Recorded at time: 34.123 map Broadcaster: /hector_mapping Broadcaster: /hector_mapping Average rate: 27.373 Hz Average rate: 27.373 Hz Most recent transform: 33.861 (0.262 sec old) Most recent transform: 33.861 (0.262 sec old) Buffer length: 2.265 sec Buffer length: 2.265 sec world scanmatcher frame Broadcaster: /ground_truth_to_tf Average rate: 100.420 Hz Most recent transform: 34.101 (0.022 sec old) Buffer length: 2.380 sec base_footprint Broadcaster: /ground_truth_to_tf Average rate: 100.420 Hz Most recent transform: 34.101 (0.022 sec old) Buffer length: 2.380 sec base_stabilized Broadcaster: /ground_truth_to_tf Average rate: 100.420 Hz Most recent transform: 34.101 (0.022 sec old) Buffer length: 2.380 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.420 Hz Average rate: 50.420 Hz Average rate: 50.420 Hz Most recent transform: 34.620 (-0.497 sec old) Most recent transform: 34.620 (-0.497 sec old) Most recent transform: 34.620 (-0.497 sec old) Buffer length: 2.380 sec Buffer length: 2.380 sec Buffer length: 2.380 sec front_cam_link laser0_frame sonar_link Broadcaster: /robot_state_publisher Average rate: 50.420 Hz Most recent transform: 34.620 (-0.497 sec old) Buffer length: 2.380 sec front_cam_optical_frame

view_frames Result