

Numerical methods for plasma sheaths

CEMRACS 2022

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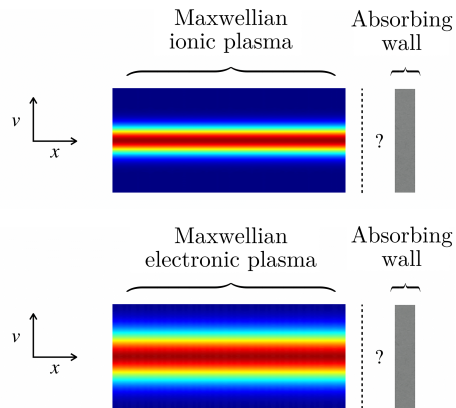
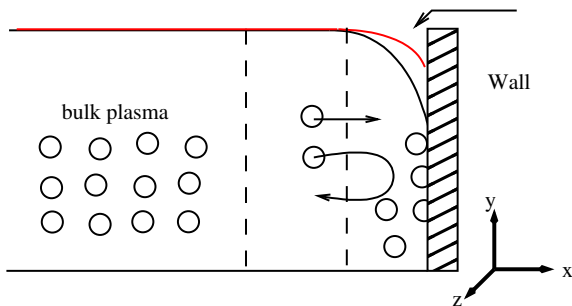
Results

Comparison between the evolutionary algorithms

Dialog with equilibrium code

Motivation

Study the formation of steady *sheath*.



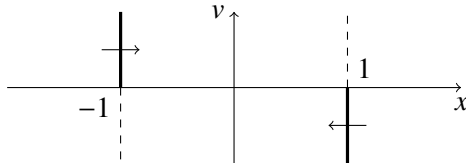
The model

$$\left\{ \begin{array}{l} \partial_t f_i(t, x, v) + v \partial_x f_i(t, x, v) - \partial_x \phi(t, x) \partial_v f_i(t, x, v) = \nu f_e(t, x, v), \\ \partial_t f_e(t, x, v) + v \partial_x f_e(t, x, v) + \frac{1}{\mu} \partial_x \phi(t, x) \partial_v f_e(t, x, v) = 0, \\ -\lambda^2 \partial_{xx} \phi(t, x) = \int_{\mathbb{R}} f_i(t, x, v) dv - \int_{\mathbb{R}} f_e(t, x, v) dv \end{array} \right. \quad (1)$$

- $f_i := f_i(t, x, v)$, $(t, x, v) \in \mathbb{R}^+ \times [-1, 1] \times \mathbb{R}$ Density of ions.
- $f_e := f_e(t, x, v)$, $(t, x, v) \in \mathbb{R}^+ \times [-1, 1] \times \mathbb{R}$ Density of electrons.
- $\phi := \phi(t, x)$, $(t, x) \in \mathbb{R}^+ \times [-1, 1]$ Electrostatic potential.
- mass ratio $\mu > 0$, ionization frequency $\nu \geq 0$, and Debye length $\lambda > 0$.

Boundary conditions

- $f_{i,e}(0, x, v) = f_{i,e}^0(x, v),$
- $f_{i,e}(t, x = -1, v > 0) = 0$ and $f_{i,e}(t, x = 1, v < 0) = 0,$
- $\phi(t, 0) = 0, \partial_x \phi(t, 0) = 0,$
- $-\lambda^2 \partial_{xx}^2 \phi(0, x) = \int_{\mathbb{R}} f_i^0(x, v) dv - \int_{\mathbb{R}} f_e^0(x, v) dv.$



Boundary conditions

We consider

$$f_i^0(x, v) := \frac{e^{-v^2/2}}{\sqrt{2\pi}}, \quad f_e^0(x, v) := \frac{\sqrt{\mu}e^{-\mu v^2/2}}{\sqrt{2\pi}}, \quad \phi(0, x) = E(0, x) := 0.$$

Let the electric field and currents be defined $\forall(t, x) \in \mathbb{R}^+ \times [-1, 1]$ as

$$E(t, x) := -\partial_x \phi(t, x), \quad \text{and} \quad J_{i,e}(t, x) := \int_{\mathbb{R}} v f_{i,e}(t, x, v) dv.$$

Then, denoting $J := J_i - J_e$,

$$\lambda^2 \partial_t E(t, \pm 1) := J(t, \pm 1) \pm \frac{v}{2} \int_{-1}^1 \int_{\mathbb{R}} f_e(t, y, v) dy dv.$$

Objectives of the CEMRACS project

- Investigate numerically the stationary solution with high-order approximation method.
- Integrate nonperiodic boundary conditions.
- Tools to approximate Vlasov equations:
 - Finite difference code (FD),
 - Semi-Lagrangian code (SL),
 - Fixed-point code (FP).

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1D Transport

$$\begin{cases} \partial_t u(t, x) + c \partial_x u(t, x) = 0 & \text{for } t \geq 0, x \in [a, b], c > 0, \\ u(0, x) = u_0(x) & \text{for } x \in [a, b], \\ u(t, a) = u_L(t) & \text{for } t \geq 0. \end{cases} \quad (2)$$

The solution is constant along the characteristic lines:

$$u(t, x) = \begin{cases} u_0(x - ct) & \text{if } x - a \geq ct, \\ u_L\left(t - \frac{x - a}{c}\right) & \text{if } x - a \leq ct. \end{cases} \quad (3)$$

Let $x_i := a + i\Delta x$, $\Delta x > 0$, $x_N = b$ and $t_n := n\Delta t$, $\Delta t > 0$.

$$u_i^{n+1} \simeq u(t_{n+1}, x_i) = u(t_n, x_i - c\Delta t). \quad (4)$$

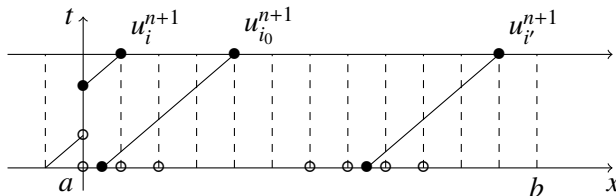
1D Transport

- Choice of Lagrange interpolation on a stencil of width $2d + 2$.
- Ghost points: **Inflow** x_{-i} , **Outflow** x_{N+i} , $i \in \mathbb{N}$.

Inflow: we set $i_0 := \lceil c\Delta t / \Delta x \rceil$, then for all $i < i_0$,

$$u_i^{n+1} \simeq u_L(t_{n+1} - i\Delta x/c). \quad (5)$$

For $i \in \llbracket i_0, d-1 \rrbracket$, interpolation with $u_{-j}^n := u_L(t_n + j\Delta x/c)$, $j \in \mathbb{N}$.



1D Transport

Outflow: if the interpolation stencil needs ghost points at the right of the domain ($i_0 \leq d$).

Idea from (Coulombel *et al.* 2020):

- Introduce the finite difference operator $(Du)_j := u_j - u_{j-1}$.
- Let $k_b \in \mathbb{N}$, and deduce u_{N+i}^n by enforcing $(D^{k_b} u^n)_{N+i} = 0, i \in \llbracket 1, d \rrbracket$.

Then u_{N+i}^n is a linear combination of $u_{N+i-1}^n, \dots, u_{N+i-k_b}^n$.

Equivalent to polynomial extrapolation of order $k_b - 1$.

Poisson equation

Let $x \in [-1, 1]$. We look for symmetric solutions: $\phi(t, x) = \phi(t, -x)$, with

$$\begin{cases} -\lambda^2 \partial_{xx}^2 \phi(t, x) &= n(t, x) := \int_{v \in \mathbb{R}} (f_i - f_e)(t, x, v) dv, \\ \phi(t, 0) = \partial_x \phi(t, 0) &= 0. \end{cases} \quad (6)$$

Let $E := -\partial_x \phi$ the electric field in (1). Then $E(t, x) = -E(t, -x)$, with

$$\begin{cases} \lambda^2 \partial_x E(t, x) &= n(t, x) \\ -E(t, 0) &= 0. \end{cases} \quad \implies \quad E(t, x) = \frac{1}{\lambda^2} \int_0^x n(t, y) dy. \quad (7)$$

- Resolution by quadrature.
- Numerically, useful to enforce the symmetry of n .

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Finite difference discretization (FD, C++)

Classical explicit upwind scheme for f_s , $s \in \{e, i\}$:

$$\frac{f_{s,k,l}^{n+1} - f_{s,k,l}^n}{\Delta t} + \left(\frac{v_l}{c_s E_k^n} \right)_+ D_{k,l}^- f_s^n + \left(\frac{v_l}{c_s E_k^n} \right)_- D_{k,l}^+ f_s^n = S_{s,k,l}^n$$

where $S_e := 0$, $S_i := \nu f_e$, $c_e := -\frac{1}{\mu}$, $c_i := 1$, and $D_{k,l}^\pm f := \pm \left(\frac{f_{k\pm 1,l} - f_{k,l}}{\Delta x}, \frac{f_{k,l\pm 1} - f_{k,l}}{\Delta v} \right)^t$.

Finite difference discretization (FD, C++)

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Integration for E , assuming $E(t, 0) = 0$:

$$E_k^{n+1} = \frac{1}{\lambda^2} \text{Trapezoid}_{\Delta x} (n_i^n - n_e^n)$$

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- First order, diffusive, CFL condition.

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$$E_k^{n+1} = \frac{1}{\lambda^2} \text{Trapezoid}_{\Delta x} (n_i^n - n_e^n)$$

- First order, diffusive, CFL condition.
- Common speed mesh for electrons and ions.

Semi-Lagrangian scheme (SL, C)

Strang splitting:

$$\frac{\Delta t}{2} \quad \begin{cases} \partial_t f_s + v \partial_x f_s = 0 & \text{Linear advection at constant speed} \\ \lambda^2 \partial_x E = n_i - n_e & \text{Resolution by (numerical) integration} \end{cases}$$
$$\frac{\Delta t}{2} \quad \begin{cases} \partial_t f_i = \nu f_e & \text{Pointwise ODE} \end{cases}$$

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$$\Delta t \quad \partial_t f_s + c_s E \partial_v f_s = 0 \quad \text{Again, advection at constant speed}$$

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- Use of the 1D solver (with appropriate boundary conditions).

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- Use of the 1D solver (with appropriate boundary conditions).
- Different speed meshes for f_e and f_i .

Fixed-point algorithm (Badsì *et al.* 2021) (FP, Julia ♥)

Equilibrium state:

$$\begin{cases} v\partial_x f_s - c_s \partial_x \phi \partial_v f_s = S_s, & \frac{d}{d\tau}[f_s(x_s(\tau), v_s(\tau))] = S_s(x_s(\tau), v_s(\tau)) \\ -\lambda^2 \partial_{xx}^2 \phi = n_i - n_e \end{cases}$$

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Suppose ϕ^k is known. Iteration of

$$f_e^k(x, v) \quad := \quad f_{e,b}(x_e(-\tau), v_e(-\tau))$$

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Suppose ϕ^k is known. Iteration of

$$\begin{aligned} f_e^k(x, v) &:= f_{e,b}(x_e(-\tau), v_e(-\tau)) \\ f_i^k(x, v) &:= f_{i,b}(x_i(-\tau), v_i(-\tau)) + \int_{-\tau}^0 v f_e^k(x_i(s), v_i(s)) ds \end{aligned}$$

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$$\begin{aligned} f_e^k(x, v) &:= f_{e,b}(x_e(-\tau), v_e(-\tau)) \\ f_i^k(x, v) &:= f_{i,b}(x_i(-\tau), v_i(-\tau)) + \int_{-\tau}^0 v f_e^k(x_i(s), v_i(s)) ds \\ -\lambda^2 \partial_{xx}^2 \phi^{k+1} &:= \int_v [f_i^k(\cdot, v) - f_e^k(\cdot, v)] dv \end{aligned}$$

until convergence.

What does equilibrium look like

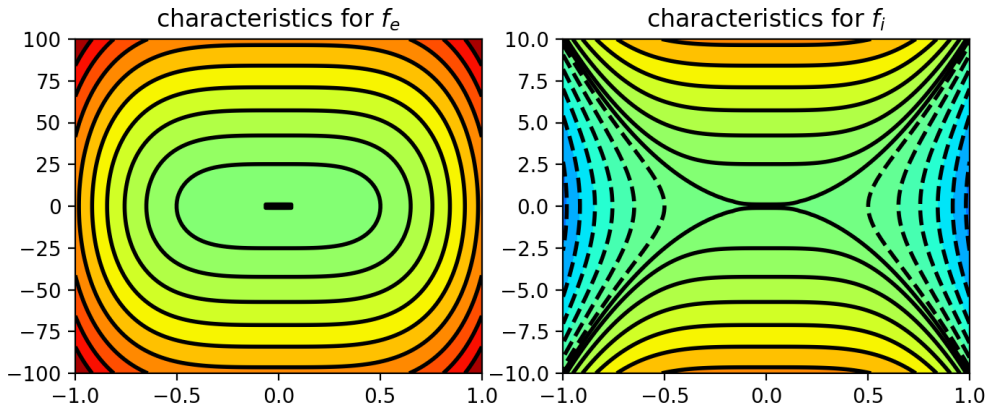
- The electron density $f_e(x, v)$ is constant along its characteristics.

What does equilibrium look like

- The electron density $f_e(x, v)$ is constant along its characteristics.
- The ion density $f_i(x, v)$ is the integral along its characteristics of $v f_e$.

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What does equilibrium look like

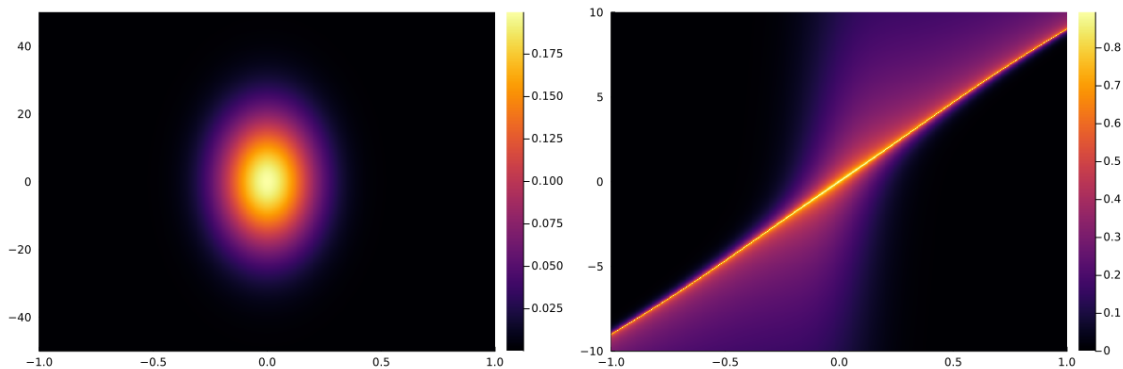


Figure: Left: electron density f_e . Right: ion density f_i (logscale).

$$\lambda = 0.1, \quad \mu := \frac{m_e}{m_i} = \frac{1}{100}, \quad \nu = 42, \quad N_{x,v_e,v_i} = 1024.$$

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Validation test case (DF): one-species (Malkov 2020)

Discretization parameters:

$$x \in [-1.5, 1.5], v_e \in [-2, 2], N_x = 2048, N_v = 2049.$$

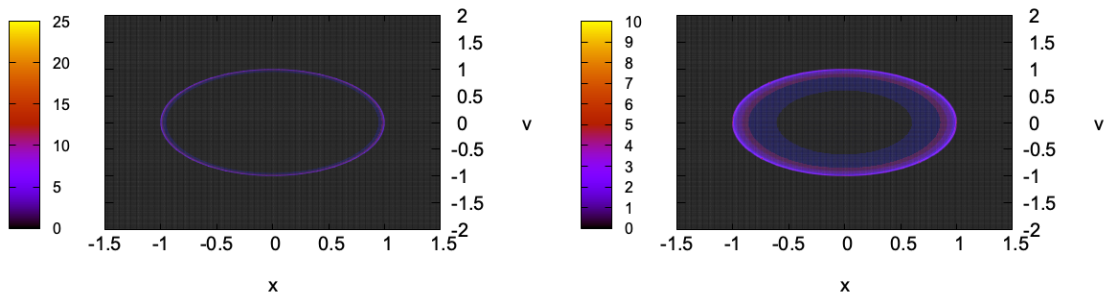


Figure: Left: solution at $t = 0.01$, Right: solution at $t = 0.05$.

Validation test case (DF): one-species (Malkov 2020)

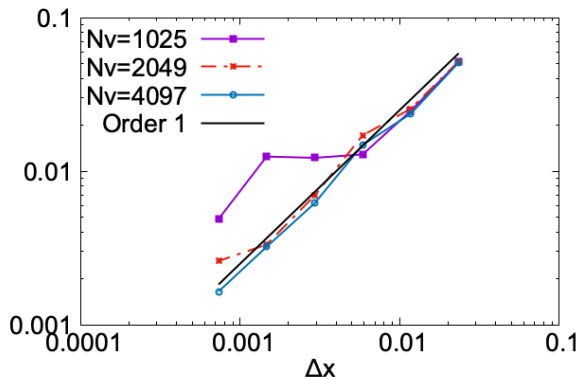


Figure: Error L^1 on the field E at time $T = 0.1$.

(SL)/(DF): Two-species Vlasov-Poisson

Simulation parameters:

$$\begin{cases} x \in [-1, 1], v_e \in [-20, 20], v_i \in [-10, 10], N_x = 256, N_{v_e} = 255, \\ N_{v_i} = 255, d = 8, k_b = 1, \mu = 1/100, \nu = 10, N_t = 3000, T = 3. \end{cases}$$

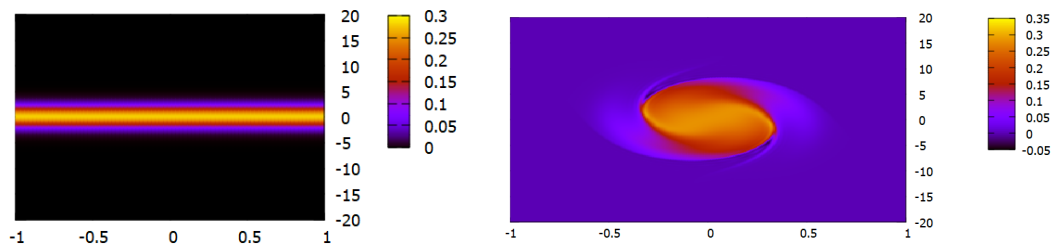


Figure: Electron distribution in phase space. Left: initial condition, right: time $T = 3$.

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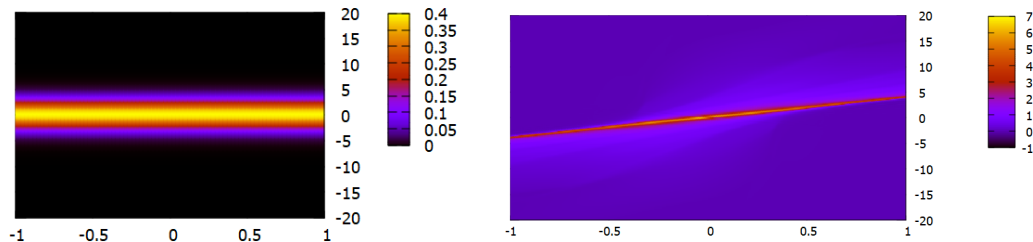


Figure: Ion distribution in phase space. Left: initial condition, right: time $T = 3$.

(SL)/(DF): Two-species Vlasov-Poisson with mask

Idea: multiply the initial conditions by a mask \mathcal{M} defined as

$$\mathcal{M}(x) := \frac{1}{2} \left(\tanh\left(\frac{x - x_l}{d_r}\right) - \tanh\left(\frac{x - x_r}{d_r}\right) \right), \quad \text{with } x_l = -0.1, x_r = 0.1, d_r = 0.1.$$

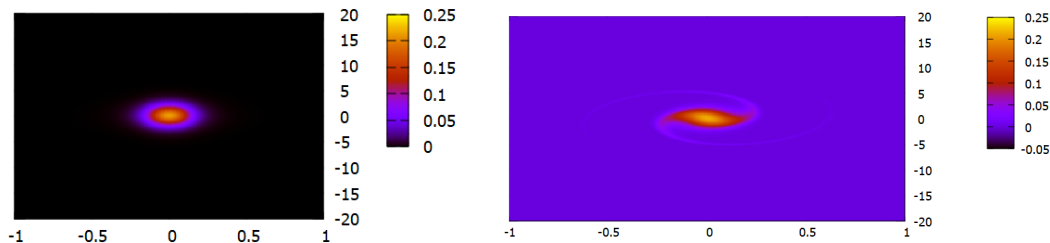


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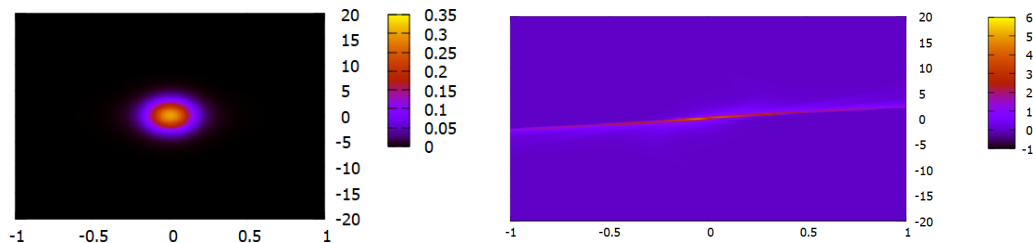


Figure: Ion distribution in phase space. Left: initial condition, right: time $T = 3$.

From (SL) to (FP)

Simulation parameters:

$$\begin{cases} x \in [-1, 1], v_e \in [-10, 10], v_i \in [-8, 8], \\ N_x = 8192, N_{v_e} = 511, N_{v_i} = 4095, \\ \mu = 1/2, \nu = 20, \lambda = 0.5. \end{cases}$$

Initial conditions:

$$\begin{cases} f_e(t = 0, x, v) &:= \mathcal{M}(x) \times f_e^0(x, v), \\ f_i(t = 0, x, v) &:= \mathcal{M}(x) \times f_i^0(x, v). \end{cases}$$

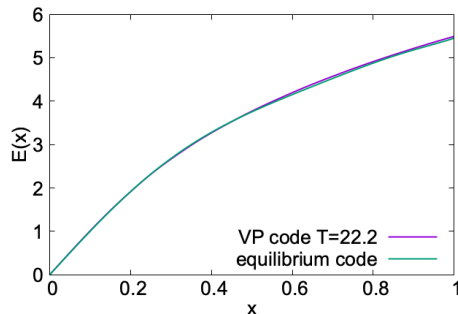


Figure: Electric field E at $T = 22.2$.

From (SL) to (FP)

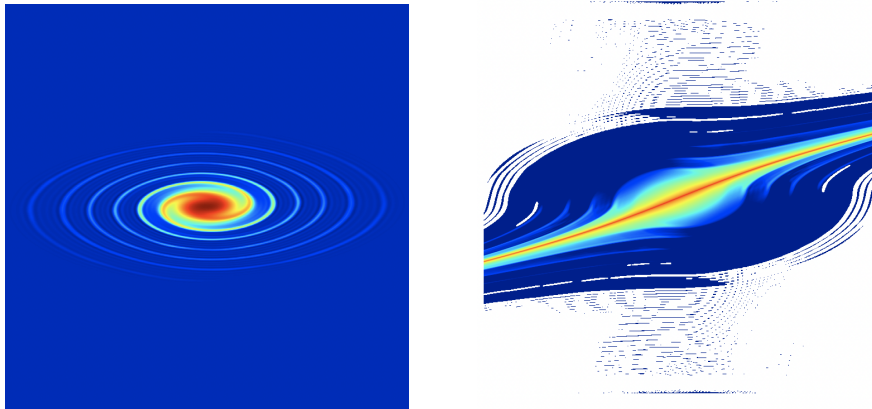


Figure: Electron and ion distributions in phase space. Left: f_e , right: f_i .

Equilibrium code

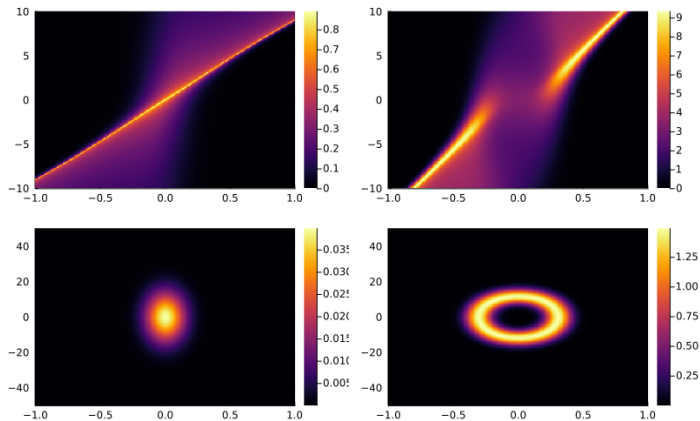


Figure: Equilibrium densities (up: f_i , down: f_e) for nonvanishing and vanishing $f_e(0,0)$.

From (FP) to (SL)

- Idea: initialize the semi-Lagrangian with the computed steady state.

From (FP) to (SL)

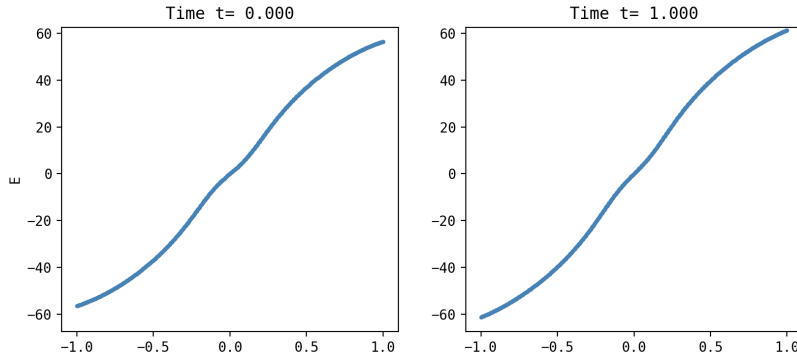
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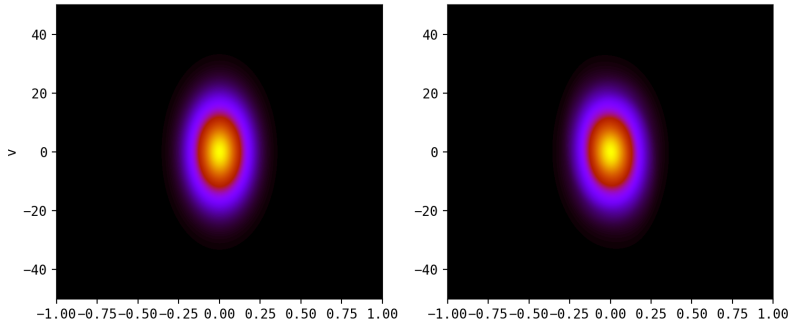
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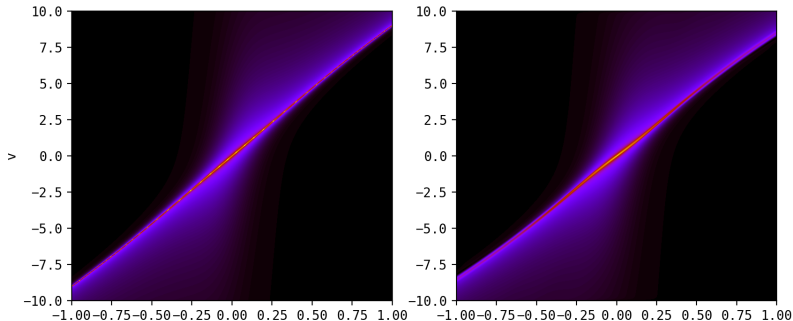
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That's all folks, enjoy the **BOUMLLABAISSE!**

Thank you for your attention

 Mehdi Badsì, Christophe Berthon, and Anaïs Crestetto.

A stable fixed point method for the numerical simulation of a kinetic collisional sheath.

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