

AVA CHEN

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EDUCATION

Columbia University

Ph.D in Mechanical Engineering, expected Spring 2025

M.S. in Mechanical Engineering, conferred Feb. 2021

Advisor: Matei Ciocarlie

2019 – present

New York, NY

Massachusetts Institute of Technology (MIT)

B.S. in Mechanical Engineering

2013 – 2017

Cambridge, MA

HONORS

NIH Ruth L. Kirschstein National Research Service Award (NRSA) F31 – NICHD

2023 – 2025

Robotics: Science & Systems (RSS) Pioneer

2024

Columbia Center for the Integration of Research, Teaching and Learning (CIRTL) Fellow

2023 – 2024

Columbia University Presidential Distinguished Fellowship

2019 – 2023

Rising Star in ME 2022 at Stanford University

2022

Honorable Mention, MIT MechE deFlorez Design Competition

2016

PUBLICATIONS

Peer-Reviewed Journal Articles

[* indicates equal contribution]

- [J.4] L. Winterbottom*, **A. Chen***, R. Mendonca, D.M. Nilsen, M. Ciocarlie, and J. Stein. “Clinician perceptions of a novel wearable robotic hand orthosis for post-stroke hemiparesis.” *Disability and Rehabilitation*, 1–10. (2024)
- [J.3] J. Palacios*, A. Deli-Ivanov*, **A. Chen***, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie, “Grasp Force Assistance via Throttle-based Wrist Angle Control on a Robotic Hand Orthosis for C6-C7 Spinal Cord Injury.” *IEEE Transactions on Medical Robotics and Bionics*, in press. (2024)
- [J.2] **A. Chen**, L. Winterbottom, S. Park, J. Xu, D. M. Nilsen, J. Stein, and M. Ciocarlie, “Thumb Stabilization and Assistance in a Robotic Hand Orthosis for Post-Stroke Hemiparesis.” *IEEE Robotics and Automation Letters*, 7, 8276–8282. (2022)
 - Presented in *2022 IEEE RAS/EMBS Intl. Conference on Biomedical Robotics and Biomechatronics (BioRob)*.
Finalist, BioRob2022 Best Paper Award
- [J.1] **A. Chen**, K. Kim, and P.S. Shamble. “Rapid mid-jump production of high-performance silk by jumping spiders.” *Current Biology*, 31, R1422–R1423. (2021)

Peer-Reviewed Conference Papers

- [C.5] P. L. La Rotta*, J. Xu*, **A. Chen**, L. Winterbottom, W. Chen, D. M. Nilsen, J. Stein, and M. Ciocarlie, “Meta-Learning for Fast Adaptation in Intent Inferral on a Robotic Hand Orthosis for Stroke.” In *2024 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS)*.
- [C.4] **A. Chen***, K. Lee*, L. Winterbottom, J. Xu, C. Lee, G. Munger, A. Deli-Ivanov, D. M. Nilsen, J. Stein, and M. Ciocarlie, “Volitional Control of the Paretic Hand Post-Stroke Increases Finger Stiffness and Resistance to Robot-Assisted Movement.” In *2024 IEEE RAS/EMBS Intl. Conference on Biomedical Robotics and Biomechatronics (BioRob)*.
- [C.3] **A. Chen**, L. Winterbottom, K. O’Reilly, S. Park, D. M. Nilsen, J. Stein, and M. Ciocarlie. “Design of Spiral-Cable Forearm Exoskeleton to Provide Supination Adjustment for Hemiparetic Stroke Subjects.” In *2022 IEEE Intl. Conference on Rehabilitation Robotics (ICORR)*.
- [C.2] J. Xu, C. Meeker, **A. Chen**, L. Winterbottom, M. Fraser, S. Park, L. M. Weber, M. Miya, D. M. Nilsen, J. Stein, and M. Ciocarlie. “Adaptive Semi-Supervised Intent Inferral to Control a Powered Hand Orthosis for Stroke.” In *2022 IEEE Intl. Conference on Robotics and Automation (ICRA)*.
- [C.1] T. Cervantes, W.E. Byun*, **A. Chen***, K. Kim*, K. Nealon*, J. Connor, and A. Slocum. “A Device for Quantitative Analysis of the Thumb Ulnar Collateral Ligament.” ASME. *Frontiers in Biomedical Devices*, 2018 *ASME Design of Medical Devices Conference*.

Submitted for Publication

- [S.1] J. Xu*, R. Wang*, S. Shang*, **A. Chen**, L. Winterbottom, L. Hsu, W. Chen, K. Ahmed, P. L. La Rotta, X. Zhu, D. M. Nilsen, J. Stein, and M. Ciocarlie, “ChatEMG: Synthetic Data Generation to Control a Robotic Hand Orthosis for Stroke.” (2024, submitted.)

Workshop and Symposium Contributions

- [W.7] L. Winterbottom, **A. Chen**, D. M. Nilsen, R. Mendonca, J. Xu, K. Lee, M. Ciocarlie, and J. Stein. “Motor learning techniques to enhance training with robotic hand orthoses for stroke survivors: challenges and opportunities.” Submitted to *American Occupational Therapy Association (AOTA) INSPIRE 2025*.
- [W.6] **A. Chen**. “Assisting Impaired Dexterity with User-Driven Robotic Hand Exoskeletons.” In *Robotics: Science and Systems (RSS) workshop: RSS Pioneers 2024*.
- [W.5] **A. Chen**, J. Xu, K. Lee, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie. “Bidirectional Human-Robot Feedback and Physical Effects of Assisted Manipulation with a Robotic Hand Orthosis for Stroke.” In *New England Manipulation Symposium (NEMS) 2024*.
- [W.4] L. Winterbottom, D. Nilsen, R. Mendonca, **A. Chen**, S. Lin, K. Carroll, J. Xu, M. Ciocarlie, and J. Stein. “Collaboration between Occupational Therapists, Engineers, and People with Neurological Conditions in the Development of Wearable Robotic Devices.” In *American Occupational Therapy Association (AOTA) INSPIRE 2024*.
- [W.3] J. Palacios*, A. Deli-Ivanov*, **A. Chen**, L. Winterbottom, D. M. Nilsen, J. Stein, and M. Ciocarlie. “Towards Tenodesis-Modulated Control of an Assistive Hand Exoskeleton for SCI.” In *2023 IEEE/RSJ Intl. Conf. on Intelligent Robots and Systems (IROS) workshop: Assistive Robotics for Citizens*.
- [W.2] L. Winterbottom, K. Carroll, S. Lin, **A. Chen**, R. Mendonca, D. M. Nilsen, M. Ciocarlie, and J. Stein. “Stroke Survivors’ Perspectives on the Design of a Novel Wearable Robotic Hand Brace.” In *2022 Janet Falk-Kessler Distinguished Lectureship and Day of Scholarship*.
- [W.1] L. Winterbottom, D. Nilsen, R. Mendonca, **A. Chen**, J. Xu, M. Ciocarlie, and J. Stein. “Perspectives of Individuals with C6-C7 Spinal Cord Injury on the Design of a Novel Robotic Hand Brace.” In *2021 Janet Falk-Kessler Distinguished Lectureship and Day of Scholarship*.

Patents

- [P.1] M. Ciocarlie, J. Stein, **A. Chen**, S. Park, D.M. Nilsen. “Robotic Hand Orthosis For Stroke”, Application #: US 63/249,456

Theses

- [T.1] “Effectiveness of Active Cooling on Torque Performance for Prosthetic Applications.” *B.S. Thesis, MIT, 2017*.

GRANT PROPOSAL EXPERIENCE

Impact of biofeedback and task-specific training with a robotic hand orthosis on voluntary muscle modulation for rehabilitation post-stroke. NIH F31 1F31HD111301 NICHD (NCMRR) 8/2023–1/2025 \$72,587 **PI: Chen**

Reciprocal Learning for Intent Inferral on an Active Hand Orthosis for Stroke. (Submitted) PI: Ciocarlie/Stein/Nilsen
NSF M3X program. Contributed to conceptualization, methodology, investigation, preliminary data, and writing.

INVITED TALKS

| | |
|--|-------------------|
| Robotic Hand Exoskeletons to Assist and Rehabilitate Impaired Dexterity Harvard University, Harvard Biorobotics Lab Meeting | June 2024 |
| Robotic Hand Orthoses for Assistance and Rehabilitation After Stroke (Co-Speaker) Global Perspectives on Medicine, Rehabilitation and Robotics Webinar Series | Sept. 2023 |
| MyHand: a Wearable Hand Orthosis for Stroke (Co-Speaker) IROS Workshop, Challenges and Opportunities of Human-Robot Symbiosis: from Wearable Robots to Neurorobotics | Oct. 2021 |
| How Jumping Spiders Use Silk to Orient Themselves in Midair Harvard University, Harvard Bauer Forum | Oct. 2018 |
| How Jumping Spiders Jump Broad Institute, CEE 35th Anniversary Celebration | Oct. 2018 |

TEACHING EXPERIENCE AND MENTORSHIP

University Courses

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|--|--------------------------|
| Teaching Assistant, Columbia MECE E4602 – Introduction to Robotics | Fall 2020 |
| Lab Assistant, Harvard LS50 – Integrated Science | Spring 2018, Spring 2019 |

Pedagogical Training

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| Participant, Columbia Center for Teaching and Learning (CTL) Teaching Development Program | 2022 – present |
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Talks on Teaching

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| Columbia CTL “Wowza!” CIRTl Discussion Series – Speaker, “Supporting Teaching as Scholarship” | Mar. 2024 |
| Columbia CTLGrads Journal Club workshop – Speaker, “Effective Teaching Online, Real-Time” | Oct. 2023 |
| Columbia Engineering Your PhD – Invited Panelist, “Insights from Experienced TAs” | Aug. 2023, 2024 |

Extracurricular

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|--|--------------------------|
| Academic Mentor, Women in Science at Columbia (WISC) | 2020, 2021, 2023 |
| Research Mentor, Columbia University Engineering the Next Generation (ENG) | Summer 2022 |
| Research Mentor and Teaching Assistant, Research Science Institute (RSI) | Summer 2014 |
| Teaching Assistant, Bellarmine University Summer Youth Camps | Summer 2012, Summer 2013 |

RESEARCH STUDENTS SUPERVISED

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|---|----------------|
| Shiyao Marcus Lam, Columbia Undergraduate | 2024 – present |
| Akshay Venkatesan, Columbia M.S. Data Science | 2023 – present |
| Matheu Campbell, Columbia Undergraduate | 2023 – present |
| Grace Munger, Columbia Undergraduate [C.4] | 2023 – present |
| Connor Lee, Columbia Undergraduate [C.4] | 2023 – present |
| Alexandra Deli-Ivanov, Columbia Undergraduate [J.3, C.4, W.3] → SpaceX | 2022 – 2024 |
| Joaquin Palacios, Columbia Undergraduate and M.S. Robotics [J.3, W.3] → Columbia Ph.D | 2021 – 2024 |
| Pedro Leandro La Rotta, Columbia M.S. Robotics [C.5, S.1] | 2023 |
| Katherine O'Reilly, Columbia Undergraduate [C.3] → UIUC M.S. | 2020 – 2023 |
| Carolyn David, Columbia M.S. Biomedical Engineering → AbbVie | 2022 – 2023 |
| Preethika Chivukula, Columbia M.S. Biomedical Engineering → BD Biosciences | 2021 – 2022 |
| Ashley Reyes, Columbia ENG Student → WPI UGrad | Summer 2022 |
| Brayan Ramos, Columbia ENG Student → Cooper Union UGrad | Summer 2022 |
| Ciara Little, Columbia Undergraduate → UMass Amherst Ph.D | 2020 – 2021 |
| Katelyn G. Mitchell, Columbia Undergraduate → ASML | 2020 – 2021 |
| Frederick Horne, Harvard Undergraduate | 2019 |
| Rowen VonPlagenhoef, Harvard Undergraduate | 2019 |
| Eliot Burnes, Harvard Undergraduate | 2018 – 2019 |
| Henry Burnes, Harvard Undergraduate | 2018 – 2019 |
| Lincoln Sorscher, Harvard Undergraduate | 2018 |
| Cheng Lu, RSI Scholar | Summer 2014 |

SERVICE

University and Conference Service

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| Workshop Co-Organizer, BioRob 2024 | 2024 |
| “ Building Responsive Body-Machine Interfaces with Biosignals and Robotic Exoskeletons ” | |
| CIRTl Fellow, Columbia University Center for Teaching and Learning | 2023 – 2024 |
| Conference Volunteer, Robotics: Science and Systems (RSS) | 2022 |

External Paper Reviewer

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| IEEE Transactions on Robotics (TRO) | 2024 |
| IEEE/RSJ Intl. Conference on Intelligent Robots and Systems (IROS) | 2024 |
| IEEE RAS/EMBS Intl. Conference on Biomedical Robotics & Biomechatronics (BioRob) | 2022, 2024 |
| IEEE Transactions on Medical Robotics and Bionics (T-MRB) | 2023 |
| Scientific Reports | 2022, 2023 |
| IEEE Intl. Conference on Robot and Human Interactive Communication (RO-MAN) | 2022, 2023 |
| IEEE Intl. Conference on Rehabilitation Robotics (ICORR) | 2022 |
| IEEE Intl. Conference on Robotics and Automation (ICRA) | 2021, 2022 |
| IEEE Robotics and Automation Letters (RA-L) | 2021, 2022 |
| IEEE Transactions on Neural Systems and Rehabilitation Engineering (TNSRE) | 2020 |

Science Volunteering and Outreach

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|---|------------------|
| Question Reviewer, U.S. Dept. of Energy National Science Bowl (NSB) | 2023, 2024 |
| Volunteer / Paper Reviewer, Research Science Institute (RSI) at MIT | 2015, 2018, 2024 |
| Columbia Engineering Achievers in Graduate Education (EngAGE) – Invited Panelist | Mar. 2024 |
| Columbia WISC STEM Field Exploration Fair – Invited Panelist, “Behind the Lab Scenes” | Apr. 2022 |
| Judge, Kentucky Science and Engineering Fair | 2021 |
| Judge, MIT Mechanical Engineering Research Exhibition | 2020 |
| Question Writer, USA Biolympiad (USABO) | 2019 |
| Volunteer, Adaptive Climbing Group NY | 2019 |
| Judge, Sweden Research Academy for Young Scientists (RAYS) | 2015 |

PREVIOUS POSITIONS

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|---|------------------------|
| Harvard Dept. of Organismic & Evolutionary Biology, Shamble Lab | 2017 – 2019 |
| Research Assistant with Dr. Paul Shamble | |
| <i>Studied jumping dynamics and mid-air silk production of jumping spiders [J.1]</i> | |
| Dephy, Inc. | Summer 2017, Fall 2018 |
| Mechanical Engineering Intern | |
| <i>Designed and built validation equipment for full-system stress testing</i> | |
| MIT Media Lab, Biomechatronics Group | 2013 – 2017 |
| Undergraduate Researcher with Dr. Hugh Herr, Arthur Petron, and Matt Carney | |
| <i>Worked on FitSocket project for soft-tissue characterization and on active motor cooling [T.1]</i> | |
| Apple Inc. | Summer 2016 |
| Product Design Validation Engineer Intern | |
| <i>Worked on design, usability, and validation for mechanical features in hardware products</i> | |
| Formlabs | Summer 2015 |
| Mechanical Engineering Intern | |
| <i>Electromechanical design for early versions of Form 2 and Form Cure products</i> | |
| Brain Power, LLC | Winter 2015 |
| Hardware Intern | |
| <i>Hardware development of Google Glass applications for users with autism</i> | |
| Cardiovascular Innovation Institute & Christine M. Kleinert Institute | 2012 – 2013 |
| Research Intern with Dr. Nolan Boyd and Dr. Christina Kaufman | |
| <i>Worked on tissue self-assembly using adipose stromal vascular fraction</i> | |
| Research Science Institute (RSI) at MIT | Summer 2012 |
| Summer Scholar with Arthur Petron | |
| <i>Worked on electromechanical designs for a variable spring stiffness emulator</i> | |

SIDE PROJECTS

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| Untethered Gait Tracking for Rehabilitation | 2018 – 2019 |
| <i>Collaboration with FIGUR8, Inc. to use their wearables platform for monitoring gait trends during self recovery & long-term effects of rehabilitation post knee-reconstruction surgery.</i> | |
| MIT East Campus Roller Coaster | 2015 |
| <i>Formed and led team of students to complete \$15,000 construction project in 8 days.</i> | |
| <i>Unofficial Guinness World Record holder for Steepest Wooden Roller Coaster.</i> | |
| More documentation on personal projects at https://www.avamakesthings.com | |