

CS 383 – Machine Learning

Kernels

Slides adapted from material created by E. Alpaydin Prof. Mordohai, Prof. Greenstadt, Pattern Classification (2nd Ed.), Pattern Recognition and Machine Learning



Objectives

Kernels



Kernels

- For many algorithms, the only time we actually use the samples themselves is when we compute some distance or similarity between two samples
- A function that takes two samples and returns a similarity is called a *kernel function*, $\kappa(X_i, X_j)$
- There are many kernel functions out there, one of the most popular is the *cosine similarity kernel*:

$$\kappa(X_i, X_j) = X_i X_i^T$$



Kernels

- Here are some other common kernels:
 - Linear/Cosine: $\kappa(X_i, X_j) = X_i X_i^T$
 - Polynomial kernel: $\kappa(X_i, X_j) = (X_i X_j^T + 1)^p$
 - Gaussian Radial Basis kernel (RBF):

$$\kappa(X_i, X_j) = e^{-\frac{1}{2\sigma^2} \left| |X_i - X_j| \right|^2}$$

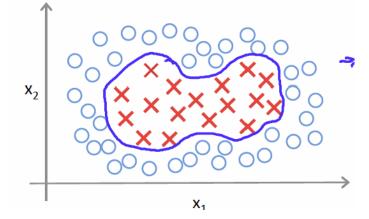
- If feature vectors are histogram
 - Histogram intersection: $\kappa(X_i, X_j) = \sum_{k=1}^N \min(X_{i,k}, X_{j,k})$
 - Hellinger kernel: $\kappa(X_i, X_j) = \sum_{k=1}^N \sqrt{X_{i,k} X_{j,k}}$



- Kernels can also provide an additional benefit.
- Sometimes we may want to go to a *higher* feature space.
- Why?

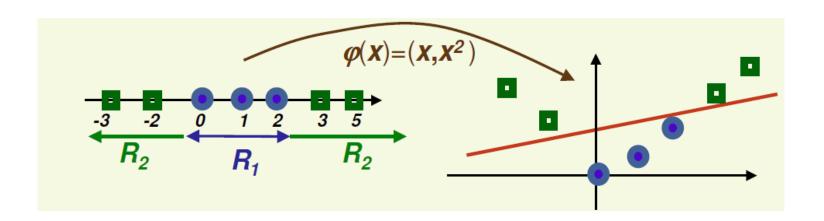
Because we have a linear classifier and the data is not

directly linearly separable.





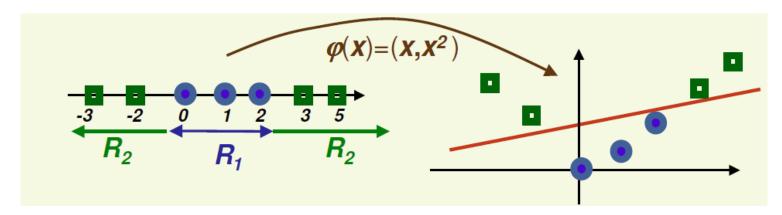
- One solution would be to map our current space to another separable space
- Then project data x to **higher** dimension using mapping function $\phi(x)$





Non-Linear Mapping

- Of course what's the issue with lifting data to higher dimensional space?
 - Overfitting
 - Computational power
- Maybe we could then project the data back down..
 (using PCA or something else)





- The "kernel trick" provides a way to avoid performing operations in high dimensional space explicitly (as if we had more/new features)
 - But the computation done in lower space produces the same value as if done in higher space
- We want a way to express $\kappa(X_i, X_j)$ as a cosine similarity in higher space:

$$\kappa(X_i, X_j) = \phi(X_i)\phi(X_j)^T$$



• Let's look at the polynomial kernel of degree two, $\kappa(X_i,X_j)=\left(X_iX_j^T+1\right)^2$ as applied to observations with one feature:

$$x = [x_1]$$

- Therefore $\kappa(X_i, X_j) = (X_i X_j^T + 1)^2 = (X_{i,1} X_{j,1} + 1)^2$ = $(X_{i,1} X_{j,1})^2 + 2(X_{i,1} X_{j,1}) + 1$ = $X_{i,1}^2 X_{i,1}^2 + 2X_{i,1} X_{j,1} + 1$
- Can we write this as the product of two things, each just dependent on its own observation?
 - I.e $\kappa(X_i, X_j) = \phi(X_i)\phi(X_j)^T$?



•
$$\kappa(X_i, X_j) = [X_{i,1}^2, \sqrt{2}X_{i,1}, 1][X_{j,1}^2, \sqrt{2}X_{j,1}, 1]$$

Therefore

$$\phi(x) = \left[x_1^2, \sqrt{2}x_1, 1\right]$$

 Using the polynomial kernel of degree two on observations with a single feature is equivalent to compute the cosine similarity on observations in 3D space.



Choice of Kernel

- Constraints on kernels
 - $\kappa(X_i, X_j)$ should correspond to $\phi(X_i)\phi(X_j)^T$ in a higher dimensional space
 - If κ and κ' are kernels then $a\kappa + b\kappa'$ is also a kernel (linear combination)
- Intuitively the kernel should measure the similarity between X_i and X_j
 - After all, the dot (inner) product measures similarity of unit vectors
 - Therefore the kernel choice may be application, problem, and or data specific



Choice of Kernel

- So which should we use?
- Again depends on the feature themselves
 - Type
 - Value
 - Quantity
- If we have tons of features then we probably don't even need to go to higher dimensional space
 - So linear is suffice
 - Consider "ton" to be more features than observations



Kernel Usage

- We've already seen one place where we could use kernels
 - K-Means
- In the next few weeks we'll look at a few more that are "kernelizable"
 - K-Nearest Neighbors (KNNs)
 - Support Vector Machines (SVMs)
 - Logistic Regression