

Filename: C:\Users\Avinash\memscript.py

Line #	Mem usage	Increment	Occurrences	Line Contents
8	73.5 MiB	73.5 MiB	1	def detect():
9	75.0 MiB	1.4 MiB	1	capture=cv2.VideoCapture(r'C:\Users\Avinash\Downloads\laser.mkv') #we use 0 for webcam and file name of
10	75.0 MiB	0.0 MiB	1	start = time.time()
11	75.0 MiB	0.0 MiB	1	kernel = cv2.getStructuringElement(cv2.MORPH_ELLIPSE,(3,3))
12				#fgbg = cv2.bgsegm.createBackgroundSubtractorMOG()
13	75.0 MiB	0.0 MiB	1	fgbg = cv2.createBackgroundSubtractorMOG2(history=100, varThreshold=50, detectShadows=True)
14	75.0 MiB	0.0 MiB	1	countt=0
15	75.0 MiB	0.0 MiB	1	totaltime=0
16	75.0 MiB	0.0 MiB	1	printt=True #used as a key to print the execution time once
17	75.0 MiB	0.0 MiB	1	while True:
18	211.9 MiB	-803.1 MiB	1393	e1 = cv2.getTickCount()
19	211.9 MiB	-803.1 MiB	1393	countt+=1
20	211.9 MiB	-764.3 MiB	1393	ret, frame = capture.read()
21				
22	211.9 MiB	-801.5 MiB	1393	if ret:
23				
24	211.0 MiB	-1527.2 MiB	1393	fgmask = fgbg.apply(frame)
25	211.0 MiB	-74.3 MiB	1393	color_mask = cv2.morphologyEx(fgmask, cv2.MORPH_OPEN, kernel)
26				
27	211.9 MiB	384.0 MiB	1393	contourparts, _ = cv2.findContours(color_mask, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE) #used to
28	211.9 MiB	-24904.3 MiB	31341	contourparts = sorted(contourparts, key=lambda x:cv2.contourArea(x), reverse=True) #selects the
29				
30	211.9 MiB	-804.0 MiB	1393	a=[] #used as a key to enter the if statement.
31	211.9 MiB	-804.0 MiB	1393	xaxis_medium=0 #this variable is used as output to draw a vertical line passing through the cent
32	211.9 MiB	-804.0 MiB	1393	yaxis_medium=0
33				
34	211.9 MiB	-804.0 MiB	1393	if contourparts!=a:
35	211.9 MiB	-796.9 MiB	1374	for cnt in contourparts:
36	211.9 MiB	-796.3 MiB	1374	(leftmost_end, bottommost_end, width, height) = cv2.boundingRect(cnt) #to get the diment
37	211.9 MiB	-796.3 MiB	1374	xaxis_medium = int((leftmost_end +(leftmost_end+width)) /2) #to get the x_axis value of
38	211.9 MiB	-796.3 MiB	1374	yaxis_medium = int((bottommost_end + (bottommost_end+height)) /2)
39	211.9 MiB	-796.3 MiB	1374	break
40				
41	211.9 MiB	-803.4 MiB	1393	e2 = cv2.getTickCount()
42	211.9 MiB	-804.0 MiB	1393	t = (e2 - e1)/cv2.getTickFrequency()
43	211.9 MiB	-804.0 MiB	1394	while printt==True:
44	194.9 MiB	0.0 MiB	1	print("The time of execution of this function:{}").format(t))
45	194.9 MiB	0.0 MiB	1	end=time.time()
46	194.9 MiB	0.0 MiB	1	print('Time consumed in seconds is {}'.format(end-start))
47	194.9 MiB	0.0 MiB	1	printt=False
48	211.9 MiB	-804.0 MiB	1393	totaltime=totaltime+t
49				
50	211.9 MiB	-804.0 MiB	1393	cv2.line(frame,(xaxis_medium,0),(xaxis_medium,1000),(0,255,0),2) #used to draw a vertical line ;
51	211.9 MiB	-804.0 MiB	1393	cv2.line(frame,(0,yaxis_medium),(1700,yaxis_medium),(0,255,0),2)
52	211.9 MiB	-801.3 MiB	1393	cv2.imshow("Frame",frame)
53	211.9 MiB	-801.3 MiB	1393	cv2.imshow("Frame2",color_mask)
54				
55				
56	211.9 MiB	-804.0 MiB	1393	key = cv2.waitKey(1) #used to terminate the program by pressing 'esc' key
57	211.9 MiB	-804.0 MiB	1393	if key==27:
58	211.0 MiB	-0.9 MiB	1	break
59	211.0 MiB	0.0 MiB	1	print(totaltime)
60	211.0 MiB	0.0 MiB	1	print(countt)
61	211.0 MiB	0.0 MiB	1	print(totaltime/countt)
62				
63	211.0 MiB	0.0 MiB	1	print(cv2.useOptimized()) #checks if OpenCV is running optimized code or not
64	174.0 MiB	-37.1 MiB	1	capture.release()
65	168.7 MiB	-5.3 MiB	1	cv2.destroyAllWindows()