# Engineering Calculus III MATH 251 at Texas A&M Using Calculus: Early Trancendentials, 8th Edition

Brandon Nguyen

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# Lecture 1

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### 1.1 Three-Dimensional Coordinate System

### Definition 1.1 Three Dimensional Coordinate System

A point in three dimensions is represented by a triple, (x, y, z), of numbers. The set of all triples is denoted by  $\mathbb{R}^3$ .

### Definition 1.2 Right Hand Rule

The **right hand rule** describes the relationship between the three axes. To use the rule, curl the fingers of your right hand around the z axis.

### Example 1.1

Plot the point (-3,4,2) in the coordinate system.

#### **Definition 1.3 Coordinate Planes**

In  $\mathbb{R}^3$  there exists the following coordinate planes:

- xy-planedefined by (x, y, 0).
- xz-planedefined by (x, 0, z).
- yz-planedefined by (0, y, z).

These coordinate planes split  $\mathbb{R}^3$  into **octants**. Octant 1 is defined to be where the x, y, z are positive.

### Definition 1.4 Projection onto Coordinate Planes

Given a point P(a, b, c):

- Q(a, b, 0) is the **projection** of P onto the xy-plane
- R(0,b,c) is the projection of P onto the yz-plane
- S(a,0,c) is the projection of P onto the xz-plane

### Example 1.2

Find the projections of (3, -1, 4) onto the coordinate planes.

### 1.2 Surfaces

### **Definition 1.5 Surfaces**

An equation given in x, y, z gives a **surface** in  $\mathbb{R}^3$ .

The coordinate planes can be represented by:

- yz-plane  $\iff x = 0$ , or all points (0, y, z)
- xz-plane  $\iff y = 0$ , or all points (x, 0, z)
- xy-plane  $\iff z = 0$ , or all points (x, y, 0)

The equations in the form of x=c,y=c,z=c in  $\mathbb{R}^3$  give planes.

#### Example 1.3

Describe and sketch the following planes

- 1. x = 5, a plane 5 units ahead and parallel to yz-plane
- 2. z = 2, a plane 2 units above and parallel to xy-plane

### Example 1.4

How do the planes x = 5, z = 2 intersect?

$$(5, y, z) \cap (x, y, 2) = (5, y, 2) \tag{1.1}$$

(5, y, 2) represents a line parallel to the y-axis.

### Method 1.1 Two-Variable Equations

A surface formed by a two-variable equation can be graphed by first creating the graph in  $\mathbb{R}^2$  corresponding to the two variables. This can then be extended to  $\mathbb{R}^3$  w.r.t. the missing axis.

### Example 1.5

Sketch and describe the following surfaces in  $\mathbb{R}^3$ 

- 1. y + x = 22.  $x^2 + y^2 = 9$ 3.  $x^2 + (z 4)^2 = 4$

#### **Spheres** 1.3

### Definition 1.6 Equation of a Sphere

The equation of a sphere with a center C(h, k, l) and radius r is given by

$$(x-h)^{2} + (y-r)^{2} + (z-l)^{2} = r^{2}$$
(1.2)

### Example 1.6

Find an equation of the sphere with center (5, 3, 2) and radius 3. Find and describe the intersection of this sphere and the coordinate planes.

# Lecture 2

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## 2.1 Spheres (cont.)

### Example 2.1

Show that

$$x^{2} + y^{2} + z^{2} - 6x + 8y - 4z = 20$$
 (2.1)

represents a sphere, find the centre and radius.

### Example 2.2

What is the equation of the sphere with center (1,2,3) that touches the xy-plane

### 2.2 Formulae

### **Definition 2.1 Distance Formula**

The distance between points P(a,b,c) and Q(x,y,z) is given by

$$|PQ| = \sqrt{(x-a)^2 + (y-b)^2 + (z-c)^2}$$
 (2.2)

### Example 2.3

Consider the points P(5, 5, 1), Q(3, 3, 2), R(1, 4, 4)

- 1. Find the lengths of the triangle
- 2. What type of triangle is it?

### Definition 2.2 Midpoint Formula

The midpoint of P(a, b, c) and Q(x, y, z) is given by

$$\left(\frac{x+a}{2}, \frac{y+b}{2}, \frac{z+c}{2}\right) \tag{2.3}$$

### Example 2.4

Find an equation of a sphere if one of its diameters has endpoints (2, 1, 4), and (4, 3, 10).

### 2.3 Solids

### Definition 2.3 Solids

Inequalities involving x, y, z gives solids in  $\mathbb{R}^3$ .

Like a circle is just a line outlining the boundary and a disk is the circle and everything inside. A sphere refers to the shell, while a ball refers to both the sphere and everything inside.

### Example 2.5

Sketch and describe the following regions in  $\mathbb{R}^3$ 

1. 
$$x^2 + y^2 \le 25$$

2. 
$$1 < x^2 + y^2 + z^2 < 16$$

### 2.4 Vectors

#### Definition 2.4 Vectors

A **vector** has both magnitude and direction.

Algebraically:

In three dimensions, a vector is given by

$$\vec{a} = \langle a_1, a_2, a_3 \rangle \tag{2.4}$$

where  $a_1, a_2, a_3$  are the components of  $\vec{a}$ , each corresponding to the x, y, z respectively.

Geometrically:

A vector has initial and terminal points. For example, a vector starting at the origin O, and terminal point  $P(a_1, a_2, a_3)$  is referred to the position vector of P.

Given the points  $A(x_1, y_1, z_1)$ ,  $B(x_2, y_2, z_2)$ , the vector with initial point A and terminal point B is given by

$$\vec{ab} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$
 (2.5)

### Definition 2.5 Magnitude

The magnitude or length of a vector

$$|\vec{a}| = \sqrt{a_1^2, a_2^2, a_3^2} \tag{2.6}$$

### 2.4.1 Vector Algebra

Addition

$$\vec{a} + \vec{b} = \langle a_1 + b1, a_2 + b2, a_3 + b3 \rangle$$
 (2.7)

Scalar Multiplication

$$c\vec{a} = \langle ca_1, ca_2, ca_3 \rangle \tag{2.8}$$

Difference

$$\vec{a} - \vec{b} = \vec{a} + (-\vec{b}) = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$$
 (2.9)

### Definition 2.6 Standard Basis Vectors