

# Local characterization of tangent plans that are martingale plans

Averil Aussedat  
Post-doc at University of Pisa

November 19, 2025  
NewOT Workshop, Orsay



UNIVERSITÀ DI PISA

# Table of Contents

Centred measure fields

Tangent measure fields

Zajíček's theorem

Decomposition in the general case

# First notations

Let  $T\Omega = \{(x, v)\}$ , with  $x \in \Omega = \mathbb{R}^d$ , and  $v \in T_x\Omega \sim \mathbb{R}^d$ .

# First notations

Let  $T\Omega = \{(x, v)\}$ , with  $x \in \Omega = \mathbb{R}^d$ , and  $v \in T_x\Omega \sim \mathbb{R}^d$ . Fix  $\mu \in \mathcal{P}_2(\Omega)$ , and denote

$$\mathcal{P}_2(T\Omega)_\mu := \{\xi \in \mathcal{P}_2(T\Omega) \mid \pi_{x\#}\xi = \mu\}.$$

Any  $\xi \in \mathcal{P}_2(T\Omega)_\mu$  can be disintegrated as  $\xi = \xi_x \otimes \mu$ , called “measure field” instead of “vector field”.

# First notations

Let  $T\Omega = \{(x, v)\}$ , with  $x \in \Omega = \mathbb{R}^d$ , and  $v \in T_x\Omega \sim \mathbb{R}^d$ . Fix  $\mu \in \mathcal{P}_2(\Omega)$ , and denote

$$\mathcal{P}_2(T\Omega)_\mu := \{\xi \in \mathcal{P}_2(T\Omega) \mid \pi_{x\#}\xi = \mu\}.$$

Any  $\xi \in \mathcal{P}_2(T\Omega)_\mu$  can be disintegrated as  $\xi = \xi_x \otimes \mu$ , called “measure field” instead of “vector field”.

**Definition –  $L_\mu^2$ –like distance on  $\mathcal{P}_2(T\Omega)_\mu$**  For any  $\xi, \zeta \in \mathcal{P}_2(T\Omega)_\mu$ , let

$$W_\mu^2(\xi, \zeta) := \int_{x \in \Omega} W^2(\xi_x, \zeta_x) d\mu(x).$$

# First notations

Let  $T\Omega = \{(x, v)\}$ , with  $x \in \Omega = \mathbb{R}^d$ , and  $v \in T_x \Omega \sim \mathbb{R}^d$ . Fix  $\mu \in \mathcal{P}_2(\Omega)$ , and denote

$$\mathcal{P}_2(T\Omega)_\mu := \{\xi \in \mathcal{P}_2(T\Omega) \mid \pi_{x\#}\xi = \mu\}.$$

Any  $\xi \in \mathcal{P}_2(T\Omega)_\mu$  can be disintegrated as  $\xi = \xi_x \otimes \mu$ , called “measure field” instead of “vector field”.

**Definition –  $L^2_\mu$ –like distance on  $\mathcal{P}_2(T\Omega)_\mu$**  For any  $\xi, \zeta \in \mathcal{P}_2(T\Omega)_\mu$ , let

$$W_\mu^2(\xi, \zeta) := \int_{x \in \Omega} W^2(\xi_x, \zeta_x) d\mu(x).$$

$W_\mu$  comes with its “scalar product”

$$\langle \xi, \zeta \rangle_\mu := \frac{1}{2} [W_\mu^2(\xi, 0_\mu) + W_\mu^2(\zeta, 0_\mu) - W_\mu^2(\xi, \zeta)] = \int_{x \in \Omega} \sup_{\alpha_x \in \Gamma(\xi_x, \zeta_x)} \int_{(v, w)} \langle v, w \rangle d\alpha_x(v, w) d\mu(x).$$

# Some literature on this pseudo-Hilbertian structure

- Introduced in [AGS05]<sup>1</sup> and [Gig08]<sup>2</sup> along with a scalar multiplication and a set-valued sum.

<sup>1</sup>L. Ambrosio, N. Gigli, and G. Savaré, *Gradient Flows* (2005).

<sup>2</sup>N. Gigli, "On the geometry of the space of probability measures endowed with the quadratic optimal transport distance" (2008).

# Some literature on this pseudo-Hilbertian structure

- Introduced in [AGS05]<sup>1</sup> and [Gig08]<sup>2</sup> along with a scalar multiplication and a set-valued sum.
- Appears for “generalized” subdifferentials in [AF14]<sup>3</sup> and [Ber24]<sup>4</sup>, to define viscosity solutions.

<sup>1</sup>L. Ambrosio, N. Gigli, and G. Savaré, *Gradient Flows* (2005).

<sup>2</sup>N. Gigli, “On the geometry of the space of probability measures endowed with the quadratic optimal transport distance” (2008).

<sup>3</sup>L. Ambrosio and J. Feng, “On a class of first order Hamilton–Jacobi equations in metric spaces” (2014).

<sup>4</sup>C. Bertucci, “Stochastic optimal transport and Hamilton–Jacobi–Bellman equations on the set of probability measures” (2024).

# Some literature on this pseudo-Hilbertian structure

- Introduced in [AGS05]<sup>1</sup> and [Gig08]<sup>2</sup> along with a scalar multiplication and a set-valued sum.
- Appears for “generalized” subdifferentials in [AF14]<sup>3</sup> and [Ber24]<sup>4</sup>, to define viscosity solutions.
- Appears in Measure Differential Equations ([Pic19]<sup>5</sup>, [Cam+21]<sup>6</sup>, [Sch25]<sup>7</sup>) and flows of dissipative measure fields ([CSS23a]<sup>8</sup>, [CSS23b]<sup>9</sup>), with aim to allow mass splitting.

<sup>1</sup>L. Ambrosio, N. Gigli, and G. Savaré, *Gradient Flows* (2005).

<sup>2</sup>N. Gigli, “On the geometry of the space of probability measures endowed with the quadratic optimal transport distance” (2008).

<sup>3</sup>L. Ambrosio and J. Feng, “On a class of first order Hamilton–Jacobi equations in metric spaces” (2014).

<sup>4</sup>C. Bertucci, “Stochastic optimal transport and Hamilton–Jacobi–Bellman equations on the set of probability measures” (2024).

<sup>5</sup>B. Piccoli, “Measure Differential Equations” (2019).

<sup>6</sup>F. Camilli et al., “Superposition principle and schemes for Measure Differential Equations” (2021).

<sup>7</sup>A. Schichl, *Non-linear degenerate parabolic flow equations and a finer differential structure on Wasserstein spaces* (2025).

<sup>8</sup>G. Cavagnari, G. Savaré, and G. E. Sodini, *A Lagrangian approach to totally dissipative evolutions in Wasserstein spaces* (2023).

<sup>9</sup>G. Cavagnari, G. Savaré, and G. E. Sodini, “Dissipative probability vector fields and generation of evolution semigroups in Wasserstein spaces” (2023).

# Some literature on this pseudo-Hilbertian structure

- Introduced in [AGS05]<sup>1</sup> and [Gig08]<sup>2</sup> along with a scalar multiplication and a set-valued sum.
- Appears for “generalized” subdifferentials in [AF14]<sup>3</sup> and [Ber24]<sup>4</sup>, to define viscosity solutions.
- Appears in Measure Differential Equations ([Pic19]<sup>5</sup>, [Cam+21]<sup>6</sup>, [Sch25]<sup>7</sup>) and flows of dissipative measure fields ([CSS23a]<sup>8</sup>, [CSS23b]<sup>9</sup>), with aim to allow mass splitting.
- Recent work [LTD24]<sup>10</sup> providing KKT conditions.

<sup>1</sup>L. Ambrosio, N. Gigli, and G. Savaré, *Gradient Flows* (2005).

<sup>2</sup>N. Gigli, “On the geometry of the space of probability measures endowed with the quadratic optimal transport distance” (2008).

<sup>3</sup>L. Ambrosio and J. Feng, “On a class of first order Hamilton–Jacobi equations in metric spaces” (2014).

<sup>4</sup>C. Bertucci, “Stochastic optimal transport and Hamilton–Jacobi–Bellman equations on the set of probability measures” (2024).

<sup>5</sup>B. Piccoli, “Measure Differential Equations” (2019).

<sup>6</sup>F. Camilli et al., “Superposition principle and schemes for Measure Differential Equations” (2021).

<sup>7</sup>A. Schichl, *Non-linear degenerate parabolic flow equations and a finer differential structure on Wasserstein spaces* (2025).

<sup>8</sup>G. Cavagnari, G. Savaré, and G. E. Sodini, *A Lagrangian approach to totally dissipative evolutions in Wasserstein spaces* (2023).

<sup>9</sup>G. Cavagnari, G. Savaré, and G. E. Sodini, “Dissipative probability vector fields and generation of evolution semigroups in Wasserstein spaces” (2023).

<sup>10</sup>N. Lanzetti, A. Terpin, and F. Dörfler, *Variational Analysis in the Wasserstein Space* (2024).

# Orthogonality

If  $\xi = (id, f)_\# \mu$  for some  $f \in L^2_\mu(\Omega; \mathbb{R}^d)$ , then  $\xi_x = \delta_{f(x)}$ , so that

$$\langle \xi, \zeta \rangle_\mu = \int_{x \in \Omega} \int_w \langle f(x), w \rangle d\zeta_x(w) d\mu(x) = \langle f, \text{Bary}(\zeta) \rangle_{L^2_\mu}.$$

# Orthogonality

If  $\xi = (id, f)_\# \mu$  for some  $f \in L^2_\mu(\Omega; \mathbb{R}^d)$ , then  $\xi_x = \delta_{f(x)}$ , so that

$$\langle \xi, \zeta \rangle_\mu = \int_{x \in \Omega} \int_w \langle f(x), w \rangle d\zeta_x(w) d\mu(x) = \langle f, \text{Bary}(\zeta) \rangle_{L^2_\mu}.$$

**Observation**  $\mathcal{P}_2(T\Omega)_\mu$  splits orthogonally into

- the set of  $\xi$  that are induced by a map,
- the set of  $\xi$  with barycenter 0, noted  $\mathcal{P}_2(T\Omega)_\mu^0$ .

$\text{Bary}(\xi) = 0$  iff  $(\pi_x, \pi_x + \pi_v)_\# \xi$  is a “martingale plan”.

# Orthogonality

If  $\xi = (id, f)_\# \mu$  for some  $f \in L^2_\mu(\Omega; \mathbb{R}^d)$ , then  $\xi_x = \delta_{f(x)}$ , so that

$$\langle \xi, \zeta \rangle_\mu = \int_{x \in \Omega} \int_w \langle f(x), w \rangle d\zeta_x(w) d\mu(x) = \langle f, \text{Bary}(\zeta) \rangle_{L^2_\mu}.$$

**Observation**  $\mathcal{P}_2(T\Omega)_\mu$  splits orthogonally into

- the set of  $\xi$  that are induced by a map,
- the set of  $\xi$  with barycenter 0, noted  $\mathcal{P}_2(T\Omega)_\mu^0$ .

On  $\mathcal{P}_2(T\Omega)_\mu^0$ , very strong property:

$$\langle \xi, \zeta \rangle_\mu = 0$$

if and only if  $\langle \xi_x, \zeta_x \rangle_{\delta_x} = 0$  for  $\mu$ -a.e.  $x$ .

$\text{Bary}(\xi) = 0$  iff  $(\pi_x, \pi_x + \pi_v)_\# \xi$  is a “martingale plan”.

# Orthogonality

If  $\xi = (id, f)_\# \mu$  for some  $f \in L^2_\mu(\Omega; \mathbb{R}^d)$ , then  $\xi_x = \delta_{f(x)}$ , so that

$$\langle \xi, \zeta \rangle_\mu = \int_{x \in \Omega} \int_w \langle f(x), w \rangle d\zeta_x(w) d\mu(x) = \langle f, \text{Bary}(\zeta) \rangle_{L^2_\mu}.$$

**Observation**  $\mathcal{P}_2(T\Omega)_\mu$  splits orthogonally into

- the set of  $\xi$  that are induced by a map,
- the set of  $\xi$  with barycenter 0, noted  $\mathcal{P}_2(T\Omega)_\mu^0$ .

On  $\mathcal{P}_2(T\Omega)_\mu^0$ , very strong property:

$$\langle \xi, \zeta \rangle_\mu = 0$$

if and only if  $\langle \xi_x, \zeta_x \rangle_{\delta_x} = 0$  for  $\mu$ -a.e.  $x$ .

$\text{Bary}(\xi) = 0$  iff  $(\pi_x, \pi_x + \pi_v)_\# \xi$  is a “martingale plan”.

*For centred fields, orthogonality is a local phenomenon.*

# Closed convex cone of centred fields

**Theorem [Aus25]<sup>1</sup>** Let  $A \subset \mathcal{P}_2(\mathbb{T}\Omega)_\mu^0$  be a  $W_\mu$ -closed nonnegative cone, which is convex along interpolation through any plan respecting the fibers.

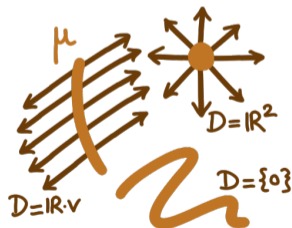


<sup>1</sup>A. Aussadat, *Local structure of centred tangent cones in the Wasserstein space* (2025). [ArXiv preprint, same as in the rest of the talk]

# Closed convex cone of centred fields

**Theorem [Aus25]<sup>1</sup>** Let  $A \subset \mathcal{P}_2(T\Omega)_\mu^0$  be a  $W_\mu$ -closed nonnegative cone, which is convex along interpolation through any plan respecting the fibers. Then there exists a measurable application  $D$  such that  $D(x)$  is a vector space, and

$$\xi \in A \quad \Longleftrightarrow \quad [\xi \text{ is centred and } v \in D(x) \text{ for } \xi - \text{almost any } (x, v).]$$

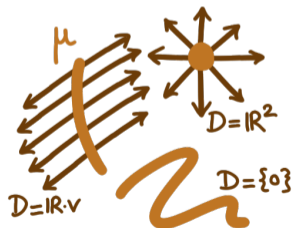


<sup>1</sup>A. Aussadat, *Local structure of centred tangent cones in the Wasserstein space* (2025). [ArXiv preprint, same as in the rest of the talk]

# Closed convex cone of centred fields

**Theorem [Aus25]<sup>1</sup>** Let  $A \subset \mathcal{P}_2(T\Omega)_\mu^0$  be a  $W_\mu$ -closed nonnegative cone, which is convex along interpolation through any plan respecting the fibers. Then there exists a measurable application  $D$  such that  $D(x)$  is a vector space, and

$$\xi \in A \quad \Longleftrightarrow \quad [\xi \text{ is centred and } v \in D(x) \text{ for } \xi - \text{almost any } (x, v).]$$



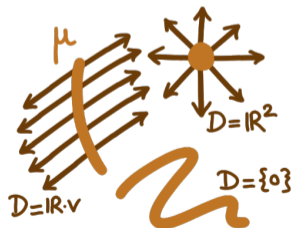
- Proved by passing to the orthogonal complement and exploiting the geometry induced by  $\langle \cdot, \cdot \rangle_\mu$ .

<sup>1</sup>A. Aussadat, *Local structure of centred tangent cones in the Wasserstein space* (2025). [ArXiv preprint, same as in the rest of the talk]

# Closed convex cone of centred fields

**Theorem [Aus25]<sup>1</sup>** Let  $A \subset \mathcal{P}_2(\mathbb{T}\Omega)_\mu^0$  be a  $W_\mu$ -closed nonnegative cone, which is convex along interpolation through any plan respecting the fibers. Then there exists a measurable application  $D$  such that  $D(x)$  is a vector space, and

$$\xi \in A \quad \Longleftrightarrow \quad [\xi \text{ is centred and } v \in D(x) \text{ for } \xi - \text{almost any } (x, v).]$$



- Proved by passing to the orthogonal complement and exploiting the geometry induced by  $\langle \cdot, \cdot \rangle_\mu$ .
- Starts with a “nonnegative cone”, ends with a “two-sided cone”.

<sup>1</sup>A. Aussadat, *Local structure of centred tangent cones in the Wasserstein space* (2025). [ArXiv preprint, same as in the rest of the talk]

# Closed convex cone of centred fields

**Theorem [Aus25]<sup>1</sup>** Let  $A \subset \mathcal{P}_2(\mathbb{T}\Omega)_\mu^0$  be a  $W_\mu$ -closed nonnegative cone, which is convex along interpolation through any plan respecting the fibers. Then there exists a measurable application  $D$  such that  $D(x)$  is a vector space, and

$$\xi \in A \quad \Longleftrightarrow \quad [\xi \text{ is centred and } v \in D(x) \text{ for } \xi - \text{almost any } (x, v).]$$



- Proved by passing to the orthogonal complement and exploiting the geometry induced by  $\langle \cdot, \cdot \rangle_\mu$ .
- Starts with a “nonnegative cone”, ends with a “two-sided cone”.
- Proves convexity as measures.

<sup>1</sup>A. Aussadat, *Local structure of centred tangent cones in the Wasserstein space* (2025). [ArXiv preprint, same as in the rest of the talk]

# Table of Contents

Centred measure fields

Tangent measure fields

Zajíček's theorem

Decomposition in the general case

# Centred tangent fields

**Definition – Geometric tangent cone [Gig08]<sup>1</sup>**  $\text{Tan}_\mu$  is the  $W_\mu$ -closure of the measure fields of the form  $(\pi_x, \lambda\pi_\nu)_\# \xi$ , where  $\lambda \geq 0$ , and  $\xi$  induces a geodesic, i.e.

$$\xi = (\pi_x, \pi_y - \pi_x)_\# \eta \quad \text{for } \eta \text{ optimal plan between } \mu \text{ and some } \nu \in \mathcal{P}_2(\Omega).$$

<sup>1</sup>N. Gigli, "On the geometry of the space of probability measures endowed with the quadratic optimal transport distance" (2008).

# Centred tangent fields

**Definition – Geometric tangent cone [Gig08]<sup>1</sup>**  $\mathbf{Tan}_\mu$  is the  $W_\mu$ -closure of the measure fields of the form  $(\pi_x, \lambda\pi_\nu)_\# \xi$ , where  $\lambda \geq 0$ , and  $\xi$  induces a geodesic, i.e.

$$\xi = (\pi_x, \pi_y - \pi_x)_\# \eta \quad \text{for } \eta \text{ optimal plan between } \mu \text{ and some } \nu \in \mathcal{P}_2(\Omega).$$

Denote  $\mathbf{Tan}_\mu^0 = \mathbf{Tan}_\mu \cap \mathcal{P}_2(T\Omega)_\mu^0$  the set of centred tangent measure fields.

<sup>1</sup>N. Gigli, "On the geometry of the space of probability measures endowed with the quadratic optimal transport distance" (2008).

# Centred tangent fields

**Definition – Geometric tangent cone [Gig08]<sup>1</sup>**  $\mathbf{Tan}_\mu$  is the  $W_\mu$ -closure of the measure fields of the form  $(\pi_x, \lambda\pi_\nu)_\# \xi$ , where  $\lambda \geq 0$ , and  $\xi$  induces a geodesic, i.e.

$$\xi = (\pi_x, \pi_y - \pi_x)_\# \eta \quad \text{for } \eta \text{ optimal plan between } \mu \text{ and some } \nu \in \mathcal{P}_2(\Omega).$$

Denote  $\mathbf{Tan}_\mu^0 = \mathbf{Tan}_\mu \cap \mathcal{P}_2(T\Omega)_\mu^0$  the set of centred tangent measure fields.

By Proposition 4.25 of the same reference,  $\mathbf{Tan}_\mu^0$  is a closed convex cone of centred fields.

<sup>1</sup>N. Gigli, “On the geometry of the space of probability measures endowed with the quadratic optimal transport distance” (2008).

# Centred tangent fields

**Definition – Geometric tangent cone [Gig08]<sup>1</sup>**  $\mathbf{Tan}_\mu$  is the  $W_\mu$ -closure of the measure fields of the form  $(\pi_x, \lambda\pi_\nu)_\# \xi$ , where  $\lambda \geq 0$ , and  $\xi$  induces a geodesic, i.e.

$$\xi = (\pi_x, \pi_y - \pi_x)_\# \eta \quad \text{for } \eta \text{ optimal plan between } \mu \text{ and some } \nu \in \mathcal{P}_2(\Omega).$$

Denote  $\mathbf{Tan}_\mu^0 = \mathbf{Tan}_\mu \cap \mathcal{P}_2(T\Omega)_\mu^0$  the set of centred tangent measure fields.

By Proposition 4.25 of the same reference,  $\mathbf{Tan}_\mu^0$  is a closed convex cone of centred fields.

**Corollary** Any  $\mu \in \mathcal{P}_2(\Omega)$  admits  $D$  such that  $\xi \in \mathbf{Tan}_\mu^0$  iff  $\xi$  is centred and  $\xi(\text{graph } D) = 1$ .

<sup>1</sup>N. Gigli, “On the geometry of the space of probability measures endowed with the quadratic optimal transport distance” (2008).

# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

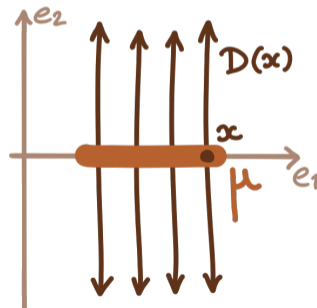
**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

**Example 3.** If  $\mu = (id, 0)_\# \mathcal{L}_{[0,1]}$  in dimension 2, then  $D(x) \equiv \text{span}\{e_2\}$ .



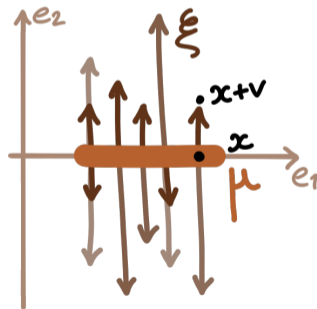
# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(T\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

**Example 3.** If  $\mu = (id, 0)_\# \mathcal{L}_{[0,1]}$  in dimension 2, then  $D(x) \equiv \text{span}\{e_2\}$ .

Indeed, any  $\xi$  concentrated on graph  $D$  induces a geodesic.



# Examples

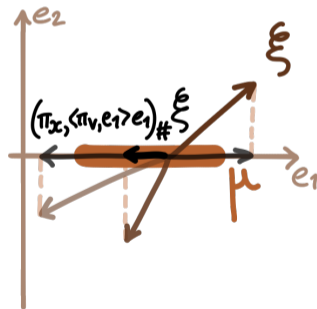
**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

**Example 3.** If  $\mu = (id, 0)_\# \mathcal{L}_{[0,1]}$  in dimension 2, then  $D(x) \equiv \text{span}\{e_2\}$ .

Indeed, any  $\xi$  concentrated on graph  $D$  induces a geodesic.

Conversely, if  $\xi$  is centred and optimal, then so is  $(\pi_x, \langle \pi_v, e_1 \rangle e_1)_\# \xi$ .



# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

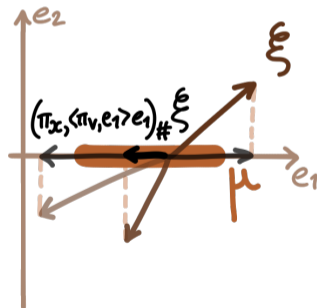
**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

**Example 3.** If  $\mu = (id, 0)_\# \mathcal{L}_{[0,1]}$  in dimension 2, then  $D(x) \equiv \text{span}\{e_2\}$ .

Indeed, any  $\xi$  concentrated on graph  $D$  induces a geodesic.

Conversely, if  $\xi$  is centred and optimal, then so is  $(\pi_x, \langle \pi_v, e_1 \rangle e_1)_\# \xi$ . Indeed, for  $(x_i, v_i)_{i=1}^N \subset \text{supp } \xi$ ,

$$\sum_{i=1}^N \langle x_i - x_{i-1}, x_i + v_i \rangle \geq 0.$$



# Examples

**Example 1.** If  $\mu = \delta_0$ , any plan is optimal, so that  $\mathbf{Tan}_\mu^0 = \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , and  $D \equiv \mathbb{R}^d$ .

**Example 2.** If  $\mu \ll \mathcal{L}$ , any optimal plan is induced by a map, so  $\mathbf{Tan}_\mu^0 = \{0_\mu\}$  and  $D \equiv \{0\}$ .

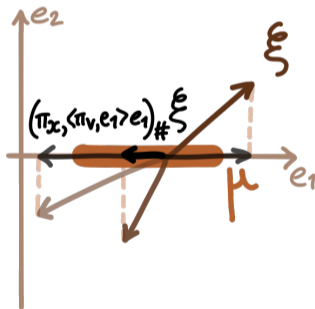
**Example 3.** If  $\mu = (id, 0)_\# \mathcal{L}_{[0,1]}$  in dimension 2, then  $D(x) \equiv \text{span}\{e_2\}$ .

Indeed, any  $\xi$  concentrated on graph  $D$  induces a geodesic.

Conversely, if  $\xi$  is centred and optimal, then so is  $(\pi_x, \langle \pi_v, e_1 \rangle e_1)_\# \xi$ . Indeed, for  $(x_i, v_i)_{i=1}^N \subset \text{supp } \xi$ ,

$$\sum_{i=1}^N \langle x_i - x_{i-1}, x_i + v_i \rangle \geq 0.$$

$\simeq$  1D optimal plan from  $\mathcal{L}_{[0,1]}$ , hence induced by a map, hence 0, so  $v \perp e_1$   $\xi$ -a.e.. Up to details, passes to  $\mathbf{Tan}_\mu^0$ .



# Lott's result

**Theorem 1.1 of [Lot16]<sup>1</sup>** If

- $\mathcal{M}$  is a smooth submanifold of dimension  $k$ ,
- $\mu \ll \mathcal{H}^k \llcorner \mathcal{M}$ , with  $\mathcal{H}^k$  the Hausdorff measure,



<sup>1</sup>J. Lott, "On tangent cones in Wasserstein space" (2016).

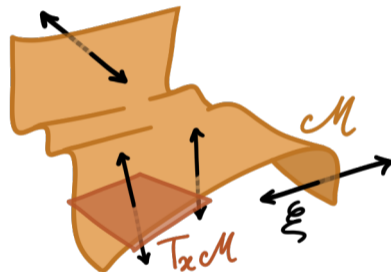
# Lott's result

**Theorem 1.1 of [Lot16]<sup>1</sup>** If

- $\mathcal{M}$  is a smooth submanifold of dimension  $k$ ,
  - $\mu \ll \mathcal{H}^k \llcorner \mathcal{M}$ , with  $\mathcal{H}^k$  the Hausdorff measure,
- then  $\xi \in \mathbf{Tan}_\mu^0$  if and only if ( $\xi$  is centred and)

$$v \perp T_x \mathcal{M} \quad \xi - \text{almost everywhere.}$$

In other words,  $D(x) = (T_x \mathcal{M})^\perp$ .



<sup>1</sup>J. Lott, "On tangent cones in Wasserstein space" (2016).

# Table of Contents

Centred measure fields

Tangent measure fields

Zajíček's theorem

Decomposition in the general case

# Statement

**Definition** A set  $A \subset \mathbb{R}^d$  is  $\text{DC}_k$  (Difference of Convex of dim  $k$ ) if up to permuting the axes,

$$A = \left\{ (x_1, \dots, x_k, \Phi(x_1, \dots, x_k)) \mid \Phi : \mathbb{R}^k \rightarrow \mathbb{R}^{d-k}, \text{ with each } \Phi_i = \text{convex} - \text{convex} \right\}.$$

# Statement

**Definition** A set  $A \subset \mathbb{R}^d$  is  $\text{DC}_k$  (Difference of Convex of dim  $k$ ) if up to permuting the axes,

$$A = \left\{ (x_1, \dots, x_k, \Phi(x_1, \dots, x_k)) \mid \Phi : \mathbb{R}^k \rightarrow \mathbb{R}^{d-k}, \text{ with each } \Phi_i = \text{convex} - \text{convex} \right\}.$$

A set  $A$  is  $\sigma\text{-DC}_k$  if it can be covered by countably many  $\text{DC}_k$  sets.

# Statement

**Definition** A set  $A \subset \mathbb{R}^d$  is  $\text{DC}_k$  (Difference of Convex of dim  $k$ ) if up to permuting the axes,

$$A = \left\{ (x_1, \dots, x_k, \Phi(x_1, \dots, x_k)) \mid \Phi : \mathbb{R}^k \rightarrow \mathbb{R}^{d-k}, \text{ with each } \Phi_i = \text{convex} - \text{convex} \right\}.$$

A set  $A$  is  $\sigma\text{-DC}_k$  if it can be covered by countably many  $\text{DC}_k$  sets.

Given  $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$  convex, let  $J_k(\varphi) := \{x \in \mathbb{R}^d \mid \dim \partial_x \varphi \geq d - k\}$ .

<sup>1</sup>L. Zajíček, "On the differentiation of convex functions in finite and infinite dimensional spaces" (1979).

See also G. Alberti, "On the structure of singular sets of convex functions" (1994).

# Statement

**Definition** A set  $A \subset \mathbb{R}^d$  is  $\text{DC}_k$  (Difference of Convex of dim  $k$ ) if up to permuting the axes,

$$A = \left\{ (x_1, \dots, x_k, \Phi(x_1, \dots, x_k)) \mid \Phi : \mathbb{R}^k \rightarrow \mathbb{R}^{d-k}, \text{ with each } \Phi_i = \text{convex} - \text{convex} \right\}.$$

A set  $A$  is  $\sigma\text{-DC}_k$  if it can be covered by countably many  $\text{DC}_k$  sets.

Given  $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$  convex, let  $J_k(\varphi) := \{x \in \mathbb{R}^d \mid \dim \partial_x \varphi \geq d - k\}$ .

**Theorem 1 of [Zaj79]<sup>1</sup>** If  $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$  is convex, then each  $J_k(\varphi)$  is  $\sigma\text{-DC}_k$ .  
Conversely, if  $A \subset \mathbb{R}^d$  is  $\sigma\text{-DC}_k$ , there exists a convex  $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$  such that  $A \subset J_k(\varphi)$ .

<sup>1</sup>L. Zajíček, "On the differentiation of convex functions in finite and infinite dimensional spaces" (1979).

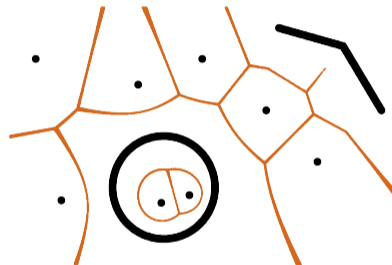
See also G. Alberti, "On the structure of singular sets of convex functions" (1994).

# An application

Let  $S \subset \mathbb{R}^d$  be closed, and consider

$$T := \{x \in \mathbb{R}^d \mid \text{proj}_S(x) \text{ has more than one element}\}.$$

Then  $T$  is  $\sigma\text{-DC}_{d-1}$ .



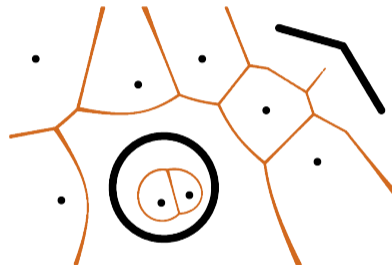
# An application

Let  $S \subset \mathbb{R}^d$  be closed, and consider

$$T := \{x \in \mathbb{R}^d \mid \text{proj}_S(x) \text{ has more than one element}\}.$$

Then  $T$  is  $\sigma$ -DC<sub>d-1</sub>. Indeed, consider

$$\varphi(x) := \min_{y \in S} |x - y|^2 = |x|^2 + \min_{y \in S} -2 \langle x, y \rangle + |y|^2.$$



# An application

Let  $S \subset \mathbb{R}^d$  be closed, and consider

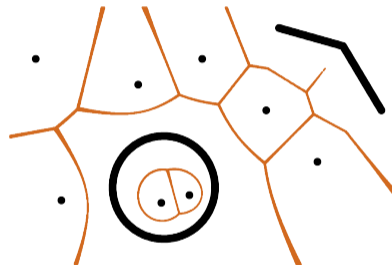
$$T := \{x \in \mathbb{R}^d \mid \text{proj}_S(x) \text{ has more than one element}\}.$$

Then  $T$  is  $\sigma$ -DC<sub>d-1</sub>. Indeed, consider

$$\varphi(x) := \min_{y \in S} |x - y|^2 = |x|^2 + \min_{y \in S} -2 \langle x, y \rangle + |y|^2.$$

Then  $\varphi$  is semiconcave and  $J_{d-1}(\varphi) = T$ .

By Zajíček,  $T$  is  $\sigma$ -DC<sub>d-1</sub>.



# An application

Let  $S \subset \mathbb{R}^d$  be closed, and consider

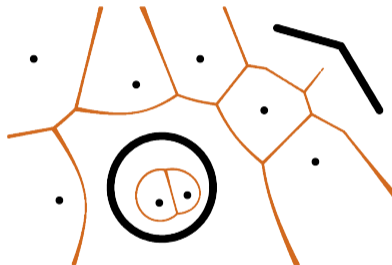
$$T := \{x \in \mathbb{R}^d \mid \text{proj}_S(x) \text{ has more than one element}\}.$$

Then  $T$  is  $\sigma$ -DC $_{d-1}$ . Indeed, consider

$$\varphi(x) := \min_{y \in S} |x - y|^2 = |x|^2 + \min_{y \in S} -2 \langle x, y \rangle + |y|^2.$$

Then  $\varphi$  is semiconcave and  $J_{d-1}(\varphi) = T$ .

By Zajíček,  $T$  is  $\sigma$ -DC $_{d-1}$ .



*The set on which there is a decision to make is  $\sigma$ -DC $_{d-1}$ .*

# Table of Contents

Centred measure fields

Tangent measure fields

Zajíček's theorem

Decomposition in the general case

# Statement

**Theorem** Let  $\mu \in \mathcal{P}_2(\Omega)$ .



# Statement

**Theorem** Let  $\mu \in \mathcal{P}_2(\Omega)$ . There exists a unique decomposition  $\mu = \sum_{k=0}^d \mu_k$  in mutually singular measures such that



# Statement

**Theorem** Let  $\mu \in \mathcal{P}_2(\Omega)$ . There exists a unique decomposition  $\mu = \sum_{k=0}^d \mu_k$  in mutually singular measures such that

- $\mu_k$  is concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ , and gives 0 mass to DC<sub>j</sub> sets for  $j < k$ ;



# Statement

**Theorem** Let  $\mu \in \mathcal{P}_2(\Omega)$ . There exists a unique decomposition  $\mu = \sum_{k=0}^d \mu_k$  in mutually singular measures such that

- $\mu_k$  is concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ , and gives 0 mass to DC<sub>j</sub> sets for  $j < k$ ;
- the application  $D$  characterizing  $\mathbf{Tan}_\mu^0$  is given by  $D(x) = (T_x A_k)^\perp$  for  $\mu_k$ -a.e.  $x \in \Omega$ .



# Statement

**Theorem** Let  $\mu \in \mathcal{P}_2(\Omega)$ . There exists a unique decomposition  $\mu = \sum_{k=0}^d \mu_k$  in mutually singular measures such that

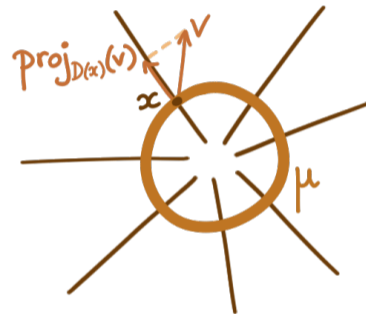
- $\mu_k$  is concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ , and gives 0 mass to DC<sub>j</sub> sets for  $j < k$ ;
- the application  $D$  characterizing  $\mathbf{Tan}_\mu^0$  is given by  $D(x) = (T_x A_k)^\perp$  for  $\mu_k$ -a.e.  $x \in \Omega$ .



Explicitly,  $\xi \in \mathbf{Tan}_\mu^0$  if and only if  $\xi$  is (centred and) concentrated on the normal spaces to each  $A_k$ .

# Projection on $\text{Tan}_\mu^0$

For each  $x$ , denote  $\text{proj}_{D(x)} : \mathbb{R}^d \rightarrow \mathbb{R}^d$  the projection over  $D(x)$ .



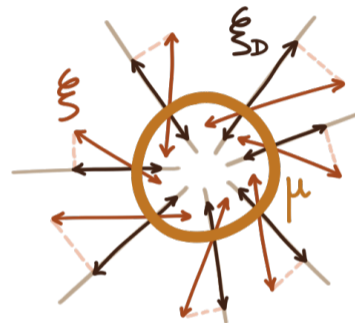
# Projection on $\mathbf{Tan}_\mu^0$

For each  $x$ , denote  $\text{proj}_{D(x)} : \mathbb{R}^d \rightarrow \mathbb{R}^d$  the projection over  $D(x)$ .

**Corollary** For any  $\xi \in \mathcal{P}_2(\mathbf{T}\Omega)_\mu^0$ , the measure field

$$\xi_D := (\pi_x, \text{proj}_{D(x)}(\pi_v))_\# \xi$$

is the unique minimizer of  $W_\mu(\zeta, \xi)$  over  $\zeta \in \mathbf{Tan}_\mu^0$ .



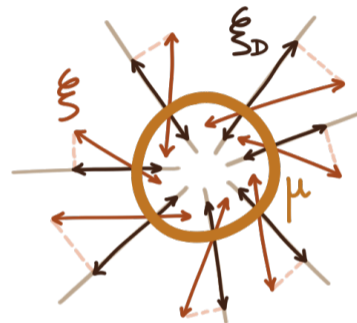
# Projection on $\mathbf{Tan}_\mu^0$

For each  $x$ , denote  $\text{proj}_{D(x)} : \mathbb{R}^d \rightarrow \mathbb{R}^d$  the projection over  $D(x)$ .

**Corollary** For any  $\xi \in \mathcal{P}_2(T\Omega)_\mu^0$ , the measure field

$$\xi_D := (\pi_x, \text{proj}_{D(x)}(\pi_v))_\# \xi$$

is the unique minimizer of  $W_\mu(\zeta, \xi)$  over  $\zeta \in \mathbf{Tan}_\mu^0$ .



By construction,  $\xi_D \in \mathbf{Tan}_\mu^0$ . Conversely, let  $\zeta \in \mathbf{Tan}_\mu^0$ , and  $\alpha$  realize  $W_\mu(\zeta, \xi)$ . Then

$$W_\mu^2(\zeta, \xi) = \int |v - w|^2 d\alpha \geq \int |\text{proj}_{D(x)}(w) - w|^2 d\alpha \geq W_\mu^2(\xi_D, \xi).$$

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ .

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

**Lemma**  $\mathbf{Tan}_{\mu_k}^0$  coincides with the “restriction” of  $\mathbf{Tan}_{\mu}^0$  to  $\{\dim D = d - k\}$ .

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

**Lemma**  $\mathbf{Tan}_{\mu_k}^0$  coincides with the “restriction” of  $\mathbf{Tan}_{\mu}^0$  to  $\{\dim D = d - k\}$ .

Now,

- get  $\xi_k \in \mathbf{Tan}_{\mu_k}^0$  splitting mass in  $d - k$  directions.

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

**Lemma**  $\mathbf{Tan}_{\mu_k}^0$  coincides with the “restriction” of  $\mathbf{Tan}_{\mu}^0$  to  $\{\dim D = d - k\}$ .

Now,

- get  $\xi_k \in \mathbf{Tan}_{\mu_k}^0$  splitting mass in  $d - k$  directions.
- Approximate by an optimal plan, which splits mass in  $d - k$  directions on a set of large  $\mu_k$ -mass.

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

**Lemma**  $\mathbf{Tan}_{\mu_k}^0$  coincides with the “restriction” of  $\mathbf{Tan}_{\mu}^0$  to  $\{\dim D = d - k\}$ .

Now,

- get  $\xi_k \in \mathbf{Tan}_{\mu_k}^0$  splitting mass in  $d - k$  directions.
- Approximate by an optimal plan, which splits mass in  $d - k$  directions on a set of large  $\mu_k$ -mass.
- Hence some Kantorovich potential must have a subdifferential of dimension  $d - k$ .

# How does it work: the measures $(\mu_k)_k$

Natural candidates:  $\mu_k = \mu \llcorner \{\dim D = d - k\}$ . How to get concentration on a  $\sigma$ -DC<sub>k</sub> set?

**Lemma**  $\mathbf{Tan}_{\mu_k}^0$  coincides with the “restriction” of  $\mathbf{Tan}_{\mu}^0$  to  $\{\dim D = d - k\}$ .

Now,

- get  $\xi_k \in \mathbf{Tan}_{\mu_k}^0$  splitting mass in  $d - k$  directions.
- Approximate by an optimal plan, which splits mass in  $d - k$  directions on a set of large  $\mu_k$ -mass.
- Hence some Kantorovich potential must have a subdifferential of dimension  $d - k$ .

Kantorovich potentials are semiconvex, so by Zajíček,  $\mu_k$  is concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ .

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC $_k$  set  $A_k$ , and give 0 mass to DC $_j$  sets for  $j < k$ .

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC $_k$  set  $A_k$ , and give 0 mass to DC $_j$  sets for  $j < k$ .

**Definition – Tangent planes** Cover  $A_k$  by  $(B_j)_{j \in \mathbb{N}}$ , with  $B_j \sim \Phi_j(\mathbb{R}^k)$  for  $\Phi_{j,\ell} = f_{j,\ell} - g_{j,\ell}$ , with  $f_{j,\ell}, g_{j,\ell} : \mathbb{R}^k \rightarrow \mathbb{R}$  convex.

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC $_k$  set  $A_k$ , and give 0 mass to DC $_j$  sets for  $j < k$ .

**Definition – Tangent planes** Cover  $A_k$  by  $(B_j)_{j \in \mathbb{N}}$ , with  $B_j \sim \Phi_j(\mathbb{R}^k)$  for  $\Phi_{j,\ell} = f_{j,\ell} - g_{j,\ell}$ , with  $f_{j,\ell}, g_{j,\ell} : \mathbb{R}^k \rightarrow \mathbb{R}$  convex. Then  $T_x A_k$  exists if

- for all  $j$  such that  $x \in B_j$ , each  $f_{j,\ell}, g_{j,\ell}$  is differentiable,

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC $_k$  set  $A_k$ , and give 0 mass to DC $_j$  sets for  $j < k$ .

**Definition – Tangent planes** Cover  $A_k$  by  $(B_j)_{j \in \mathbb{N}}$ , with  $B_j \sim \Phi_j(\mathbb{R}^k)$  for  $\Phi_{j,\ell} = f_{j,\ell} - g_{j,\ell}$ , with  $f_{j,\ell}, g_{j,\ell} : \mathbb{R}^k \rightarrow \mathbb{R}$  convex. Then  $T_x A_k$  exists if

- for all  $j$  such that  $x \in B_j$ , each  $f_{j,\ell}, g_{j,\ell}$  is differentiable,
- all  $\nabla_x \Phi_j$  coincide, in which case  $T_x A_k := \nabla_x \Phi_j(\mathbb{R}^k)$ .

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ , and give 0 mass to DC<sub>j</sub> sets for  $j < k$ .

**Definition – Tangent planes** Cover  $A_k$  by  $(B_j)_{j \in \mathbb{N}}$ , with  $B_j \sim \Phi_j(\mathbb{R}^k)$  for  $\Phi_{j,\ell} = f_{j,\ell} - g_{j,\ell}$ , with  $f_{j,\ell}, g_{j,\ell} : \mathbb{R}^k \rightarrow \mathbb{R}$  convex. Then  $T_x A_k$  exists if

- for all  $j$  such that  $x \in B_j$ , each  $f_{j,\ell}, g_{j,\ell}$  is differentiable,
- all  $\nabla_x \Phi_j$  coincide, in which case  $T_x A_k := \nabla_x \Phi_j(\mathbb{R}^k)$ .

*By Zajíček,  $T_x A_k$  exists  $\mu_k$ -almost everywhere.*

# How does it work: the tangent planes $T_x A_k$

Let  $\mu_k$  be concentrated on a  $\sigma$ -DC<sub>k</sub> set  $A_k$ , and give 0 mass to DC<sub>j</sub> sets for  $j < k$ .

**Definition – Tangent planes** Cover  $A_k$  by  $(B_j)_{j \in \mathbb{N}}$ , with  $B_j \sim \Phi_j(\mathbb{R}^k)$  for  $\Phi_{j,\ell} = f_{j,\ell} - g_{j,\ell}$ , with  $f_{j,\ell}, g_{j,\ell} : \mathbb{R}^k \rightarrow \mathbb{R}$  convex. Then  $T_x A_k$  exists if

- for all  $j$  such that  $x \in B_j$ , each  $f_{j,\ell}, g_{j,\ell}$  is differentiable,
- all  $\nabla_x \Phi_j$  coincide, in which case  $T_x A_k := \nabla_x \Phi_j(\mathbb{R}^k)$ .

*By Zajíček,  $T_x A_k$  exists  $\mu_k$ -almost everywhere.*

Stays to show that  $D(x) = (T_x A_k)^\perp$  for  $\mu_k$ -a.e. point  $x \in \Omega$ .

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ .

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

For any smooth curve  $\gamma \subset J_k(\varphi)$ , there holds

$$\varphi(\gamma_t) \geq \varphi(\gamma_0) + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle$$

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

For any smooth curve  $\gamma \subset J_k(\varphi)$ , there holds

$$\varphi(\gamma_t) \geq \varphi(\gamma_0) + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle \geq \varphi(\gamma_t) + \langle g_0(\gamma_t), \gamma_0 - \gamma_t \rangle + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle.$$

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

For any smooth curve  $\gamma \subset J_k(\varphi)$ , there holds

$$\varphi(\gamma_t) \geq \varphi(\gamma_0) + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle \geq \varphi(\gamma_t) + \langle g_0(\gamma_t), \gamma_0 - \gamma_t \rangle + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle.$$

Therefore, dividing by  $t > 0$ ,

$$0 \geq \left\langle g_i(\gamma_0) - g_0(\gamma_t), \frac{\gamma_t - \gamma_0}{t} \right\rangle$$

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

For any smooth curve  $\gamma \subset J_k(\varphi)$ , there holds

$$\varphi(\gamma_t) \geq \varphi(\gamma_0) + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle \geq \varphi(\gamma_t) + \langle g_0(\gamma_t), \gamma_0 - \gamma_t \rangle + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle.$$

Therefore, dividing by  $t > 0$ ,

$$0 \geq \left\langle g_i(\gamma_0) - g_0(\gamma_t), \frac{\gamma_t - \gamma_0}{t} \right\rangle \xrightarrow[t \searrow 0]{} \langle g_i(\gamma_0) - g_0(\gamma_0), \dot{\gamma}_0 \rangle.$$

# How does it work: orthogonality

Let  $\varphi$  be convex with  $J_k(\varphi) = \{x \mid \dim \partial_x \varphi \geq d - k\}$  a smooth surface. Assume that for any  $x \in J_k(\varphi)$ , there holds  $\partial_x \varphi = \text{conv} \{g_0(x), \dots, g_{d-k}(x)\}$  for continuous  $(g_i)_i$ . Then

$$\text{span } \partial_x \varphi := \text{span} \{g_i(x) - g_0(x)\}_{i=1}^{d-k} \perp T_x J_k(\varphi).$$

For any smooth curve  $\gamma \subset J_k(\varphi)$ , there holds

$$\varphi(\gamma_t) \geq \varphi(\gamma_0) + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle \geq \varphi(\gamma_t) + \langle g_0(\gamma_t), \gamma_0 - \gamma_t \rangle + \langle g_i(\gamma_0), \gamma_t - \gamma_0 \rangle.$$

Therefore, dividing by  $t > 0$ ,

$$0 \geq \left\langle g_i(\gamma_0) - g_0(\gamma_t), \frac{\gamma_t - \gamma_0}{t} \right\rangle \xrightarrow[t \searrow 0]{} \langle g_i(\gamma_0) - g_0(\gamma_0), \dot{\gamma}_0 \rangle.$$

Interchanging  $i$  and  $0$ , we get  $g_i(x) - g_0(x) \perp T_x J_k(\varphi)$ .

# Directions and open questions

- Ongoing work (and part of the motivation); edge cases where the tangent cone does not behave as expected.

# Directions and open questions

- Ongoing work (and part of the motivation); edge cases where the tangent cone does not behave as expected.

## Open questions

- What can be said about the projection on  $\mathbf{Tan}_\mu$  for fields that are induced by a map?

# Directions and open questions

- Ongoing work (and part of the motivation); edge cases where the tangent cone does not behave as expected.

## Open questions

- What can be said about the projection on  $\mathbf{Tan}_\mu$  for fields that are induced by a map?
- Is there a similar decomposition with *rectifiable* pieces / what would be the correct cost?

# Directions and open questions

- Ongoing work (and part of the motivation); edge cases where the tangent cone does not behave as expected.

## Open questions

- What can be said about the projection on  $\mathbf{Tan}_\mu$  for fields that are induced by a map?
- Is there a similar decomposition with *rectifiable* pieces / what would be the correct cost?

*Thank you for your attention!*