

The Peeling Decoder : Theory and some Applications

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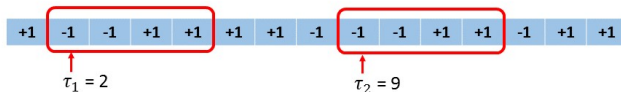
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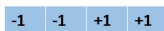


Pattern Matching

Database (x)



Query (y)



- **Database/String:** $\underline{x} = [x[0], x[1], \dots, x[N]]$ (length N)
- **Query/Substring:** $\underline{y} = [y[0], y[1], \dots, y[M]]$ (length $M = N^\mu$)
- Determine all the **L locations** $\underline{\tau} = [\tau_1, \tau_2, \dots, \tau_L]$ with **high probability** where
 - 1 **Exact Matching:** \underline{y} appears **exactly** in \underline{x}
 - $\underline{y} := \underline{x}[\tau : \tau + M - 1]$
 - 2 **Approximate Matching:** \underline{y} is a **noisy substring** of \underline{x}
 - $\underline{y} := \underline{x}[\tau : \tau + M - 1] \odot \underline{b}$
 - \underline{b} is a noise sequence with $d_H(\underline{y}, \underline{x}[\tau : \tau + M - 1]) \leq K$

Main Result

Theorem 1

Assume that a sketch of \underline{x} of size $O(\max(M, N/M) \log N)$ can be precomputed and stored. Then for the exact pattern matching and approximate pattern matching (with $K = \eta M$, $0 \leq \eta \leq 1/6$) problems, with the number of matches L scaling as $O(N^\lambda)$, our algorithm has

- a sketching function for \underline{y} that computes $O(\max(M, \frac{N}{M}) \log N) = O(N^{\max(\mu, 1-\mu)} \log N)$ *samples*
- a *computational complexity* of
 - $O(\max(N^{1-\mu} \log^2 N, N^{\mu+\lambda} \log N))$ for $\mu < 0.5$
 - $O(\max(N^\mu \log^2 N, N^{1-\mu+\lambda} \log N))$ for $\mu > 0.5$
- a decoder that recovers all the L matching positions with a *failure probability that approaches zero asymptotically*

Note: Particularly when $L = O(1)$ or $L < \frac{N}{M}$ (i.e. $\lambda < 1 - \mu$) our algorithm has a *sub-linear time* complexity.

Some Prior Work

Exact Matching

- **boyer1977fast**: First occurrence of the match (only τ_1)
 - Average complexity - $O(N^{1-\mu} \log N)$ (sublinear)
 - Worst case complexity - $O(N \log N)$

Approximate Matching

- **chang1994approximate**: Generalization of **boyer1977fast**
 - Average complexity - $O(NK/M \log N)$ (sub-linear only when $K \ll M$)
- **andoni2013shift**: $O(N/M^{0.359})$ (sub-linear even when $K = O(M)$)
 - Combinatorial in nature

Sparse Fourier Transform Approach

- **hassanieh2012faster**: Faster GPS receiver
 - Exploited sparsity in Correlation function R_{XY}
- **pawar2014robust**: Robust Sparse Fourier Transform
 - Sparse Graph code Approach
 - Computational complexity : $O(N \log N)$

Motivation

- **Cross-correlation** (\underline{r}):

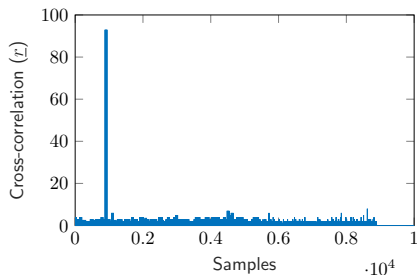
$$r[m] = (\underline{x} * \underline{y})[m] \triangleq \sum_{i=0}^{M-1} x[m+i]y[i], \quad 0 \leq m \leq N-1$$

- **Naive implementation:** $O(MN) = O(N^{1+\mu})$ (**super-linear** complexity)
- **Fourier Transform Approach:** $O(N \log N)$ complexity

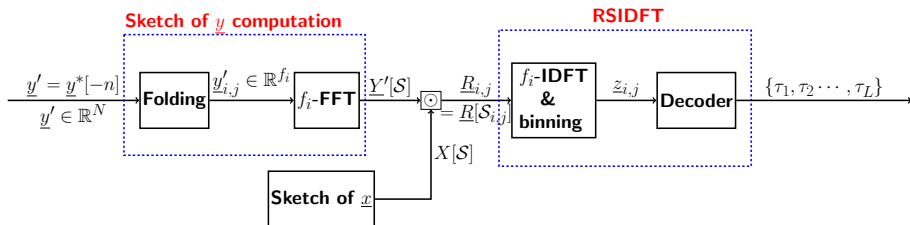
Key Observation

- \underline{r} is **Sparse** with some noise.

$$r[m] = \begin{cases} M, & \text{if } m \in \mathcal{T} \\ n_m, & m \in [N] - \mathcal{T} \end{cases}$$



Sparse Fourier Transform Approach



$$\underline{r} = \underset{1}{\mathcal{F}_N^{-1}} \{ \underset{2}{\mathcal{F}_N\{\underline{x}\}} \odot \underset{3}{\mathcal{F}_N\{\underline{y}'\}} \}$$

1. **Sketch of \underline{x}** : Assume $\underline{X}[l] = \mathcal{F}\{\underline{x}\}$ is precomputed at positions $l \in S$.
2. **Sketch of \underline{y}** :
 - Compute $\underline{Y}'[l] = \mathcal{F}\{\underline{y}'\}$ for $l \in S$.
 - Only M non-zero values in \underline{y}' - Efficient computation (folding and adding)
3. **Sparse \mathcal{F}^{-1}** :
 - Robust Sparse Inverse Fourier Transform (RSIDFT)
 - Efficient Implementation- **sublinear** time and sampling complexity

Questions?



Thank you!