
LMLVQ using distance Documentation

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ALGORITHM DESCRIPTION

Learning Vector Quantization(LVQ) is well-known for Supervised Vector Quantization. Large margin LVQ is to maximize the distance of sample margin or to maximize the distance between decision hyperplane and datapoints.

1.1 Pseudo-code

1. Get data with labels e.g. $x \in X, |X| = n, X \subset R^n$, where X are datapoints and $c(X) \in C$, where C are data labels.
2. Initialize prototypes with labels e.g. $w \in R^n$, where w are prototypes and $c(w) \in C$, where C are prototype labels.
3. Calculate Euclidean distance between datapoints and prototypes.

$$d_{i,j} = d_E(x_i, w_j) = \sqrt{\sum (x_i - w_k)^2}$$

4. Calculate closest correct matching prototype for every data point and also calculate $|P_k|$ is the number of data points for which w_k is the closest prototype with same label.
5. Calculate 1_{P_k} , A vector which has **1** where data point has closest prototype otherwise zero.
6. Compute A_k ,
 - The index $A_k[i, K * i + l]$, should be **+1** if data point i is in $|P_k|$, i.e. if prototype k is the closest prototype to data point i with the same label, and if prototype l has a different label.
 - The index $A_k[i, K * i + k]$ should be **-1** if datapoint i has a different label than prototype k .
 - The index $A_k[i, K * i + l]$ should be zero in all other cases. So most of A_k is zero.

7. Compute the cost function:

$$E = \min_{\vec{\lambda} \in \mathbb{R}^{m \cdot K}} \frac{1}{2} \vec{\lambda}^T \cdot \left(C \cdot I - \sum_{k=1}^K \mathbf{A}_k^T \cdot \frac{D}{|P_k|} \cdot \mathbf{A}_k \right) \cdot \vec{\lambda} - \left(\gamma \cdot \vec{1}^T + \sum_{k=1}^K \vec{1}_{P_k}^T \cdot \frac{D}{|P_k|} \cdot \mathbf{A}_k \right) \cdot \vec{\lambda}$$

- such that $\vec{\lambda} \geq 0$ and $\vec{1}^T \cdot \mathbf{A}_k^T \cdot \vec{\lambda} = 0, \forall k \in \{1, \dots, K\}$

8. Finally updates the prototypes:

$$\lambda(t+1) = \lambda(t) - \eta \frac{\partial E}{\partial w(t)}$$

INSTALLATION REQUIREMENTS

Following are the basic requirements to run this program:

1. `python` with minimum version 3.8.
2. `numpy` with minimum version 1.19.0.
3. `matplotlib`.
4. `Scikit Learn` .

2.1 Execution

- Open the `lmlvq_call.py` file and set parameters with margin, prototypes per class and epochs then run it.

CLASSES AND FUNCTIONS

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class `lmlvq_distance.LMLVQ` (*prototype_per_class=1*)
Bases: `object`

Large margin LVQ is to maximize the distance of sample margin or to maximize the distance between decision hyperplane and data point.

prototype_per_class: The number of prototypes per class to be learned.

A_k (*input_data, prototype_labels, w_plus_index*)

A_K used to translating the lambda numbers to the beta numbers.

The index $A_k[i, K*i+1]$ should be +1 if data point i is in P_k , i.e. if prototype k is the closest prototype to data point i with the same label, *_and_* if prototype l has a different label.

The index $A_k[i, K*i+k]$ should be -1 if datapoint i has a different label than prototype k .

The index $A_k[i, K*i+1]$ should be zero in all other cases. So most of A_k is zero.

input_data: A $n \times m$ matrix of datapoints.

prototype_labels: A n -dimensional vector containing the labels for each prototype.

w_plus_index: A n -dimensional vector containing the indices for nearest prototypes to datapoints with same label.

a_k: A $N \times (N*K)$ dimensional array where N is data points and K are prototypes. This is for every prototype

beta_k (*lam, prototype_labels, ak, one_pk*)

Use to compute Euclidean distance between data points and prototypes.

$\text{beta}_k = A_k * \text{lambda} + 1_{\{P_k\}}$

lam: A $N*K$ lambda vector where N is the number of data points and K is the number of prototypes

prototype_labels: A n -dimensional vector containing the labels for each

ak: A $N \times (N*K)$ dimensional array where N is data points and K are prototypes. This is for every prototype.

one_pk: A m -dimensional vector which has 1 for data point has closest prototype otherwise zero.

result: A $K \times (N \times 1)$ matrix with K is number of prototypes, N is number of datapoints.

cost_function (*lam, C, gamma, ak, D, one_pk, pk, prototype_labels, kappa*)

Calculate cost function of LMLVQ.

cost function: $0.5 * \lambda^T * H * \lambda - q^T * \lambda$ where $H = C * I - \sum_k (A_k * (D/P_k) * A_k)$ and $q = \gamma * 1.T + \sum_k (1_{\{P_k\}} * (D/P_k) * A_k)$

lam: A N*K lambda vector where N is the number of data points and K is the number of prototypes

C: The regularization constant.

gamma: The margin parameter.

ak: A N x (N*K) dimentional array where N is data points and K are prototypes. This is for every prototype.

D: A n x n matrix with Euclidean distance between datapoints.

one_pk: A m-dimensional vector which has 1 for data point has closest prototype otherwise zero.

pk: A list of numbers of datapoints for which w_k is closest prototype.

prototype_labels: A n-dimensional vector containing the labels for each prototype.

kappa: A hyperparameter.

H: A n x n matrix of result $C * I - \sum_k (A_k * (D/P_k) * A_k)$

q: A n-dimensional vector of result: $\gamma * 1.T + \sum_k (1_{\{P_k\}} * (D/P_k) * A_k)$

cf: A n x n matrix of result of cost function.

d_i_k (*input_data, prototype_labels, D, beta*)

Calculate distance between data points and prototypes.

Formula:

$$d_{\{i,k\}} = \frac{\sum_j \eta_{k[j]} * D[i, j]}{\text{np.sum}(\beta_k) - 0.5 * \text{np.dot}(\beta_k, \text{np.dot}(D, \beta_k)) / (\text{np.sum}(\beta_k) ** 2)}$$

input_data: A n x m matrix of datapoints.

prototype_labels: A n-dimensional vector containing the labels for each

D: A n x n matrix with Euclidean distance between datapoints.

beta: A K x (N x 1) matrix with K is number of prototypes, N is number of datapoints.

dik: A n x m matrix with distance between datapoints and prototypes.

euclidean_dist (*input_data, prototypes*)

Calculate squared Euclidean distance between datapoints and prototypes.

input_data: A n x m matrix of datapoints.

prototpes: A n x m matrix of prototyeps of each class.

eu_dist: A n x m matrix with Euclidean distance between datapoints and prototypes.

D: A n x n matrix with Euclidean distance between datapoints.

fit (*input_data, data_labels, learning_rate, epochs, margin, constant, kappa*)

Train the Algorithm.

input_data: A n x m matrix of datapoints.

data_labels: A n-dimensional vector containing the labels for each datapoint.

learning_rate: The step size.

epochs: The maximum number of optimization iterations.

margin: The margin parameter.

Constant: The regularization constant.

kappa: A hyperparameter.

beta: A $K \times (N \times 1)$ updated beta matrix with K is number of prototypes, N is number of datapoints.

mod_Pk (*input_data, data_labels, prototype_labels, eu_dist*)

Calculate the number of datapoints for which w_k is closest prototype.

input_data: A $n \times m$ matrix of datapoints.

data_labels: A n-dimensional vector containing the labels for each datapoint.

prototype_labels: A n-dimensional vector containing the labels for each prototype.

eu_dist: A $n \times m$ matrix with Euclidean distance between datapoints and prototypes.

w_plus_index: A n-dimensional vector containing the indices for nearest prototypes to datapoints with same label.

pk: A list of numbers of datapoints for which w_k is closest prototype.

normalization (*input_data*)

Normalize the data between range 0 and 1.

input_value: A $n \times m$ matrix of input data.

normalized_data: A $n \times m$ matrix with values between 0 and 1.

one_p_k (*input_data, prototype_labels, w_plus_index*)

A vector which has 1 where data point has closest prototype otherwise zero.

input_data: A $n \times m$ matrix of datapoints.

prototype_labels: A n-dimensional vector containing the labels for each prototype.

w_plus_index: A n-dimensional vector containing the indices for nearest prototypes to datapoints with same label.

pk: A m-dimensional vector which has 1 for data point has closest prototype otherwise zero.

predict (*input_value, input_data*)

Predicts the labels for the data represented by the given test-to-training distance matrix.

input_value: A $n \times m$ matrix of distances from the test to the training datapoints.

input_data: A $n \times m$ matrix of datapoints.

ylabel: A n-dimensional vector containing the predicted labels for each datapoint.

pvt (*input_data, data_labels, prototype_per_class*)

Calculate prototypes with labels either at mean or randomly depends on prototypes per class.

input_value: A $n \times m$ matrix of datapoints.

data_labels: A n-dimensional vector containing the labels for each datapoint.

prototypes per class: The number of prototypes per class to be learned. If it is equal to 1 then prototypes assigned at mean position else it assigns randomly.

prototype_labels: A n-dimensional vector containing the labels for each prototype.

prototypes: A n x m matrix of prototypes for training.

lambda: A n*m array of zeros

pri_labels = array([], dtype=float64)

update (*lam, H, q, learning_rate*)

To update the lambda vector.

$\text{gradient} = H * \text{lambda} - q * \text{lambda}(t+1) = \text{lambda} - \text{learning rate} * \text{gradient}$

lam: A N*K lambda vector where N is the number of data points and K is the number of prototypes

H: A n x n matrix of result $C * I - \sum_k (A_k * (D/P_k) * A_k)$

q: A n-dimensional vector of result: $\gamma * 1.T + \sum_k (1_{\{P_k\}} * (D/P_k) * A_k)$

learning_rate: The step size.

lam_update: A N*K updated lambda vector where N is the number of data points and K is the number of prototypes.

update_beta = array([], dtype=float64)

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