

Scheduling Problem for OFDMA Uplink in IEEE 802.11ax Networks

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Abstract—In the modern world to have a high-speed Internet connection is already more a necessity than a luxury. But in current realities, a wireless connection does not work well in dense networks. So new generation of Wi-Fi devices is coming due to development of the standard IEEE 802.11ax, which should be publicly released in a couple of years. This new standard has the challenging goal of improving performance indicators such as throughput per user, spectral efficiency, etc. It takes the best of Wi-Fi and adds technology from cellular technologies, hence combination of both technologies will be key in designing the best performing IEEE 802.11ax solutions. The most ground-breaking technology taken from 4G is OFDMA which gives opportunity for Access Point to serve several users simultaneously with frequency division. It gives rise to the problem of a resource planning in Wi-Fi networks with new constraints. In this paper we investigate the scheduling problem, study peculiarities of this technology union in Wi-Fi and offer a new type of schedulers. Also we show a way to adapt traditional schedulers to IEEE 802.11ax networks.

Index Terms—Wi-Fi, IEEE 802.11ax, High Efficiency WLAN, OFDMA, Scheduling

I. INTRODUCTION

нужно подвести к проблеме

Wireless networks have become an indispensable thing in the modern world. Nowadays, Wireless Local Area Network (WLAN) is believed to be the most popular technology for information transmission. It is not surprising. People can go online literally anywhere — in a restaurant, cafe, shopping center, park, public transport, airport, at work and, of course, at home. The main concern is just to be within the range of the access point. Such popularity of this technology has led to the problem of congestion of Wi-Fi networks, when one network interrupts the signal of another. To cope with this and many other circumstances, IEEE 802 LAN/MAN Standard committee is developing a new amendment for Wi-Fi standard: IEEE 802.11ax (further in the paper referred to as 11ax).

This amendment provides various ways to improve the efficiency of Wi-Fi, some of which are borrowed from cellular technology. One of such most significant enhancements of 11ax is the usage of Orthogonal Frequency-Division Multiple Access (OFDMA). It allows the Wi-

Fi Access Point (AP) to service several stations (STA) simultaneously, to better cope with fading and, in case of uplink transmission, to improve the spectral power density.

The rest of the paper is organized as follows. Section II briefly describes the basic OFDMA features in 11ax networks. Section III provides an overview on related papers. Network scenario is shown in Section IV. In Section V, we cover scheduling problem in 11ax networks and describe main principles of 11ax schedulers. In Section VI, we illustrate, how known schedulers can be adapted for 11ax networks. In Section VII, we demonstrate and discuss numerical results. Section VIII concludes the paper.

II. OFDMA FEATURES IN 11AX

Data transmission in Wi-Fi with OFDMA has a number of peculiarities which make it different from data transmission in 4G, although it also uses OFDMA.

A. Channelization in 802.11ax

The available channel can be split into sets of OFDMA subcarriers called resource units (RUs). The 11ax defines RUs that consist of 26, 52, 106, 242, 484, 996 and 2×996 OFDM tones. The set of available RUs depends on the channel width, e.g., in a 40 MHz channel the STAs can use RUs with up to 484 tones. A wide RUs can be split into narrower RUs: 52-tone, 106-tone RU and 484-tone RUs can be split in two approximately twice-narrower RUs from available set, while 242-tone and 996-tone RUs are split into three RBs (see Fig. 1). Note, that these the divisions of the RUs can be made independently from others.

The scheduler can allocate only one RU to a STA, but it can vary the RU size for each STA according to the aforementioned limitations. In other words we have 37 26-tone RUs and certain groups of 2, 4, 9, 18 or all 37 of them can be united in order to obtain larger RUs. According to the standard, such a limitation appears because of the need to have service tones next to each allocated RU of any size. Note, that position of these divided RBs is declared in standard and cannot be arbitrary. For example, as shown at Fig. 1 two first RUs are united in one 52-tone RU, but we cannot unite the second and the third ones.

The size of an RU determines the set of modulation-coding schemes (MCSs) that can be used for transmission in the RU. For example, the standard prohibits usage of the novel 1024-QAM in small RUs. At the same time, for

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26	26	26	26	26	26	26	26	26	26	26	26	26	26	26	26	26	26	26
52	52	26	52	52	52	52	52	26	52	52								
106	26	106		106	106	26	106											
242						242												
484 tones																		

Figure 1: RU locations in 40 MHz channel

Table I: Data rate in different RU at each MCS in Mbps

	MCS	26-tone	52-tone	106-tone	242-tone	484-tone	996-tone
1	BPSK, 1/2	0.8	1.7	3.5	8.1	16.3	34
2	QPSK, 1/2	1.7	3.3	7.1	16.3	32.5	68.1
3	QPSK, 3/4	2.5	5	10.6	24.4	48.8	102.1
4	16-QAM, 1/2	3.3	6.7	14.2	32.5	65	136.1
5	16-QAM, 3/4	5	10	21.3	48.8	97.5	204.2
6	64-QAM, 2/3	6.7	13.3	28.3	65	130	272.2
7	64-QAM, 3/4	7.5	15	31.9	73.1	146.3	306.3
8	64-QAM, 5/6	8.3	16.7	35.4	81.3	162.5	340.3
9	256-QAM, 3/4	10	20	42.5	97.5	195	408.3
10	256-QAM, 5/6	11.1	22.2	47.2	108.3	216.7	453.7
11	1024-QAM, 3/4	—	—	—	121.9	243.8	510.4
12	1024-QAM, 5/6	—	—	—	135.4	270.8	576.1

each RU width, the standard defines the minimal receiver sensitivity to signal transmitted with a specific MCS, and the faster the MCS, the higher is the sensitivity threshold. As the result, a STA cannot use high-speed MCSs if it has poor channel conditions.

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A wider RU does not necessarily mean that the STA transmits at greater speed. A STA uses the same transmission power both for wide and narrow RUs, which results in greater signal-to-noise ratio (SNR) values for narrow RUs. As the result, in a narrow RU it can use higher MCSs which can yield greater summary transmission rate. Data rates of MCSs used in the 11ax are indicated in Table I.

Another problem is that to make it possible to use OFDMA all STAs should transmit with the same synchronized MCS. There is one exception in this rule: when we use 1024-QAM in big RUs we still can transmit data in smaller ones with 256-QAM.

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In order to enable the AP to successfully receive the signal from several STAs, these STAs should transmit with such power that the incoming signal is the same at the AP.

Such constraints complicate scheduling problem in 11ax networks.

B. Data Transmission Sequence

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To organize data transmission process in UL with OFDMA, the AP transmits Trigger Frames, in which it

includes the scheduling information (see Fig. 2). Specifically, for each allocated RU it adds a User Info element that indicates the RU, the MCS that should be used in that RU and the AID of the designated STA. If the AID is 0, then the RU is allocated for random access, which can be used by STAs to request channel resources from the AP.

III. RELATED WORKS

написать

Despite the fact that 11ax is expected to be finished by 2019, it has been already studied a lot in the literature.

IV. NETWORK SCENARIO AND PROBLEM STATEMENT

The considered Wi-Fi network scenario is shown in Fig 3. A group of N STAs (STA) is associated to the Access point (AP). From time to time, STAs generate finite data flows to be delivered to the AP.

We study UL scheduling problem in deterministic access, so let STAs transmit their BSR in EDCA transmissions period, so there is no need for AP to allocate resources for RA during trigger-interval. Also we have several defined schedulers for deterministic access (which will be discussed later on). Let time unit be the period with which the AP broadcasts trigger-frames. So each time unit scheduler allocates resources for associated users in a certain way.

Users' STAs are transmitting data in uplink using OFDMA. It means that STAs should transmit their data with synchronized MCS and that AP should choose this MCS and allocate RUs satisfying the OFMA features described above.

Consider 40 MHz channel, so we have RUs location shown in Fig. 1. Also correspondence of RUs and given rates is demonstrated at Table. I.

Problem statement: *to adapt known schedulers which work in traditional cellular networks to 11ax networks.*

V. SCHEDULING IN 11AX

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Usually, it is formulated as the following optimization problem. Consider a network described in section IV. Each time unit, the AP runs defined scheduler which allocates M RUs to some STAs in order to maximize some network-wide utility function U where M is a total number of RUs in chosen set of RUs. For example, if scheduler chooses the following RU set: 242, 106, 26, 52, 26, 26-tones RUs to STAs respectively then $M = 6$. Note that utility function intuitively should be $U = U(RUset, allocation, mcs)$ here because as it was shown in section II that several performance indicators can vary greatly depending on the allocation and MCS.

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As justified in {Scheduling Algorithms for Multicarrier Wireless Data Systems Matthew Andrews and Lisa Zhang}, in multi resource unit systems like OFDMA, we

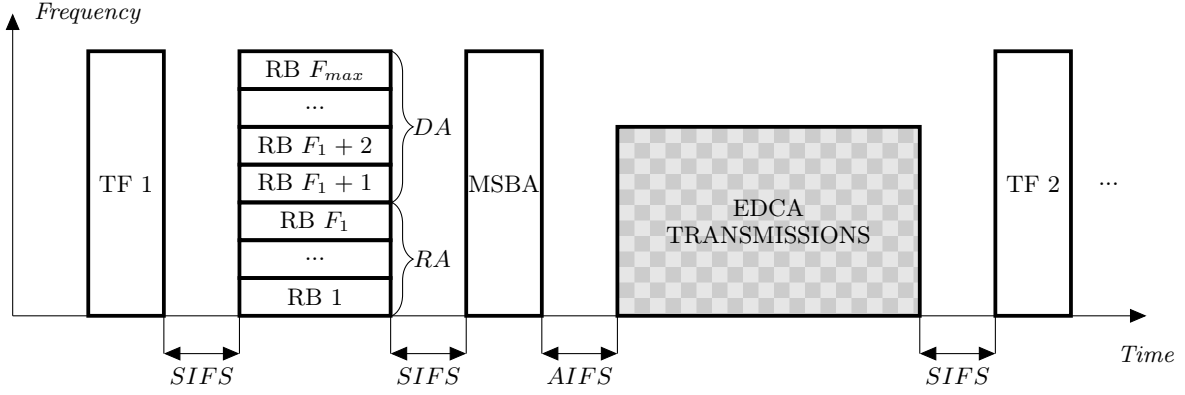


Figure 2: Frame handshake for UL OFDMA transmission (NEED TO CHECK).

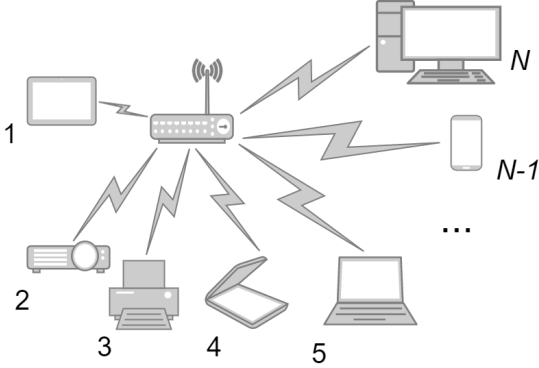


Figure 3: The network scenario

can represent the utility function $U(t)$ in the following objective form

$$U(t) = \sum_i \sum_j x_i^j \lambda_i^j(t)$$

where x_i^j is an indicator which equals 1 if STA i is assigned to RU j , and 0, otherwise and λ_i^j is the scheduler metric value which client STA i has in RU j at time slot t .

For shortness, X is the two-dimensional matrix of $\{x_i^j\}$ representing RU assignment to the STAs and $C = \{1 \dots 12\}$ be a set of all MCS (according to the table I). Let R be a set of all RU configurations. With all aforementioned instructions we can rewrite common optimization problem for fixed RU set $r \in R$ and fixed MCS $c \in c$ for all possible scheduler metrics:

$$\max U_{c,r}(t, X) = \max \sum_i \sum_j x_i^j \lambda_i^j(t); \quad (1)$$

$$\text{subject to } \sum_i x_i^j \leq 1, \quad \forall j; \quad (2)$$

$$\sum_j x_i^j \leq 1, \quad \forall i; \quad (3)$$

$$\sum_i \sum_j x_i^j \leq M, \quad (4)$$

where conditions (2)-(4) are related to the OFDMA constraints described before. Namely, (2) represents the fact that one STA cannot be assigned to more than one RU. Condition (3) works in opposite way: one RU cannot be assigned for more than one station. The last condition (4) comes with a total number M of RUs in this fixed RU set.

This problem is known as the assignment problem, which can be resolved in polynomial time using dynamic programming algorithm named as the Hungarian algorithm, [?]. It also known as the Kuhn-Munkers algorithm. Its solution is the assignment \hat{X} , which gives maximum value of $U_{c,r}(t, X)$ for any possible allocation matrix X with fixed RU set and MCS. Briefly, the algorithm makes up the matrix $\Lambda = \{\lambda_i^j\}$ and chooses the best λ_i^j in each line in order to maximize objective function 1. Example is given in Fig. 4 where grey cells of this matrix describe solution \hat{X} .

With this algorithm the AP can allocate fixed RU set with fixed MCS, but it needs to determine them as well. The best RU set and the best MCS can be chosen among all possible variants by considering them one by one. This is final decision made by the AP. The examination of RU set can be hastened by excluding configurations that are obviously worse than the known alternatives, and the examination of MCS should consider only supported mcs and can be hastened by excluding MCSs lower than the highest MCS supported by all stations. It means that we have borders for MCS: mcs_{min}^* and mcs_{max}^*

Algorithm 1 General 11ax scheduler algorithm

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1: procedure SCHEDULER
2:   for  $r$  in  $\{R\}$  do
3:     for  $c$  in  $[mcs_{min}^*; mcs_{max}^*]$  do
4:        $\hat{X} = \text{HungarianAlg}(\Lambda(r, c))$ 
5:       if  $U_{best} < U(\hat{X})$  then
6:          $U_{best} = U(\hat{X})$ ,
7:          $X_{best} = \hat{X}$ ,
8:          $c_{best} = c$ ,
9:          $r_{best} = r$ .
10:  return  $r_{best}, c_{best}, X_{best}$ 

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Figure 4: Example on Hungarian algorithm

x_i^j	Client Stations, i									
Resource Units, j	2	2	3	6	7	1	3	6	2	6
	1	4	5	8	9	5	3	8	5	1
	9	4	7	5	3	2	6	1	3	1
	2	3	8	4	5	6	1	2	7	4
	7	4	9	3	7	1	2	8	5	8
	9	7	4	7	8	2	2	4	3	6
	9	8	5	6	1	2	4	5	6	7

VI. AX-ADAPTATIONS OF KNOWN SCHEDULERS

(The most widely used utility functions and corresponding schedulers are listed below.)

designations used below:

r_i — nominal data rate of station i in the whole frequency band.

A. MR

The AP in legacy Wi-Fi use MR (Max Rate) scheduler in order to maximize throughput $S = S(t)$ at current moment t . This scheduler considers all client stations and assigns the whole frequency band to a station with the highest nominal data rate r_i in channel. However, with appearance of 11ax standard AP can consider channel division and maximize cumulative throughput $S = \sum S_i(t)$, where $S_i(t)$ is throughput of station i at time instant t . We should simply make

$$\lambda_i^j(c) = r_i^j(c); \quad (5)$$

B. PF

PF (Proportional Fair) scheduler

$$\lambda_i^j(c) = \begin{cases} r_i^j(c) \cdot \frac{\text{time in system}}{\text{transmitted data}}, \\ 0, \text{ if transmitted data} = 0; \end{cases} \quad (6)$$

C. Shortest Remaining Time First

SRTF (Shortest Remaining Time First) scheduler

If the channel properties do not change with time, the rate in different RUs is the same and additive, the Shortest Remaining Time First (SRTF) scheduler is proven to provide minimal average upload time. The second assumption made to derive such a scheduler is completely incorrect for UL OFDMA transmission in 11ax networks.

But still, simplistically, SRTF allocates the whole channel to a user for which $\frac{D_i(t)}{r_i}$ is the minimal one, where $D_i(t)$ is the remaining amount of data of user i and as before r_i is its rate in the whole channel.

In this section, we design a novel scheduler called MUTAX, Minimizing Upload Time in 11AX networks. While deriving formulae we neglect the effects related to packetization (including aggregation and fragmentation) overhead. Apart from that, for shortness we consider only n STAs with flows and assume that each STA has only one flow. Both STA and flow are denoted as $i, i = 1, \dots, n$.

Let slot be a time interval between two consequent TFs. It should be noted that slots may have different duration. The maximal one is related to the standard limit of 5484 μs for the physical protocol data unit (PPDU) duration. A slot can be shorter, if at least one STA which transmits in this slot has no more data.

The MUTAX algorithm has two steps. At the first step, we order existing flows and calculate the sum upload time of the flows, as if we used exhaustive service. At the second stage, we try to improve the sum upload time by serving some flows in parallel. Let us consider the steps in detail.

At the first step, we serve each flows exhaustively. Except for waiting, the time needed to upload flow i equals $t_i = \frac{D_i}{r_i}$. The first STA finishes delivering its flow by time t_1 . The second STA starts right after the first one and delivers its flow by time $t_2 + t_1$, etc. As the result, the total upload time for existing flows is

$$T_{step1} = \sum_{i=1}^n (n-i) t_i.$$

Obviously, to minimize the sum upload time we have to sort the STAs in the ascending order by t_i .

At the second step, we divide the channel into several RUs. Let m be the number of RUs and $j, 1 \leq j \leq m$ be the index of RU in the considered RU configuration. x_i^j is an indicator which equals 1 if STA i is assigned to RU j , and 0, otherwise. For shortness, X is the two dimensional matrix of $\{x_i^j\}$ representing RU assignment to the STAs.

With defined notation, the total upload time $T(X)$ of existing flows differs from T_{step1} in the following way. First, the upload time of each of n flows increases by the current slot duration τ . Second, if $x_i^j = 1$, the remaining amount of data of flow i decreases by the amount of data the STA transmits in RU j of the current slot: $\Delta D_i^j = \min \{D_i, \tau \times r_i^j\}$. Thus

$$T(X) = n\tau + \sum_{i=1}^n (n-i) \frac{D_i - \sum_{k=1}^m x_i^k \Delta D_i^k}{r_i}$$

Since both τ and ΔD_i^j depend on the resource allocation X , minimization of $T(X)$ requires exhaustive search by possible ways to allocate the RUs to the STAs, and to simplify the task we propose an heuristic approach based on two assumptions. Firstly, we neglect the change of $n\tau_t$ for different allocations, as a slot cannot be too long due to standard limitations. Secondly, we sort the STAs in the ascending order by t_n only once, before considering different ways to assign RUs to the STAs. Under these assumptions, to minimize $T(X)$, we have to maximize the following expression $\sum_{k=1}^m \sum_{i=1}^n (n-i) \frac{x_i^k \Delta D_i^k}{r_i}$.

Finally, let us denote $\lambda_i^j = (n-i) \frac{x_i^j \Delta D_i^j}{r_i}$ and we can define the following optimization problem:

VII. NUMERICAL RESULTS

only one resource unit - the whole channel itself.
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We have implemented SRTF, MR and PF schedulers as well as 11ax analogs described in the previous section.

We run simulation in a scenario described in Section IV.

The flow sizes are drawn from truncated lognormal distribution with minimal, average and maximal values of 1 KB, 200 KB, 3 MB respectively. When a flow is delivered, the next flow is generated after a random delay drawn from truncated exponential distribution with minimal, average and maximal values of 0.1s, 0.3s and 0.6s respectively. Also we used the following 802.11ax path-loss model for the residential scenario [?]:

$$PL(d) = 40.05 + 20 \lg \left(\frac{f_c}{2.4} \right) + 20 \lg(\min(d, 5)) + \\ + \mathbb{I}(d > 5) \cdot 35 \lg \left(\frac{d}{5} \right),$$

where PL is the path-loss in dB, f_c is the central frequency in GHz, d is the distance between the devices and $\mathbb{I}x$ equals 1 if x is true and 0 otherwise. The AP receives the signal from the STAs with power $P(d)$ calculated as

$$P(d) = P_0 + 10 \lg \left(\frac{F}{F_{max}} \right) - PL(d),$$

where P_0 is the STA's transmission power, possibly corrected as mentioned in Section II, d is the distance between the STA and the AP, F is the number of tones in the RU, and F_{max} is the maximal number of tones in a RU in the considered channel.

In first set of experiments, the STAs are located uniformly within a small circle of radius $D/2 = 5$ m around the AP. In such a case, the channel quality is so high that the STAs use the maximal MCS to transmit in RUs of any width. Obviously, in this case OFDMA cannot bring any profit against legacy Wi-Fi which uses the whole channel for transmissions, as its division without changing the MCS cannot increase the data rate according to the Table I unless MCS can cope with the noise. The only possible exception here is ax-PF scheduler which tries to serve STAs with fairness, but actually multiplier $r_i^j(c)$ is a lot larger for $c = 12$ in 484-tone RU, compared to other RUs, so even 11ax PF scheduler decides to allocate the whole channel to one user (need to check).

This result is supported by simulation, see Fig ??, which shows that if the channel for all STAs is well enough, schedulers which consider channel division yields the same upload time as others (curves coincide for them in this Fig.). Also this result illustrates that schedulers belonging to SRTF-family outperform the PF and MR-families by up to 30%.

As we consider traffic model of a closed loop system, along with the reduction of upload time SRTF-based

schedulers provide the increase of goodput compared to the other schedulers.

The second set of experiments corresponds to the case when STAs are located in a larger circle of radius $R = 20$ m. Such conditions provide variety of MCSs among STAs and among RU widths, so it becomes feasible to split the channel between different users. If in previous set of experiments we could divide schedulers by their family belonging, here OFDMA usage is the main factor of success. According to simulation results, see Fig. ??, in this case non-OFDMA schedulers are much less efficient than channel-splitting schedulers. The gap between these two groups increases with the number of client STAs. Thus, usage of OFDMA gives advantage compared to non-OFDMA schedulers. For example, designed to minimize upload time the classic SRTF works much worse than even 11ax adaptation of PF. At the same time, MUTAX and its SO version shows approximately the same upload time as ax-PF and ax-MR, they keep leading position unless number of STAs is less than 20.

VIII. CONCLUSION

In the paper, we have studied scheduling problem in 11ax networks, the standard of which is currently under development. Constraints connected to a OFDMA usage and common approach to all possible schedulers for 11ax network were shown here. Also we have demonstrated how classic schedulers can be adapted to 11ax networks and numerical results about their performance. Meanwhile, a new family of schedulers based on traditional SRTF scheduler was introduced. We can admit that MUTAX and MUTAX-SO make some brutal force optimization, they even start to lose to 11ax adaptations of PF and MR with increase in number of associated STAs. Thus, this problem should be investigated more deeply, but the main point of this paper stands that the AP can get gain in performance indicators due to division of channel.

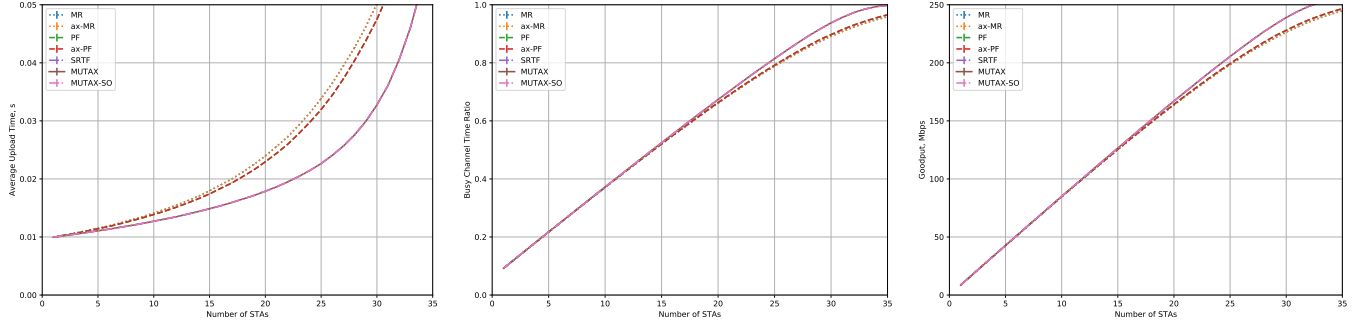


Figure 5: Upload time, busy channel time ratio and goodput vs the number of STAs in the small circle.

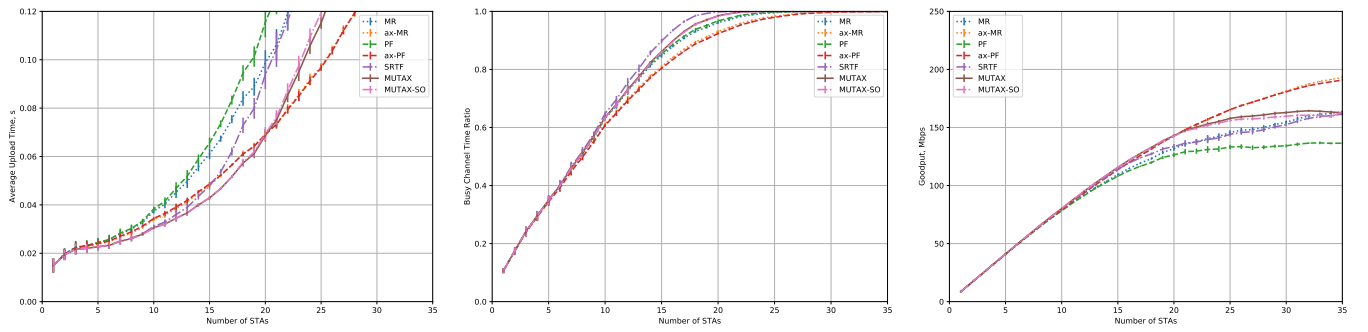


Figure 6: Upload time, busy channel time ratio and goodput vs the number of STAs in the large circle.