

Fundamental Aerodynamics

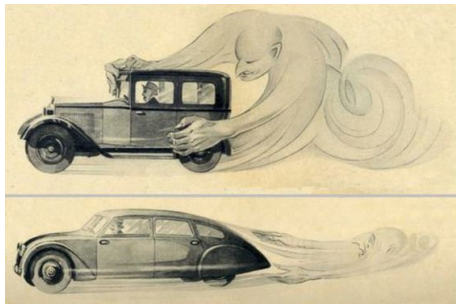
Boundary Layers (1)

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Introduction

Boundary layer equations

- Prandtl's BL equations

- Definitions of skin friction and BL thicknesses

Solutions for Laminar boudary layers

- Inviscid/viscous coupling

- Blasius solutions

- von Kármán integral equation

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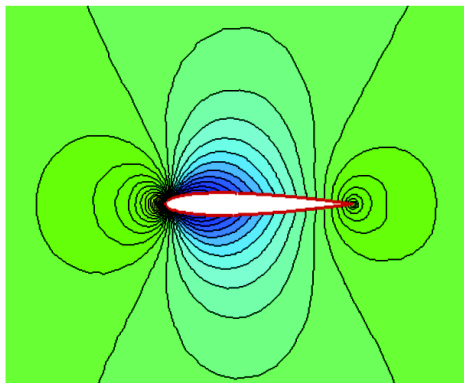
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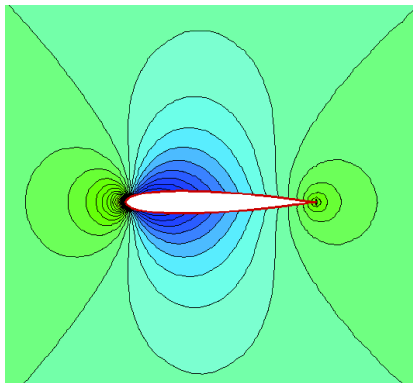
- von Kármán integral equation

Pressure field around an airfoil is sensibly the same, both in inviscid and in viscous flow. **Why?**

Pressure contours for NACA0012, $M=0.5$, $\alpha=0^\circ$

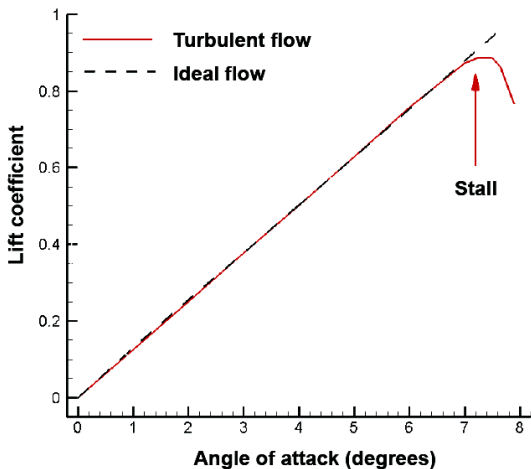


Ideal flow



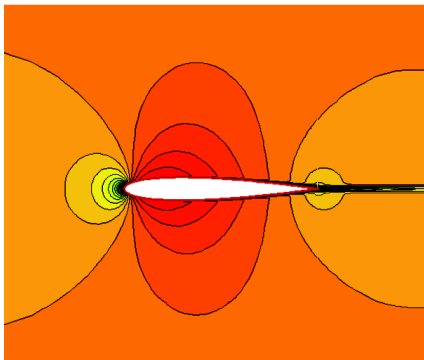
Viscous flow

Moreover, inviscid flow theories provide an excellent estimate of the lift coefficient, at least for low values of the angle of attack

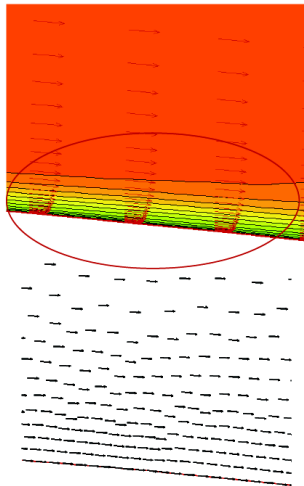


Explanation: presence of a **boundary layer**

Velocity contours



Viscous flow

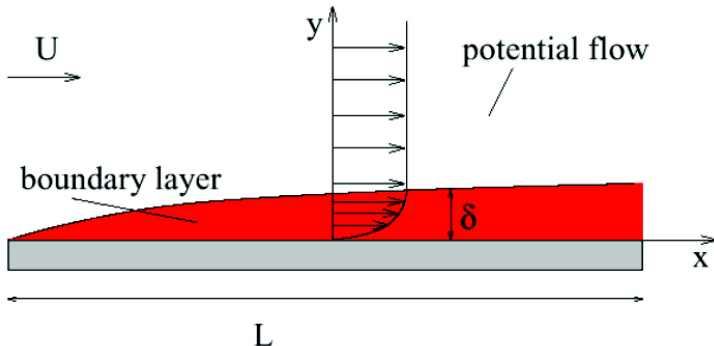


Ideal flow

Boundary layer: definition

Thin layer close to the wall where viscous effects cannot be neglected

- ▶ The higher Re , the thinner the boundary layer
- ▶ Close to the wall, viscous effects are always important
- ▶ Flow has to satisfy the no-slip condition



Qualitative aspects

- ▶ Ideal fluid: $\mathbf{T} = -p\mathbf{I}$ → Euler equations
- ▶ Actually, air = Newtonian viscous fluid

$$\begin{cases} \mathbf{T} = -p\mathbf{I} + \boldsymbol{\tau} \\ \boldsymbol{\tau} = 2\mu\mathbf{D} - \frac{2}{3}\text{Tr}(\mathbf{D})\mathbf{I} \end{cases}$$

- ▶ μ = dynamic viscosity [$\sim 1.8 \times 10^{-5}$ kg/(m s)] at normal conditions for T and p
- ▶ viscous stresses are not negligible in regions characterized by high velocity gradients (shear layers)

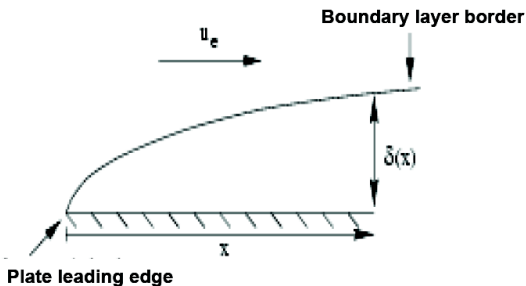
Description of a BL

Evolution of boundary layer thickness along a wal

► convection: $\frac{\partial u}{\partial t} + u_e \frac{\partial u}{\partial x} = 0 \Rightarrow u_e \propto x/t$

► diffusion: $\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial y^2} \Rightarrow 1/t \propto \nu/\delta^2$

$$\Rightarrow \frac{\delta(x)}{x} \propto \frac{1}{\sqrt{u_e x / \nu}}$$



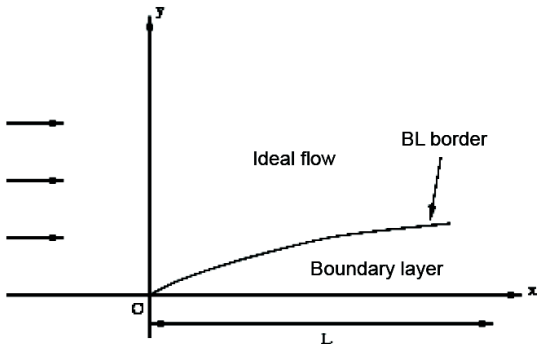
Nombre de Reynolds local:

$$Re_x = \frac{u_e x}{\nu}$$

$$\frac{\delta(x)}{x} \propto \frac{1}{\sqrt{Re_x}}$$

- ▶ Orders of magnitude of BL thickness in Aeronautics :
 - ▶ cruise flight speed of an aircraft: *several hundreds* m/s
 - ▶ air kinematic viscosity of the order of 10^{-5} m²/s
- ▶ Ratio u_e/ν of the order of 10^7 m⁻¹
- ▶ BL thickness :
 - ▶ some mm at a wing leading edge,
 - ▶ some cm at a wing trailing edge,
 - ▶ some dm at the rear of the fuselage

- ▶ General description of viscous fluid flow: **Navier-Stokes equations**
- ▶ **High-Reynolds** flow past an obstacle:
Boundary layer thickness \ll obstacle length (e.g., chord)
 \hookrightarrow *simplified* flow description



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- Navier-Stokes equations for 2D incompressible steady flow:

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \\ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \end{array} \right. \quad (1)$$

- Non-dimensional equations: *Unique* length scale L and velocity scale

$$\left\{ \begin{array}{l} x = L\bar{x}, \quad y = L\bar{y} \\ u = U_{\infty}\bar{u}, \quad v = U_{\infty}\bar{v} \\ p = \rho U_{\infty}^2 \bar{p} \end{array} \right.$$

- Non-dimensional equations:

$$\left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{x}} + \frac{1}{Re} \left(\frac{\partial^2 \bar{u}}{\partial \bar{x}^2} + \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \right) \\ \bar{u} \frac{\partial \bar{v}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{v}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{y}} + \frac{1}{Re} \left(\frac{\partial^2 \bar{v}}{\partial \bar{x}^2} + \frac{\partial^2 \bar{v}}{\partial \bar{y}^2} \right) \end{array} \right. \xrightarrow{Re \rightarrow \infty} \left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{x}} \\ \bar{u} \frac{\partial \bar{v}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{v}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{y}} \end{array} \right.$$

- Flow characteristic Reynolds number: $Re = \frac{U_{\infty} L}{\nu}$

→ Euler equations / ideal flow *incompatible* with no-slip condition at solid walls

- ▶ Existence of a region with thickness tending to 0 when the Reynolds number becomes large, not governed by the Euler equations
 \hookrightarrow solution of problem (1) is decomposed into the solution of two sub-problems:
 - ▶ **External problem**, governed by ideal flow equations (Euler equations)
 Characteristic length scale = L
 - ▶ **Internal problem** in the immediate neighborhood of solid walls governed by the **boundary layer equations**
 Characteristic length scale = BL thickness $\delta \ll L$
- ▶ Both solution satisfy matching conditions, at the interface of both regions, so that the inner solution *matches* the external solution (FP)
 Characteristic velocity scale in the inner region = $V_0 \ll U_\infty$

- ▶ System non-dimensionalization:

$$\begin{cases} x = L\bar{x}, & y = L\bar{y} \\ u = U_{\infty}\bar{u}, & v = U_{\infty}\bar{v} \\ p = \rho U_{\infty}^2 \bar{p} \end{cases} \longrightarrow \begin{cases} x = L\bar{x}, & y = \delta\tilde{y} \\ u = U_{\infty}\bar{u}, & v = V_0\tilde{v} \\ p = \rho U_{\infty}^2 \bar{p} \end{cases}$$

- ▶ Matching of the inner and outer solutions

$$\lim_{\tilde{y} \rightarrow \infty} \bar{u}(\bar{x}, \tilde{y}) = \lim_{\bar{y} \rightarrow \infty} \bar{u}(\bar{x}, \bar{y}) = \bar{u}_e(\bar{x})$$

Similar condition holds for the pressure p

- Transformation of system (1):

$$\left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{L}{\delta} \frac{V_0}{U_\infty} \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{L}{\delta} \frac{V_0}{U_\infty} \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{x}} + \frac{1}{Re} \left(\frac{\partial^2 \bar{u}}{\partial \bar{x}^2} + \left(\frac{L}{\delta} \right)^2 \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \right) \\ \bar{u} \frac{\partial \bar{v}}{\partial \bar{x}} + \frac{L}{\delta} \frac{V_0}{U_\infty} \bar{v} \frac{\partial \bar{v}}{\partial \bar{y}} = -\frac{L}{\delta} \frac{U_\infty}{V_0} \frac{\partial \bar{p}}{\partial \bar{y}} + \frac{1}{Re} \left(\frac{\partial^2 \bar{v}}{\partial \bar{x}^2} + \left(\frac{L}{\delta} \right)^2 \frac{\partial^2 \bar{v}}{\partial \bar{y}^2} \right) \end{array} \right.$$

- Minimal degeneracy principle: $\frac{\delta}{L} = \frac{V_0}{U_\infty}$ and $\frac{1}{Re} \left(\frac{L}{\delta} \right)^2 = 1$
↪ BL characteristic lengths

$$\delta = \frac{L}{\sqrt{Re}}, \quad V_0 = \frac{U_\infty}{\sqrt{Re}}$$

- Transformation of system (1):

$$\left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{x}} + \frac{1}{Re} \frac{\partial^2 \bar{u}}{\partial \bar{x}^2} + \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \\ \frac{1}{Re} \left(\bar{u} \frac{\partial \bar{v}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{v}}{\partial \bar{y}} \right) = -\frac{\partial \bar{p}}{\partial \bar{y}} + \frac{1}{Re^2} \frac{\partial^2 \bar{v}}{\partial \bar{x}^2} + \frac{1}{Re} \frac{\partial^2 \bar{v}}{\partial \bar{y}^2} \end{array} \right.$$

- Thus, for $Re \rightarrow \infty$

$$\left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = -\frac{\partial \bar{p}}{\partial \bar{x}} + \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \\ 0 = -\frac{\partial \bar{p}}{\partial \bar{y}} \end{array} \right.$$

Constant pressure
across the boundary layer, i.e.

$$\bar{p} = \bar{p}_e(x)$$

Pressure verifies Bernoulli's relation

$$\bar{p}_e + \frac{1}{2} \bar{u}_e^2 = \text{cste}$$

- ▶ Boundary layer equations or Prandtl equations

$$\begin{cases} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = \bar{u}_e \frac{d\bar{u}_e}{d\bar{x}} + \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \end{cases}$$

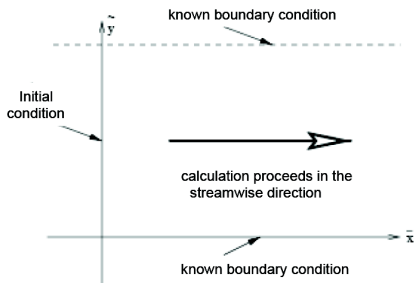
- ▶ no-slip condition: $\bar{u}(\bar{x}, 0) = 0$, $\bar{v}(\bar{x}, 0) = 0$
- ▶ matching with external layer: $\bar{u}(\bar{x}, \infty) = \bar{u}_e(\bar{x})$

- ▶ Dimensional boundary layer equations:

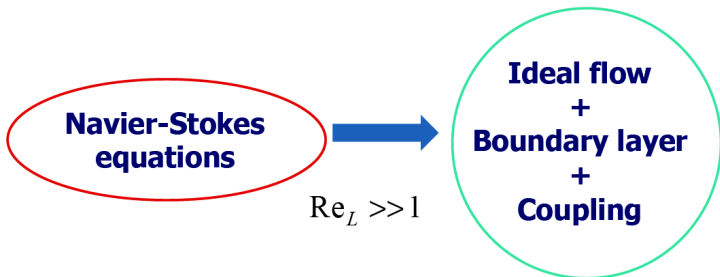
$$\begin{cases} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \\ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = u_e \frac{du_e}{dx} + \nu \frac{\partial^2 u}{\partial y^2} \end{cases}$$

- ▶ no-slip condition: $u = v = 0$ for $y = 0$
- ▶ matching with external layer: $u(x, \infty) = u_e(x)$

- ▶ System of parabolic equations *i.e.* describing a **marching problem in the streamwise flow direction x**
 - ↪ the system of Prandtl equations admits a unique solution when the problem is posed in the following form :



- ▶ Solved by space marching from upstream to downstream
- ▶ Solution blowup if flow separates ($\bar{u}(\bar{x}, \bar{y}) < 0$ becomes negative, so information propagates in the opposite sense)



If:

- ▶ there is no flow separation
- ▶ no strong wall curvature

- ▶ Viscous stress tensor:

$$\boldsymbol{\tau} = \begin{pmatrix} 2\mu \frac{\partial u}{\partial x} & \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \\ \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) & 2\mu \frac{\partial v}{\partial y} \end{pmatrix}$$

- ▶ Total stress tensor: $\mathbf{T} = -p\mathbf{I} + \boldsymbol{\tau}$
for high Reynolds number flow

$$\boldsymbol{\tau} = \begin{pmatrix} -p & \mu \frac{\partial u}{\partial y} \\ \mu \frac{\partial u}{\partial y} & -p \end{pmatrix}$$

→ Wall stress : $\mathbf{t} = \mathbf{T} \cdot \mathbf{n}$, where \mathbf{n} = unit normal to the wall

- ▶ Total wall stress:
 - ▶ purely normal (pressure) for ideal flow
 - ▶ both normal and tangential (viscous friction) components are present for viscous flow

$$\mathbf{t} = \mathbf{T} \cdot \mathbf{n} = \begin{pmatrix} \mu \frac{\partial u}{\partial y} \Big|_{y=0} = \tau_w \\ -p_e(x) \end{pmatrix}$$

with τ_w the viscous wall stress (skin friction)

- ▶ Skin friction normalized with wall pressure = friction coefficient

$$C_f = \frac{\tau_w}{\frac{1}{2} \rho u_e^2}$$

- ▶ Total viscous friction force = **friction drag** for instance, on the upper face of a flat plate of length L :

$$D = \int_0^L \tau_w(x) dx$$

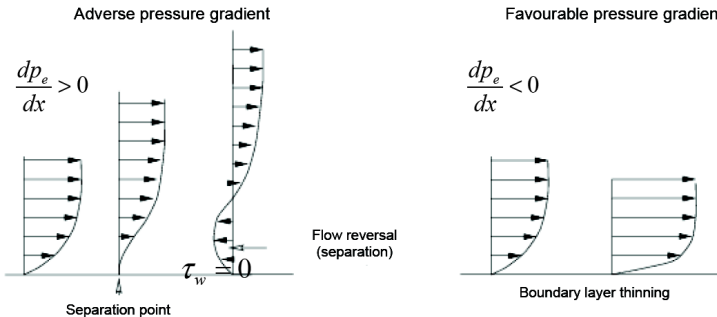
- ▶ Friction drag coefficient:

$$C_D = \frac{D}{\frac{1}{2}\rho u_e^2 L} = \frac{1}{L} \int_0^L \tau_w(x) dx \propto \frac{1}{\sqrt{Re_L}}$$

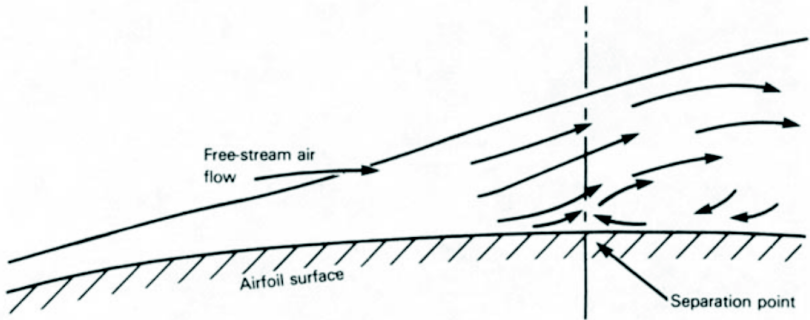
Friction drag = **substantial** contribution to the total drag of modern aircraft

↪ friction drag reduction is a major challenge in Aeronautics

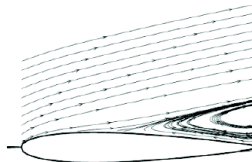
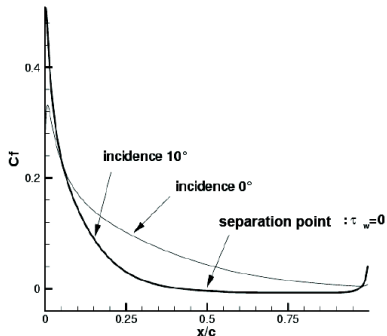
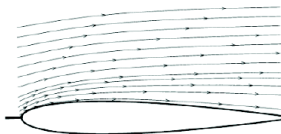
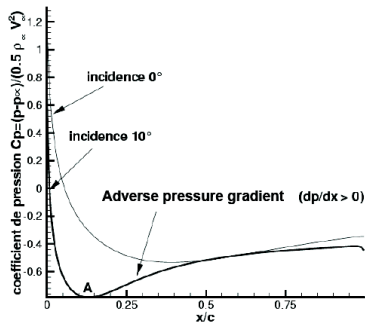
- ▶ Viscous friction slows down the flow in the vicinity of solid walls
- ▶ Positive pressure gradient $dp_e/dx > 0 \Rightarrow$ further **slow down** the flow
 \hookrightarrow fluid layer closest to the wall may be slowed down to zero velocity, and even reverse their direction: this phenomenon is called **separation**



Sketch of streamline patterns around a separation point

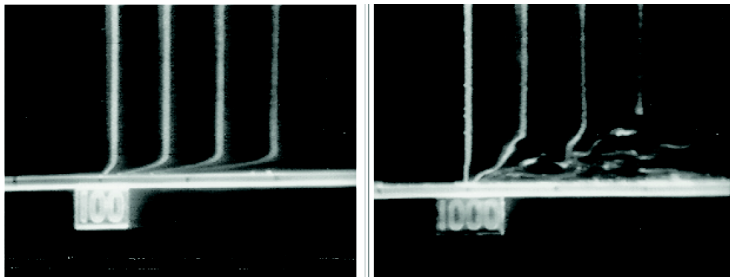


Flow separation past an airfoil



Experimental observations show that:

- ▶ Laminar BL are characterized by a regular flow motion, similar to the relative motion of thin fluid "laminae"
- ▶ For Reynolds numbers in the range 300 000 to 3 000 000 BL flow is no longer regular (laminar) and tends to become chaotic → **transition**

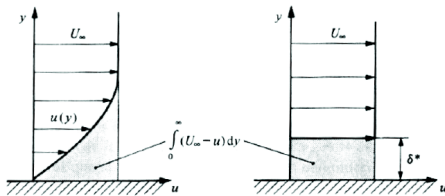


- ▶ Origin of laminar/turbulent transition :
 - ▶ Solutions of the Navier-Stokes equations become unstable when the Reynolds number exceeds a "critical" value which strongly depend on the specific flow configuration: small perturbations (due, e.g. to wall roughness) become unstable and amplified, leading to laminar/turbulent transition
 - ▶ Exact transition mechanisms are ill known yet (very active research field)
- ▶ Laminar BL and turbulent BL have a very different behavior, namely in terms of viscous friction and flow separation
 - accurate localization of the transition point is of the utmost importance for predicting aerodynamic performance
- ▶ Presently, predictions are mostly based on empirical criteria (experimental correlations):
 - ▶ implies a Reynolds number based on abscissa x and a Reynolds number based on boundary layer thickness

$$(Re_{\theta})_{\text{trans}} \simeq 2.9(Re_x)_{\text{trans}}^{0.4} \quad \text{Michel (1952)}$$

- ▶ **BL Thickness** (conventional definition): $\frac{u(x, \delta(x))}{u_e(x)} = 0.99$
- ▶ **Displacement thickness** δ^* : mass flow lost wrt ideal flow, due to the BL

$$\int_0^\delta \rho_e u_e dy - \int_0^\delta \rho u dy = \rho_e u_e \delta^* \quad \text{thus} \quad \delta^* = \int_0^\delta \left(1 - \frac{u}{u_e}\right) dy$$



- **Momentum thickness θ :** momentum lost wrt to ideal flow (for a given mass flow rate), due to the BL

$$\left(\int_0^\delta \rho u dy \right) u_e - \int_0^\delta \rho u^2 dy = \rho_e u_e^2 \theta \quad \text{thus} \quad \theta = \int_0^\delta \frac{u}{u_e} \left(1 - \frac{u}{u_e} \right) dy$$

- **Shape factor:**

$$H = \frac{\delta^*}{\theta}$$

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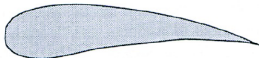
Inviscid/viscous coupling

Blasius solutions

von Kármán integral equation

- ▶ **Main objective** of quantitative flow analyses :
 - ▶ estimate **wall stress** τ_w and found friction drag
 - ▶ predict boundary layer separation (if any)
 - ▶ estimate the laminar/turbulent transition region
- ▶ The **outer velocity** u_e is a **datum** from preliminary inviscid flow analysis

- ▶ Compute the pressure distribution for an ideal flow around an airfoil
→ $p_e(x)$



- ▶ Solve the BL equations using $p_e(x)$ or $u_e(x)$ with
$$\rho u_e(x) \frac{du_e(x)}{dx} = - \frac{dp_e(x)}{dx}$$
 $\hookrightarrow u(x, y) \text{ and } v(x, y) \rightarrow c_f \text{ (friction drag) and } \delta^*$

- ▶ Construct a fictitious airfoil by augmenting the true airfoil by the computed displacement thickness + a wake



- ▶ Update the pressure distribution → find pressure drag

Remark: this kind of coupling is only possible for attached flow

- ▶ No known analytical solutions of the Prandtl equations for general configurations
→ Use of approximate solutions:
numerical solution of local equations by means, e.g. of finite difference methods
- ▶ Existence of quasi-exact (self-similar) solutions for simple geometries, corresponding to simple outer pressure distributions
→ Can be used to validate approximation methods
- ▶ Calculation of approximate solutions using the integral equations + use of self-similar solutions where needed
→ this is the approach studied in the following

Flow over a semi-infinite flat plate with zero incidence in incompressible inviscid flow

- ▶ no geometrical length scale
- ▶ outer flow solution: $u_e = U_\infty$
- ▶ BL equations become:

$$\left\{ \begin{array}{l} \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0 \\ \bar{u} \frac{\partial \bar{u}}{\partial \bar{x}} + \bar{v} \frac{\partial \bar{u}}{\partial \bar{y}} = \frac{\partial^2 \bar{u}}{\partial \bar{y}^2} \end{array} \right. \quad \text{with} \quad \left\{ \begin{array}{l} \bar{u} = \bar{v} = 0 \quad \text{for } \bar{y} = 0 \\ \bar{u} = 1 \quad \bar{y} \rightarrow \infty \end{array} \right.$$

- ▶ we look for a solution under the form

$$\bar{u} = h(\bar{x}, \bar{y}) \quad \text{thus} \quad \frac{u}{U_\infty} = h\left(\frac{x}{L}, \frac{y}{L} \sqrt{\frac{U_\infty L}{\nu}}\right)$$

- ▶ L being arbitrary, we look for u/U_∞ under the form of a function $h(\eta)$ where η is a non-dimensional parameter built upon \bar{x} and \tilde{y} and independent on L :

$$\frac{u}{U_\infty} = h\left(\frac{\tilde{y}}{\sqrt{\bar{x}}}\right) = h\left(\frac{y}{\sqrt{\frac{\nu x}{U_\infty}}}\right) = h(\eta) = f'(\eta)$$

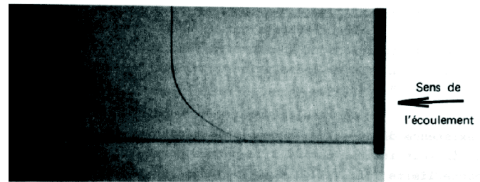
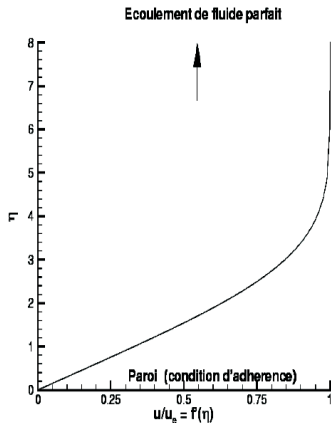
- ▶ u = self-similar velocity profile
 h = similarity variable
- ▶ we plug this expression into Prandtl equations

- ▶ After some manipulations, we come to the following ordinary differential equation:

$$\begin{cases} f'''(\eta) + \frac{1}{2}f(\eta)f''(\eta) = 0 \\ f(0) = 0, \quad f'(0) = 0 \\ f'(\infty) = 1 \end{cases}$$

- ▶ Requires numerical solution:
 - ▶ results for f and its derivatives can be tabulated
 - ▶ with f being known, velocity profiles can be derived

Excellent agreement between theory and experience



Visualisation d'une couche limite laminaire

Visualisation est obtenue en photographiant à un instant donné la trace laissée par une particule de bleu de Prusse tombant lentement dans un fluide en mouvement de droite à gauche : loin du bord (immobile), la trace est sensiblement rectiligne, montrant que l'écoulement extérieur de fluide parfait est pratiquement uniforme ; par contre, cette trace s'incurve près de la paroi, décelant la présence d'une couche limite.

Cliché réalisé au laboratoire de mécanique des fluides de l'ENSTA

The velocity profile being known

- ▶ calculation of the friction coefficient: $\tau_w = \mu \left. \frac{\partial u}{\partial y} \right|_w$

$$C_f = \frac{\tau_w}{\frac{1}{2}\rho u_e^2} = \frac{0.664}{\sqrt{Re_x}} \quad \text{with} \quad Re_x = \frac{U_\infty x}{\nu}$$

- ▶ boundary layer thickness along the plate:

$$\frac{\delta_{0.99}}{x} \approx \frac{5}{\sqrt{Re_x}}$$

- ▶ displacement and momentum thicknesses along the plate:

$$\delta^* = 1.72 \sqrt{\frac{\nu x}{U_\infty}}, \quad \theta = 0.664 \sqrt{\frac{\nu x}{U_\infty}},$$

- ▶ Exact solutions of (laminar) BL equations are known for a few special outer velocity u_e distributions, which enable looking for self-similarity solutions
- ▶ For arbitrary velocity distributions, similarity solutions cannot be found in general → calculation of approximate solutions by means of **von Kármán integral equation**

- ▶ Steady incompressible BL equations

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \\ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = u_e \frac{du_e}{dx} + \frac{1}{\rho} \frac{\partial \tau}{\partial y} \end{array} \right.$$

with $\tau = \mu \frac{\partial u}{\partial y}$ the shear stress for laminar flow

- ▶ + no-slip conditions and matching with the outer flow
- ▶ + far-field conditions $\tau(y \rightarrow \infty) = 0$ and $v(y \rightarrow \infty) = 0$

- Transformation of the integral equation:

$$\int_{y=0}^{y \rightarrow \infty} \left\{ \underbrace{\left[u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - u_e \frac{du_e}{dx} - \frac{1}{\rho} \frac{\partial \tau}{\partial y} \right]}_{(ii)} + (u - u_e) \underbrace{\left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right]}_{(i)} \right\} dy = 0$$

- Boundary conditions applied at integration limits

$$\frac{1}{\rho} \tau_w = \frac{du_e}{dx} \int_0^\infty (u_e - u) dy + \frac{\partial}{\partial x} \left[\int_0^\infty u(u_e - u) dy \right]$$

- Introduce displacement and momentum thickness

$$\frac{\tau_w}{\rho u_e^2} = \frac{1}{u_e} \frac{du_e}{dx} (\delta^* + 2\theta) + \frac{d\theta}{dx} \Leftrightarrow \frac{C_f}{2} = \frac{d\theta}{dx} + (H + 2) \frac{\theta}{u_e} \frac{du_e}{dx}$$

- An exact BL solution satisfies :

$$\frac{C_f}{2} = \frac{d\theta}{dx} + (H + 2) \frac{\theta}{u_e} \frac{du_e}{dx} \quad (2)$$

- (2) may be used as a filter to obtain a good approximation of the friction coefficient C_f from a rough approximation of the true velocity profil u/u_e

Typical use of VK integral (2):

- Define an approximate BL velocity profile $\frac{u}{u_e} = f\left(\frac{y}{\delta}\right)$ verifying a given number of boundary conditions,

$$\text{for example, } \frac{u}{u_e}(y=0) = f(0) = 0 \text{ and } \frac{u}{u_e}(y=\delta) = f(1) = 1$$

NB δ is one of the problem unknowns

- Compute the displacement and momentum thicknesses:

$$\delta^* = \int_0^\delta \left(1 - \frac{u}{u_e}\right) dy = \delta \int_0^1 (1 - f(\xi)) d\xi = k_1 \delta$$

$$\theta = \delta \int_0^1 f(\xi)(1 - f(\xi)) d\xi = k_2 \delta$$

Typical use of VK integral (2):

- ▶ For a laminar BL, skin friction is given by:

$$\tau_w = \mu \left(\frac{\partial u}{\partial y} \right)_w = \frac{\mu u_e}{\delta} f'(\xi)|_w = \frac{\mu u_e}{\delta} f'(0) \Rightarrow \frac{C_f}{2} = \frac{\tau_w}{\rho u_e^2} = \frac{\nu}{u_e \delta} f'(0)$$

- ▶ Plug the preceding expressions in (2):

$$\boxed{\frac{\nu f'(0)}{u_e} = k_2 \delta \frac{d\delta}{dx} + (2k_2 + k_1) \frac{\delta^2}{u_e} \frac{du_e}{dx}}$$

- ▶ $u_e(x)$ is known $\rightarrow \delta^2$ calculated $\rightarrow C_f$

$u/u_e = f(\xi)$ modelled as a polynomial of $\xi = y/\delta$ with a sufficiently high degree to satisfy all of the following conditions:

- ▶ no-slip condition at the wall : $u(y = 0) = 0$ or $f(0) = 0$
- ▶ matching of the BL solution with outer flow: $u(y = \delta) = u_e$ or $f(1) = 1$
- ▶ vanishing of viscous stresses outside the BL: $\frac{\partial u}{\partial y}(y = \delta) = 0$ or $f'(1) = 0$
- ▶ momentum conservation inside BL: $u \frac{\partial u}{\partial x} + \nu \frac{\partial u}{\partial y} = u_e \frac{du_e}{dx} + \nu \frac{\partial^2 u}{\partial y^2}$
 - ▶ $y = \delta$: $u = u_e$ and $\frac{\partial u}{\partial y} = 0 \rightarrow \frac{\partial^2 u}{\partial y^2}(y = \delta) = 0$ or $f''(1) = 0$
 - ▶ $y = 0$: $u = 0$ and $\nu = 0 \rightarrow \frac{\partial^2 u}{\partial y^2}(y = 0) = -\frac{u_e}{\nu} \frac{du_e}{dx}$ or $f''(0) = -\frac{\delta^2}{\nu} \frac{du_e}{dx} = -\Lambda$

$\hookrightarrow f(\xi)$ can be modelled as a **4th-order polynomial**

► **Polhausen polynomial (1921):**

$$\frac{u}{u_e} = \left[2\xi - 2\xi^3 + \xi^4 \right] + \frac{\Lambda}{6} \xi (1 - \xi)^3 \quad (3)$$

- first term: velocity profile with no pressure gradient ($du_e/dx = 0 \rightarrow \Lambda = 0$)
 - second term: effect of a pressure gradient on the velocity profile
- This approach is not very accurate in general (generic u_e) and cannot predict correctly the separation point location for adverse pressure gradients ($\Lambda < 0$)

- ▶ 1940: Holstein and Bohlen introduce a non-dimensional parameter for describing BL, by correlating the most significant non-dimensional quantities in VK integral eq. (2)

$$\lambda = \frac{\theta^2}{\nu} \frac{du_e}{dx} : \quad H = H(\lambda) \quad \text{and} \quad \frac{\tau_w \theta}{\mu u_e} = S(\lambda)$$

↪ (2) rewritten as:

$$u_e \frac{d}{dx} \left(\frac{\lambda}{u_e'} \right) = 2 [S(\lambda) - \lambda (2 + H(\lambda))] = F(\lambda)$$

- ▶ 1941 : Walz shows that if $F(\lambda)$ is linear, the preceding expression can be integrated analytically, and leads to

$$\frac{\theta^2}{\nu} = \Phi(u_e)$$

- ▶ 1949 : after analyzing several analytic and experimental results, Thwaites shows that data fit the following correlation:

$$F(\lambda) \approx 0.45 - 6\lambda$$

→ then, momentum thickness of a BL is well approximated by:

$$\theta^2(x) = \frac{0.45\nu}{u_e^6(x)} \int_0^x u_e^5(x') dx' \quad (4)$$

- ▶ If the outer velocity is known, then it is possible to write

$$\lambda = \frac{\theta^2}{\nu} \frac{du_e}{dx} \quad \text{with the preceding formula}$$

- ▶ With λ being known, we compute $H(\lambda)$ and $S(\lambda)$ from correlation tables given by Thwaites
- ▶ Wall friction is deduced from $S(\lambda)$ as well as the separation point ($S(\lambda) = 0$ for $\lambda = -0.082$)
- ▶ Remark: preceding information obtained without postulating anything about the BL velocity profile