Recorded at time: 7368.435 world Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.929 (-0.494 sec old) Buffer length: 4.960 sec base_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec shoulder_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 7368.422 (0.013 sec old) Buffer length: 4.960 sec wrist_3_link Broadcaster: /robot state publisher Average rate: 50.202 Hz Most recent transform: 7368.929 (-0.494 sec old) Buffer length: 4.960 sec ee_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 7368.929 (-0.494 sec old) Most recent transform: 7368.929 (-0.494 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec tool_interface_plate gripper_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 7368.929 (-0.494 sec old) Most recent transform: 7368.929 (-0.494 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec gripper_body tcp_frame

view_frames Result