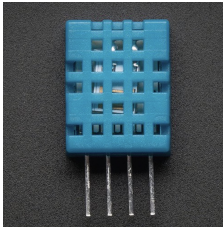


Humidity & Temperature Sensor

<https://learn.adafruit.com/dht>

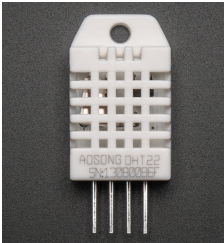
go to the left bar of this website for usage & related documents.

This sensor is super convenient!



DHT11

- Ultra low cost
- 3 to 5V power and I/O
- 2.5mA max current use during conversion (while requesting data)
- Good for 20-80% humidity readings with 5% accuracy
- Good for 0-50°C temperature readings $\pm 2^{\circ}\text{C}$ accuracy
- No more than 1 Hz sampling rate (once every second)
- Body size 15.5mm x 12mm x 5.5mm
- 4 pins with 0.1" spacing



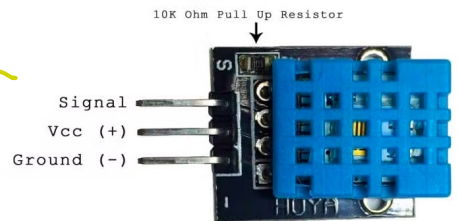
DHT22 / AM2302 (Wired version)

- Low cost
- 3 to 5V power and I/O
- 2.5mA max current use during conversion (while requesting data)
- Good for 0-100% humidity readings with 2-5% accuracy
- Good for -40 to 80°C temperature readings $\pm 0.5^{\circ}\text{C}$ accuracy
- No more than 0.5 Hz sampling rate (once every 2 seconds)
- Body size 15.1mm x 25mm x 7.7mm
- 4 pins with 0.1" spacing

Yellow line: Data out

Red line: 3.3V-5V in

Black line: GND (ground)



<https://create.arduino.cc/projecthub/pibots555/how-to-connect-dht11-sensor-with-arduino-uno-f4d239>

* Refer to the website for including the selective library and detailed usage.

Electret Microphone Amplifier

<https://www.adafruit.com/product/1063#description>

Guess we have the same manufacturer as our humidity & temp sensor. This website does not contain too much useful info though.

Using it is simple: connect GND to ground, VCC to 2.4-5VDC. For the best performance, use the "quietest" supply available (on an Arduino, this would be the 3.3V supply). The audio waveform will come out of the OUT pin. The output will have a DC bias of $VCC/2$ so when it's perfectly quiet, the voltage will be a steady $VCC/2$ volt (it is DC coupled). If the audio equipment you're using requires AC coupled audio, place a 100uF capacitor between the output pin and the input of your device. If you're connecting to an audio amplifier that has differential inputs or includes decoupling capacitors, the 100uF cap is not required.



A sample project using this microphone to detect noise level:

<https://hester.mtholyoke.edu/idesign/SensorAmp.html>

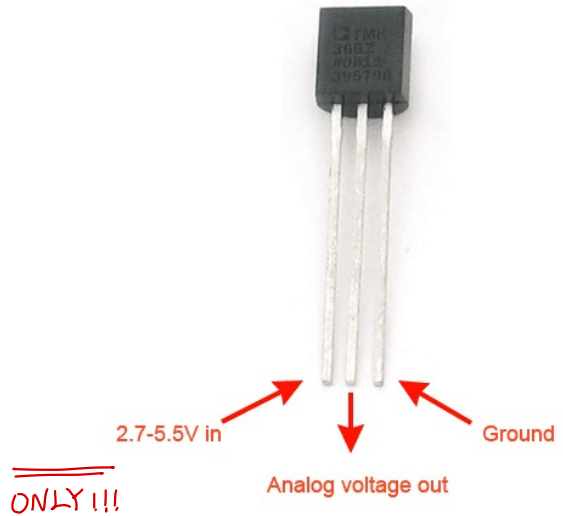
TMP36 Temperature sensor

<https://learn.adafruit.com/tmp36-temperature-sensor>

same old manufacturer! This webpage contains some VERY useful information.

Wide range, low power temperature sensor outputs an analog voltage that is proportional to the ambient temperature. To use, connect pin 1 (left) to power (between 2.7 and 5.5V), pin 3 (right) to ground, and pin 2 to analog in on your microcontroller.

The voltage out is 0V at -50°C and 1.75V at 125°C. You can easily calculate the temperature from the voltage in millivolts: $\text{Temp } ^\circ\text{C} = 100 * (\text{reading in V}) - 50$



Tutorial on how to read temperature from this sensor

using Arduino:

<https://create.arduino.cc/projecthub/ingo-lohs/temperature-sensing-with-tmp36-b51ddb>

* we will likely not utilize this sensor..

Light Dependent Resistor

<https://create.arduino.cc/projecthub/SBR/working-with-light-dependent-resistor-ldr-1ded4f>

code source



Image Source: <https://scitronics.com/?product=ldr>

```
const int LDR = A0;
int input_val = 0;

void setup()
{
  Serial.begin(9600);
}

void loop()
{
  input_val = analogRead(LDR);
  Serial.print("LDR Value is: ");
  Serial.println(input_val);
  delay(1000);
}
```

there is not a certain definitive answer to the values we will read from this sensor, so we will need to experiment & find our thresholds.

Traditionally resistance increases when brightness decreases. So the brightness is proportionally related to the current going through the LDR.

PIR Motion Sensor

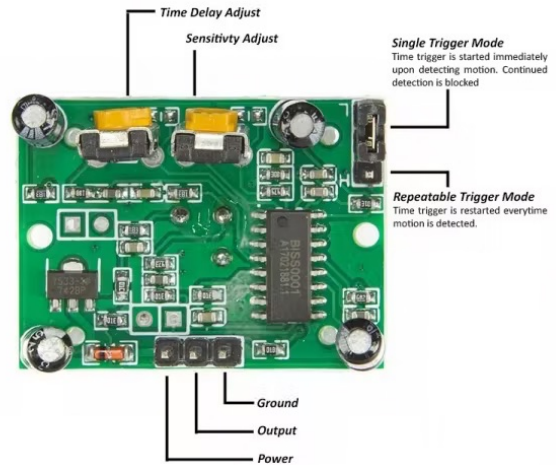
<https://electropeak.com/pir-motion-sensor>

Passive Infra Red sensors can detect movement of objects that radiate IR light (like human bodies). Therefore, using these sensors to detect human movement or occupancy in security systems is very common.

For proper calibration, there should not be any movement in front of the PIR sensor for up to 15 seconds (until pin 13 is turned off).

Source:

<https://create.arduino.cc/projecthub/electropeak/pir-motion-sensor-how-to-use-pirs-w-arduino-raspberry-pi-18d7fa>



It uses `digitalRead(pin-number)` to see if any one passed by. When it is equal to HIGH, the sensor detects activities and vice versa.

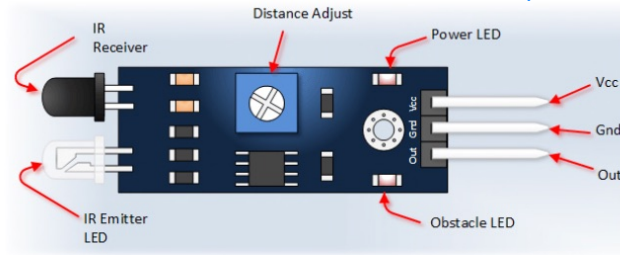
Might need to implement a few more for accurate detection of movements or population density.

Also, it is important to track frequency of human activity. See how `delay(time_in_ms)` can help with that.

IR OBSTACLE DETECTION MODULE

<https://osoyoo.com/2018/12/21/ir-obstacle-avoidance-module/>

Lots of info on manufacturers website



Pin, Control Indicator

Vcc
Gnd
Out
Power LED
Obstacle LED
Distance Adjust
IR Emitter
IR Receiver

Description

3.3 to 5 Vdc Supply Input
Ground Input
Output that goes low when obstacle is in range
Illuminates when power is applied
Illuminates when obstacle is detected
Adjust detection distance. CCW decreases distance.
CW increases distance.
Infrared emitter LED
Infrared receiver that receives signal transmitted by Infrared emitter.

can be used to see if the sensors are being blocked by objects that might disrupt its normal functionalities.

According to the website:

- threshold adjusted by a potentiometer
- Uses `digitalRead (pin-number)`
- reads `LOW` when obstacle detected.

should maybe implement a delay (time-in-ms) as well to see if the obstacle is persistent.