

Additive Models vs Interaction models

the effect of a covariate is the impact that changing it has on the expected response.

Numeric covariate: effect is the slope parameter

factor covariate: effects are the difference in expected response from one level to another. (e.g. $b_2 - b_1$)

A model with multiple covariates is additive if the effect of each covariate does not depend on the values of the other variables

A model has an interaction between two variables if the effect of one variable depends on the value of the other.

By definition, models with interactions are not additive.

Example: additive model

factor: city (2 levels) $j(i)$

numeric: 7am temperature x_i

response: 3pm temperature y_i

model for y_i : $Y_i = b_0 + b_{j(i)} + c_0 x_i + \epsilon_i$

effect of Tam temp is c_0 :

$$\begin{aligned} E(Y_1) &= b_0 + b_1 + c_0 x_1 \\ E(Y_2) &= b_0 + b_1 + c_0 x_2 \end{aligned} \rightarrow E(Y_2) - E(Y_1) = c_0(x_2 - x_1)$$

effect of changing Tam temp by $x_2 - x_1$ is $c_0(x_2 - x_1)$
does not depend on city (same effect in both cities)

effect of city is $b_2 - b_1$:

$$\begin{aligned} E(Y_3) &= b_0 + b_1 + c_0 47 \\ E(Y_4) &= b_0 + b_2 + c_0 47 \end{aligned} \rightarrow E(Y_4) - E(Y_3) = b_2 - b_1$$

effect of changing city while holding Tam temp constant
is $b_2 - b_1$. Does not depend on value of Tam temp.

Example: interaction model

$$Y_i = b_0 + b_{j(i)} + (c_0 + c_{j(i)})x_i + \epsilon_i$$

$$\begin{aligned} E(Y_1) &= b_0 + b_1 + (c_0 + c_1)52 \\ E(Y_2) &= b_0 + b_1 + (c_0 + c_1)54 \end{aligned} \rightarrow E(Y_2) - E(Y_1) = (c_0 + c_1)(2)$$

$$\begin{aligned} E(Y_5) &= b_0 + b_2 + (c_0 + c_2)52 \\ E(Y_6) &= b_0 + b_2 + (c_0 + c_2)54 \end{aligned} \rightarrow E(Y_6) - E(Y_5) = (c_0 + c_2)(2)$$

in city 1, effect is $c_0 + c_1$

in city 2, effect is $c_0 + c_2$

$$E(Y_3) = b_0 + b_1 + (c_0 + c_1)47$$

$$E(Y_4) = b_0 + b_2 + (c_0 + c_2)47$$

$$E(Y_4) - E(Y_3) = b_2 - b_1 + (c_2 - c_1)47$$

effect of changing the city depends on Jan temp!

This example was a factor-numeric interaction model.

We can also have numeric-numeric interactions

and factor-factor interactions (2-factor interactions)

Factor-Numeric interactions

factor has J levels

$$Y_i = b_0 + b_{j(i)} + (c_0 + c_{j(i)})x_i + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} N(0, \sigma^2)$$

Each level gets its own regression line

intercept: $b_0 + b_k$

slope: $c_0 + c_k$

How many model degrees of freedom?

$(2J)$

How many mean parameters?

$(2J + 2)$

in R, default constraints are $b_1 = 0$ and $c_1 = 0$

Exercise: state the reduced model, the full model, the null hypothesis (in terms of parameters), and give the degrees of freedom in the F-test comparing the factor numeric additive model to the factor-numeric interaction model.

reduced model: $Y_i = b_0 + b_{j(i)} + c_0 x_i + \epsilon_i$

full model: $Y_i = b_0 + b_{j(i)} + (c_0 + c_{j(i)}) x_i + \epsilon_i$

$H_0: c_1 = c_2 = \dots = c_J$

numerator dof = $2J - (J+1) = J-1$

denominator dof = $n - 2J$

Factor-factor interactions

Factor 1: $j(i)$, J levels

Factor 2: $k(i)$, K levels

$$Y_i = b_0 + b_{j(i)} + c_{k(i)} + (bc)_{j(i), k(i)} + \epsilon_i$$

Example: $J=2, K=3$

		k		
		1	2	3
j	1	$b_0 + b_1 + c_1 + (bc)_{11}$	$b_0 + b_1 + c_2 + (bc)_{12}$	$b_0 + b_1 + c_3 + (bc)_{13}$
	2	$b_0 + b_2 + c_1 + (bc)_{21}$	$b_0 + b_2 + c_2 + (bc)_{22}$	$b_0 + b_2 + c_3 + (bc)_{23}$

Each of the JK possible combinations gets its own unrestricted expected value.

model dof = JK, $1 + J + K + JK$ parameters

in R, default constraint sets every parameter with a "1" subscript equal to 0.

$$b_1 = c_1 = (bc)_{11} = \dots = (bc)_{j1} = \dots = (bc)_{1K} = 0$$

		k		
		1	2	3
j	1	b_0	$b_0 + c_2$	$b_0 + c_3$
	2	$b_0 + b_2$	$b_0 + b_2 + c_2 + (bc)_{22}$	$b_0 + b_2 + c_3 + (bc)_{23}$

interactions:

i	j	k
1	1	1
2	1	2
3	2	1
4	2	2

$$E(Y_2) - E(Y_1) = c_2$$

$$E(Y_4) - E(Y_3) = c_2 + (bc)_{22}$$

$$E(Y_3) - E(Y_1) = b_2$$

$$E(Y_4) - E(Y_2) = b_2 + (bc)_{22}$$

No interaction means

$$(E(Y_4) - E(Y_2)) - (E(Y_3) - E(Y_1)) = (bc)_{22} = 0$$

"difference of differences"

Degrees of freedom:

Interaction model: JK

Additive Model: $J + K - 1$

$$\text{Difference} = JK - J - K + 1 = (J-1)(K-1)$$

	1	2	3	4	
1	*	*	*	*	
2	*				
3	*				
4	*				

} $J-1$

} $K-1$

Numeric - numeric interactions

x_{i1} - numeric covariate

x_{i2} - numeric covariate

y_i - response

$$\text{Model: } Y_i = b_0 + b_1 x_{i1} + b_2 x_{i2} + b_3 x_{i1} x_{i2} + \epsilon_i$$
$$\epsilon_i \stackrel{iid}{\sim} N(0, \sigma^2)$$

This is a multiple linear model \rightarrow define $x_{i3} = x_{i1} x_{i2}$

example

$$X = \begin{bmatrix} 1 & 3 & 5 & 15 \\ 1 & 4 & 1 & 4 \\ 1 & 7 & 8 & 56 \\ 1 & 2 & 12 & 24 \\ 1 & 6 & 1 & 6 \end{bmatrix}$$

The effect of x_{i1} depends on x_{i2} :

$$E(Y_i) = (b_0 + b_2 x_{i2}) + (b_1 + b_3 x_{i2}) x_{i1}$$

intercept: $b_0 + b_2 x_{i2}$

slope: $b_1 + b_3 x_{i2} \leftarrow \begin{matrix} \text{effect} \\ \text{depends on } x_{i2} \end{matrix}$

The effect of x_{i2} depends on x_{i1}

$$E(Y_i) = (b_0 + b_1 x_{i1}) + (b_2 + b_3 x_{i1}) x_{i2}$$

intercept: $b_0 + b_1 x_{i1}$

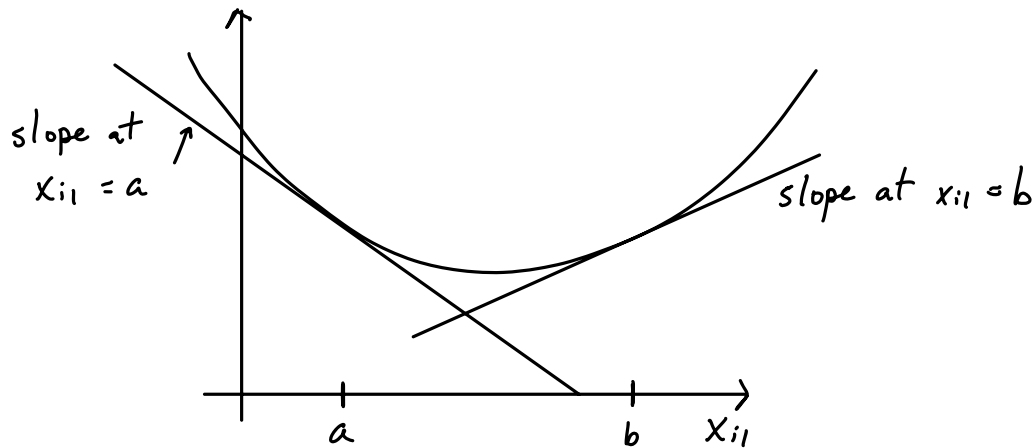
slope: $b_2 + b_3 x_{i1} \leftarrow \begin{matrix} \text{effect depends} \\ \text{on } x_{i1} \end{matrix}$

Quadratic Models

$$Y_i = b_0 + b_1 x_{i1} + b_2 x_{i1}^2 + \epsilon_i$$

this is still a multiple linear model: $x_{i2} = x_{i1}^2$

Can think of this as an interaction btw x_{i1} and x_{i1}



Interpretations

$$b_0 = E(Y_i) \text{ when } x_{i1} = 0$$

$$\frac{dE(Y_i)}{dx_{i1}} = b_1 + 2b_2 x_{i1} \quad \text{effect (slope) depends on } x_{i1}$$

$$b_1 = \text{slope at } x_{i1} = 0$$

b_2 tells us whether $E(Y_i)$ concave up or down.

$$-\frac{b_1}{2b_2} = \text{location of maximum or minimum.}$$

polynomial models:

$$Y_i = \sum_{j=0}^p b_j x_i^j + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} N(0, \sigma^2)$$

Two-variable quadratic models

$$\begin{aligned}Y_i &= b_0 + b_1 x_{i1} + b_2 x_{i2} + b_{12} x_{i1} x_{i2} + b_{11} x_{i1}^2 + b_{22} x_{i2}^2 + \epsilon_i \\&= (b_0 + b_2 x_{i2} + b_{22} x_{i2}^2) + (b_1 + b_{12} x_{i2}) x_{i1} + (b_{11}) x_{i1}^2 + \epsilon_i \\&= (b_0 + b_1 x_{i1} + b_{11} x_{i1}^2) + (b_2 + b_{12} x_{i1}) x_{i2} + (b_{22}) x_{i2}^2 + \epsilon_i\end{aligned}$$

additive in x_{i1} and x_{i2} if $b_{12} = 0$

$$Y_i = b_0 + [x_{i1} \ x_{i2}] \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} + \frac{1}{2} [x_{i1} \ x_{i2}] \begin{bmatrix} 2b_{11} & b_{12} \\ b_{12} & 2b_{22} \end{bmatrix} \begin{bmatrix} x_{i1} \\ x_{i2} \end{bmatrix} + \epsilon_i$$

can add more predictors and have quadratic model
in all variables

$$\begin{aligned}Y_i &= b_0 + \underline{x}_i^T \underline{b} + \frac{1}{2} \underline{x}_i^T B \underline{x}_i + \epsilon_i \quad [B]_{ij} = b_{ij} \\&= b_0 + \sum_{j=1}^p x_{ij} b_j + \frac{1}{2} \sum_{j=1}^p \sum_{k=1}^p x_{ij} x_{ik} b_{jk} + \epsilon_i\end{aligned}$$

Useful in situations where you want to find an
optimal \underline{x} for some process.

if B is p.d. \underline{x}^* = value that minimizes $E(Y_i)$

$$\begin{aligned}\nabla_{\underline{x}} E(Y_i) &= \underline{b} + B \underline{x} \\ \Rightarrow \underline{x}^* &= -B^{-1} \underline{b}\end{aligned}$$