciocarlie, and J. Stein. "Perspectives of Individuals with C6-C7 Spinal Cord Injury on the Design of a Novel Robotic Hand Brace." In 2021 Janet Falk-Kessler Distinguished Lectureship and Day of Scholarship.

Patents

[P.1] M. Ciocarlie, J. Stein, A. Chen, S. Park, D.M. Nilsen. "Robotic Hand Orthosis For Stroke", Application #: US 63/249,456

Theses

[T.1] "Effectiveness of Active Cooling on Torque Performance for Prosthetic Applications." B.S. Thesis, MIT, 2017.

GRANT PROPOSAL EXPERIENCE

Impact of biofeedback and task-specific training with a robotic hand orthosis on voluntary muscle modulation for rehabili-NIH F31 1F31HD111301 NICHD (NCMRR) 8/2023-1/2025 \$72,587

Reciprocal Learning for Intent Inferral on an Active Hand Orthosis for Stroke. (Submitted) PI: Ciocarlie/Stein/Nilsen Contributed to conceptualization, methodology, investigation, preliminary data, and writing. NSF M3X program.

MyHand-SCI: A Powered Wrist/Hand Orthosis for Individuals With Tetraplegia. (Submitted) PI: Stein DOD SCIRP-CTRA. Contributed to conceptualization, methodology, investigation, administration, supervision, writing.

INVITED TALKS

Robotic Hand Exoskeletons to Assist and Rehabilitate Impaired Dexterity

June 2024

Harvard University, Harvard Biorobotics Lab Meeting

Robotic Hand Orthoses for Assistance and Rehabilitation After Stroke (Co-Speaker)

Sept. 2023

MyHand: a Wearable Hand Orthosis for Stroke (Co-Speaker)

Global Perspectives on Medicine, Rehabilitation and Robotics Webinar Series

Oct. 2021

IROS Workshop, Challenges and Opportunities of Human-Robot Symbiosis: from Wearable Robots to Neurorobotics

How Jumping Spiders Use Silk to Orient Themselves in Midair

Oct. 2018

Harvard University, Harvard Bauer Forum

How Jumping Spiders Jump

Oct. 2018

TEACHING EXPERIENCE AND MENTORSHIP

University Courses Teaching Assistant, Columbia MECE E4602 – Introduction to Robotics Lab Assistant, Harvard LS50 – Integrated Science	Fall 2020 Spring 2018, Spring 2019
Pedagogical Training Participant, Columbia Center for Teaching and Learning (CTL) Teaching Development Pro	$_{ m ogram}$ 2022 – present
Talks on Teaching Columbia CTL "Wowza!" CIRTL Discussion Series – Speaker, "Supporting Teaching as Sc. Columbia CTLGrads Journal Club workshop – Speaker, "Effective Teaching Online, Real-T	holarship" Mar. 2024
Extracurricular Columbia Engineering Your PhD – Invited Panelist, "Insights from Experienced TAs" Academic Mentor, Women in Science at Columbia (WISC) Research Mentor, Columbia University Engineering the Next Generation (ENG) Research Mentor and Teaching Assistant, Research Science Institute (RSI) Teaching Assistant, Bellarmine University Summer Youth Camps Sur	Aug. 2023, Aug. 2024 2020, 2021, 2023 Summer 2022 Summer 2014 nmer 2012, Summer 2013
RESEARCH STUDENTS SUPERVISED	
Shiyao Marcus Lam, Columbia Undergraduate Matheu Campbell, Columbia Undergraduate Grace Munger, Columbia Undergraduate [C.4] Akshay Venkatesan, Columbia M.S. Data Science Runsheng Wang, Columbia M.A. Statistics [S.1] → Columbia Ph.D Connor Lee, Columbia Undergraduate [C.4] → Arctic Capture Alexandra Deli-Ivanov, Columbia Undergraduate [J.3, C.4, W.3] → SpaceX Joaquin Palacios, Columbia Undergraduate and M.S. Robotics [J.3, W.3] → Columbia P Pedro Leandro La Rotta, Columbia M.S. Robotics [C.5, S.1] Katherine O'Reilly, Columbia Undergraduate [C.3] → UIUC M.S. Carolyn David, Columbia M.S. Biomedical Engineering → AbbVie Preethika Chivukula, Columbia M.S. Biomedical Engineering → BD Biosciences Ashley Reyes, Columbia ENG Student → WPI UGrad Brayan Ramos, Columbia ENG Student → Cooper Union UGrad Ciara Little, Columbia Undergraduate → UMass Amherst Ph.D Katelyn G. Mitchell, Columbia Undergraduate → ASML Frederick Horne, Harvard Undergraduate Rowen VonPlagenhoef, Harvard Undergraduate Eliot Burnes, Harvard Undergraduate Henry Burnes, Harvard Undergraduate Lincoln Sorscher, Harvard Undergraduate Cheng Lu, RSI Scholar	2024 - present 2023 - present 2023 - present 2023 - 2024 2023 - 2024 2023 - 2024 2022 - 2024 2021 - 2024 2022 - 2023 2020 - 2023 2021 - 2022 Summer 2022 Summer 2022 Summer 2022 2020 - 2021 2019 2019 2018 - 2019 2018 Summer 2014
SERVICE	_
University and Conference Service Workshop Co-Organizer, BioRob 2024 "Building Responsive Body-Machine Interfaces with Biosignals and Robotic Exoskeletons CIRTL Fellow, Columbia University Center for Teaching and Learning Conference Volunteer, Robotics: Science and Systems (RSS)	2024 $2023 - 2024$ 2022
External Paper Reviewer IEEE Transactions on Robotics (TRO) IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS) IEEE RAS/EMBS Intl. Conference on Biomedical Robotics & Biomechatronics (BioRob) IEEE Transactions on Medical Robotics and Bionics (T-MRB) Scientific Reports IEEE Intl. Conference on Robot and Human Interactive Communication (RO-MAN) IEEE Intl. Conference on Rehabilitation Robotics (ICORR) IEEE Intl. Conference on Robotics and Automation (ICRA) IEEE Robotics and Automation Letters (RA-L) IEEE Transactions on Neural Systems and Rehabilitation Engineering (TNSRE)	2024 2024 2022, 2024 2023 2022, 2023 2022, 2023 2022 2021, 2022 2021, 2022 2020

Science Volunteering and Outreach Question Reviewer, U.S. Dept. of Energy National Science Bowl (NSB) Volunteer / Paper Reviewer, Research Science Institute (RSI) at MIT Columbia Engineering Achievers in Graduate Education (EngAGE) – Invited Panelist Columbia WISC STEM Field Exploration Fair – Invited Panelist, "Behind the Lab Scenes" Judge, Kentucky Science and Engineering Fair Judge, MIT Mechanical Engineering Research Exhibition Question Writer, USA Biolympiad (USABO) Volunteer, Adaptive Climbing Group NY Judge, Sweden Research Academy for Young Scientists (RAYS)	2023, 2024 2015, 2018, 2024 Mar. 2024 Apr. 2022 2021 2020 2019 2019 2015
PREVIOUS POSITIONS	
Harvard Dept. of Organismic & Evolutionary Biology, Shamble Lab Research Assistant with Dr. Paul Shamble Studied jumping dynamics and mid-air silk production of jumping spiders [J.1]	2017 - 2019
Dephy, Inc. Mechanical Engineering Intern Designed and built validation equipment for full-system stress testing	Summer 2017, Fall 2018
MIT Media Lab, Biomechatronics Group Undergraduate Researcher with Dr. Hugh Herr, Arthur Petron, and Matt Carney Worked on FitSocket project for soft-tissue characterization and on active motor cooling [T.	2013 – 2017
Apple Inc. Product Design Validation Engineer Intern Worked on design, usability, and validation for mechanical features in hardware products	Summer 2016
Formlabs Mechanical Engineering Intern Electromechanical design for early versions of Form 2 and Form Cure products	Summer 2015
Brain Power, LLC Hardware Intern Hardware development of Google Glass applications for users with autism	Winter 2015
Cardiovascular Innovation Institute & Christine M. Kleinert Institute Research Intern with Dr. Nolan Boyd and Dr. Christina Kaufman Worked on tissue self-assembly using adipose stromal vascular fraction	2012 - 2013
Research Science Institute (RSI) at MIT Summer Scholar with Arthur Petron Worked on electromechanical designs for a variable spring stiffness emulator	Summer 2012
SIDE PROJECTS	
Unterhered Gait Tracking for Rehabilitation Collaboration with FIGUR8, Inc. to use their wearables platform for monitoring gait trends during self recovery & long-term effects of rehabilitation post knee-reconstruction surgery.	2018 - 2019
MIT East Campus Roller Coaster Formed and led team of students to complete \$15,000 construction project in 8 days.	2015

 $Formed\ and\ led\ team\ of\ students\ to\ complete\ \$15,000\ construction\ project\ in\ 8\ days.$ Unofficial Guinness World Record holder for Steepest Wooden Roller Coaster.

More documentation on personal projects at https://www.avamakesthings.com