

Sub-string/Pattern Matching in Sub-linear Time Using a Sparse Fourier Transform Approach

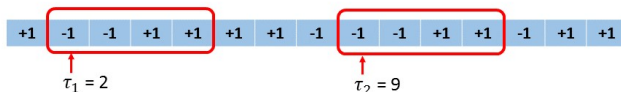
Krishna R. Narayanan

Department of Electrical and Computer Engineering
Texas A&M University

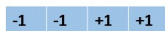


Problem Statement

Database (x)



Query (y)



- **Database/String:** $\underline{x} = [x[0], x[1], \dots, x[N-1]]$ (length N)
- **Query/Substring:** $\underline{y} = [y[0], y[1], \dots, y[M-1]]$ (length $M = N^\mu$)
- Determine all the **L locations** $\underline{\tau} = [\tau_1, \tau_2, \dots, \tau_L]$ with **high probability** where
 - 1 **Exact Matching:** \underline{y} appears **exactly** in \underline{x}
 - $\underline{y} := \underline{x}[\tau : \tau + M - 1]$
 - 2 **Approximate Matching:** \underline{y} is a **noisy substring** of \underline{x}
 - $\underline{y} := \underline{x}[\tau : \tau + M - 1] \odot \underline{b}$
 - \underline{b} is a noise sequence with $d_H(\underline{y}, \underline{x}[\tau : \tau + M - 1]) \leq K$

Main Result

Theorem 1

Assume that a sketch of \underline{x} of size $O(\frac{N}{M} \log N)$ can be precomputed and stored. Then for the exact pattern matching and approximate pattern matching (with $K = \eta M$, $0 \leq \eta \leq 1/6$) problems, with the number of matches L scaling as $O(N^\lambda)$, our algorithm has

- a sketching function for \underline{y} that computes $O(\frac{N}{M} \log N) = O(N^{1-\mu} \log N)$ *samples*
- a *computational complexity* of $O(\max(N^{1-\mu} \log^2 N, N^{\mu+\lambda} \log N))$
- a decoder that recovers all the L matching positions with a *failure probability that approaches zero asymptotically*

Main Result

Theorem 1

Assume that a sketch of \underline{x} of size $O(\frac{N}{M} \log N)$ can be precomputed and stored. Then for the exact pattern matching and approximate pattern matching (with $K = \eta M$, $0 \leq \eta \leq 1/6$) problems, with the number of matches L scaling as $O(N^\lambda)$, our algorithm has

- a sketching function for \underline{y} that computes $O(\frac{N}{M} \log N) = O(N^{1-\mu} \log N)$ *samples*
- a *computational complexity* of $O(\max(N^{1-\mu} \log^2 N, N^{\mu+\lambda} \log N))$
- a decoder that recovers all the L matching positions with a *failure probability that approaches zero asymptotically*

Note

Particularly when $L = O(1)$ or $L < \frac{N}{M}$ (i.e. $\lambda < 1 - \mu$) our algorithm has a *sub-linear time* complexity.

Some Prior Work

Exact Matching

- [?]: First occurrence of the match (only τ_1)
 - Average complexity - $O(N^{1-\mu} \log N)$ (sublinear)
 - Worst case complexity - $O(N \log N)$

Approximate Matching

- [?]: Generalization of [?]
 - Average complexity - $O(NK/M \log N)$ (sub-linear only when $K \ll M$)
- [?]: $O(N/M^{0.359})$ (sub-linear even when $K = O(M)$)
 - Combinatorial in nature

Sparse Fourier Transform Approach

- [?]: Faster GPS receiver
 - Exploited sparsity in Correlation function R_{XY}
- [?]: Robust Sparse Fourier Transform
 - Sparse Graph code Approach
 - Computational complexity : $O(N \log N)$

Motivation

- **Cross-correlation** (\underline{r}):

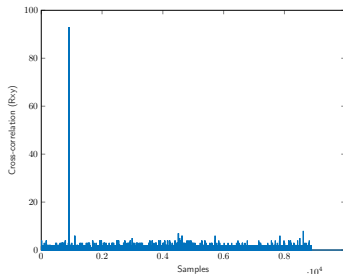
$$r[m] = (\underline{x} * \underline{y})[m] \triangleq \sum_{i=0}^{M-1} x[m+i]y[i], \quad 0 \leq m \leq N-1$$

- **Naive implementation:** $O(MN) = O(N^{1+\mu})$ (**super-linear** complexity)
- **Fourier Transform Approach:** $O(N \log N)$ complexity

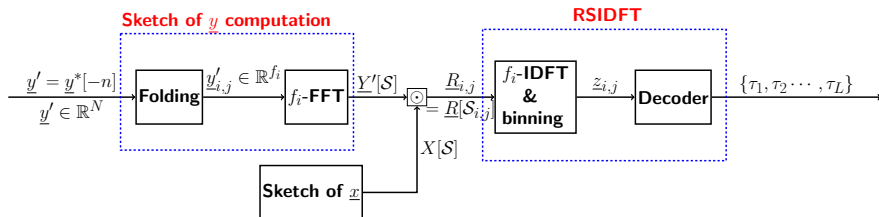
Key Observation

- \underline{r} is **Sparse** with some noise.

$$r[m] = \begin{cases} M, & \text{if } m \in \mathcal{T} \\ n_m, & m \in [N] - \mathcal{T} \end{cases}$$



Sparse Fourier Transform Approach

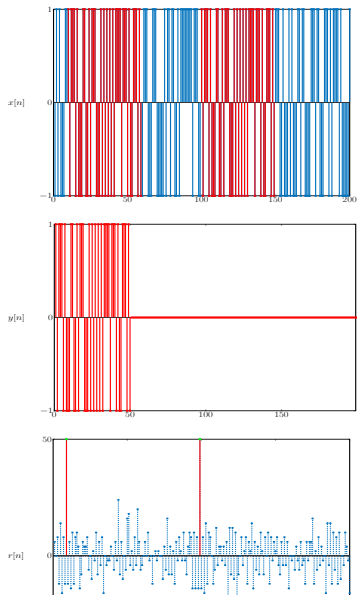


$$\underline{r} = \mathcal{F}_N^{-1} \{ \mathcal{F}_N \{ \underline{x} \} \odot \mathcal{F}_N \{ \underline{y}' \} \}$$

3
1
2

1. *Sketch of \underline{x}* : Assume $\underline{X}[l] = \mathcal{F}\{\underline{x}\}$ is precomputed at positions $l \in S$.
2. *Sketch of \underline{y}* :
 - Compute $\underline{Y}'[l] = \mathcal{F}\{\underline{y}'\}$ for $l \in S$.
 - Only M non-zero values in \underline{y}' - Efficient computation (folding and adding)
3. *Sparse \mathcal{F}^{-1}* :
 - Robust Sparse Inverse Fourier Transform (RSIDFT)
 - Efficient Implementation- sublinear time and sampling complexity

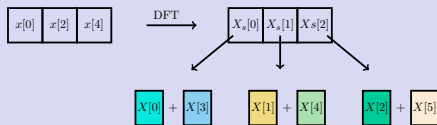
Example



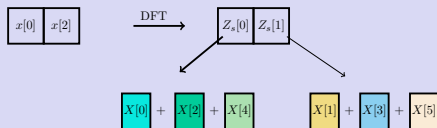
Aliasing and Sparse Graph Codes



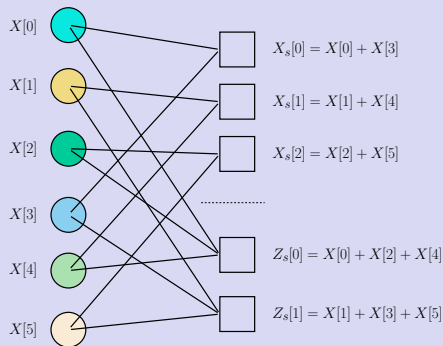
x_s : Sub-sampled by $f_1 = P_1 = 2$



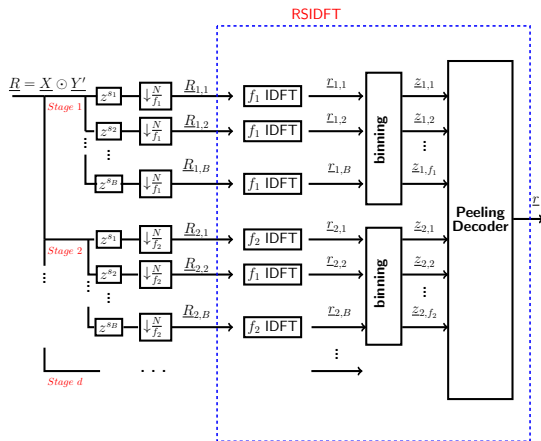
z_s : Sub-sampled by $f_2 = P_2 = 3$



Factor graph

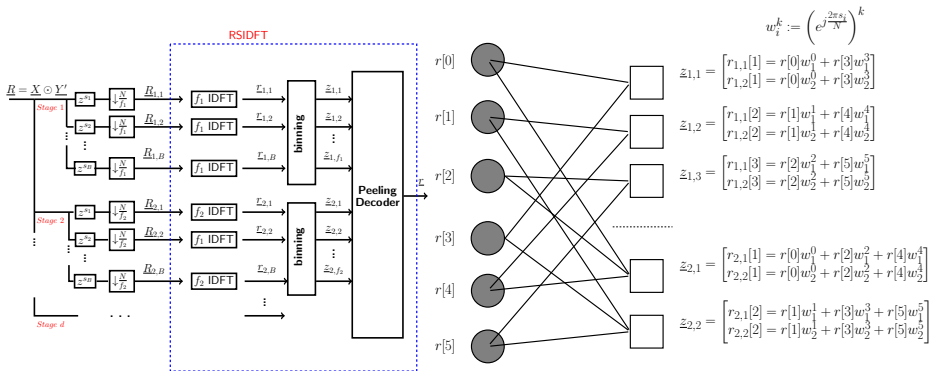


RSIDFT Framework

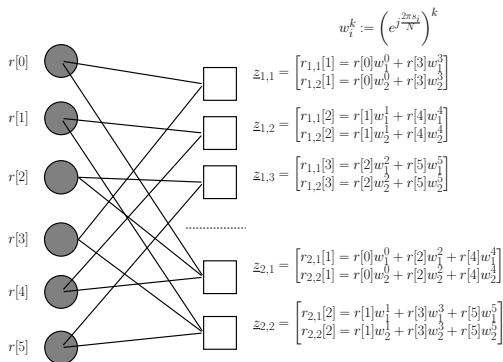


- Similar to FFAST
- Key modifications
 - Correlation peak is always **positive**
 - Take advantage in decoding algorithm - **sub-linear** time complexity

RSIDFT Framework



RSIDFT-Decoding (Peeling Decoder)



- **Observations:** $\underline{z}_{i,k} = [r_{i,1}[k], r_{i,2}[k], \dots, r_{i,B}[k]]^T$
- **Decoding- 3 steps**
 - 1 Bin Classification
 - 2 Position Identification
 - 3 Peeling Process

Decoder

Bin Classification

- Classify each check-node - Zero-ton / Single-ton / Multi-ton
- **Threshold constraints** on first observation $z_{i,k}[1] = z$
- Threshold varies with η
 - different for exact($\eta = 0$) and approximate matching

$$\hat{\mathcal{H}}_{i,j} = \begin{cases} \mathcal{H}_z & z/M < \gamma_1 \\ \mathcal{H}_s & \gamma_1 < z/M < \gamma_2 \\ \mathcal{H}_d & \gamma_2 < z/M < \gamma_3 \\ \mathcal{H}_m & z/M > \gamma_3 \end{cases}$$

where $(\gamma_1, \gamma_2, \gamma_3) = (\frac{1-2\eta}{2}, \frac{3-4\eta}{2}, \frac{5-6\eta}{2})$

Decoder

Position Identification

- Observation:

$$\underline{z}_{i,k} = \mathbb{W}_{i,k} \times \begin{bmatrix} r[k + (0)f_i] \\ r[k + (1)f_i] \\ \vdots \\ r[k + (g_i - 1)f_i] \end{bmatrix}$$

- Sensing Matrix:

$$\mathbb{W}_{i,k} = \left[\underline{w}^k, \underline{w}^{k+f_i}, \dots, \underline{w}^{k+(g_i-1)f_i} \right] \text{ where } \underline{w}^k = \begin{bmatrix} e^{\frac{j2\pi ks_1}{N}} \\ e^{\frac{j2\pi ks_2}{N}} \\ \vdots \\ e^{\frac{j2\pi ks_B}{N}} \end{bmatrix}, \quad g_i = \frac{N}{f_i}$$

- Column that gives **maximum correlation** with the observation

$$\hat{k} = \arg \max_{k \in \{j+lg_i\}} \underline{z}_{i,j}^\dagger \underline{w}^k$$

Decoder

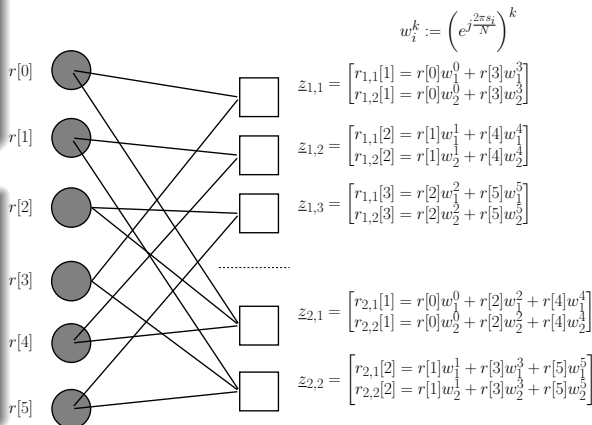
Peeling Process:

Exact Matching

- Remove a decoded variable node's contribution from **all** participating bin nodes

Approximate Matching

- Remove a decoded variable node's contribution only from neighboring **single-tons** and **double-tons**
- Avoid error propagation



Simulation Results

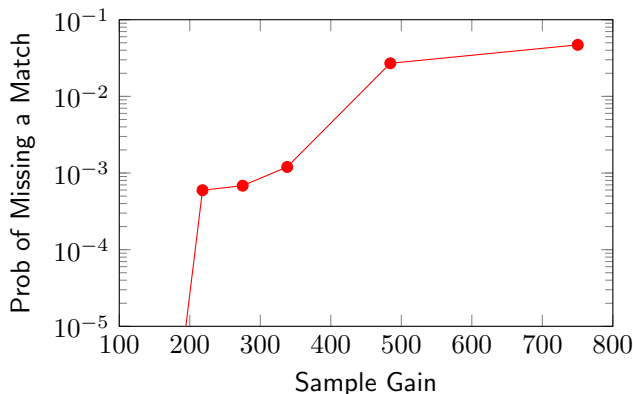


Figure: Plot of Probability of Missing a Match vs. Sample Gain for Exact Matching of a substring of length $M = 10^5$ from a equiprobable binary $\{+1, -1\}$ sequence of length $N = 10^{12}$, divided into $G = 10^5$ blocks each of length $\tilde{N} = 10^7$. The substring was simulated to repeat in $L = 10^6$ locations uniformly at random.

Simulation Results

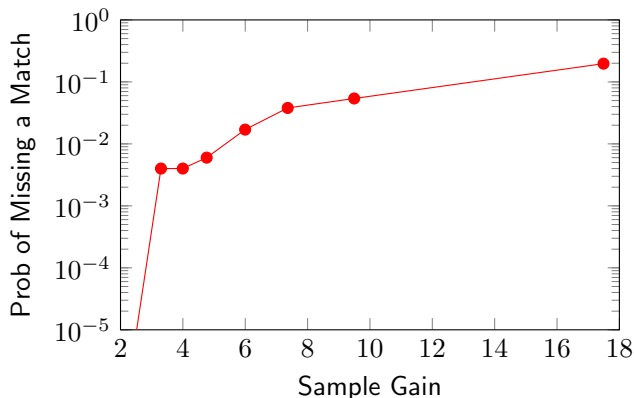


Figure: Plot of Probability of Missing a Match vs. Sample Gain for Exact Matching of a substring of length $M = 10^3$ from a equiprobable binary $\{+1, -1\}$ sequence of length $N = 10^{12}$, divided into $G = 10^6$ blocks each of length $\tilde{N} = 10^6$. The substring was simulated to repeat in $L = 10^6$ locations uniformly at random.

Questions?



Thank you!