# Hawaiian SFPW movement analysis

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#### Introduction

This workshop is an introduction to the use of the crawl package to predict individual movement paths from the posterior distribution of a correlated random walk model. Using the model fits, we can calculate utilization distributions for comparison with environmental variables.

#### Data included

Tag data from 2 short-finned pilot whales tagged near Maui. The data set includes latitude, longitude, location quality and datetime. The last column was modified from date and time columns to be understood in the R environment.

### Data plot

Using leaflet, an interactive plot of the data for two individuals.

#### Crawl model fit

##

##

For each individual, fit a correlated random walk model to the data and estimate parameters a and P.

## -					
##	term	estimate	std.error		
## - ##	ln tau 1c943			4.39	5.121
## ##	ln tau 1c942	6.275	0.126	6.028	6.523
## ##	ln tau lc941	6.666	0.134	6.403	6.929
## ##	ln tau 1c940	7.68	0.158	7.371	7.99
## ##	ln tau lc94A	8.071	0.184	7.71	8.431
## ##	ln tau 1c94B	7.672	0.212	7.257	8.087
## ## 1:	n sigma (Intercept)	4.262	0.052	4.16	4.364
## ## 1:	n beta (Intercept)	-8.37	0.246	-8.851	-7.889
## ##	logLik	-4376	NA	NA	NA
## ##	AIC	8768	NA	NA	NA
## -					

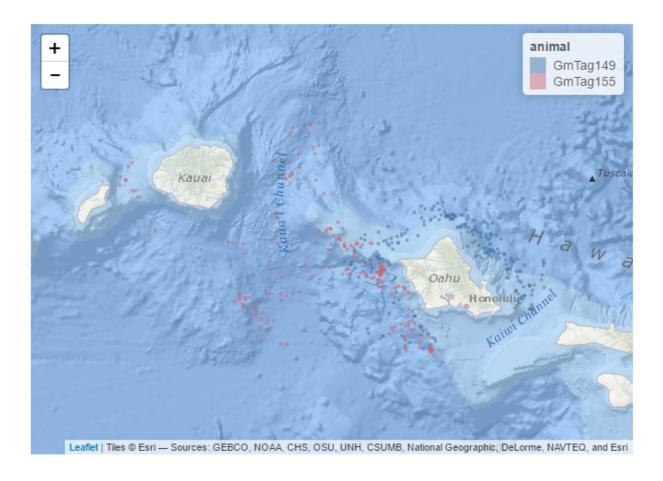


Figure 1:

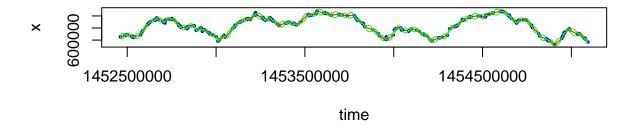
##	Table: crwMLE fit parameters						
## ##							
##	term	estimate	std.error	conf.low	conf.high		
##	ln tau 1c943						
## ##	ln tau 1c942	6.119	0.157	5.81	6.427		
## ##	ln tau lc941	7.214	0.137	6.944	7.483		
## ##	ln tau 1c940	7.841	0.163	7.521	8.161		
##							
##				7.396			
## ##	ln tau 1c94B	8.103	0.177	7.756	8.45		
## ##	<pre>ln sigma (Intercept)</pre>	4.273	0.059	4.158	4.388		
	<pre>ln beta (Intercept)</pre>	-7.979	0.244	-8.457	-7.501		
##	logLik	-3500	NA	NA	NA		
## ##	AIC	7015	NA	NA	NA		
##							

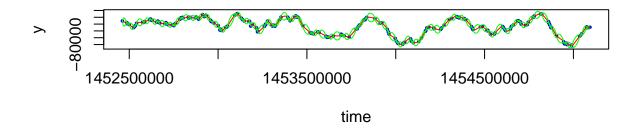
## Table: crwMLE fit parameters

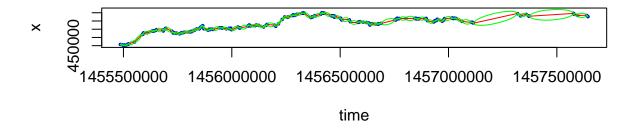
## Predicted paths

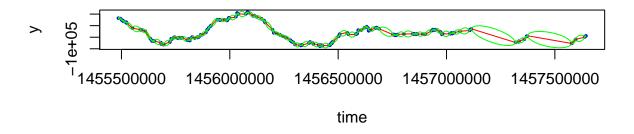
##

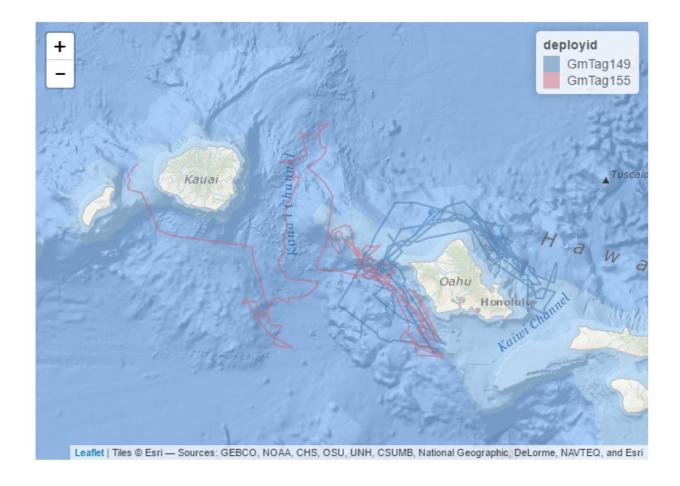
Using the fit parameters, predict the most likely paths for two animals. The below graphs show the estimated  $\mathbf{x}$  and  $\mathbf{y}$  track for each individual, and then a final map pulling all the data together.











## Simulate error in track prediction

Use the posterior distributin of the model to generate N simulated tracks Create and map simulated tracks from posterior distribution using crawlr.

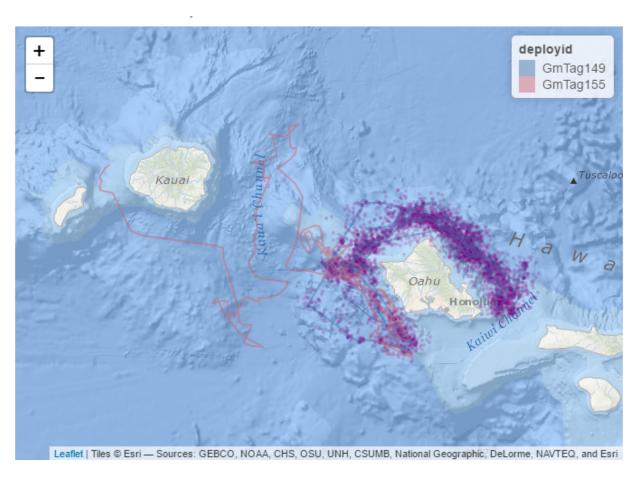


Figure 2: