Notes on fixed-point procedure

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1 Notations and assumptions

We suppose that

- 1. $f_{e,b}$ is nonnegative.
- 2. $f_{e,b}$ satisfies the boundary condition, i.e. $f_{e,b}(v) = 0$ as soon as $\mathcal{L}_e(0,v) \leqslant \mathcal{L}_e(1,0)$.
- 3. $f_{e,b}$ is bounded from above by a constant $\bar{c} \ge 0$.
- 4. There exists $\underline{c} > 0$ and $0 \leq \underline{v} < \overline{v}$ such that $f_{e,b}(v) \geq \underline{c}$ for all $v \in [-\overline{v}, -\underline{v}]$.
- 5. The function φ satisfies $\varphi(0) = \varphi'(0) = 0$.
- 6. The function φ is strongly concave, i.e. there exists $\alpha > 0$ such that $\varphi((1-\tau)x + \tau y) \ge (1-\tau)\varphi(x) + \tau \varphi(y) + \frac{\alpha}{2}(1-\tau)\tau |x-y|^2$.
- 7. There exists $\beta > \alpha$ such that $\varphi(1) \ge -\beta$. Uniformly over the fixed-point iterations

We use the following notations: the Liapunov functions of the electrons and the ions are

$$\mathcal{L}_e(x,v) := \frac{v^2}{2} - \frac{1}{\mu}\varphi(x). \tag{1.1}$$

$$\mathcal{L}_i(x,v) := \frac{v^2}{2} + \varphi(x). \tag{1.2}$$

We define an upper bound \overline{v}_e over the velocities in the support of f_e , given as

$$\mathcal{L}_e(0, \overline{v}_e) := \frac{1}{\mu} \beta \geqslant -\frac{1}{\mu} \varphi(1) = \mathcal{L}_e(1, 0), \quad \text{i.e.} \quad \overline{v}_e := \sqrt{\frac{2}{\mu} \beta}.$$
 (1.3)

For a given point $(x, v) \in [0, 1] \times \mathbb{R}^-$, we denote by (x_b, v_b) the intersection of the boundary $\{x = 0\} \cup \{v = 0\}$ with the ion characteristic issued from (x, v). The values are given by

$$\begin{pmatrix} x_b(x,v) \\ v_b(x,v) \end{pmatrix} := \begin{pmatrix} \varphi^{-1}\left(\min\left(0, \frac{v^2}{2} + \varphi(x)\right)\right) \\ -\sqrt{\max\left(0, v^2 + 2\varphi(x)\right)} \end{pmatrix}$$
 (1.4)

2 Estimates

2.1 Useful elementary lemmas

Lemma 2.1. Let $\alpha > 0$, $\overline{x} \geqslant 0$ and $\overline{y} \geqslant 0$. Then

$$\mathcal{I}\coloneqq \int_{x=0}^{\overline{x}}\int_{y=0}^{\overline{y}}\frac{1}{(x^2+\alpha y^2)^{1/2}}dydx\leqslant 2\frac{\sqrt{2\overline{xy}}}{\alpha^{1/4}}.$$

Demonstration By the change of variable $z = \sqrt{\alpha}y$, with $\overline{z} := \sqrt{\alpha}\overline{y}$, we have

$$\mathcal{I} = \frac{1}{\sqrt{\alpha}} \int_{x=0}^{\overline{x}} \int_{z=0}^{\overline{z}} \frac{1}{(x^2 + z^2)^{1/2}} dz dx.$$

Notice that $x + z \leq \sqrt{2} (x^2 + y^2)^{1/2}$. Then,

$$\mathcal{I} \leqslant \frac{1}{\sqrt{\alpha}} \int_{x=0}^{\overline{x}} \int_{z=0}^{\overline{z}} \frac{\sqrt{2}}{x+z} dz dx = \sqrt{\frac{2}{\alpha}} \int_{x=0}^{\overline{x}} \ln\left(\frac{x+\overline{z}}{x}\right) dx = \sqrt{\frac{2}{\alpha}} \int_{x=0}^{\overline{x}} \ln\left(1+\frac{\overline{z}}{x}\right) dx.$$

Using $\ln(1+a) \leqslant \sqrt{a}$, we get

$$\mathcal{I}\leqslant \sqrt{\frac{2}{\alpha}}\int_{x=0}^{\overline{x}}\sqrt{\frac{\overline{z}}{x}}dx=\sqrt{\frac{2}{\alpha}}2\sqrt{\overline{x}\overline{z}}=2\frac{\sqrt{2\overline{x}\overline{y}}}{\alpha^{1/4}}.$$

Remark 2.1 (Exact value). Let $\overline{r} := \sqrt{\overline{x}^2 + \overline{z}^2}$. Then

$$\mathcal{I} = \overline{x} \ln \left(\frac{1 + \overline{z}/\overline{r}}{\overline{x}/\overline{r}} \right) + \overline{z} \ln \left(\frac{1 + \overline{x}/\overline{r}}{\overline{z}/\overline{r}} \right).$$

Lemma 2.2. If $a \ge 0$ and $b \ge 0$, then $|a - b| \le \sqrt{|a^2 - b^2|}$.

Demonstration If $a \geqslant b$, then $|a-b| = \sqrt{(a-b)(a-b)} \leqslant \sqrt{(a-b)(a+b)} = \sqrt{a^2-b^2}$, else |a-b| = |b-a|. \square

2.2 Properties of the electron density n_e

Lemma 2.3. The electron density n_e is bounded and continuous.

Demonstration For each $0 \le x \le y \le 1$, we define the velocity $v_x(y) \ge 0$ such that

$$\mathcal{L}_e(x, v_x(y)) = \mathcal{L}_e(y, 0) \quad \iff \quad v_x(y) = \left(\frac{2}{\mu} \left(\varphi(x) - \varphi(y)\right)\right)^{1/2}.$$

In particular, owing to the boundary conditions, the function $v \to f_e(x, v)$ vanishes for $|v| \ge v_x(1)$. Then

$$n_e(x) = \int_{v = -v_x(1)}^{v_x(1)} f_e(x, v) dv \leqslant 2\overline{c}v_x(1) = 2\overline{c} \left(\frac{2}{\mu} (\varphi(x) - \varphi(1))\right)^{1/2} \leqslant 2\overline{c} \sqrt{\frac{2\beta}{\mu}}.$$

Moreover, using the symmetry $f_e(x, v) = f_e(x, -v)$, we may write

$$n_e(x) - n_e(y) = 2\underbrace{\int_{v=0}^{v_x(y)} f_e(x, v) dv}_{=: \mathcal{I}^+} + 2\underbrace{\left(\underbrace{\int_{v=v_x(y)}^{v_x(1)} f_e(x, v) dv}_{v=v_x(y)} - \int_{v=0}^{v_y(1)} f_e(y, v) dv}_{=: \mathcal{I}^-}\right)}_{=: \mathcal{I}^-}.$$

The term \mathcal{I}^+ is bounded by $\overline{c}v_x(y) = \overline{c}\left(\frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2}$, and by continuity of φ , we have $\mathcal{I}^+ \underset{y \to x}{\longrightarrow} 0$. On the first integral of \mathcal{I}^- , we apply the change of variable

$$w = \left(v^2 - \frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2} \quad \Longleftrightarrow \quad dv = \frac{w}{\left(w^2 + \frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2}} dw, \quad w \in [0, v_y(1)]$$

to get

$$\mathcal{I}^{-} = \int_{w=0}^{v_{y}(1)} f_{e}\left(x, \left(w^{2} + \frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2}\right) \frac{w}{\left(w^{2} + \frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2}} dw - \int_{v=0}^{v_{y}(1)} f_{e}(y, v) dv.$$

Notice that

$$f_e\left(x, \left(w^2 + \frac{2}{\mu}\left(\varphi(x) - \varphi(y)\right)\right)^{1/2}\right) = f_{e,b}\left(\frac{w^2}{2} + \frac{1}{\mu}\left(\varphi(x) - \varphi(y)\right) - \frac{1}{\mu}\varphi(x)\right) = f_e(y, w).$$

Renaming w in v, we obtain the (clearly nonpositive) expression

$$\mathcal{I}^{-} = \int_{v=0}^{v_{y}(1)} f_{e}(y, v) \left(\frac{v}{\left(v^{2} + \frac{2}{\mu} \left(\varphi(x) - \varphi(y)\right)\right)^{1/2}} - 1 \right) dv \geqslant \overline{c} \int_{v=0}^{v_{y}(1)} \left(\frac{v}{\left(v^{2} + \frac{2}{\mu} \left(\varphi(x) - \varphi(y)\right)\right)^{1/2}} - 1 \right) dv$$

$$= \overline{c} \left(\left(v_{y}(1)^{2} + \frac{2}{\mu} \left(\underbrace{\varphi(x) - \varphi(y)}_{\geqslant 0} \right) \right)^{1/2} - \left(\frac{2}{\mu} \left(\varphi(x) - \varphi(y)\right) \right)^{1/2} - v_{y}(1) \right) \geqslant -\overline{c} \left(\frac{2}{\mu} \left(\varphi(x) - \varphi(y)\right) \right)^{1/2}$$

and this shows that $\mathcal{I}^- \xrightarrow{y \to x} 0$.

Lemma 2.4. Let n_e^{φ} and n_e^{ψ} be the electron densities generated by potentials φ and ψ satisfying the assumptions. Then

1. If $f_{e,b}$ is Lipschitz-continuous with constant $[f_{e,b}]$, then

$$|n_e^{\varphi}(x) - n_e^{\psi}(x)| \le 2[f_{e,b}]\overline{v}_e\sqrt{\frac{2}{\mu}}|\varphi(x) - \psi(x)|^{1/2} \quad \forall (x,y) \in [0,1]^2.$$

2. If there exists a constant $[f_{e,b}]$ such that $|f_{e,b}(x)-f_{e,b}(y)| \leq |f_{e,b}||x^2-y^2|$ (or equivalently, $x \to f_{e,b}(\sqrt{x})$ is a lipschitz function, as for instance e^{-x^2}), then

$$|n_e^{\varphi}(x) - n_e^{\psi}(x)| \leqslant \frac{4\overline{v}_e[f_{e,b}]_2}{\mu} |\varphi(x) - \psi(x)| \quad \forall (x,y) \in [0,1]^2.$$

Demonstration We have

$$\left|n_e^{\varphi}(x)-n_e^{\psi}(x)\right|\leqslant 2\int_{v=0}^{\overline{v}_e}\left|f_e^{\varphi}(x,v)-f_e^{\psi}(x,v)\right|dv=2\int_{v=0}^{\overline{v}_e}\left|f_{e,b}\left(\left(v^2-\frac{2}{\mu}\varphi(x)\right)^{1/2}\right)-f_{e,b}\left(\left(v^2-\frac{2}{\mu}\psi(x)\right)^{1/2}\right)\right|dv.$$

Then, if $f_{e,b}$ is Lipschitz with constant $[f_{e,b}]$, we obtain

$$\left| n_e^{\varphi}(x) - n_e^{\psi}(x) \right| \leqslant 2[f_{e,b}] \int_{v=0}^{\overline{v}_e} \left| \left(v^2 - \frac{2}{\mu} \varphi(x) \right)^{1/2} - \left(v^2 - \frac{2}{\mu} \psi(x) \right)^{1/2} \right| dv.$$

Using lemma (2.2) yields

$$\left| n_e^{\varphi}(x) - n_e^{\psi}(x) \right| \leqslant 2[f_{e,b}] \int_{v=0}^{\overline{v}_e} \left| -\frac{2}{\mu} \varphi(x) + \frac{2}{\mu} \psi(x) \right|^{1/2} dv = 2[f_{e,b}] \overline{v}_e \sqrt{\frac{2}{\mu}} \left| \varphi(x) - \psi(x) \right|^{1/2}.$$

If $f_{e,b}(\sqrt{\cdot})$ is Lipschitz with constant $[f_{e,b}]_2$, we may directly write

$$\left| n_e^{\varphi}(x) - n_e^{\psi}(x) \right| \leqslant 2\overline{v}_e[f_{e,b}]_2 \frac{2}{\mu} \left| \varphi(x) - \psi(x) \right|.$$

2.3 Properties of the ion density n_i

The estimates will rely on two particular cases, the we treat independently as lemmas. For a given x, we define $g_x : [0, x] \mapsto \mathbb{R}^+$ by

$$\mathcal{L}_i(x, -g_x(y)) = \mathcal{L}_i(y, 0), \text{ i.e. } g_x(y) = (2(\varphi(y) - \varphi(x)))^{1/2}.$$

Lemma 2.5. Let $0 \le y < x \le 1$. We have

$$\mathcal{I} := \int_{v = -q_x(y)}^{0} \int_{z = x_b(x, v)}^{x} \frac{1}{\left(v^2 - q_x^2(z)\right)^{1/2}} dz \, dv \leqslant 2\sqrt{\frac{2}{\alpha}} \left(\varphi(y) - \varphi(x)\right)^{1/4} \sqrt{x - y}.$$

Demonstration Let us first use Fubini's theorem to switch the order of integration. The lower bound $x_b(x, v) \ge z$ becomes an upper bound $v \le -g_x(z)$, and we have

$$\mathcal{I} = \int_{z=y}^{x} \int_{v=-q_x(z)}^{-g_x(z)} \frac{1}{(v^2 - q_x^2(z))^{1/2}} dv dz = \int_{z=y}^{x} \int_{v=q_x(z)}^{g_x(y)} \frac{1}{(v^2 - q_x^2(z))^{1/2}} dv dz.$$

With the change of variable $w = v - g_x(z)$, and using $\frac{d}{dw} \left[\sinh^{-1} \left(\sqrt{\frac{w}{a}} \right) \right] = \left(w^2 + 2aw \right)^{-1/2}$, we get

$$\mathcal{I} = \int_{z=y}^{x} \int_{w=0}^{g_x(y) - g_x(z)} \frac{1}{\left(w^2 + 2wg_x(z)\right)^{1/2}} dw \, dz = \int_{z=y}^{x} \sinh^{-1} \left(\sqrt{\frac{g_x(y) - g_x(z)}{g_x(z)}}\right) dz.$$

Using the coarse estimates $\sinh^{-1}(a) \leqslant a$ and $\sqrt{\frac{a-b}{b}} \leqslant \sqrt{\frac{a}{b}}$, we get

$$\mathcal{I} \leqslant \int_{z=u}^{x} \sqrt{\frac{g_x(y)}{g_x(z)}} dz = \int_{z=u}^{x} \left(\frac{\varphi(y) - \varphi(x)}{\varphi(z) - \varphi(x)}\right)^{1/4} dz.$$

The assumption of strong convexity yields $\varphi(z) - \varphi(x) \ge -\varphi'(z)(x-z) + \frac{\alpha}{2}|x-z|^2 \ge \frac{\alpha}{2}(x-z)^2$, so that

$$\mathcal{I} \leqslant \sqrt{\frac{2}{\alpha}} \left(\varphi(y) - \varphi(x) \right)^{1/4} \int_{z=y}^{x} \frac{1}{\left(x - z \right)^{1/2}} dz = 2\sqrt{\frac{2}{\alpha}} \left(\varphi(y) - \varphi(x) \right)^{1/4} \sqrt{x - y}.$$

Lemma 2.6. Let $0 \le y \le x \le 1$, and $-v_0 < -g_x(y)$. We have

$$\mathcal{I} \coloneqq \int_{v=-v_0}^{-g_x(y)} \int_{z=y}^{1} \frac{1}{\left(v^2 + 2\left(\varphi(x) - \varphi(z)\right)\right)^{1/2}} dz \, dv \leqslant \frac{2\sqrt{2(1-y)}}{\alpha^{1/4}} \left(v_0^2 + 2\left(\varphi(x) - \varphi(y)\right)\right)^{1/4}.$$

Demonstration We first shift the v-integration from the vertical line z = x to z = y. Let w = w(v) be such that

$$\mathcal{L}_{i}(y, w(v)) = \mathcal{L}_{i}(x, v), \text{ i.e. } w(v) = -\left(v^{2} + 2\left(\varphi(x) - \varphi(y)\right)\right), \text{ and } dv = \frac{-w}{\left(w^{2} + 2\left(\varphi(y) - \varphi(x)\right)\right)^{1/2}}dw.$$

Then, defining $w_0 := (v_0^2 + 2(\varphi(x) - \varphi(y)))^{1/2}$, and noticing that $w(-g_x(y)) = 0$, we get

$$\mathcal{I} = \int_{w=-w_0}^{0} \int_{z=y}^{1} \frac{1}{\left(w^2 + 2\left(\varphi(y) - \varphi(z)\right)\right)^{1/2}} dz \frac{-w}{\left(w^2 + 2\left(\varphi(y) - \varphi(x)\right)\right)^{1/2}} dw.$$

Since $y \leqslant x$, we have $\varphi(y) \geqslant \varphi(x)$, and $\frac{-w}{\left(w^2 + 2(\varphi(y) - \varphi(x))\right)^{1/2}} \leqslant \frac{-w}{|w|} = 1$. By the strong convexity assumption, we have $\varphi(y) - \varphi(z) \geqslant -\varphi'(y)(z-y) + \frac{\alpha}{2}|z-y|^2 \geqslant \frac{\alpha}{2}(z-y)^2$, so that

$$\mathcal{I} \leqslant \int_{w=-w_0}^{0} \int_{z=y}^{1} \frac{1}{(w^2 + \alpha(z-y)^2)^{1/2}} dz dw = \int_{w=0}^{w_0} \int_{z=0}^{1-y} \frac{1}{(w^2 + \alpha z^2)^{1/2}} dz dw.$$

Using lemma (2.1), we conclude that

$$\mathcal{I} \leqslant 2 \frac{\sqrt{2w_0(1-y)}}{\alpha^{1/4}} = \frac{2\sqrt{2(1-y)}}{\alpha^{1/4}} \left(v_0^2 + 2 \left(\varphi(x) - \varphi(y) \right) \right)^{1/4}$$

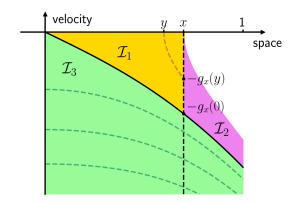


Figure 1: Decomposition of the integral defining n_i .

The phase space is divided by the critical characteristic (in solid black). Whenever $v \leq -g_x(0)$, the characteristics (dotted green lines) are reaching the boundary with $x_b(x,v) = 0$.

Proposition 2.1. The density n_i is bounded by a constant depending on φ only through $\varphi(1)$.

Demonstration We use the symmetry of f_i to write

$$n_i(x) = \int_{v = -\infty}^{\infty} f_i(x, v) dv = 2 \int_{v = -\infty}^{0} f_i(x_b(x, v), v_b(x, v)) dv = 2 \int_{v = -\infty}^{0} \int_{t = -\infty}^{0} f_e(x(t), v(t)) dt dv,$$

where $(x(t), v(t))_{t \leq 0}$ is the ion characteristic reaching $(x_b(x, v), v_b(x, v))$ at t = 0. Notice that the lower bounds are artificial, since the characteristic enters the support of f_e in finite time: we may use $v \geq -\overline{v}_e$, and consider only times t for which $x(t) \in [0, 1]$.

We first reparametrize (x(t), v(t)) using the space variable. Define $z = x(t) \in [x_b, 1]$, and observe that

$$dz = \dot{x}(t)dt = v(t)dt$$
, with $\mathcal{L}_i(z, v(t)) = \mathcal{L}_i(x, v)$ \iff $v(t) = -\left(v^2 + 2\left(\varphi(x) - \varphi(z)\right)\right)^{1/2}$.

Then, the density rewrites

$$n_i(x) = 2 \int_{v = -\overline{v}_e}^0 \int_{z = x_b(x, v)}^1 \frac{f_e\left(z, -\left(v^2 + 2\left(\varphi(x) - \varphi(z)\right)\right)^{1/2}\right)}{\left(v^2 + 2\left(\varphi(x) - \varphi(z)\right)\right)^{1/2}} \, dz dv.$$

Let us show that n_i is bounded. We use the coarse estimate $f_e \leqslant \bar{c}$, and decompose the integral in three:

$$n_{i}(x) \leqslant 2\overline{c} \left[\underbrace{\int_{v=-g_{x}(0)}^{0} \int_{z=x_{b}(x,v)}^{x}}_{\mathcal{I}_{1}} + \underbrace{\int_{v=-g_{x}(0)}^{0} \int_{z=x}^{1}}_{\mathcal{I}_{2}} + \underbrace{\int_{v=-\overline{v}_{e}}^{-g_{x}(0)} \int_{z=x_{b}(x,v)}^{1}}_{\mathcal{I}_{3}} \right] \frac{1}{(v^{2} + 2(\varphi(x) - \varphi(z)))^{1/2}} dz dv.$$

The corresponding domains are represented figure (1).

Notice that whenever $z \le x$, we have $0 \ge 2(\varphi(x) - \varphi(z)) = -(2(\varphi(z) - \varphi(x)))^{2/2} = -g_x^2(z)$. Then, the integral \mathcal{I}_1 may be bounded using lemma (2.5) with y = 0:

$$\mathcal{I}_{1} = \int_{v=-g_{x}(0)}^{0} \int_{z=x_{b}(x,v)}^{x} \frac{1}{\left(v^{2}-g_{x}^{2}(z)\right)^{1/2}} \, dz dv \leqslant 2\sqrt{\frac{2}{\alpha}} \left(-\varphi(x)\right)^{1/4} \sqrt{x} \leqslant 2\sqrt{\frac{2}{\alpha}} \left(-\varphi(1)\right)^{1/4}.$$

We use lemma (2.6) to bound \mathcal{I}_2 and \mathcal{I}_3 . In the first case, we take y=x and $v_0=g_x(0)$, and notice that $-g_x(x)=0$. In the second case, we take $v_0=\overline{v}_e$ and y=0, and notice that on $v \leq -g_x(0)$, we have $x_b(x,v)=0$ (the velocity is low enough so that the characteristic ends on $x_b=0$). This yields

$$\mathcal{I}_{2} \leqslant \frac{2\sqrt{2(1-x)}}{\alpha^{1/4}} \left(g_{x}^{2}(0)\right)^{1/4} \leqslant \frac{4}{\alpha^{1/4}} \left(-\varphi(1)\right)^{1/2}, \quad \text{and} \quad \mathcal{I}_{3} \leqslant \frac{2\sqrt{2}}{\alpha^{1/4}} \left(\overline{v}_{e}^{\ 2} + 2\varphi(x)\right)^{1/4} \leqslant \frac{4}{\alpha^{1/4}} \left(\frac{\beta}{\mu}\right)^{1/4}.$$

Proposition 2.2. The density n_i is continuous.

Demonstration Let $0 \le y < x \le 1$. For convenience, we represent $n_i(x)$ (resp. $n_i(y)$) as an integral with the artificial lower bound $-g_x(-\overline{v}_e) \le -\overline{v}_e$ (resp. $-g_y(-\overline{v}_e)$). Then

$$n_{i}(x) - n_{i}(y) = 2 \int_{v = -g_{x}(-\overline{v}_{e})}^{0} f_{i}(x_{b}(x, v), v_{b}(x, v)) dv - 2 \int_{v = -g_{y}(-\overline{v}_{e})}^{0} f_{i}(x_{b}(y, v), v_{b}(y, v)) dv$$

$$= 2 \underbrace{\left[\int_{v = -g_{x}(-\overline{v}_{e})}^{-g_{x}(y)} f_{i}(x_{b}(x, v), v_{b}(x, v)) dv - \int_{v = -g_{y}(-\overline{v}_{e})}^{0} f_{i}(x_{b}(y, v), v_{b}(y, v)) dv \right]}_{=:\mathcal{T}^{-}} + 2 \underbrace{\int_{v = -g_{x}(y)}^{0} f_{i}(x_{b}(x, v), v_{b}(x, v)) dv}_{=:\mathcal{T}^{+}}.$$

The term \mathcal{I}^+ is clearly nonnegative, and may be addressed using our lemmas. Indeed, using the integral representation of $f_i(x_b, v_b)$ and the reparametrization by a space variable z, we have

$$\begin{split} \mathcal{I}^{+} &= \int_{v=-g_{x}(y)}^{0} \left[\int_{z=x_{b}(x,v)}^{x} + \int_{z=x}^{1} \left[\frac{f_{e}(z, -\left(v^{2}+2\left(\varphi(x)-\varphi(z)\right)\right)^{1/2})}{\left(v^{2}+2\left(\varphi(x)-\varphi(z)\right)\right)^{1/2}} \, dz dv \right. \\ &\leqslant \overline{c} \int_{v=-g_{x}(y)}^{0} \int_{z=x_{b}(x,v)}^{x} \frac{1}{\left(v^{2}-g_{x}^{2}(z)\right)^{1/2}} \, dz dv + \overline{c} \int_{v=-g_{x}(y)}^{0} \int_{z=x}^{1} \frac{1}{\left(v^{2}+2\left(\varphi(x)-\varphi(z)\right)\right)^{1/2}} \, dz dv \\ &\leqslant \overline{c} \left(2\sqrt{\frac{2}{\alpha}} \left(\varphi(y)-\varphi(x)\right)^{1/4} \sqrt{x-y} + \frac{2\sqrt{2}}{\alpha^{1/4}} \left(2(\varphi(y)-\varphi(x))\right)^{1/2} \right), \end{split}$$

where we used lemma (2.5) for the first term, and lemma (2.6) for the second term (with y=x and $v_0=-g_x(y)$ under the notations of the lemma). Since φ is continuous, we deduce that $\mathcal{I}^+\underset{y\to x}{\longrightarrow} 0$. Taking the extreme case y=0 and x=1, we obtain that

$$\mathcal{I}^{+} \leqslant \overline{c} \left(2\sqrt{\frac{2}{\alpha}} \left(-\varphi(1) \right)^{1/4} + \frac{2\sqrt{2}}{\alpha^{1/4}} \left(-2\varphi(1) \right)^{1/2} \right) =: K.$$

Let us now focus on \mathcal{I}^- . On the first integral, we make the change of variable

$$w = -(v^2 + 2(\varphi(x) - \varphi(y)))^{1/2}$$
 $v = -(w^2 + 2(\varphi(y) - \varphi(x)))^{1/2}$.

Since $\mathcal{L}_i(x,v) = \mathcal{L}_i(y,w)$, this yields $x_b(x,v) = x_b(y,w)$ and $v_b(x,v) = v_b(y,w)$. The bounds $v \in [-g_x(-\overline{v}_e), -g_x(y)]$ are exactly transported to $w \in [-g_y(-\overline{v}_e), 0]$. Renaming w in v, we get

$$\mathcal{I}^{-} = \int_{v = -g_{y}(-\overline{v}_{e})}^{0} f_{i}(x_{b}(y, v), v_{b}(y, v)) \left(\frac{-v}{\left(v^{2} + 2\left(\varphi(y) - \varphi(x)\right)\right)^{1/2}} - 1\right) dv.$$

Since $\varphi(y) \geqslant \varphi(x)$, the factor of f_i is nonpositive, and so is \mathcal{I}^- . Moreover,

$$n_i(x) - n_i(y) = 2\mathcal{I}^- + 2\mathcal{I}^+ \leqslant 2\mathcal{I}^- + 2K \quad \Longleftrightarrow \quad \mathcal{I}^- = -K + n_i(x) - n_i(y) \geqslant -K - |n_i|_{\infty}$$

and \mathcal{I}^- is bounded. The function $\frac{-v}{\left(v^2+2(\varphi(y)-\varphi(x))\right)^{1/2}}-1$ converges pointwise to 0 when $x\to y$ and f_i is almost everywhere finite, and by Lebesgue's dominated convergence, $\mathcal{I}^-\underset{x\to y}{\longrightarrow} 0$. Then n_i is continuous.

In the future:

- Now that we have estimates, write it in function of α and β , and see how to get stability of the set of strongly concave functions satisfying all the hypotheses by the Poisson problem (essentially, find tweaks of λ , μ , ν , α and/or β such that the estimates are propagated).
- If $f_{e,b}$ vanishes in a neighbourhood of (0,0) (or decreases fast enough, see how fast), show that f_i is bounded.
- Under that same assumption, we should obtain stronger continuity over n_i , and n_i may be continuous with respect to φ (in the same sense as n_e in lemma (2.4)).
- If the estimates with respect to $|\varphi \psi|_{\infty}$ succeed, define numerical scheme and see what we cas say about it.