Proposed problems for the IMC 2025

Problem 1 (Alex Avdiushenko, Neapolis University Paphos, Cyprus). Find all strictly monotonic functions $f : \mathbb{R} \to \mathbb{R}$ such that

$$f(x) f^{-1}(x) = x^2$$
.

Solution.

1. Value at the origin. Substituting x = 0 into equation gives

$$f(0) f^{-1}(0) = 0.$$

If $f(0) \neq 0$ then $f^{-1}(0) = 0$; applying f to both sides forces f(0) = 0 — a contradiction. Hence

$$f(0) = 0 \tag{1}$$

2. It is clear that either there exists an a such that f(a) = ka with $k \neq 1$, or else $\forall x f(x) = x$. Substituting x = ka into the given equation yields $f(ka) = k^2a$. Proceeding by induction, one easily shows that

$$f(k^n a) = k^{n+1} a \qquad (n \in \mathbb{Z}_{>0}).$$

Now take a number x lying between a and f(a) = ka and set f(x) = lx. By monotonicity, the value $f^n(x)$ lies between $f^n(a)$ and $f^{n+1}(a)$. In other words, the number l^nx is always situated between k^na and $k^{n+1}a$, whence it follows that l = k.

3. Because f is a strictly monotonic bijection, every real number lies between some (forward or backward) iterate of a and f(a) = ka; thus

$$f(x) \equiv k \, x$$

4. Verification. For f(x) = kx we have $f^{-1}(x) = x/k$, hence

$$f(x) f^{-1}(x) = (kx) \left(\frac{x}{k}\right) = x^2.$$

If k > 0 the function is strictly increasing; if k < 0 it is strictly decreasing, fulfilling the monotonicity requirement.

Problem 2 (Alex Avdiushenko, Neapolis University Paphos, Cyprus). Find all continuous functions $f : \mathbb{R} \to \mathbb{R}$ such that, for every $x, y \in \mathbb{R}$,

$$(x-y) f(x+y) = (x+y) (f(x) - f(y)).$$

Solution. Answer: $ax^2 + bx$.

1. f(0) = 0. Put y = 0 in the equation:

$$x f(x) = x(f(x) - f(0)) \implies f(0) = 0.$$

2. Consider the three special pairs (1, z), (1, z + 1), (2, z):

Fix $z \in \mathbb{R} \setminus \{0, 1, 2\}$. Using original equation with the pairs listed, we successively get

$$(1,z): f(1+z) = \frac{1+z}{1-z}f(1) - \frac{1+z}{1-z}f(z),$$

$$(1,z+1): f(z+2) = -\frac{2+z}{z}f(1) + \frac{2+z}{z}f(z+1),$$

$$(2,z): f(z+2) = \frac{2+z}{2-z}f(2) - \frac{2+z}{2-z}f(z).$$

Substituting the first line into the second yields

$$f(z+2) = \frac{2+z}{z} \left(-f(1) + \frac{1+z}{1-z} f(1) - \frac{1+z}{1-z} f(z) \right) =$$

$$= \frac{2+z}{z} \left(\frac{2z}{1-z} f(1) - \frac{1+z}{1-z} f(z) \right) =$$

$$= \frac{2(2+z)}{z(1-z)} f(1) - \frac{(2+z)(1+z)}{z(1-z)} f(z)$$
(3)

3. Using the third line (for (2, z)) and (3), we get

$$f(z+2) = \frac{2+z}{2-z} f(2) - \frac{2+z}{2-z} f(z) = \frac{2(2+z)}{z(1-z)} f(1) - \frac{(2+z)(1+z)}{z(1-z)} f(z)$$
we reduce $(2+z)$

$$\frac{1}{2-z} f(2) - \frac{1}{2-z} f(z) = \frac{2}{z(1-z)} f(1) - \frac{1+z}{z(1-z)} f(z)$$
and group $f(z)$

$$\left(\frac{1+z}{z(1-z)} - \frac{1}{2-z}\right) f(z) = \frac{2}{z(1-z)} f(1) - \frac{1}{2-z} f(2)$$
and multiply $z(1-z)(2-z)$

$$((1+z)(2-z) - z(1-z)) f(z) = 2(2-z) f(1) - z(1-z) f(2)$$

$$2f(z) = 2(2-z) f(1) - z(1-z) f(2)$$

$$f(z) = 2 f(1) - z \left(f(1) + \frac{f(2)}{2}\right) + \frac{z^2}{2} f(2)$$

4. That is, the function can only be quadratic, and f(0) = 0, and therefore $f(x) = ax^2 + bx$, which, as can and should be verified, satisfies the original equation.

Remark. In a similar way it can be calculated that f(z+2) - 2f(z+1) + f(z) = 0, which is discrete analogue of "second derivative = 0".

Problem 3 (Alex Avdiushenko, Neapolis University Paphos, Cyprus). Let $P, Q, R \in O(3)$ be real orthogonal 3×3 matrices, i.e. $P^{\mathsf{T}}P = Q^{\mathsf{T}}Q = R^{\mathsf{T}}R = I_3$.

Show that the matrix equation

$$P + Q = R$$

has no solutions in O(3).

Solution. Assume, for contradiction, that $P, Q, R \in O(3)$ satisfy P + Q = R.

1. Reduce to one orthogonal matrix. Set

$$S := P^{\mathsf{T}}Q \in O(3), \qquad Q = PS, \qquad R = P(I_3 + S).$$

2. Orthogonality of R. Because R is orthogonal,

$$I_3 = R^{\mathsf{T}}R = (I_3 + S)^{\mathsf{T}}(I_3 + S) = I_3 + S^{\mathsf{T}} + S + S^{\mathsf{T}}S = I_3 + S^{\mathsf{T}} + S + I_3,$$

whence

$$S + S^{\mathsf{T}} = -I_3$$

3. Minimal polynomial of S. Multiplying the last identity on the left by S gives

$$S^2 + S + I_3 = 0.$$

Hence every eigenvalue λ of S satisfies $\lambda^2 + \lambda + 1 = 0$, i.e.

$$\lambda = \exp(\pm 2\pi i/3)$$
 (non-real)

- 4. Dimension parity contradiction. For a real matrix, non-real eigenvalues occur in complex-conjugate pairs; thus a real 3×3 matrix with only non-real eigenvalues cannot exist (the dimension is odd). Therefore such an $S \in O(3)$ does not exist.
- **5. Conclusion.** Since S cannot exist, neither can a triple $(P, Q, R) \in O(3)^3$ with P + Q = R. Hence the equation admits no solutions in O(3).

Remark. The same argument generalises to any dimension n. If an orthogonal matrix $S \in O(n)$ satisfies $S + S^{\mathsf{T}} = -I_n$, then it obeys the polynomial identity $S^2 + S + I_n = 0$; hence its eigenvalues are the two complex cubic roots of unity

$$\lambda = \exp(\pm 2\pi i/3),$$

which are non-real. Because complex eigenvalues of a real matrix occur in conjugate pairs, such an S can exist only when the dimension n is even.

Consequently, the n=2 construction based on a 120° rotation extends to every even dimension by taking block-diagonal (direct sum) copies of the 2×2 block, whereas for every odd n no orthogonal matrices P, Q, R satisfy P+Q=R.