

Ashutosh Mukherjee

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[Projects Website](#)

[Github](#)

Education

10/2021 – 04/2024	M.Sc. Computer-Aided Conception of Machines in Mechanical Engineering <i>RWTH Aachen</i>	CGPA : 1,6
08/2016 – 06/2020	B.Tech in Mechanical Engineering <i>Punjab Engineering College, Chandigarh</i>	CGPA : 8.3/10

Work Experience

Master Thesis Student/Working Student **October 2023 - Ongoing**
Rheinmetall Technology Centre - New Technologies, Rheinmetall AG, Neuss, Germany

Distributed Data-Fusion and Control over a network of Unmanned Aerial Vehicles

- Development of a localization algorithm for a swarm of GPS-denied UAVs using Ultra-wideband (UWB) sensors and embedding the developed localization algorithm into *Arducopter*, an open-source auto-pilot for UAVs, in order to facilitate verification of the algorithm through flight tests.
- Development of a simulation model of an integrated flight control system for a single UAV, including a flight controller, 6 degree-of-freedom UAV dynamic model, IMU, Magnetometer, Barometer and GPS sensor models and an Extended Kalman Filter for attitude estimation.

Werkstudent (Working Student) **June 2022 - September 2023**
Rheinmetall Technology Centre - New Technologies, Rheinmetall AG, Neuss, Germany

- Development of a mathematical model for the force analysis of a flexible electrostatic synchronous actuator based on the concept of *Method of Moments*, a discretization technique for electric fields.
- Maintenance of the developed mathematical model code-base, making use of software engineering principles like object orientation, version control and comprehensive code documentation

Project Assistant **October 2022 - April 2023**
Institut für Getriebetechnik, Maschinendynamik und Robotik (IGMR), RWTH Aachen

- Development of a virtual control system to stabilize the multi-body model of a standard mountain bike being excited by external loads measured by sensors fitted on the bike.
- The work in this project culminated in a [mini-thesis](#) worth 9 ECTS.

Research Assistant **September 2020 - July 2021**
Thapar Institute of Engineering and Technology, Patiala, India

- Reduced-order dynamic modeling of a strength augmentation exoskeleton designed by [Defence Bio-Engineering and Electro-Medical Laboratory](#) (DEBEL), India and development of a *Computed Torque Control* algorithm for strength augmentation.
- All published work output from this project can be referred from *Conference Presentations and Publications* section.

- Teaching Assistant for the graduate level course *Modern Control of Dynamic Systems*, which covers basic and advanced topics in linear systems theory like state-space representations, canonical forms, controller and observer design using pole-placement, and some concepts of optimal control theory.
- Helped set mid-term examinations and quizzes, and grade them as part of assistantship duties.

Technical Skills

Programming	Computational Techniques
<ol style="list-style-type: none"> Scripting Languages <ul style="list-style-type: none"> • MATLAB & Simulink • Python Programming Languages <ul style="list-style-type: none"> • C++ • Java General <ul style="list-style-type: none"> • Object-Oriented Programming • Version Control using Git 	<ol style="list-style-type: none"> 1. State Estimation using Extended-Kalman Filters 2. Strapdown Algorithms for Inertial Navigation 3. Sensor Fusion 4. Sensor Noise Parameter Identification using Allan-Deviation Analysis 5. Unconstrained Non-linear Optimization using Gauß-Newton and Quasi-Newton methods 6. Regression and Classification using Neural Networks 7. Multi-Body Dynamics 8. Finite Element Analysis 9. Method of Moments in Electrostatics

Conference Presentations and Publications

1. Chander, S., Mukherjee, Shivling, V.D., and Singla, A. (June 24, 2024). Enhanced Euler-Lagrange Formulation for Analyzing Human Gait with Moving Base Reference, *ASME Journal of Mechanisms and Robotics*. January 2025; 17(1): 011006, [DOI](#), [PDF](#).
2. Chander, S., Mukherjee, A., & Singla, A. (2023, July). *Estimation of Ground Reaction Force for Coupled Dynamic Modelling and Control of the Lower-Limb Exoskeleton*, AIR 2023: Proceedings of the 2023 6th International Conference on Advances in Robotics, July 2023, Article No.: 37, Pages 1-8, [DOI](#)
3. Chander, S., Mukherjee, A., Shivling, V., & Singla, A. (2022, October 16-20). *Modelling and Validation of Human Gait Dynamics using Modified Euler-Lagrange Approach* [Paper Presentation], 6th Joint International Conference on Multibody System Dynamics and 10th Asian Conference on Multibody Dynamics, New Delhi, India, [URL](#)